

## List of topics in this lecture

- Feynman-Kac formula for the forward equation, path integral  $u(x, t)$ , interpretation of path integral as ensemble density at time  $t$  of the surviving ensemble, governing equation of  $u(x, t)$
- An application of Feynman-Kac formula: reconstruct potential  $V(x)$  from a set of sample paths of particle position; non-equilibrium with an applied force, modeling the effect of applied force as a fatality rate

## Review

### Feynman-Kac formula

Stochastic differential equation (SDE)

$$dX = b(X, t)dt + \sqrt{a(X, t)}dW$$

$u(x, t, T)$  is defined using path integral

$$u(x, t, T) = E \left( \exp \left( - \int_t^T \psi(X(s), s) ds \right) f(X(T)) \middle| X(t) = x \right)$$

Paths,  $X(s)$ , are from the SDE, independent of function  $\psi(x, s)$ .

### Meaning of $u(x, t, T)$

= reward at final time  $T$  per population at time  $t$ ,  
averaged over all paths starting at  $X(t) = x$   
(including the effects of fatality/growth in  $[t, T]$ )

### Governing equation for $u(x, t, T)$

$$0 = u_t + b(x, t)u_x + \frac{1}{2}a(x, t)u_{xx} - \psi(x, t)u$$

This is the backward equation with a fatality/growth term

The end/final condition

$$u(x, t, T)|_{t=T} = f(x)$$

### Key step in deriving the equation

Law of total probability

$$E_{\{X(s), t \leq s \leq T\}}(*|X(t)=x) = E_{dX} \left( E_{\{X(s), t+\Delta t \leq s \leq T\}}(*|X(t+dt)=x+dX) \right)$$

Remarks:

- If we know the PDE, we can solve the PDE for solution  $u(x, t, T)$ .
- If we don't know the PDE but we are given a set of sample paths, we can calculate  $u(x, t, T)$  using Feynman-Kac formula, and use it to learn about the PDE.

End of review

**Feynman-Kac formula for the forward equation** (continued)

$$u(x, t) = E \left( \delta(X(t) - x) \exp \left( - \int_0^t \psi(X(s), s) ds \right) \right)$$

Items of the discussion:

- 1) We need to explain the  $\delta$  function in the average.
- 2) We need to derive the governing equation for  $u(x, t)$ .
- 3) We need to explain the meaning of  $u(x, t)$  and discuss the distribution of  $X(0)$ .

Item #1:

$$\text{Definition 1: } u(x, t) = \lim_{\Delta x \rightarrow 0} \frac{1}{\Delta x} E \left( I_{[x, x+\Delta x]}(X(t)) \exp \left( - \int_0^t \psi(X(s), s) ds \right) \right)$$

$$\text{Definition 2: } \int h(x) u(x, t) dx = E \left( h(X(t)) \exp \left( - \int_0^t \psi(X(s), s) ds \right) \right)$$

Item #2: Derivation of the governing equation for  $u(x, t)$

We use the forward view for  $u(x, t)$ :

$[0 \rightarrow t+\Delta t]$  is divided into  $[0 \rightarrow t]$  and  $[t \rightarrow t+\Delta t]$

$$\begin{aligned} \underbrace{h(x)u(x, t+dt)dx}_{\text{LHS}} &= E \left( h(X(t)+dX) \exp \left( - \int_0^{t+dt} \psi(X(s), s) ds \right) \right) \\ &= E \left( h(X(t)+dX) \exp \left( - \int_0^t \psi(X(s), s) ds - \int_t^{t+dt} \psi(X(s), s) ds \right) \right) \\ &= E \left( h(X(t)+dX) \exp \left( - \int_t^{t+dt} \psi(X(s), s) ds \right) \times \exp \left( - \int_0^t \psi(X(s), s) ds \right) \right) \end{aligned}$$

$$\begin{aligned}
 & \text{Taylor expansion of } h(X(t)+dX) \text{ and } \exp\left(-\int_t^{t+dt} \psi(X(s),s)ds\right) \\
 &= E\left[\left[h(X(t))+h'(X(t))dX+\frac{1}{2}h''(X(t))(dX)^2\right]\left(1-\psi(X(t),t)dt\right)\right. \\
 &\quad \left.\times \exp\left(-\int_0^t \psi(X(s),s)ds\right)\right] \\
 &= E\left[\left[h(X(t))+h'(X(t))dX+\frac{1}{2}h''(X(t))(dX)^2-h(X(t))\psi(X(t),t)dt\right]\right. \\
 &\quad \left.\times \underbrace{\exp\left(-\int_0^t \psi(X(s),s)ds\right)}_{\text{independent of } dX}\right]
 \end{aligned}$$

