## Optimal Stochastic Algorithms for Convex-Concave Saddle Point Problems

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- Introduction
  Problem Setup
  Main Contribution
- 2 Preliminaries
- **3** Algorithm for  $\mu = 0$
- **6** Future Directions

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$$\min_{x \in \mathcal{X}} \max_{y \in \mathcal{Y}} \left[ S(x, y) \triangleq f(x) + g(x) + \Phi(x, y) - J(y) \right], \tag{SPP}$$

Consider the following convex-concave saddle point problem (SPP)

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 $\triangleright$   $\mathcal{X} \subseteq \mathbb{X}$  and  $\mathcal{Y} \subseteq \mathbb{Y}$  are nonempty, closed and convex sets, where  $\mathbb{X}$  and  $\mathbb{Y}$  be two finite-dimensional real normed spaces.

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- $\triangleright$  X\* and Y\* are the dual spaces of X and Y, respectively.
- ho  $\Phi: \mathbb{X} \times \mathbb{Y} \to [-\infty, +\infty]$  is convex-concave, i.e.,  $\Phi(\cdot, y)$  is convex and  $\Phi(x, \cdot)$  is concave, for any  $(x, y) \in \mathbb{X} \times \mathbb{Y}$ .

 $\triangleright$  f is  $\mu$ -strong convex (s.c.) and L-smooth on  $\mathcal{X}$  ( $L \ge \mu \ge 0$ ), i.e.,

$$\frac{\mu}{2} \|x - x'\|_{\mathbb{X}}^2 \le f(x) - f(x') - \langle \nabla f(x'), x - x' \rangle \le \frac{L}{2} \|x - x'\|_{\mathbb{X}}^2, \forall x, x' \in \mathcal{X}.$$

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- $\triangleright$  g and J admit tractable Bregman proximal projections on  $\mathcal{X}$  and  $\mathcal{Y}$ , respectively. Also, dom  $g \cap \mathcal{X} \neq \emptyset$  and dom  $J \cap \mathcal{Y} \neq \emptyset$ .

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- $\triangleright \Phi$  is  $(L_{xx}, L_{yx}, L_{yy})$ -smooth on  $\mathcal{X} \times \mathcal{Y}$ , i.e.,

$$\|\nabla_x \Phi(x, y) - \nabla_x \Phi(x', y)\|_{\mathbb{X}^*} \le L_{xx} \|x - x'\|_{\mathbb{X}},$$
 (1a)

$$\|\nabla_x \Phi(x, y) - \nabla_x \Phi(x, y')\|_{\mathbb{X}^*} \le L_{yx} \|y - y'\|_{\mathbb{Y}},$$
 (1b)

$$\|\nabla_y \Phi(x, y) - \nabla_y \Phi(x', y)\|_{\mathbb{V}^*} \le L_{yx} \|x - x'\|_{\mathbb{X}},$$
 (1c)

$$\|\nabla_y \Phi(x, y) - \nabla_y \Phi(x, y')\|_{\mathbb{V}^*} \le L_{yy} \|y - y'\|_{\mathbb{V}}.$$
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$$\|\nabla_{y}\Phi(x,y) - \nabla_{y}\Phi(x,y')\|_{\mathbb{V}^{*}} \le L_{yy} \|y - y'\|_{\mathbb{V}}. \tag{1d}$$

 $\triangleright$  A saddle point  $(x^*, y^*) \in \mathcal{X} \times \mathcal{Y}$  exists for (SPP), i.e.,

$$S(x^*, y) \le S(x^*, y^*) \le S(x, y^*), \quad \forall (x, y) \in \mathcal{X} \times \mathcal{Y}.$$

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  - Kernel Matrix Learning

#### Stochastic First-Order Oracles

$$f(x) \triangleq \mathbb{E}_{\xi}[\tilde{f}(x,\xi)] \qquad \quad \Phi(x,y) \triangleq \mathbb{E}_{\zeta}[\tilde{\Phi}(x,y,\zeta)]$$

### Stochastic First-Order Oracles

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#### Oracle model (Stochastic approximation):

Return estimators of  $\nabla f$ ,  $\nabla \Phi(\cdot, y)$  and  $\nabla \Phi(x, \cdot)$ , i.e.,  $\hat{\nabla} f$ ,  $\hat{\nabla} \Phi(\cdot, y)$  and  $\hat{\nabla} \Phi(x, \cdot)$ , that

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- ▷ (may also) obey "light-tailed" distributions

Gradient Noise	Mean	Variance
$\delta_{x,f} \triangleq \hat{\nabla} f - \nabla f$	0	$\sigma_{x,f}^2$
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 $ightharpoonup (SPP) o SPP(L, L_{xx}, L_{yx}, L_{yy}, \sigma, \mu), \text{ where } \sigma \triangleq \sigma_{x,f} + \sigma_{x,\Phi} + \sigma_{y,\Phi}.$ 

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- $\triangleright$  Consider the *sub-Gaussian* gradient noises.
- $\triangleright$  To obtain an  $\epsilon$ -duality gap w.p.  $\geq 1 \nu$ , the oracle complexity is

$$O\left(\left(\sqrt{\frac{L}{\mu}} + \frac{L_{xx}}{\mu}\right)\log\left(\frac{1}{\epsilon}\right) + \frac{L_{yx}}{\sqrt{\mu\epsilon}} + \frac{L_{yy}}{\epsilon} + \left(\frac{(\sigma_{x,f} + \sigma_{x,\Phi})^2}{\mu\epsilon} + \frac{\sigma_{y,\Phi}^2}{\epsilon^2}\right)\log\left(\frac{\log(1/\epsilon)}{\nu}\right)\right).$$

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- The complexities of  $L_{xx}$  and  $L_{yy}$  are the best-known. (Lower bound? Acceleration?)

