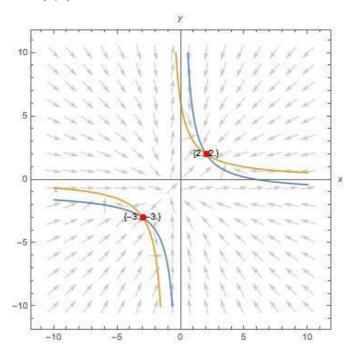
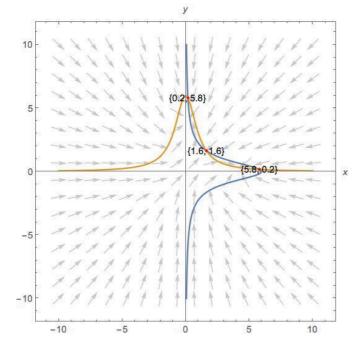
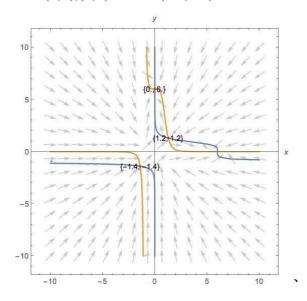
1. n=1 (2,2) stable



 $n{=}2\ (0.2,\, 5.8),\, (5.8,\! 0.2)\ stable/\ (1.6,\! 1.6)\ unstable$



n=5 (0,6),(6,0) stable/ (1.2,1.2) unstable



1b.

$$\frac{dm}{dt} = \alpha_m (1 - Probability_{goff}) - \gamma_m[m]$$

$$\frac{dm}{dt} = \alpha_m (1 - Probabilty_{A_{unbound}} * Probabiluty_{P_{unbound}}) - \gamma_m[m]$$

$$\frac{dm}{dt} = \alpha_m \left(1 - \frac{[A]}{k1 + [A]} * \frac{[P]^2}{k2^2 + [P]^2} \right) - \gamma_m[m]$$

$$[m]_{ss} = \frac{\alpha_m}{\gamma_m} \left(\frac{[A]}{k1 + [A]} * \frac{[P]^2}{k2^2 + [P]^2} \right)$$

$$\frac{dP}{dt} = \frac{\alpha_m \alpha_p}{\gamma_m} \left(1 - \frac{[A]}{k1 + [A]} * \frac{[P]^2}{k2^2 + [P]^2} \right) - \gamma_p[P]$$

$$\frac{dP}{dt} = \frac{\alpha_m \alpha_p}{\gamma_m} \left(\frac{[A]}{k1 + [A]} + \frac{[P]^2}{k2^2 + [P]^2} - \frac{k1 * k2^2}{(k1 + [A])(k2^2 + [P]^2)} \right) - \gamma_p[P]$$

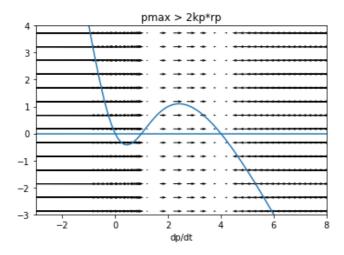
2b.

$$\frac{dP}{dt} = P_{max} \left(\frac{[P]^2}{k2^2 + [P]^2} \right) - \gamma_p[P] = 0$$

$$P_{max}\left(\frac{[P]^2}{k2^2 + [P]^2}\right) = \gamma_p[P]$$

$$\frac{dP}{dt} = 0 \rightarrow [P] = 0,$$
 $\frac{P_{max} \pm \sqrt{P_{max}^2 - 4\gamma_p^2 k 2^2}}{2\gamma_p}$

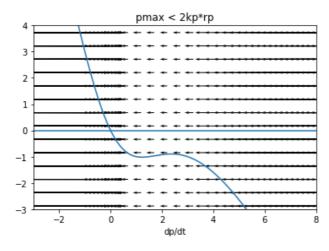
When $P_{max} > 2\gamma_p k2$, 3 equilibrium points. (k₂=kp)



Pmax=10, k=2, rp=2

>> 2 stable points, 1 unstable, which is P=
$$\frac{P_{max} - \sqrt{P_{max}^2 - 4\gamma_p^2 k 2^2}}{2\gamma_p}$$
.

When $P_{max} < 2\gamma_p k2$, 1 equilibrium point. only when P=0



Pmax=10, k=3, rp=2

>> P=0, stable point.

3a

$$A_{off} + I \leftarrow \frac{k_{AI}^+}{k_{AI}^-} \!\!\!\!\! \to A_{on}$$

$$R_{on} + I \leftarrow \frac{k_{RI}^+}{k_{RI}^-} \rightarrow A_{on}$$

$$g_{0} + nA_{on} \leftarrow \frac{k_{A}^{+}}{k_{A}^{-}} \rightarrow g_{A}$$

$$g_{0} + nR_{on} \leftarrow \frac{k_{R}^{+}}{k_{R}^{-}} \rightarrow g_{R}$$

$$[g_{A}]_{ss} = \frac{k_{A}^{+}}{k_{A}^{-}} [g_{0}][A]^{n}$$

$$[g_{R}]_{ss} = \frac{k_{R}^{+}}{k_{R}^{-}} [g_{0}][A]^{n}$$

$$\frac{g_{A}}{g_{TOT}} = \frac{\frac{k_{A}^{+}}{k_{A}^{-}} [g_{0}][A]^{n} + \frac{k_{R}^{+}}{k_{R}^{-}} [g_{0}][R]^{n}}{1 + \frac{k_{A}^{+}}{k_{A}^{-}} [A]^{n} + \frac{k_{R}^{+}}{k_{R}^{-}} [R]^{n}}$$

$$3c.$$

$$[A_{on}]_{ss} = \frac{k_{AI}^{+}}{k_{AI}^{-}} [A_{off}][I]$$

$$[R_{on}]_{ss} = \frac{k_{RI}^{-}}{k_{RI}^{+}} \frac{[R_{off}]}{[I]}$$

$$\frac{k_{AI}^{+}}{k_{AI}^{-}} = k_{AI}, \frac{k_{RI}^{-}}{k_{RI}^{+}} = k_{RI}^{-1}$$

$$\frac{g_{A}}{g_{TOT}} = \frac{k_{A}k_{AI}^{n} [A_{off}]^{n} [I]^{n}}{1 + k_{A}k_{AI}^{n} [A_{off}]^{n} [I]^{n} + k_{R}k_{RI}^{-n} \frac{[R_{off}]^{n}}{[I]^{n}}}$$

Although the paper mentioned the hill coefficient can combine up to multiplicatively, as it suggested, the final hill coefficient should be n*n; however, it's hard to derive from the above equation.