Using the law of total expectation to write the average over  $\{X(s), 0 \leq s \leq t+dt\}$  as

$$= E_{\{X(s), 0 \leq s \leq t+dt\}}(*) = E_{\{X(s), 0 \leq s \leq t\}}(E_{dX(t)}(*)|X(t))$$

Using the moments of  $dX$ ,  $E_{dX(t)}(h'(X(t))dX|X(t)) = h'(X(t))b(X(t),t)dt$ , ...

$$\begin{aligned}
 &= E\left[\left[h(X(t))+h'(X(t))b(X(t),t)dt+\frac{1}{2}h''(X(t))a(X(t),t)dt-h(X(t))\psi(X(t),t)dt\right]\right. \\
 &\quad \left.\times \exp\left(-\int_0^t \psi(X(s),s)ds\right)\right] \\
 &\quad \underbrace{\hspace{15em}}_{\text{RHS}}
 \end{aligned}$$

Note that definition #2 (method of test function) of  $u(x, t)$  gives

$$E\left(g(X(t))\exp\left(-\int_0^t \psi(X(s),s)ds\right)\right) = \int g(x)u(x,t)dx$$

Setting  $g(x) = h'(x)b(x, t)$ ,  $g(x) = h''(x)a(x, t)$ , ..., we write the RHS above as

$$\text{RHS} = \int \left( h(x) + h'(x)b(x,t)dt + \frac{1}{2}h''(x)a(x,t)dt - h(x)\psi(x,t)dt \right) u(x,t)dx$$

Taylor expanding the LSH and integrating by parts the RHS yields

$$\text{LHS} = \int h(x)(u(x,t) + u_t dt)dx$$

$$\text{RHS} = \int h(x) \left( u(x,t) - (b(x,t)u)_x dt + \frac{1}{2}(a(x,t)u)_{xx} dt - \psi(x,t)u dt \right) dx$$

Subtracting  $\int h(x) u(x, t)dx$ , dividing by  $dt$ , and taking the limit as  $dt \rightarrow 0$ , we obtain

$$\text{LHS} = \int h(x) u_t dx$$

$$\text{RHS} = \int h(x) \left( -\left( b(x,t)u \right)_x + \frac{1}{2} \left( a(x,t)u \right)_{xx} - \psi(x,t)u \right) dx$$

Since LHS = RHS for arbitrary test function  $h(x)$ , we arrive at

$$u_t = -\left( b(x,t)u \right)_x + \frac{1}{2} \left( a(x,t)u \right)_{xx} - \psi(x,t)u$$

This is the governing PDE for  $u(x, t)$ .

It is the forward equation with a fatality/growth term.

### Item #3: Meaning of $u(x, t)$

Consider an ensemble of paths  $\{X(s)\}$ .

Based on definition #1 of  $u(x, t)$ ,

$$\begin{aligned} u(x, t) &= \lim_{\Delta x \rightarrow 0} \frac{1}{\Delta x} E \left( I_{[x, x+\Delta x]}(X(t)) \exp \left( - \int_0^t \psi(X(s), s) ds \right) \right) \\ &= \lim_{\Delta x \rightarrow 0} \frac{1}{\Delta x} \left( \# \text{ of paths surviving to reach time } t \text{ with } X(t) \in [x, x+dx] \right) \\ &= \text{ensemble density at time } t \text{ of paths surviving to reach time } t. \\ &= \text{ensemble density at time } t \text{ of the surviving ensemble.} \end{aligned}$$

### Initial condition for $u(x, t)$

$u(x, 0) = f_0(x) =$  ensemble density of the starting ensemble.

$u(x, t) =$  ensemble density at time  $t$  of the surviving ensemble.

### Remarks:

- Although we interpret  $\psi(x, s)$  as the fatality rate, the Feynman-Kac formula is well defined for any function  $\psi(x, s)$ , not associated with any physical fatality.
- The Feynman-Kac formula provides a way of calculating  $u(x, t)$  from a set of sample paths of the SDE. The SDE is not affected by the fatality function.

$$dX = b(X, t)dt + \sqrt{a(X, t)}dW$$

- Given a set of sample paths  $\{X^{(j)}(t), j = 1, 2, \dots, N\}$  of the SDE, we can calculate  $u(x, t)$  as follows

$$u(x, t) = \frac{1}{N \cdot \Delta x} \sum_{x \leq X^{(j)}(t) < x + \Delta x} \exp\left(-\int_0^t \psi(X^{(j)}(s), s) ds\right)$$

- When function  $b(x, t)$  in the SDE is unknown but a set of sample paths is available, we can use the Feynman-Kac formula to calculate the unknown  $b(x, t)$ .