## Comparison with Other Methods

Algorithm	Problem Class	Oracle Complexity	
PDHG-type	$\sigma = 0$ $L = 0$	$O\left(\frac{L+L_{xx}+L_{yx}}{\sqrt{\mu\epsilon}}\right)$	
[Hamedani & Aybat'18]	$\sigma = 0, L_{yy} = 0$	$O\left(\frac{\sqrt{\mu\epsilon}}{\sqrt{\epsilon}}\right)$	
Mirror-Prox-B		/ - \	
[Juditsky &	$\sigma = 0, L_{yy} = 0$	$O\left(\frac{L+L_{xx}}{\mu}\log\left(\frac{1}{\epsilon}\right) + \frac{L_{yx}}{\sqrt{\mu\epsilon}}\right)$	
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- For  $\sigma = 0$  and  $L_{yy} = 0$ , strictly better than the previous methods.
- For  $\sigma > 0$  and  $L_{yy} > 0$ , the first complexity result.

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- The complexities of  $L_{xx}$  and  $L_{yy}$  are the best-known. (Lower bound? Acceleration?)
- $\triangleright$  If the gradient noises are sub-Gaussian, to obtain an  $\epsilon$ -duality gap w.p. at least  $1 \nu$ , the oracle complexity is

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PDHG-type	$\sigma = 0$	$O\left(\frac{L}{\epsilon} + \frac{L_{xx} + L_{yx} + L_{yy}}{\epsilon}\right)$
[Hamedani & Aybat'18]	$\theta = 0$	$O\left(\frac{\epsilon}{\epsilon} + \frac{\epsilon}{\epsilon}\right)$
Mirror-Prox	$\sigma = 0$	$O\left(\frac{L}{\epsilon} + \frac{L_{xx} + L_{yx} + L_{yy}}{\epsilon}\right)$
[Nemirovski'05]	$\sigma = 0$	$O\left(\frac{\epsilon}{\epsilon} + \frac{\epsilon}{\epsilon}\right)$
Stoc. MP	$\sigma > 0$	$O\left(\frac{L}{\epsilon} + \frac{L_{xx} + L_{yx} + L_{yy}}{\epsilon} + \frac{(\sigma_{x,f} + \sigma_{x,\Phi})^2 + \sigma_{y,\Phi}^2}{\epsilon^2}\right)$
[Juditsky et al.'11]	0 > 0	$O\left(\frac{\epsilon}{\epsilon} + \frac{\epsilon}{\epsilon} + \frac{\epsilon^2}{\epsilon}\right)$
Stoc. Acc. MP	$\sigma > 0$	$O\left(\sqrt{\frac{L}{\epsilon}} + \frac{L_{xx} + L_{yx} + L_{yy}}{\epsilon} + \frac{(\sigma_{x,f} + \sigma_{x,\Phi})^2 + \sigma_{y,\Phi}^2}{\epsilon^2}\right)$
[Chen et al.'17]	0 > 0	$O\left(\sqrt{\frac{\epsilon}{\epsilon}} + \frac{\epsilon}{\epsilon} + \frac{\epsilon^2}{\epsilon}\right)$
Algorithm 1	$\sigma > 0$	$O\left(\sqrt{\frac{L}{\epsilon}} + \frac{L_{xx} + L_{yx} + L_{yy}}{\epsilon} + \frac{(\sigma_{x,f} + \sigma_{x,\Phi})^2 + \sigma_{y,\Phi}^2}{\epsilon^2}\right)$
[Zhao'19]	0 > 0	$O\left(\sqrt{\frac{\epsilon}{\epsilon}} + \frac{1}{\epsilon}\right) + \frac{1}{\epsilon^2}$

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$$u' \mapsto u^+ \triangleq \mathbf{prox}_{\lambda\varphi}(u' - \lambda u^*).$$

$$(\mathbb{P}): \ \min_{x \in \mathcal{X}} \left[ \bar{S}(x) \triangleq \sup_{y \in \mathcal{Y}} S(x,y) \right], \quad (\mathbb{D}): \ \max_{y \in \mathcal{Y}} \left[ \underline{S}(x) \triangleq \inf_{x \in \mathcal{X}} S(x,y) \right].$$

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- $\triangleright$  Define the duality gap

$$G(x,y) \triangleq \bar{S}(x) - \underline{S}(y) = \sup_{x' \in \mathcal{X}, y' \in \mathcal{Y}} S(x,y') - S(x',y).$$

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### Algorithm 1: An Optimal Algorithm for $\mu = 0$

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$$t := t + 1$$

▶ Output:  $(\bar{x}^t, \bar{y}^t)$ 

▷ Bregman diameters:

$$\Omega_{h_{\mathcal{X}}} \triangleq \sup_{x \in \mathcal{X}, x' \in \mathcal{X}^o} D_{h_{\mathcal{X}}}(x, x'), \quad \Omega_{h_{\mathcal{Y}}} \triangleq \sup_{y \in \mathcal{Y}, y' \in \mathcal{Y}^o} D_{h_{\mathcal{Y}}}(y, y').$$

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 $\triangleright$  Gradient noises at iteration t:

$$\begin{split} & \delta_{y,\Phi}^t \triangleq \hat{\nabla}_y \Phi(x^t, y^t, \zeta_y^t) - \nabla_y \Phi(x^t, y^t), \\ & \delta_{x,\Phi}^t \triangleq \hat{\nabla}_x \Phi(x^t, y^{t+1}, \zeta_x^t) - \nabla_x \Phi(x^t, y^{t+1}), \\ & \delta_{x,f}^t \triangleq \hat{\nabla} f(\tilde{x}^{t+1}, \xi^t) - \nabla f(\tilde{x}^{t+1}). \end{split}$$

#### Assumptions 1 (On Constraint Sets)

- **A** The Bregman diameters  $\Omega_{h_{\mathcal{X}}}$  and  $\Omega_{h_{\mathcal{Y}}}$  are bounded.
- **B** The set  $\mathcal{X}$  is bounded and the Bregman diameter  $\Omega_{h_{\mathcal{Y}}}$  is bounded.

