### SVMs / Kernel Machines

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## **Support Vector Machines**

 Easier to convert into a quadratic optimisation problem with linear constraints

$$\min_{\boldsymbol{w},b} \frac{1}{2} ||\boldsymbol{w}||^2$$

such that

$$y_i(\mathbf{w}^T\mathbf{x}_i+b)\geqslant 1, i=1,\ldots,m$$

Objective function + inequality constraints → constrained optimisation problem



### **Support Vector Machines**

• Such problems are "dealt with" using Lagrange multipliers  $\alpha_i \ge 0$  and a Lagrangian:

$$L(\mathbf{w}, b, \alpha) = \frac{1}{2} ||\mathbf{w}||^2 - \sum_{i=1}^{m} \alpha_i (y_i(\mathbf{w}^T \mathbf{x}_i + b) - 1)$$

$$L(\mathbf{w}, b, \alpha) = \frac{1}{2} ||\mathbf{w}||^2 - \sum_{i=1}^m \alpha_i y_i (\mathbf{w}^T \mathbf{x}_i + b) + \sum_{i=1}^m \alpha_i$$

 The minimum is found by taking its partial derivatives and setting them equal to zero:

$$\frac{\partial L}{\partial \mathbf{w}} = \mathbf{w} - \sum_{i} \alpha_{i} \mathbf{y}_{i} \mathbf{x}_{i} = 0$$

$$\frac{\partial L}{\partial b} = -\sum_{i} \alpha_{i} y_{i} = 0$$





### **Support Vector Machines**

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 Substituting these (and simplifying) we get a dual representation:

$$\arg\max_{\alpha} \sum_{i=1}^{m} \alpha_{i} - \frac{1}{2} \sum_{i,j=1}^{m} \alpha_{i} \alpha_{j} y_{i} y_{j} (\mathbf{x}_{i} \cdot \mathbf{x}_{j})$$



#### **Decision function**

- Linear classifier has the form  $y = \mathbf{w}^T \mathbf{x} + b$
- Remember that for a specific x we want to know whether it is +1 or a −1.
- We can stay in the dual representation.
- If we substitute, the decision function can be written as:

$$h(\mathbf{x}) = sign\left(\sum_{i} \alpha_{i} y_{i}(\mathbf{x} \cdot \mathbf{x}_{i}) + b\right)$$

• We only need to do this for the  $\mathbf{x}_i$  that are support vectors.



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- We only need to do this for the  $\mathbf{x}_i$  that are support vectors.
- How about b?
- Any support vector x satisfies:

$$y_i(\mathbf{w}^T\mathbf{x}_i+b)=1$$

$$y_i \left( \sum_i \alpha_i y_i (\mathbf{x} \cdot \mathbf{x}_i) + b \right) = 1$$





### **Decision function**

- How about b?
- Any support vector x satisfies:

$$y_i\left(\sum_i \alpha_i y_i(\mathbf{x} \cdot \mathbf{x}_i) + b\right) = 1$$

- Multiply through by  $y_i$  and use  $y_i^2 = 1$
- Average these equations over all support vectors and solve for b:

$$b = \frac{1}{N} \sum_{j} \left( y_{i} - \sum_{i} \alpha_{i} y_{i} (\mathbf{x} \cdot \mathbf{x}_{i}) \right)$$

where *N* is the total number of support vectors.



• We do this by allowing slack variables:

$$\xi_i \geqslant 0$$

for all  $i = 1 \dots m$ 

Then, instead of looking for

$$y_i(\mathbf{w}\cdot\mathbf{x}_i+b)\geqslant 1$$

for all *i* in the original weight/feature space, we look for:

$$y_i(\mathbf{w} \cdot \mathbf{x}_i + b) \geqslant 1 - \xi_i$$

for all i.

• Points for which  $\xi = 0$  are correctly classified;  $0 < \xi \le 1$  lie inside the margin;  $\xi > 1$  lie on the wrong side of the boundary and are misclassified.

$$\tau(\mathbf{w}, \xi) = \frac{1}{2} ||\mathbf{w}||^2 + C \sum_{i=1}^{m} \xi_i$$

- The constant C > 0 determines the amount of slack that is allowed.
- This controls the trade-off between margin maximization
  - which needs more slack and minimizing training errors
    - which needs less slack
- Typically have to search to find the optimal C for a given problem.