### An application of Feynman-Kac formula

Consider a particle diffusing in a potential well.

$X(t)$ : position of particle at time  $t$

$V(x)$ : static potential well

The stochastic motion is governed by the over-damped Langevin equation.

$$dX = -\frac{D}{k_B T} V'(X) dt + \sqrt{2D} dW$$

After non-dimensionalization, we have

$$dX = -V'(X) dt + \sqrt{2} dW$$

What we can measure:

a (large) set of sample paths  $\{X^{(j)}(t), j = 1, 2, \dots, N\}$

Goal:

to determine the potential  $V(x)$  in the SDE

Method:

We use Feynman-Kac formula to reconstruct the potential  $V(x)$ .

The forward equation (the Fokker-Planck equation)

Let  $\rho(x, t)$  = probability density of  $X$  at time  $t$ .

The time evolution of density  $\rho(x, t)$  is governed by the forward equation

$$\rho_t = -\left(b(x)\rho\right)_x + \frac{1}{2}\left(a(x)\rho\right)_{xx}, \quad a(x) = 2, \quad b(x) = -V'(x)$$

$$\implies \rho_t = \left(V'(x)\rho\right)_x + \rho_{xx}$$

We write the forward equation in conservation form

$$\rho_t = -\frac{\partial}{\partial x} J(x, t), \quad J(x, t) = -(V'(x)\rho + \rho_x)$$

### Equilibrium distribution

At equilibrium, the probability flux must be identically zero.

$$J(x) \equiv 0, \quad \text{for all } x$$

$$\Rightarrow V'(x)\rho + \rho_x = 0$$

$$\Rightarrow (\exp(V(x))\rho(x))' = 0$$

$$\Rightarrow \exp(V(x))\rho(x) = \text{const}$$

$$\Rightarrow \rho^{(\text{eq})}(x) \propto \exp(-V(x))$$

As expected, the equilibrium is the Maxwell-Boltzmann distribution.

### Caution:

When  $J(x, t) \equiv \text{const} \neq 0$ , we still have  $\rho_t = 0$ .

It is called a steady state, which is different from equilibrium.

At equilibrium, we must have  $J(x) \equiv 0$  for all  $x$ .

In the terminology of deterministic dynamical systems, “steady state” and “equilibrium” are not properly distinguished.

### Estimating potential from equilibrium measurements

Suppose we measure a set of sample paths  $\{X^{(j)}(t), j = 1, 2, \dots, N\}$  when the system is at equilibrium.

The equilibrium density  $\rho^{(\text{eq})}(x)$  can be calculated as

$$\rho^{(\text{eq})}(x) \approx \frac{1}{N \cdot \Delta x} \sum_{x \leq X^{(j)}(t_k) < x + \Delta x} 1 \quad \text{at a particular time level } t_k$$

where  $N$  is the number of sample paths.

To fully utilize the data set, we average  $\rho^{(\text{eq})}(x)$  over all  $t_k$ 's after equilibrium

$$\rho^{(\text{eq})}(x) \approx \frac{1}{K_T} \sum_{k=1}^{K_T} [\rho^{(\text{eq})}(x) \text{ estimated at } t_k]$$

where  $K_T$  is the number of time levels.

At equilibrium  $\rho^{(\text{eq})}(x) \propto \exp(-V(x))$ . We write the potential  $V(x)$  as

$$V(x) = -\log \rho^{(\text{eq})}(x) + \underbrace{C}_{\substack{\text{additive constant} \\ \text{won't matter}}}$$

### A practical issue with equilibrium data

Unfortunately, the approach of using only equilibrium measurements does not work well. It requires an impractically large amount of data.

At equilibrium, a region with high  $V(x)$  value is visited only very infrequently.

$$\rho^{(\text{eq})}(x) \propto \exp(-V(x))$$

Consider a set of discrete sites (intervals of  $x$ ). For a site with probability  $10^{-8}$ , we need to sample  $10^9$  times to get 10 visits to that particular site.

It is practically impossible to accurately estimate  $\rho^{(\text{eq})}(x)$  in a region with high  $V(x)$  value.

### Remedy:

We need to perturb the system to non-equilibrium.

### Non-equilibrium with an applied force

Let  $F(t)$  be the applied force, non-dimensionalized.

$$F(t) = \frac{L}{k_B T} F_{\text{phy}}(t)$$

In experiments,  $F(t)$  is controlled.

For example, in AFM (Atomic Force Microscopy) experiments, the force is controlled by moving an actuator to stretch an elastic link.

$$F^{(\text{AFM})}(t) = k \int_0^t u(s) ds$$

where  $k$  = spring constant;  $u(s)$  velocity of actuator at time  $s$ .