#### Assumptions 2 (On Gradient Noises)

Define  $\mathbb{E}_t[\cdot] \triangleq \mathbb{E}[\cdot \mid \mathcal{F}_t]$ . For any  $x \in \mathcal{X}$  and  $y \in \mathcal{Y}$  and any  $t \in \mathbb{N}$ , there exist positive constants  $\sigma_{y,\Phi}$ ,  $\sigma_{x,\Phi}$  and  $\sigma_{x,f}$  such that

- $\mathbb{E}_{t-1}[\delta_{y,\Phi}^t] = 0, \ \mathbb{E}_{t-1}[\delta_{x,\Phi}^t] = 0, \ \mathbb{E}_{t-1}[\delta_{x,f}^t] = 0 \ a.s.,$
- **B** (Bounded variance)  $\mathbb{E}_{t-1}[\|\delta_{y,\Phi}^t\|_*^2] \leq \sigma_{y,\Phi}^2$ ,  $\mathbb{E}_{t-1}[\|\delta_{x,\Phi}^t\|_*^2] \leq \sigma_{x,\Phi}^2$ ,  $\mathbb{E}_{t-1}[\|\delta_{x,f}^t\|_*^2] \leq \sigma_{x,f}^2$  a.s.,
- (Sub-Gaussian distributions)

$$\mathbb{E}_{t-1} \left[ \exp \left( \|\delta_{y,\Phi}^t\|_*^2 / \sigma_{y,\Phi}^2 \right) \right] \le \exp(1), \ \mathbb{E}_{t-1} \left[ \exp \left( \|\delta_{x,\Phi}^t\|_*^2 / \sigma_{x,\Phi}^2 \right) \right] \le \exp(1),$$

$$\mathbb{E}_{t-1} \left[ \exp \left( \|\delta_{x,f}^t\|_*^2 / \sigma_{x,f}^2 \right) \right] \le \exp(1) \ a.s..$$

#### Convergence Results

#### Theorem 1

Let Assumptions 1(A) and 2(A) hold. In Algorithm 1, for any  $t \in \mathbb{N}$ , choose

$$\begin{split} \theta_t &= \frac{t-1}{t}, \quad \beta_t = \frac{2}{t+1}, \quad \alpha_t = \frac{1}{16\left(L_{yx} + L_{yy} + \rho\sigma_{y,\Phi}\sqrt{t}\right)}, \\ \tau_t &= \frac{t}{2\left(2L + (L_{xx} + L_{yx})t + \rho'(\sigma_{x,\Phi} + \sigma_{x,f})t^{3/2}\right)}, \end{split}$$

where  $\rho, \rho' > 0$  are constants independent of the parameters of interest, i.e.,  $(L, L_{xx}, L_{yx}, L_{yy}, \sigma_{x,f}, \sigma_{x,\Phi}, \sigma_{y,\Phi}, t)$ .

**1** If Assumption 2(B) also holds, then for any  $T \geq 3$ , we have

$$\begin{split} &\mathbb{E}[G(\bar{x}^T, \bar{y}^T)] \leq B_{\mathrm{e}}(T) \triangleq \frac{16L}{T(T-1)} \Omega_{h_{\mathcal{X}}} + \frac{8(L_{xx} + L_{yx})}{T} \Omega_{h_{\mathcal{X}}} \\ &+ \frac{128(L_{yx} + L_{yy})}{T} \Omega_{h_{\mathcal{Y}}} + \frac{8\sigma_{y,\Phi}}{\sqrt{T}} \left(\frac{1}{\rho} + 16\rho\Omega_{h_{\mathcal{Y}}}\right) + \frac{8(\sigma_{x,f} + \sigma_{x,\Phi})}{\sqrt{T}} \left(\frac{1}{\rho'} + \rho'\Omega_{h_{\mathcal{X}}}\right). \end{split}$$

#### Convergence Results

Thus, the oracle complexity of obtaining an  $\epsilon$ -expected duality gap is

$$O\left(\sqrt{L/\epsilon} + (L_{xx} + L_{yx} + L_{yy})/\epsilon + \left((\sigma_{x,f} + \sigma_{x,\Phi})^2 + \sigma_{y,\Phi}^2\right)/\epsilon^2\right).$$

**2** Let  $\nu \in (0, 1/6]$ . If Assumption 2(C) also holds, then w.p. at least  $1 - 6\nu$ ,

$$G(\bar{x}^T, \bar{y}^T) \le B_{\mathrm{e}}(T) + \frac{8\sigma_{y,\Phi}}{\sqrt{T}} \left( \frac{\log(1/\nu)}{\rho} + \sqrt{\log(1/\nu)\Omega_{h_{\mathcal{Y}}}} \right) + \frac{8(\sigma_{x,\Phi} + \sigma_{x,f})}{\sqrt{T}} \left( \frac{\log(1/\nu)}{\rho'} + \sqrt{\log(1/\nu)\Omega_{h_{\mathcal{X}}}} \right).$$

Thus, the oracle complexity of obtaining an  $\epsilon$ -duality gap  $w.p. \geq 1 - \nu$  is

$$O\left(\sqrt{\frac{L}{\epsilon}} + \frac{L_{xx} + L_{yx} + L_{yy}}{\epsilon} + \frac{(\sigma_{x,f} + \sigma_{x,\Phi})^2 + \sigma_{y,\Phi}^2}{\epsilon^2} \log\left(\frac{1}{\nu}\right)\right).$$

- Introduction Problem Setup Main Contribution
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- **a** Restart Scheme for  $\mu > 0$ Subroutine Stochastic Restart Scheme
- **6** Future Directions

Most of the subroutines need to satisfy: For any starting point  $\bar{x}^1$  and any  $\epsilon, \delta > 0$ , there exists  $T \in \mathbb{N}$  such that

$$\mathbb{E}[\|\bar{x}^1 - x^*\|^2] \le \delta \quad \Longrightarrow \quad \mathbb{E}[f(\bar{x}^T) - f(x^*)] \le \epsilon.$$

where  $\bar{x}^T$  denotes the T-th iterate produced by the subroutine.

