Moldova State University Faculty of Mathematics and Informatics Department of Informatics

Operations on graphs

Laboratory Report II

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Table of contents

Project code Task 0 1) Picture 2) Results Task 2 1) results Task 3 1) results Task 4 1) results Task 5 1) results Task 6 1) results Task 7 1) results Task 8 1) results Task 9 1) results Task 10

1) results

Project Code

```
#include <iostream>
#include <fstream>
#include <string>
using namespace std;
class Vertex;
class Edge
{
private:
      Vertex* _vertex1;
      Vertex* _vertex2;
      int _weight;
public:
      Edge(Vertex* v1, Vertex* v2, int weight)
             _weight = weight;
             _vertex1 = v1;
             _{vertex2} = v2;
      }
      int GetWeight()
      {
             return _weight;
      }
      Vertex* GetVertex1()
      {
             return _vertex1;
      }
      Vertex* GetVertex2()
      {
             return _vertex2;
      }
};
class Vertex
private:
      Edge** _edges;
      unsigned int _size;
      int _ID;
public:
      Vertex(unsigned int size, unsigned int ID)
             _edges = new Edge * ();
             _size = size;
             _edges = (Edge**)calloc(_size, sizeof(Edge*));
             for (int i = 0; i < _size; i++)</pre>
                    _edges[i] = (Edge*)malloc(sizeof(Edge));
                    _edges[i] = NULL;
             _{ID} = ID;
```

```
void EnlargeEdgeList()
             _size++;
             Edge* edge = (Edge*)malloc(sizeof(Edge));
             _edges = (Edge**)realloc(_edges, sizeof(Edge*) * _size);
             _edges[_size - 1] = edge;
      }
      void ShortenEdgeList(int ID)
             _size--;
             for (int i = ID; i < _size; i++)</pre>
                    _{edges[i]} = _{edges[i + 1]};
             Edge** tempEdges = (Edge**)calloc(_size, sizeof(Edge*));
             for (int i = 0; i < _size; i++)</pre>
                    tempEdges[i] = _edges[i];
             _edges = tempEdges;
      }
      unsigned int GetID() {
             return _ID;
      }
      void ChangeID(int delta)
      {
             _ID += delta;
      }
      Edge* GetEdge(int ID)
             return _edges[ID];
      }
      void SetEdge(Edge* edge, unsigned int ID)
      {
             _edges[ID] = edge;
      }
      Edge** GetEdgeArray()
             return _edges;
      }
};
class Graph
private:
      Vertex** _verts;
unsigned int _size;
      Edge** _allEdges;
      unsigned int _edgesArraySize;
public:
      Graph(int size)
```