### Stochastic differential equation in the presence of an applied force

The applied force tilts the static potential. At time  $t$ , the tilted potential is

$$H(x, t) = V(x) - \underbrace{F(t) \cdot x}_{\text{Effect of applied force}}$$

Replacing  $V(x)$  with  $H(x, t)$ , we get the new SDE.

$$dX = -H_x(X, t)dt + \sqrt{2} dW$$

In the presence of the applied force  $F(t)$ , the potential  $H(x, t)$  changes with time. As a result, the system is not at equilibrium and the Boltzmann distribution does not apply.

Nevertheless we consider a “hypothetical” density that has the same form as the Boltzmann distribution, with  $V(x)$  replaced by  $H(x, t)$  while the normalizing constant  $Z$  is kept unchanged. Consider  $\rho^{(F)}(x, t)$  defined as

$$\rho^{(F)}(x, t) \equiv \frac{1}{Z} \exp(-H(x, t)) = \frac{1}{Z} \exp(-V(x) + F(t) \cdot x)$$

$$\text{where } Z = \int \exp(-V(x)) dx$$

Remark:

We call  $\rho^{(F)}(x, t)$  “hypothetical” density because it is not the density of some physical population. In particular,  $\rho^{(F)}(x, t)$  is NOT the density of particle position in potential well  $V(x)$ , under applied force  $F(t)$ . In the procedure below for constructing potential  $V(x)$ , we interpret  $\rho^{(F)}(x, t)$  as the density of a “hypothetical” population, whose fatality/growth is only in our mathematical imagination.

Advantage of working with  $H(x, t)$  and  $\rho^{(F)}(x, t)$

With a properly designed force schedule  $F(t)$ , a region of relatively high value in the static potential  $V(x)$  can have a relatively low value in the tilted potential  $H(x, t)$ .

In this framework, different regions of  $V(x)$  can be very well explored/sampled at different time  $t$  with a time-dependent force schedule  $F(t)$ .

Goal: construct potential  $V(x)$

Steps of working with  $H(x, t)$  and  $\rho^{(F)}(x, t)$  toward that goal:

1. Find the governing PDE for  $\rho^{(F)}(x, t)$
2. Identify the “fatality” term  $\psi(x, s)$  in the PDE
3. Express  $\rho^{(F)}(x, t)$  in the Feynman-Kac formula
4. Use the Feynman-Kac formula to calculate  $\rho^{(F)}(x, t)$  from a set of sample paths.
5. Determine potential  $V(x)$  from  $\rho^{(F)}(x, t)$ .

Step 1: Find the governing PDE for  $\rho^{(F)}(x, t)$

Let  $\rho(x, t)$  be the density of particle position in the presence of applied force  $F(t)$ .

$\rho(x, t)$  is NOT the same as  $\rho^{(F)}(x, t)$ .

$$\rho(x, t) \neq \rho^{(F)}(x, t)$$

Stochastic motion of particle is governed by

$$dX = -H_x(X, t)dt + \sqrt{2} dW$$

The corresponding forward equation (Fokker-Planck equation) for  $\rho(x, t)$  is



$$\frac{\partial \rho}{\partial t} = \frac{\partial}{\partial x} \left( H_x(x, t) \rho + \frac{\partial}{\partial x} \rho \right)$$

We write the Fokker-Planck equation in terms of a differential operator.

$$\rho_t = L_{\{H\}}[\rho] \quad (\text{FP\_forced})$$

$$\text{where} \quad L_{\{H\}}[\bullet] = \frac{\partial}{\partial x} \left( H_x(x, t) \bullet + \frac{\partial}{\partial x} \bullet \right)$$

Now consider the “hypothetical” density  $\rho^{(F)}(x, t)$ .

$$\rho^{(F)}(x, t) = \frac{1}{Z} \exp(-H(x, t)), \quad Z = \int \exp(-V(x)) dx$$

Substitute  $\rho^{(F)}(x, t)$  into operator  $L_{\{H\}}[\bullet]$  and into operator  $\partial/\partial t$

$$L_{\{H\}}[\rho^{(F)}(x, t)] = \frac{\partial}{\partial x} \left( H_x(x, t) \rho^{(F)}(x, t) + \frac{\partial}{\partial x} \rho^{(F)}(x, t) \right) = 0$$

$$\rho_t^{(F)}(x, t) = F'(t)x \cdot \rho^{(F)}(x, t)$$

It follows that  $\rho^{(F)}(x, t)$  satisfies

$$\rho_t^{(F)} = L_{\{H\}}[\rho^{(F)}] + \underbrace{F'(t)x \cdot \rho^{(F)}}_{\substack{\text{We view this} \\ \text{as the fatality term}}}$$