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 $\triangleright$  By the strong convexity of f, we can bound

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- $\triangleright$  However, this does not work for SPP (convergence measured by duality gap, and only diameters  $\Omega_{h_{\mathcal{X}}}$  and  $\Omega_{h_{\mathcal{Y}}}$  appear in the bound)
  - $\Longrightarrow$  New schemes need to be developed.

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- $\triangleright$  Define a rescaled DGFs on  $\bar{\mathcal{X}}(x_c, R)$ :

$$\tilde{h}_{\bar{\mathcal{X}}(x_{c},R)}(x) \triangleq R^{2} h_{\mathcal{X}}\left(\frac{x-x_{c}}{R}\right).$$
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▷ The corresponding Bregman distances are

$$D_{\tilde{h}_{\bar{\mathcal{X}}(x_{\mathsf{c}},R)}}(x,x') = R^2 \left\{ h_{\mathcal{X}} \left( \frac{x-x_{\mathsf{c}}}{R} \right) - h_{\mathcal{X}} \left( \frac{x'-x_{\mathsf{c}}}{R} \right) - \left\langle \nabla h_{\mathcal{X}} \left( \frac{x'-x_{\mathsf{c}}}{R} \right), \frac{x-x'}{R} \right\rangle \right\}.$$

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Define  $\mathcal{B}(x_{c}, R) \triangleq \{x \in \mathbb{X} : ||x - x_{c}|| \leq R\}$ . If  $\mathcal{B}(0, 1) \subseteq \text{dom } h_{\mathcal{X}}$ , then  $\sup_{x \in \mathcal{X} \cap \mathcal{B}(x_{c}, R)} D_{\bar{h}_{\bar{\mathcal{X}}(x_{c}, R)}}(x, x_{c}) \leq R^{2} \Omega'_{h_{\mathcal{X}}},$ where  $\Omega'_{h_{\mathcal{X}}} \triangleq \sup_{z \in \mathcal{B}(0, 1)} D_{h_{\mathcal{X}}}(z, 0) < +\infty$ .

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  - where  $\Omega'_{h_{\mathcal{X}}} \triangleq \sup_{z \in \mathcal{B}(0,1)} D_{h_{\mathcal{X}}}(z,0) < +\infty.$
- ightharpoonup If X is a Hilbert space and  $h_{\mathcal{X}} = (1/2) \|\cdot\|^2$ , then

$$\tilde{h}_{\bar{\mathcal{X}}(x_{\text{c}},R)}(x) = (1/2) \|x - x_{\text{c}}\|^2, \quad D_{\tilde{h}_{\bar{\mathcal{X}}(x_{\text{c}},R)}}(x,x') = (1/2) \|x - x'\|^2.$$

▶ Input: Starting primal variable  $x^0 \in \mathcal{X}^o$ , radius R, primal constraint set  $\mathcal{X}'$  ( $\mathcal{X}' \subseteq \mathcal{X}$ ), number of iterations T, interp. seq.  $\{\beta_t\}_{t \in \mathbb{N}}$ , dual stepsizes  $\{\alpha_t\}_{t \in \mathbb{N}}$ , primal stepsizes  $\{\tau_t\}_{t \in \mathbb{N}}$ , relaxation seq.  $\{\theta_t\}_{t \in \mathbb{N}}$ , DGFs  $h_{\mathcal{Y}}: \mathbb{Y} \to \overline{\mathbb{R}}$  and  $h_{\mathcal{X}}: \mathbb{X} \to \overline{\mathbb{R}}$ 

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$$y^{t+1} := \arg\min_{y \in \mathcal{Y}} J(y) - \langle s^t, y - y^t \rangle + \alpha_t^{-1} D_{\tilde{h}_{\mathcal{Y}}}(y, y^t) \qquad \text{(Dual Ascent)}$$

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$$\tilde{x}^{t+1} := (1 - \beta_t) \bar{x}^t + \beta_t x^t$$
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$$+ \tau_t^{-1} D_{\tilde{h}_{\tilde{\mathcal{X}}(x^1, R)}}(x, x^t) \qquad \text{(Primal Descent)}$$

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- ▶ For t = 1, ..., T 1

$$\begin{split} y^{t+1} &:= \arg\min_{y \in \mathcal{Y}} J(y) - \langle s^t, y - y^t \rangle + \alpha_t^{-1} D_{\tilde{h}_{\mathcal{Y}}}(y, y^t) & \text{(Dual Ascent)} \\ \tilde{x}^{t+1} &:= (1 - \beta_t) \bar{x}^t + \beta_t x^t & \text{(Interpolation)} \\ x^{t+1} &:= \arg\min_{x \in \mathcal{X}'} g(x) + \langle \hat{\nabla}_x \Phi(x^t, y^{t+1}, \zeta_x^t) + \hat{\nabla} f(\tilde{x}^{t+1}, \xi^t), x - x^t \rangle \\ & + \tau_t^{-1} D_{\tilde{h}_{\bar{\mathcal{X}}(x^1, R)}}(x, x^t) & \text{(Primal Descent)} \\ s^{t+1} &:= (1 + \theta_{t+1}) \hat{\nabla}_y \Phi(x^{t+1}, y^{t+1}, \zeta_y^{t+1}) - \theta_{t+1} \hat{\nabla}_y \Phi(x^t, y^t, \zeta_y^t) & \text{(Extrap.)} \end{split}$$

 $\bar{x}^{t+1} := (1 - \beta_t)\bar{x}^t + \beta_t x^{t+1}, \quad \bar{y}^{t+1} := (1 - \beta_t)\bar{y}^t + \beta_t y^{t+1}$  (Averaging)

