Iteration 2 Requirements

CSCI3081

Program Design and Development

Entities

- Player
- Robot
- SuperBot
- Home Base
- Recharge Station
- Obstacle

Behavior

- WIN: Freeze all the robots
- LOSE: All robots become SuperBots OR run out of battery
- Robots autonomously avoid collision UNLESS distress call sensed
- Player-Robot collision: robot freezes
- Robot-FrozenRobot collision: unfreeze Robot
- Player-SuperBot collison: Player freezes
- Time unfreezes Player
- Robot-HomeBae collision: robot becomes SuperBot
- Bounce off of walls and other entities.

Sensors and Events

EVENTS

- Collision
- Proximity
- DistressCall
- TypeEmit

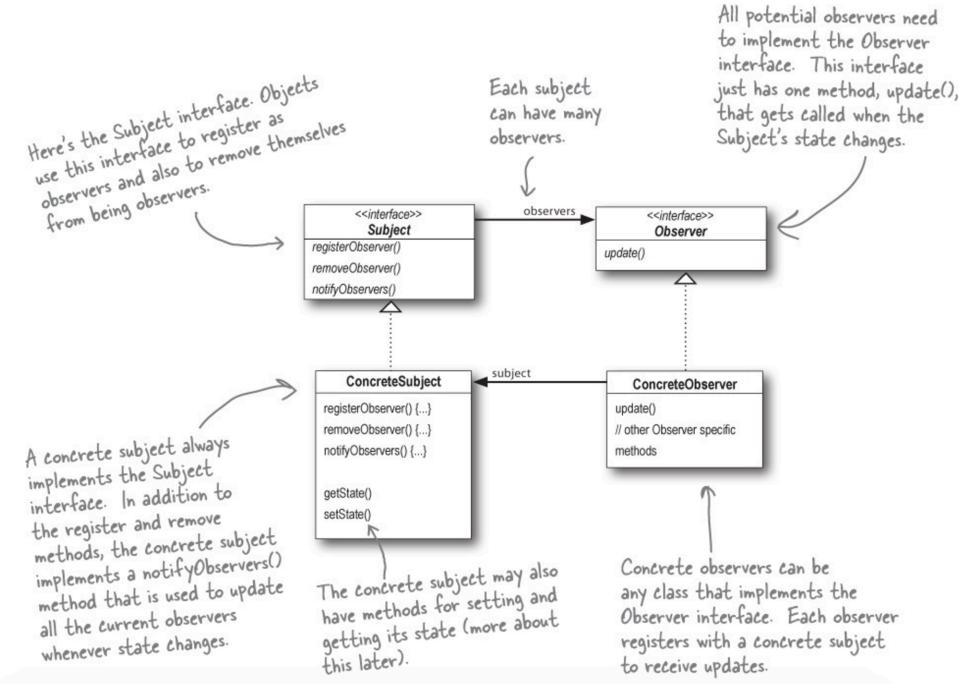
Sensors

- Touch
- Proximity
- Distress
- EntityType

Observer Pattern

Current Conditions is one of three different displays. The user can also get weather stats and a forecast displays Humidity pulls data Current < sensor device Conditions Temp: 72° Humidity: 60 Pressure: Temperature WeatherData sensor device object Weather Station Display device Pressure sensor device Weather-O-Rama provides What we implement

The Observer Pattern defined: the class diagram



Design Decisions

- Initialization of all entities.
- Sensor and Event class.
 - What's in the base class?
 - What's in each of the classes?
- Design of registration of sensors with arena (through entity, or directly from sensor)??
 - How do entities and sensor know about the arena?
- Should design of entities change?
 - Recharge and regular obstacles might move in the future.
- Motion Handle: Different uses of sensor information.
 - Strategy?
 - Template?
 - Something else?
- How to turn Robot into SuperBot?
- How are type and distress calls emitted and sensed in Arena?