We end up solving:

$$\arg\max_{\alpha} \sum_{i} \alpha_{i} - \frac{1}{2} \sum_{i,j} \alpha_{i} \alpha_{j} y_{i} y_{j} K(\mathbf{x}_{i}, \mathbf{x}_{j})$$

subject to the additional constraints:

$$0 \leqslant \alpha_i \leqslant C$$

for all i = 1, ..., m and:

$$\sum_{i=1}^m \alpha_i y_i = 0$$





- The only difference with the separable case is the upper bound C on the α<sub>i</sub>.
- This limits the influence of individual data points.
- The intuition is that this prevents outliers from having a big effect on the separator.

#### Kernels

- SVM can be re-cast into a dual representation based on the dot product between our feature vectors
- Replace the scalar product with a kernel
- We can use a kernel function  $K(\mathbf{x}, \mathbf{z})$
- $K(\mathbf{x}, \mathbf{z}) = F(\mathbf{x}) \cdot F(\mathbf{z})$
- e.g. for quadratic,  $K(\mathbf{x}, \mathbf{z}) = (\mathbf{x} \cdot \mathbf{z})^2$
- Since x · z is a scalar, once we have computed the dot product, just have to do the kernel computation on this one number.
- We've computed the inner product in the feature space R<sup>3</sup> without ever having to transform data into R<sup>3</sup>!



#### Kernels

- How can we construct kernels?
- Choose a feature mapping F(x) and use this to find your kernel
- Or construct kernel functions directly
- Ensure the function is a valid kernel

$$K(\mathbf{x}, \mathbf{z}) = (\mathbf{x}^{\mathsf{T}}\mathbf{z})^2$$

$$K(\mathbf{x}, \mathbf{z}) = (x_1 z_1 + x_2 z_2)^2 = x_1^2 z_1^2 + 2x_1 z_1 x_2 z_2 + x_2^2 z_2^2 =$$

$$= (x_1^2, \sqrt{2} x_1 x_2, x_2^2) (z_1^2, \sqrt{2} z_1 z_2, z_2^2)^{\mathsf{T}}$$

$$= F(\mathbf{x})^{\mathsf{T}} F(\mathbf{z})$$





### Kernels

$$k(\mathbf{x}, \mathbf{x}') = ck_1(\mathbf{x}, \mathbf{x}')$$

$$k(\mathbf{x}, \mathbf{x}') = f(\mathbf{x})k_1(\mathbf{x}, \mathbf{x}')f(\mathbf{x}')$$

$$k(\mathbf{x}, \mathbf{x}') = q(k_1(\mathbf{x}, \mathbf{x}'))$$

$$k(\mathbf{x}, \mathbf{x}') = \exp(k_1(\mathbf{x}, \mathbf{x}'))$$

$$k(\mathbf{x}, \mathbf{x}') = k_1(\mathbf{x}, \mathbf{x}') + k_2(\mathbf{x}, \mathbf{x}')$$

$$k(\mathbf{x}, \mathbf{x}') = k_1(\mathbf{x}, \mathbf{x}')k_2(\mathbf{x}, \mathbf{x}')$$

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$$k(\mathbf{x}, \mathbf{x}') = k_3(\phi(\mathbf{x}), \phi(\mathbf{x}'))$$

$$k(\mathbf{x}, \mathbf{x}') = k_3(\phi(\mathbf{x}), \phi(\mathbf{x}'))$$

$$k(\mathbf{x}, \mathbf{x}') = k_3(\mathbf{x}_a, \mathbf{x}_a') + k_b(\mathbf{x}_b, \mathbf{x}_b')$$

$$k(\mathbf{x}, \mathbf{x}') = k_a(\mathbf{x}_a, \mathbf{x}_a')k_b(\mathbf{x}_b, \mathbf{x}_b')$$



#### References

Christopher M. Bishop. Pattern Recognition and Machine Learning. Springer. 2006