- ▶ Input: Starting primal variable  $x^0 \in \mathcal{X}^o$ , radius R, primal constraint set  $\mathcal{X}'$  ( $\mathcal{X}' \subseteq \mathcal{X}$ ), number of iterations T, interp. seq.  $\{\beta_t\}_{t \in \mathbb{N}}$ , dual stepsizes  $\{\alpha_t\}_{t \in \mathbb{N}}$ , primal stepsizes  $\{\underline{\tau}_t\}_{t \in \mathbb{N}}$ , relaxation seq.  $\{\theta_t\}_{t \in \mathbb{N}}$ , DGFs  $h_{\mathcal{Y}}: \mathbb{Y} \to \overline{\mathbb{R}}$  and  $h_{\mathcal{X}}: \mathbb{X} \to \overline{\mathbb{R}}$
- ▶ Init:  $(x^1, y^1) \in \mathcal{X}^o \times \mathcal{Y}^o$ ,  $\bar{x}^1 = x^1$ ,  $\bar{y}^1 = y^1$ ,  $s^1 = \hat{\nabla}_y \Phi(x^1, y^1, \zeta_y^1)$
- ▶ **Define**:  $\bar{\mathcal{X}}(x^1, R)$  and  $\tilde{h}_{\bar{\mathcal{X}}(x^1, R)}$  using  $h_{\mathcal{X}}$ ,  $x^1$  and R
- ▶ For t = 1, ..., T 1

$$\begin{split} y^{t+1} &:= \arg\min_{y \in \mathcal{Y}} J(y) - \langle s^t, y - y^t \rangle + \alpha_t^{-1} D_{\tilde{h}_{\mathcal{Y}}}(y, y^t) & \text{(Dual Ascent)} \\ \tilde{x}^{t+1} &:= (1 - \beta_t) \bar{x}^t + \beta_t x^t & \text{(Interpolation)} \\ x^{t+1} &:= \arg\min_{x \in \mathcal{X}'} g(x) + \langle \hat{\nabla}_x \Phi(x^t, y^{t+1}, \zeta_x^t) + \hat{\nabla} f(\tilde{x}^{t+1}, \xi^t), x - x^t \rangle \\ &+ \tau_t^{-1} D_{\tilde{h}_{\tilde{\mathcal{X}}(x^1, R)}}(x, x^t) & \text{(Primal Descent)} \end{split}$$

$$s^{t+1} := (1 + \theta_{t+1}) \hat{\nabla}_y \Phi(x^{t+1}, y^{t+1}, \zeta_y^{t+1}) - \theta_{t+1} \hat{\nabla}_y \Phi(x^t, y^t, \zeta_y^t) \text{ (Extrap.)}$$
$$\bar{x}^{t+1} := (1 - \beta_t) \bar{x}^t + \beta_t x^{t+1}, \quad \bar{y}^{t+1} := (1 - \beta_t) \bar{y}^t + \beta_t y^{t+1} \text{ (Averaging)}$$

▶ Output:  $(\bar{x}^T, \bar{y}^T)$ 

$$\underset{x \in \mathcal{X}'}{\arg\min} g(x) + \langle x^*, x \rangle + \tau_t^{-1} R^2 h_{\mathcal{X}} \left( \frac{x - x_c}{R} \right)$$

$$\underset{x \in \mathcal{X}'}{\arg\min} g(x) + \langle x^*, x \rangle + \tau_t^{-1} R^2 h_{\mathcal{X}} \left( \frac{x - x_c}{R} \right)$$

$$\triangleright g \equiv 0 \text{ and } \mathcal{X}' = \mathcal{X} = \mathbb{X},$$

$$\underset{x \in \mathcal{X}'}{\arg\min} g(x) + \langle x^*, x \rangle + \tau_t^{-1} R^2 h_{\mathcal{X}} \left( \frac{x - x_c}{R} \right)$$

- $\triangleright g \equiv 0 \text{ and } \mathcal{X}' = \mathcal{X} = \mathbb{X},$
- $\triangleright$  X is a Hilbert space

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- $\triangleright$  X is a Hilbert space
  - $\mathcal{X}' = \mathcal{X}$  and  $h_{\mathcal{X}} = (1/2) \|\cdot\|_{\mathbb{X}}^2$ ,

### Easily Computable Solutions

$$\underset{x \in \mathcal{X}'}{\arg\min} g(x) + \langle x^*, x \rangle + \tau_t^{-1} R^2 h_{\mathcal{X}} \left( \frac{x - x_c}{R} \right)$$

Has an easily computable solution if

- $\triangleright g \equiv 0 \text{ and } \mathcal{X}' = \mathcal{X} = \mathbb{X},$
- $\triangleright$  X is a Hilbert space
  - $\mathcal{X}' = \mathcal{X}$  and  $h_{\mathcal{X}} = (1/2) \|\cdot\|_{\mathbb{X}}^2$ ,
  - $g \equiv 0$ ,  $\mathcal{X}' = \text{any set with easily computable projection}$ ,  $h_{\mathcal{X}} = (1/2) \|\cdot\|_{\mathbb{X}}^2$ .

#### Theorem 2

Assume that  $\mathcal{B}(0,1) \subseteq \text{dom } h_{\mathcal{X}}$ , and let Assumptions 1(B), 2(A) and 2(C) hold. Fix any  $\varsigma \in (0,1/6]$ . In Algorithm 1R, choose  $\mathcal{X}'$  such that  $x^* \in \mathcal{X}'$  and  $D_{\mathcal{X}'} \leq R$ , and choose

#### Theorem 2

Assume that  $\mathcal{B}(0,1) \subseteq \text{dom } h_{\mathcal{X}}$ , and let Assumptions 1(B), 2(A) and 2(C) hold. Fix any  $\varsigma \in (0,1/6]$ . In Algorithm 1R, choose  $\mathcal{X}'$  such that  $x^* \in \mathcal{X}'$  and  $D_{\mathcal{X}'} \leq R$ , and choose

$$T \geq \left[ \max \left\{ 3, \ 64\sqrt{(L/\mu)\Omega'_{h_{\mathcal{X}}}}, \ 2048(L_{xx}/\mu)\Omega'_{h_{\mathcal{X}}}, \ 4096L_{yx}(\mu R)^{-1}\sqrt{\Omega'_{h_{\mathcal{X}}}\Omega_{h_{\mathcal{Y}}}}, \right. \\ 128^{2}L_{yy}(\mu R^{2})^{-1}\Omega_{h_{\mathcal{Y}}}, \ 512^{2}(\sigma_{x,f} + \sigma_{x,\Phi})^{2}(\mu R)^{-2}\left(4\sqrt{(1+\log(1/\nu))\Omega'_{h_{\mathcal{X}}}} + 2\sqrt{\log(1/\nu)}\right)^{2}, \\ 512^{2}\sigma_{y,\Phi}^{2}(\mu R^{2})^{-2}\left(8\sqrt{2(1+\log(1/\nu))\Omega_{h_{\mathcal{Y}}}} + 2\sqrt{\log(1/\nu)\Omega_{h_{\mathcal{Y}}}}\right)^{2}\right].$$

