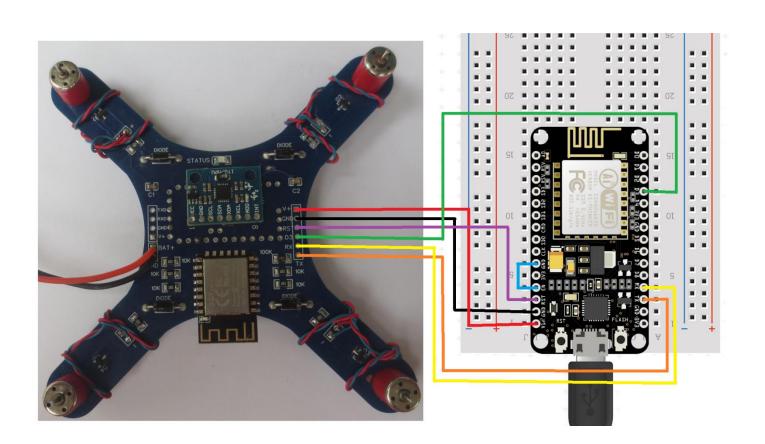
Configuring Blynk App

- Download blynk app from playstore(https://play.google.com/store/apps/details?id=cc.blynk&hl=en https://play.google.com/store/apps/details?id=cc.blynk&hl=en
 IN&gl=US)
- Create account
- Scan the QR code(top right corner in blynk)



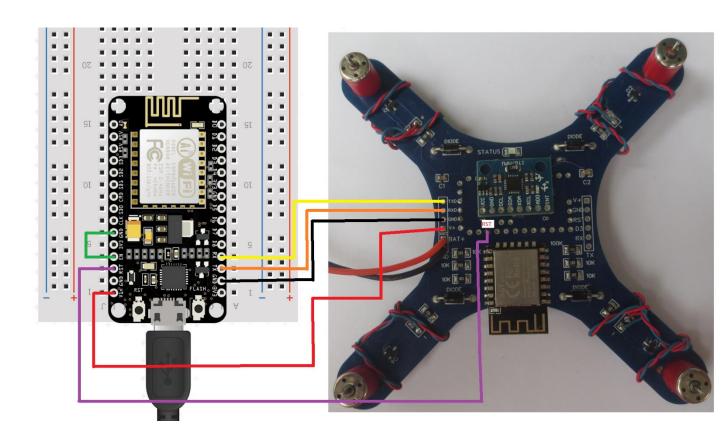
Uploading code to receiver

- Open wifi_v3 folder
- Open wifi_v3.ino
- Add auth code (available in mail)(line 11)
- Add mobile hotspot name(line 12)
- Add mobile hotspot password(line 13)
- Connect as per this diagram
- Choose board as node MCU 1.0
- Click upload



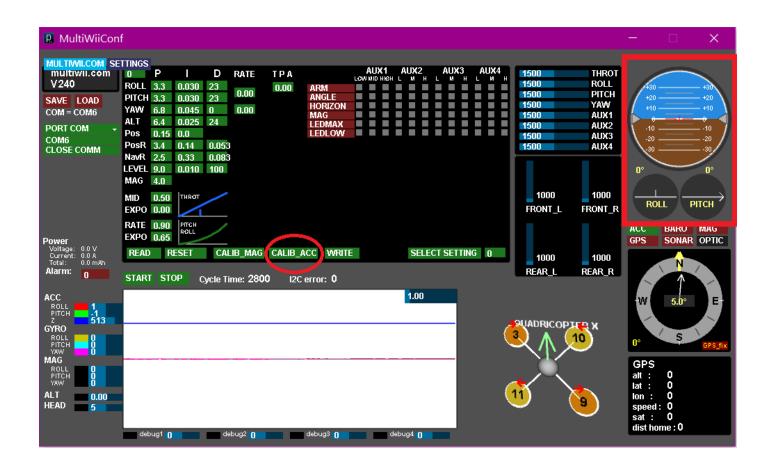
Uploading code to flight controller

- open **MultiWii** folder
- open MultiWii.ino file
- connect as per this diagram
- choose board as Arduino pro mini
- click upload

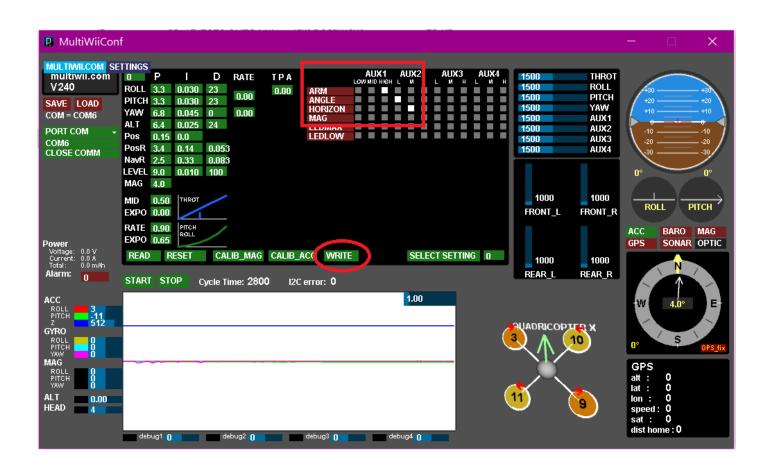


Configuring flight controller

- open MultiWiiConf folder
- Based on the operating system open the required folder
- Run the MultiWiiConf.exe file
- Choose the COM port
- Click Start
- Keep the Drone in FLAT SURFACE
- Click CALIB_ACC
- Don't move the drone wait few second
- Until Roll and Pitch become zero



- For ARM choose AUX1(HIGH)
- For ANGLE choose AUX2(LOW)
- For HORIZON choose AUX2(MID)
- Click WRITE



REMOVE WIRING, CONNECT BATTERY AND START FLYING!!!

Refer version 2 for more information about transmitter.

Github link(https://github.com/Renga-rider/Wifi-Control-Drone-V2)