Step 2: Identify the “fatality” term  $\psi(x, s)$  in the PDE

$\rho^{(F)}(x, t)$  satisfies the forward equation with a fatality term

$$\rho_t^{(F)} = L_{\{H\}}[\rho^{(F)}] - \psi(x, t) \cdot \rho^{(F)}, \quad \psi(x, t) = -F'(t)x$$

Step 3: Express  $\rho^{(F)}(x, t)$  using the Feynman-Kac formula

$$\rho^{(F)}(x, t) = E \left( \delta(X(t) - x) \exp \left( - \int_0^t \psi(X(s), s) ds \right) \right), \quad \psi(x, s) = -F'(s)x$$

$$\Rightarrow \rho^{(F)}(x, t) = E \left( \delta(X(t) - x) \exp \left( \int_0^t F'(s)X(s) ds \right) \right)$$

Step 4: Calculate  $\rho^{(F)}(x, t)$  from a set of sample paths.

Suppose we measure a set of sample paths  $\{X^{(j)}(t), j = 1, 2, \dots, N\}$  when the system is driven by the applied force schedule  $F(t)$ .

At each time level  $t_k$ ,  $\rho^{(F)}(x, t_k)$  can be calculated using the Feynman-Kac formula.

$$\rho^{(F)}(x, t_k) \approx \frac{1}{N \cdot \Delta x} \sum_{x \leq X^{(j)}(t_k) < x + \Delta x} \exp\left(\int_0^{t_k} F'(s) X^{(j)}(s) ds\right) \quad \text{at each time level } t_k$$

where  $N$  is the number of sample paths.

Step 5: Determine potential  $V(x)$  from  $\rho^{(F)}(x, t)$

Note that  $\rho^{(F)}(x, t)$  and  $\rho^{(eq)}(x)$  are related by

$$\begin{aligned} \rho^{(eq)}(x) &= \frac{1}{Z} \exp(-V(x)) \\ \rho^{(F)}(x, t) &= \frac{1}{Z} \exp(-V(x) + F(t)x) \\ \implies \rho^{(eq)}(x) &= \rho^{(F)}(x, t) \exp(-F(t)x) \end{aligned}$$

Once  $\rho^{(F)}(x, t_k)$  is obtained at a time level  $t_k$ , we use it to calculate a sample version of equilibrium density  $\rho^{(eq)}(x)$ .

$$\rho^{(eq)}(x) = \rho^{(F)}(x, t_k) \exp(-F(t_k)x) \quad \text{at each time level } t_k$$

Then we average the sample versions of  $\rho^{(eq)}(x)$  over all  $t_k$ 's.

$$\rho^{(eq)}(x) \approx \frac{1}{K_T} \sum_{k=1}^{K_T} \rho^{(F)}(x, t_k) \exp(-F(t_k)x)$$

where  $K_T$  is the number of time levels.

Once  $\rho^{(eq)}(x)$  is accurately estimated, we write the potential  $V(x)$  as

$$V(x) = -\log \rho^{(eq)}(x) + \underbrace{C}_{\substack{\text{additive constant} \\ \text{won't matter}}}$$

Summary:

- The stochastic evolution of  $X(t)$  is independent of the fatality/growth rate  $\psi(x, t)$ .
- Mathematically, the surviving ensemble is obtained by evolving the starting ensemble according to the SDE and at each time step removing a path or adding a new path according to fatality/growth rate.

- We can use any function  $\psi(x, t)$  in the Feynman-Kac formula. The resulting path integral is governed by the forward equation with the corresponding fatality/growth rate.
- The “hypothetical” density  $\rho^{(F)}(x, t)$  satisfied the forward equation with fatality/growth rate  $\psi(x, t) = -F'(t)x$  where  $F(t)$  is the applied force schedule. This is a hypothetical fatality/growth rate that exists only in the mathematical imagination. It does not correspond to any physical fatality/growth.
- $\rho^{(F)}(x, t)$  is the ensemble density of the surviving ensemble determined according to the hypothetical fatality/growth rate  $\psi(x, t) = -F'(t)x$ .
- The path integral expression (Feynman-Kac formula) of  $\rho^{(F)}(x, t)$  allows us to calculate  $\rho^{(F)}(x, t)$  from measured data.
- The analytical expression of  $\rho^{(F)}(x, t)$  in terms of potential  $V(x)$  allows us to construct potential  $V(x)$  once we obtain  $\rho^{(F)}(x, t)$ .