#### Theorem 2

Assume that  $\mathcal{B}(0,1) \subseteq \text{dom } h_{\mathcal{X}}$ , and let Assumptions 1(B), 2(A) and 2(C) hold. Fix any  $\varsigma \in (0,1/6]$ . In Algorithm 1R, choose  $\mathcal{X}'$  such that  $x^* \in \mathcal{X}'$  and  $D_{\mathcal{X}'} \leq R$ , and choose

$$\begin{split} T &\geq \left\lceil \max\left\{3, \ 64\sqrt{(L/\mu)\Omega_{h_{\mathcal{X}}}'}, \ 2048(L_{xx}/\mu)\Omega_{h_{\mathcal{X}}}', \ 4096L_{yx}(\mu R)^{-1}\sqrt{\Omega_{h_{\mathcal{X}}}'}\Omega_{h_{\mathcal{Y}}}, \right. \\ & 128^{2}L_{yy}(\mu R^{2})^{-1}\Omega_{h_{\mathcal{Y}}}, \ 512^{2}(\sigma_{x,f} + \sigma_{x,\Phi})^{2}(\mu R)^{-2}\left(4\sqrt{(1+\log(1/\nu))\Omega_{h_{\mathcal{X}}}'} + 2\sqrt{\log(1/\nu)}\right)^{2}, \\ & 512^{2}\sigma_{y,\Phi}^{2}(\mu R^{2})^{-2}\left(8\sqrt{2(1+\log(1/\nu))\Omega_{h_{\mathcal{Y}}}} + 2\sqrt{\log(1/\nu)\Omega_{h_{\mathcal{Y}}}}\right)^{2}\right\} \right\rceil. \end{split}$$

If we choose  $R \ge 2||x^0 - x^*||$ ,  $\{\beta_t\}_{t \in [T]}$  and  $\{\theta_t\}_{t \in [T]}$  as in Theorem 1, and  $\alpha_t = \alpha$  and  $\tau_t = t\tau$  for any  $t \in [T]$ , where

$$\alpha = 1/\left(16\left(\eta^{-1}L_{yx} + L_{yy} + \rho\sigma_{y,\Phi}\sqrt{T}\right)\right), \quad \rho = (4R)^{-1}\sqrt{(1+\log(1/\varsigma))/(2\Omega'_{h_{\mathcal{X}}}\Omega_{h_{\mathcal{Y}}})},$$

$$\tau = 1/\left(4L + 2(L_{xx} + \eta L_{yx})T + \rho'(\sigma_{x,\Phi} + \sigma_{x,f})T^{3/2}\right), \quad \eta = (4/R)\sqrt{\Omega_{h_{\mathcal{Y}}}/\Omega'_{h_{\mathcal{X}}}},$$

$$\rho' = (8R)^{-1}\sqrt{(1+\log(1/\varsigma))/(\Omega'_{h_{\mathcal{X}}}\Omega_{h_{\mathcal{Y}}})},$$

then w.p. at least  $1 - 6\nu$ ,

$$G(\bar{\boldsymbol{x}}^T, \bar{\boldsymbol{y}}^T) \leq B_R^{\text{det}}(T) + B_R^{\text{var}}(T) \leq \mu R^2/16,$$

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$$G(\bar{\boldsymbol{x}}^T, \bar{\boldsymbol{y}}^T) \leq B_R^{\text{det}}(T) + B_R^{\text{var}}(T) \leq \mu R^2/16,$$

where

$$\begin{split} B_R^{\text{det}}(T) &\triangleq \frac{16LR^2}{T(T-1)} \Omega_{h_{\mathcal{X}}}' + \frac{8L_{xx}R^2}{T-1} \Omega_{h_{\mathcal{X}}}' \\ &\quad + \frac{8L_{yx}R}{T-1} \left( \sqrt{\eta_x/\eta_y} \Omega_{h_{\mathcal{X}}}' + 16\sqrt{\eta_y/\eta_x} \Omega_{h_{\mathcal{Y}}} \right) + \frac{128L_{yy}}{T} \Omega_{h_{\mathcal{Y}}}, \\ B_R^{\text{var}}(T) &\triangleq \frac{4(\sigma_{x,\Phi} + \sigma_{x,f})R}{\sqrt{T}} \left\{ 4\sqrt{(1 + \log(1/\nu))\Omega_{h_{\mathcal{X}}}'} + 2\sqrt{\log(1/\nu)} \right\} \\ &\quad + \frac{4\sigma_{y,\Phi}}{\sqrt{T}} \left\{ 8\sqrt{2(1 + \log(1/\nu))\Omega_{h_{\mathcal{Y}}}} + 2\sqrt{\log(1/\nu)\Omega_{h_{\mathcal{Y}}}} \right\}. \end{split}$$

then w.p. at least  $1 - 6\nu$ ,

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Furthermore,  $\|\bar{x}^T - x^*\| \le \sqrt{(2/\mu)(B_R^{\text{det}}(T) + B_R^{\text{var}}(T))} \le R/(2\sqrt{2})$  w.p. at least  $1 - 6\nu$ .