}

```
{
             _verts = new Vertex * ();
             _size = size;
             _verts = (Vertex**)calloc(_size, sizeof(Vertex*));
             for (int i = 0; i < _size; i++)</pre>
                   _verts[i] = new Vertex(_size, i);
             }
             _allEdges = (Edge**)malloc(sizeof(Edge*));
             _edgesArraySize = 0;
      }
      int GetSize() {
             return _size;
      }
      Vertex** GetVertexArray()
      {
             return _verts;
      }
      Edge** GetEdgeArray()
      {
             return _allEdges;
      }
      int GetEdgeArraySize()
      {
             return _edgesArraySize;
      }
      void CreateEdge(unsigned ID1, unsigned ID2, unsigned int weight)
             Edge* edge = new Edge(_verts[ID1], _verts[ID2], weight);
             _verts[ID1]->SetEdge(edge, ID2);
             _verts[ID2]->SetEdge(edge, ID1);
             AddToEdgeList(edge);
      }
      void AddToEdgeList(Edge* edge)
             if (_allEdges[0] == NULL)
                   _allEdges[0] = edge;
             }
             else
                   _edgesArraySize++;
                   Edge** tempEdges = (Edge**)calloc(_edgesArraySize,
sizeof(Edge*));
                   for (int i = 0; i < _edgesArraySize; i++)</pre>
                          tempEdges[i] = _allEdges[i];
                   }
                   tempEdges[_edgesArraySize - 1] = edge;
                   _allEdges = tempEdges;
```

```
}
      }
      void RemoveFromEdgeList(unsigned int ID1, unsigned int ID2)
             for (int i = 0; i < _edgesArraySize; i++)</pre>
                    if (((_allEdges[i]->GetVertex1()->GetID() == ID1) or
(_allEdges[i]->GetVertex1()->GetID() == ID2))
                          and ((_allEdges[i]->GetVertex2()->GetID() == ID1) or
(_allEdges[i]->GetVertex2()->GetID() == ID2)))
                          for (int j = i; j < _edgesArraySize - 1; j++)</pre>
                                 _allEdges[j] = _allEdges[j + 1];
                           _edgesArraySize--;
                          Edge** tempEdges = (Edge**)calloc(_edgesArraySize,
sizeof(Edge*));
                          for (int j = 0; j < _edgesArraySize; j++)</pre>
                                 tempEdges[j] = _allEdges[j];
                          _allEdges = tempEdges;
                          break;
                    }
             }
      }
      void AddVertex()
             for (int i = 0; i < _size; i++)</pre>
                    _verts[i]->EnlargeEdgeList();
             _size++;
             Vertex* vert = new Vertex(_size, _size - 1);
             Vertex** tempVerts = (Vertex**)calloc(_size, sizeof(Vertex*));
             for (int i = 0; i < _size; i++)</pre>
                    tempVerts[i] = _verts[i];
             tempVerts[_size - 1] = vert;
             _verts = tempVerts;
      }
      void DeleteEdge(int ID1, int ID2)
      {
             for (int i = 0; i < _edgesArraySize; i++)</pre>
                    if ((_allEdges[i]->GetVertex1()->GetID() == ID1) and
(_allEdges[i]->GetVertex2()->GetID() == ID2))
                    {
                          _allEdges[i]->GetVertex1()->SetEdge(NULL, ID2);
                          _allEdges[i]->GetVertex2()->SetEdge(NULL, ID1);
```

```
RemoveFromEdgeList(ID1, ID2);
                     }
                     else if (((_allEdges[i]->GetVertex2()->GetID() == ID1) and
(_allEdges[i]->GetVertex1()->GetID() == ID2)))
                     {
                            _allEdges[i]->GetVertex1()->SetEdge(NULL, ID1);
_allEdges[i]->GetVertex2()->SetEdge(NULL, ID2);
                            RemoveFromEdgeList(ID1, ID2);
                     }
              }
      }
       void DeleteVertex(int ID)
              for (int i = 0; i < _edgesArraySize; i++)</pre>
                     int a = _allEdges[i]->GetVertex1()->GetID();
                     int b = _allEdges[i]->GetVertex2()->GetID();
                     if (a == ID)
                            RemoveFromEdgeList(a, b);
                     else if (b == ID)
                            RemoveFromEdgeList(b, a);
                            i--;
                     }
              }
              for (int i = 0; i < ID; i++)</pre>
                     _verts[i]->ShortenEdgeList(ID);
              _size--;
              for (int i = ID; i < _size; i++)</pre>
                     _verts[i] = _verts[i + 1];
                     _verts[i]->ShortenEdgeList(ID);
                     _verts[i]->ChangeID(-1);
              }
              Vertex** tempVerts = (Vertex**)calloc(_size, sizeof(Vertex*));
              for (int i = 0; i < _size; i++)</pre>
                     tempVerts[i] = _verts[i];
              _verts = tempVerts;
      }
      void PrintAdjacenceMatrix()
       {
              std::cout << "\n\n\t[ ADJACENCE MATRIX ]\n";</pre>
              printf("\n");
```

```
for (int i = 0; i < _size; i++)</pre>
                     Vertex vert = *_verts[i];
                     for (int j = 0; j < _size; j++)</pre>
                            if (vert.GetEdge(j) != NULL) {
                                   std::cout << "\t" << 1 << "\t ";
                            }
                            else {
                                   std::cout << "\t" << 0 << "\t ";
                            }
                     printf("\n\n");
             }
      }
       void PrintWeightMatrix()
       {
              std::cout << "\n\t[ WEIGHT MATRIX ]\n";</pre>
              printf("\n");
              for (int i = 0; i < _size; i++)</pre>
                     Vertex vert = *_verts[i];
                     for (int j = 0; j < _size; j++)</pre>
                            if (vert.GetEdge(j) != NULL) {
                                   std::cout << "\t" << vert.GetEdge(j)->GetWeight() <<</pre>
"\t ";
                            }
                            else {
                                   std::cout << "\t" << 0 << "\t ";
                            }
                     printf("\n\n");
             }
       }
       void PrintEdgesList()
              std::cout << "\n\t[ ALL EDGES ]\n";</pre>
              for (int i = 0; i < _edgesArraySize; i++)</pre>
                     if (_allEdges[i] != NULL)
                            std::cout << "\n\t[ \t" << _allEdges[i]->GetVertex1()-
>GetID()
                                   << "\t,\t" << _allEdges[i]->GetVertex2()->GetID() <<</pre>
"\t]\n";
                     }
             }
              std::cout << "\n";</pre>
      }
       void PrintNeighboursList()
              std::cout << "\n\t[ ALL NEIGHBOURS ]\n";</pre>
              for (int i = 0; i < _size; i++)</pre>
                     std::cout << "\n\t[" << _verts[i]->GetID() << "]\t";
```

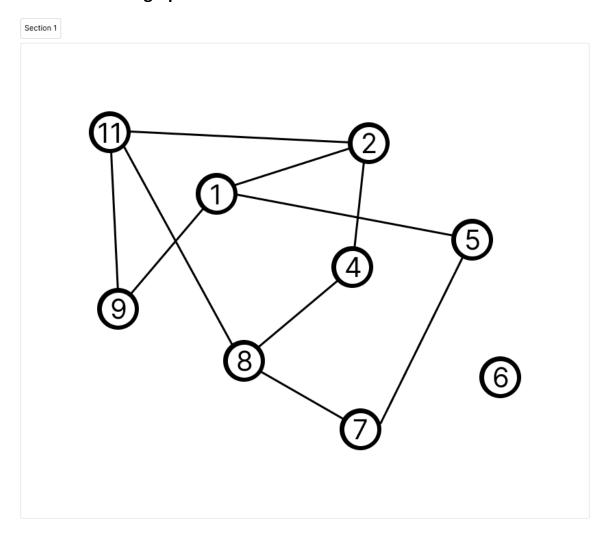
```
Edge** edges = _verts[i]->GetEdgeArray();
                    for (int j = 0; j < _size; j++)</pre>
                           if (edges[j] != NULL)
                                 if (edges[j]->GetVertex1()->GetID() == i)
                                        std::cout << edges[j]->GetVertex2()->GetID()
<< " \t";
                                 }
                                 else
                                        std::cout << edges[j]->GetVertex1()->GetID()
<< " \t";
                                 }
                           }
                    std::cout << "\n";
             }
      }
       void PerformDFS(int start)
             int vertsArrSize = _msize(_verts) / sizeof(Vertex*);
             std::cout << "\t[DFS]\n";</pre>
             bool** visited = (bool**)calloc(vertsArrSize, sizeof(bool*));
             for (int i = 0; i < vertsArrSize; i++)</pre>
                    visited[i] = (bool*)malloc(sizeof(bool));
                    *visited[i] = 0;
             }
             DFS(start, visited);
       }
      bool** DFS(int current, bool** visited)
             int vertsArrSize = _msize(_verts) / sizeof(Vertex*);
             *visited[current] = 1;
             std::cout << "\n\tVisited - " << current;</pre>
             for (int i = 0; i < vertsArrSize; i++)</pre>
                    if ((_verts[current]->GetEdgeArray()[i] != NULL) and
(*visited[i] == 0))
                           visited = DFS(i, visited);
                    }
             return visited;
       }
      void PerformBFS(int start)
             int vertsArrSize = _msize(_verts) / sizeof(Vertex*);
             std::cout << "\n\t[BFS]\n";
             bool** visited = (bool**)calloc(vertsArrSize, sizeof(bool*));
             for (int i = 0; i < vertsArrSize; i++)</pre>
             {
                    visited[i] = (bool*)malloc(sizeof(bool));
                    *visited[i] = 0;
             }
             bool** checked = (bool**)calloc(vertsArrSize, sizeof(bool*));
             for (int i = 0; i < vertsArrSize; i++)</pre>
```

```
{
                    checked[i] = (bool*)malloc(sizeof(bool));
                    *checked[i] = 0;
             }
             visited = VisitVertex(start, visited);
             BFS(start, visited, checked);
      }
      void BFS(int current, bool** visited, bool** checked)
             int vertsArrSize = _msize(_verts) / sizeof(Vertex*);
             *checked[current] = 1;
             for (int i = 0; i < vertsArrSize; i++)</pre>
                   bool b = (*checked[i] == 0);
                   bool d = (_verts[current]->GetEdgeArray()[i] != NULL);
                   bool g = (*visited[i] == 0);
                   if ((_verts[current]->GetEdgeArray()[i] != NULL) and
(*visited[i] == 0) and (*checked[i] == 0))
                          visited = VisitVertex(i, visited);
                   }
             }
             for (int i = 0; i < vertsArrSize; i++)</pre>
                    if ((_verts[current]->GetEdgeArray()[i] != NULL) and
(*checked[i] == 0))
                          BFS(i, visited, checked);
                    }
             }
      }
      bool** VisitVertex(int vertex, bool** visited)
             *visited[vertex] = 1;
             std::cout << "\n\tVisited - " << vertex;</pre>
             return visited;
      }
};
      };