- Introduction
   Problem Setup
   Main Contribution
- 2 Preliminaries
- **3** Algorithm for  $\mu = 0$
- **4** Restart Scheme for  $\mu > 0$ Subroutine Stochastic Restart Scheme
- Stochastic Restart Scheme

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▶ Input: Diameter estimate  $U \ge D_{\mathcal{X}}$ , starting primal variable  $x_0 \in \mathcal{X}^o$ , desired accuracy  $\epsilon > 0$ , error probability  $\nu \in (0, 1]$ ,  $K = \lceil \max \{0, \log_2 (\mu U^2/(4\epsilon))\} \rceil + 1$ ,  $\varsigma = \nu/(6K)$ 

- ▶ Input: Diameter estimate  $U \ge D_{\mathcal{X}}$ , starting primal variable  $x_0 \in \mathcal{X}^o$ , desired accuracy  $\epsilon > 0$ , error probability  $\nu \in (0, 1]$ ,  $K = \lceil \max \{0, \log_2 (\mu U^2/(4\epsilon))\} \rceil + 1$ ,  $\varsigma = \nu/(6K)$
- ▶ Init:  $R_1 = 2U, x_1 = x_0, y_0 \in \mathcal{Y}^o$

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- ▶ Init:  $R_1 = 2U, x_1 = x_0, y_0 \in \mathcal{Y}^o$
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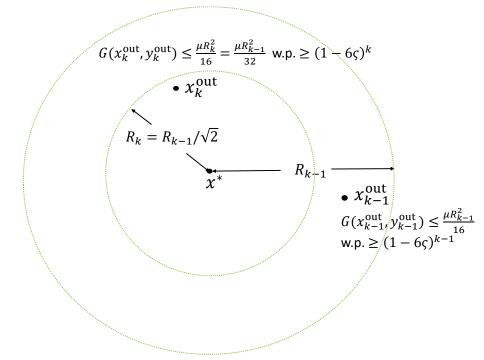
$$512^{2}\sigma_{y,\Phi}^{2}(\mu R_{k}^{2})^{-2}\left(8\sqrt{2(1+\log(1/\varsigma))\Omega_{h_{y}}}+2\sqrt{\log(1/\varsigma)\Omega_{h_{y}}}\right)^{2}\right].$$

• Run Algorithm 1S for  $T_k$  iterations with starting primal variable  $x_k$ , radius  $R_k$ , constraint set  $\mathcal{X}_k = \{x \in \mathcal{X} : ||x - x_k|| \le R_k/2\}$  and other input parameters set as in Theorem 2, with output  $(\bar{x}_k^{T_k}, \bar{y}_k^{T_k})$ .

- ▶ Input: Diameter estimate  $U \ge D_{\mathcal{X}}$ , starting primal variable  $x_0 \in \mathcal{X}^o$ , desired accuracy  $\epsilon > 0$ , error probability  $\nu \in (0, 1]$ ,  $K = \lceil \max\{0, \log_2(\mu U^2/(4\epsilon))\} \rceil + 1$ ,  $\varsigma = \nu/(6K)$
- ▶ Init:  $R_1 = 2U$ ,  $x_1 = x_0$ ,  $y_0 \in \mathcal{Y}^o$
- ► For k = 1, ..., K•  $T_k := \lceil \max \left\{ 3, \ 64\sqrt{(L/\mu)\Omega'_{h_{\mathcal{X}}}}, \ 2048(L_{xx}/\mu)\Omega'_{h_{\mathcal{X}}}, \right.$   $512^2(\sigma_{x,f} + \sigma_{x,\Phi})^2(\mu R_k)^{-2} \left( 4\sqrt{(1 + \log(1/\varsigma))\Omega'_{h_{\mathcal{X}}}} + 2\sqrt{\log(1/\varsigma)} \right)^2,$   $128^2 L_{yy}(\mu R_k^2)^{-1}\Omega_{h_{\mathcal{Y}}}, \ 4096L_{yx}(\mu R_k)^{-1}\sqrt{\Omega'_{h_{\mathcal{X}}}\Omega_{h_{\mathcal{Y}}}},$   $512^2 \sigma_{u,\Phi}^2(\mu R_k^2)^{-2} \left( 8\sqrt{2(1 + \log(1/\varsigma))\Omega_{h_{\mathcal{Y}}}} + 2\sqrt{\log(1/\varsigma)\Omega_{h_{\mathcal{Y}}}} \right)^2 \right\} \rceil.$ 
  - Run Algorithm 1S for  $T_k$  iterations with starting primal variable  $x_k$ , radius  $R_k$ , constraint set  $\mathcal{X}_k = \{x \in \mathcal{X} : ||x x_k|| \le R_k/2\}$  and
  - other input parameters set as in Theorem 2, with output  $(\bar{x}_k^{T_k}, \bar{y}_k^{T_k})$ .

      $R_{k+1} := R_k/\sqrt{2}, x_{k+1} := \bar{x}_k^{T_k}$ .

- ▶ Input: Diameter estimate  $U \ge D_{\mathcal{X}}$ , starting primal variable  $x_0 \in \mathcal{X}^o$ , desired accuracy  $\epsilon > 0$ , error probability  $\nu \in (0, 1]$ ,  $K = \lceil \max\{0, \log_2(\mu U^2/(4\epsilon))\} \rceil + 1$ ,  $\varsigma = \nu/(6K)$
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  - Run Algorithm 1S for  $T_k$  iterations with starting primal variable  $x_k$ , radius  $R_k$ , constraint set  $\mathcal{X}_k = \{x \in \mathcal{X} : ||x x_k|| \le R_k/2\}$  and other input parameters set as in Theorem 2, with output  $(\bar{x}_k^{T_k}, \bar{y}_k^{T_k})$ .
  - $R_{k+1} := R_k/\sqrt{2}, x_{k+1} := \bar{x}_k^{T_k}.$
  - **Output**:  $(x_{K+1}, y_{K+1})$



# Oracle Complexity

#### Theorem 3

Assume  $\mathcal{B}(0,1) \subseteq \text{dom } h_{\mathcal{X}}$  and let Assumptions 1(B), 2(A) and 2(C) hold. In Algorithm 2, for any  $x_0 \in \mathcal{X}^o$ , desired accuracy  $\epsilon \in (0, \mu U^2/4]$  and error probability  $\nu \in (0,1]$ , it holds that  $G(x_{K+1},y_{K+1}) \leq \epsilon$  w.p. at least  $1-\nu$ .

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Furthermore, the number of oracle calls

$$\begin{split} &C_{\epsilon}^{\mathrm{st}} \leq \left(3 + 64\sqrt{(L/\mu)\Omega_{h_{\mathcal{X}}}'} + 2048(L_{xx}/\mu)\Omega_{h_{\mathcal{X}}}'\right) \left(\left\lceil \log_2\left(\mu U^2/(4\epsilon)\right)\right\rceil + 1\right) \\ &+ 256^2 \left(L_{yx}/\sqrt{\mu\epsilon}\right)\sqrt{\Omega_{h_{\mathcal{X}}}'}\Omega_{h_{\mathcal{Y}}} + 64^2 \left(L_{yy}/\epsilon\right)\Omega_{h_{\mathcal{Y}}} \\ &+ 1024^2 \left\{ (\sigma_{x,f} + \sigma_{x,\Phi})^2/(\epsilon\mu) \right\} \left\{ (4\Omega_{h_{\mathcal{X}}}' + 1)\log\left(6\left[\log_2\left(\mu U^2(4\epsilon)^{-1}\right) + 2\right]/\nu\right) + 4\Omega_{h_{\mathcal{X}}}'\right\} \\ &+ 1024^2 \left(\sigma_{y,\Phi}^2/\epsilon^2\right) \left\{ 1 + \log\left(6\left[\log_2\left(\mu U^2(4\epsilon)^{-1}\right) + 2\right]/\nu\right) \right\}\Omega_{h_{\mathcal{Y}}} \end{split}$$

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$$\begin{split} &C_{\epsilon}^{\text{st}} \leq \left(3 + 64\sqrt{(L/\mu)\Omega_{h_{\mathcal{X}}}'} + 2048(L_{xx}/\mu)\Omega_{h_{\mathcal{X}}}'\right) \left(\left\lceil \log_{2}\left(\mu U^{2}/(4\epsilon)\right)\right\rceil + 1\right) \\ &+ 256^{2}\left(L_{yx}/\sqrt{\mu\epsilon}\right)\sqrt{\Omega_{h_{\mathcal{X}}}'}\Omega_{h_{\mathcal{Y}}} + 64^{2}\left(L_{yy}/\epsilon\right)\Omega_{h_{\mathcal{Y}}} \\ &+ 1024^{2}\left\{(\sigma_{x,f} + \sigma_{x,\Phi})^{2}/(\epsilon\mu)\right\}\left\{(4\Omega_{h_{\mathcal{X}}}' + 1)\log\left(6\left[\log_{2}\left(\mu U^{2}(4\epsilon)^{-1}\right) + 2\right]/\nu\right) + 4\Omega_{h_{\mathcal{X}}}'\right\} \\ &+ 1024^{2}\left(\sigma_{y,\Phi}^{2}/\epsilon^{2}\right)\left\{1 + \log\left(6\left[\log_{2}\left(\mu U^{2}(4\epsilon)^{-1}\right) + 2\right]/\nu\right)\right\}\Omega_{h_{\mathcal{Y}}} \\ &= O\left(\left(\sqrt{\frac{L}{\mu}} + \frac{L_{xx}}{\mu}\right)\log\left(\frac{1}{\epsilon}\right) + \frac{L_{yx}}{\sqrt{\mu\epsilon}} + \frac{L_{yy}}{\epsilon} + \left(\frac{(\sigma_{x,f} + \sigma_{x,\Phi})^{2}}{\mu\epsilon} + \frac{\sigma_{y,\Phi}^{2}}{\epsilon^{2}}\right)\log\left(\frac{\log(1/\epsilon)}{\nu}\right)\right). \end{split}$$

ightharpoonup Assume that  $\operatorname{\mathsf{dom}} g$  and  $\operatorname{\mathsf{dom}} J$  are closed.

- $\triangleright$  Assume that dom g and dom J are closed.
- ightharpoonup By compactness of  $\mathcal X$  and  $\mathcal Y$ , invoke Berge's maximum theorem to conclude that  $\bar S$  and  $\underline S$  are continuous on  $\mathcal X\cap\operatorname{\mathsf{dom}} g$  and  $\mathcal Y\cap\operatorname{\mathsf{dom}} J$ , respectively, so there exists  $\Gamma<+\infty$  such that

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#### Theorem 4

Assume  $\mathcal{B}(0,1) \subseteq \operatorname{dom} h_{\mathcal{X}}$  and let Assumptions 1(B), 2(A) and 2(C) hold. In Algorithm 2, for any  $x_0 \in \mathcal{X}^o$  and  $\varepsilon \in (0, \mu U^2/2]$ , choose  $\nu = \min\{\varepsilon/(2\Gamma), 1\}$  and  $K = \lceil \log_2(\mu U^2/(2\varepsilon)) \rceil + 1$ . Then it holds that  $\mathbb{E}[G(x_{K+1}, y_{K+1})] \leq \varepsilon$ .

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Furthermore, the oracle complexity is

$$O\left(\left(\sqrt{\frac{L}{\mu}} + \frac{L_{xx}}{\mu}\right)\log\left(\frac{1}{\varepsilon}\right) + \frac{L_{yx}}{\sqrt{\mu\varepsilon}} + \frac{L_{yy}}{\varepsilon} + \left(\frac{(\sigma_{x,f} + \sigma_{x,\Phi})^2}{\mu\varepsilon} + \frac{\sigma_{y,\Phi}^2}{\varepsilon^2}\right)\log\left(\frac{1}{\varepsilon}\right)\right).$$

- Introduction Problem Setup Main Contribution
- 2 Preliminaries
- **3** Algorithm for  $\mu = 0$
- **4** Restart Scheme for  $\mu > 0$ Subroutine Stochastic Restart Scheme
- **6** Future Directions

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  - Remove the additional  $\log(1/\epsilon)$  factors in the oracle complexities of  $\sigma_{x,f}$ ,  $\sigma_{x,\Phi}$  and  $\sigma_{y,\Phi}$ , in obtaining the  $\epsilon$ -expected duality gap.

# Thank you!