Graph CreateComplementaryGraph(Graph graph) // Not really a good code but it works
      int size = graph.GetSize();
      Graph complementaryGraph = *new Graph(size);
      for (int i = 0; i < size; i++)</pre>
             for (int j = 0; j < size; j++)</pre>
                    if (graph.GetVertexArray()[i]->GetEdgeArray()[j] == NULL)
                          complementaryGraph.CreateEdge(i, j, 1);
                   }
             }
      }
```

```
return complementaryGraph;
}
Graph CreateAssociatedGraph(Graph graph) // Not really a good code too but it works
       int size = graph.GetEdgeArraySize();
      Graph asGraph = *new Graph(size);
      for (int i = 0; i < size - 1; i++)</pre>
             graph.GetEdgeArray()[i];
             for (int j = i + 1; j < size; j++)</pre>
                    if ((graph.GetEdgeArray()[i]->GetVertex1()->GetID() ==
graph.GetEdgeArray()[j]->GetVertex1()->GetID()) or
                            (graph.GetEdgeArray()[i]->GetVertex2()->GetID() ==
graph.GetEdgeArray()[j]->GetVertex1()->GetID()) or
                            (graph.GetEdgeArray()[i]->GetVertex1()->GetID() ==
graph.GetEdgeArray()[j]->GetVertex2()->GetID()) or
                            (graph.GetEdgeArray()[i]->GetVertex2()->GetID() ==
graph.GetEdgeArray()[j]->GetVertex2()->GetID()))
                           asGraph.CreateEdge(i, j, 1);
                    }
             }
      }
      return asGraph;
}
int main()
      cout << "\n Created Graph\n";</pre>
      Graph graph = *new Graph(11);
                                                //Task 1
      graph.CreateEdge(0, 1, 1);
graph.CreateEdge(0, 4, 4);
      graph.CreateEdge(0, 8, 9);
graph.CreateEdge(1, 3, 13)
      graph.CreateEdge(1, 10, 110);
      graph.CreateEdge(10, 8, 108);
      graph.CreateEdge(10, 7, 107);
      graph.CreateEdge(7, 3, 73);
      graph.CreateEdge(7, 6, 76);
      graph.CreateEdge(6, 4, 64);
      graph.PrintAdjacenceMatrix();
      cout << "\n Printed edges \n";</pre>
      graph.PrintEdgesList();
                                                //Task 2
      graph.PrintNeighboursList();
      cout << "\n Created vertex \n";</pre>
      graph.AddVertex();
                                                //Task 3
      graph.PrintAdjacenceMatrix();
      cout << "\n Deleted vertex \n";</pre>
      graph.DeleteVertex(5);
                                                //Task 4
      graph.PrintAdjacenceMatrix();
      cout << "\n Created edge \n";</pre>
      graph.CreateEdge(0, 3, 3);
                                                //Task 5
      graph.PrintAdjacenceMatrix();
```

```
cout << "\n Deleted edge \n";
graph.DeleteEdge(0, 3);
                                                //Task 6
      graph.PrintAdjacenceMatrix();
      cout << "\n Created complementary graph \n";</pre>
      Graph compGraph = CreateComplementaryGraph(graph); // Task 7
      compGraph.PrintAdjacenceMatrix();
      cout << "\n Created assiciated graph \n";</pre>
      Graph asGraph = CreateAssociatedGraph(graph);
                                                         // Task 8
      asGraph.PrintAdjacenceMatrix();
      cout << "\n Performed DFS \n";</pre>
      graph.PerformDFS(0);
                                                //Task 9
      cout << "\n Performed BFS \n";</pre>
      graph.PerformBFS(0);
                                                //Task 10
      return 0;
}
```

1. Picture of graph



2. Results

[ADJACE	NCE MATRIX]					
0						0
1						1
0						0
0						0
1						0
0						0
0						0
Ø						1
1						1
0						0
Ø						0

Task 2

```
[ ALL EDGES ]

[ 1 , 2 ]

[ 1 , 5 ]

[ 1 , 9 ]

[ 11 , 9 ]

[ 11 , 9 ]

[ 11 , 8 ]

[ 11 , 8 ]

[ 8 , 4 ]

[ 2 , 4 ]

[ 5 , 7 ]

[ 7 , 8 ]

[ ALL NEIGHBOURS ]

[ 1] 2 5 9

[ 2] 1 4 11

[ 3]

[ 4] 2 8

[ 5] 1 7

[ 6]

[ 7] 5 8

[ 8] 4 7 11

[ 9] 1 11

[ 10]
```

Results

Created vertex											
[ADJACE	NCE MATRIX]										
0							9		ø		1
1		0					9		ø		1
0							0		ø		1
0		0				0			e		1
1							9		ø		1
0							9		ø		1
0		0				0			ø		1
0							0		ø		1
1		0				0	0		ø		1
0							9		ø		1
0						0			0		1
9	0	0	0	0	9	0	0	9	0	9	9

Task 4

Deleted vertex										
[ADJACE	NCE MATRIX]									
0	1	0	0	1	0	0	1	0	0	1
1	0	0	1	0	0	0	0	0	1	1
0	0	0	0	0	0	0	0	0	0	1
0	1	0	0	0	0		0	0	9	1
1	0	0	0	0	1	0	0	0	9	1
0	0	0	0	1	0	1	0	0	0	1
0	0	0	1	0	1	0	0	0		1
1	0	0	0	0	0	0	0	0		1
0	0	0	0	0	0	0	0	0	0	1
0	1	0	0	0	0	1	1	0	0	1
0	0	0	0	0	0	0	0	0	9	0

Results

Created edg	ge						
[AD	JACENCE MATRIX]						
0		0					1
1				9			1
0				0			1
1							1
1							1
0							1
0				0			1
1		0		0			1
0				0		0	1
0		0					1
0				0			0

Task 6

Delete	d edge										
	[ADJACENCE MAT	RIX]									
	0		0	0			0		0	0	1
		0	0		0		0	0			1
	0	0	0	0	0	0	0	0		0	1
	0		0	0	0			0		0	1
		0	0	0	0		0	0			1
	0	0	0	0				0			1
	0	0	0		0		0	0			1
		0	0	0	0		0	0			1
	0	0	0	0	0		0	0		0	1
	0		0	0	0	0				0	1
	0	0	0	0	0		0	0	0	0	0

Results

[ADJACENCE MATRIX					
1 0					1
0 1				ø	1
1 1					1
1 0					1
0 1					1
1 1					1
1 1				ø	1
0 1				ø	1
1 1					1
1 0					1
1 1					1

Task 8

Results

Created assiciat	ed graph								
[ADJACEN	ICE MATRIX]								
0	1	1	1	1	0	0	0	0	0
1	0	1	0	0	0	0	0	0	1
1	1	0	0	0	1	0	0	0	0
1	0	0	0	1	0	0	1	0	0
1	0	0	1	0	1	1	0	0	0
0	0	1	0	1	0	1	0	0	0
0	0	0	0	1	1	0	1	1	0
0	0	0	1	0	0	1	0	1	0
0	0	0	0	0	0	1	1	0	1
0	1	0	0	0	0	0	0	1	0

Task 9

```
Performed DFS
[DFS]

Visited - 0
Visited - 1
Visited - 3
Visited - 6
Visited - 5
Visited - 4
Visited - 10
Visited - 9
Visited - 7
```

```
Performed BFS

[BFS]

Visited - 0

Visited - 1

Visited - 4

Visited - 7

Visited - 10

Visited - 3

Visited - 9

Visited - 6
```