

# Wind project initial constants

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## Introduction

In these slides, I have determined the initial parameters needed for the model of the wind power production. These parameters are  $\varepsilon$  ,  $\theta_0$  and  $\alpha$ .

## Model

The wind power production is modeled as follows, where  $X_t$  is the normalized real production :

$$\begin{cases} dX_t = (\dot{p}_t - \theta_t (X_t - p_t)) dt + \sqrt{2\alpha\theta_0 X_t (1 - X_t)} dW_t, & t \in [0, T] \\ X_0 = x_0 \in [0, 1] \end{cases}$$

We may introduce the following model for the forecast error of the normalized wind power production where  $X_t$  is the real production,  $p_t$  the forecast and  $V_t = X_t - p_t$  is the error :

$$\begin{cases} dV_t = -\theta_t V_t dt + \sqrt{2\alpha\theta_0 (V_t + p_t) (1 - V_t - p_t)} dW_t, & t \in [0, T] \\ V_0 = v_0 \in [-1 + \varepsilon, 1 - \varepsilon] \end{cases}$$

## Model

To guarantee a unique solution for the process  $X_t$ ,  $\theta_t$  needs to be bounded for  $t \in [0, T]$ . We have that :

$$\theta_t = \max \left( \theta_0, \frac{\alpha \theta_0 + |2 \dot{p}_t|}{2 \min(1-p_t, p_t)} \right)$$

This is not true for  $\theta_t$  if  $p_t \rightarrow 0^+$  or  $p_t \rightarrow 1^-$ . Therefore we need to ensure that  $p_t \in [\varepsilon, 1 - \varepsilon]$  for some  $0 < \varepsilon < \frac{1}{2}$ ,  $\forall t \in [0, T]$ .

## Model

We define then the corrected forecast :

$$p_t^\varepsilon = \begin{cases} \varepsilon & \text{if } p_t < \varepsilon \\ p_t & \text{if } \varepsilon \leq p_t < 1 - \varepsilon \\ 1 - \varepsilon & \text{if } p_t \geq 1 - \varepsilon \end{cases}$$

and the corrected (and bounded) drift coefficient is therefore :

$$\theta_t^\varepsilon = \max \left( \theta_0, \frac{\alpha \theta_0 + 2 |\dot{p}_t^\varepsilon|}{2 \min(1 - p_t^\varepsilon, p_t^\varepsilon)} \right)$$

## Least Square Minimization : LSM

In order to evaluate the constants of our model we apply the least square method on the forecast error  $V_t$ .

We consider the transition  $\Delta V_i = V_{i+1} - V_i$  with  $\Delta t = t_{i+1} - t_i$ .  $(V_{i+1}|V_i)$  is a random variable which conditional mean can be approximated by the solution of the following system :

$$\begin{cases} d\mathbb{E}[V] = -\theta_t^\varepsilon \mathbb{E}[V] dt \\ \mathbb{E}[V(t_i)] = V_i \end{cases}$$

evaluated in  $t_{i+1}$  (i.e.,  $\mathbb{E}[V(t_{i+1})]$  ).

Then, the random variable  $(V_{i+1} - \mathbb{E}[V(t_{i+1})])$  has a mean equal to 0 approximately.

If we assume that  $\theta_t^\varepsilon = c \in \mathbb{R}^+$  for all  $t \in [t_i, t_{i+1}]$ , then  $\mathbb{E}[V(t_{i+1})] = V_i e^{-c\Delta t}$ .

If we have a total of  $n$  transitions, we can write the regression problem for the conditional mean with  $L^2$  loss function as :

$$\begin{aligned} c^* &\approx \arg \min_{c \geq 0} \left[ \sum_{i=1}^n (V_{i+1} - \mathbb{E}[V(t_{i+1})])^2 \right] \\ &= \arg \min_{c \geq 0} \left[ \sum_{i=1}^n (V_{i+1} - V_i e^{-c\Delta t})^2 \right] \end{aligned} \quad (1)$$

## Least Square Minimization : LSM

We take the first order approximation of  $e^{-c\Delta t}$  w.r.t.  $c$  :

$$e^{-c\Delta t} = 1 - c\Delta t + O((c\Delta t)^2)$$

and introduce it in equation (1). We get

$$c^* \approx \arg \min_{c \geq 0} \underbrace{\left[ \sum_{i=1}^n (V_{i+1} - V_i(1 - c\Delta t))^2 \right]}_{=f(c)}$$

As  $f(c)$  is convex in  $c$ , solving (5) (finding  $c^*$ ) is equivalent to solving

$$\frac{\partial f}{\partial c}(c^{**}) = 0$$

and choosing  $c^* = \max\{0, c^{**}\}$



## Least Square Minimization : LSM

$$\begin{aligned}\frac{\partial f}{\partial c} &= \sum_{i=1}^n 2(-V_i)(-\Delta t)(V_{i+1} - V_i(1 - \theta_0 \Delta t)) \\ &= \sum_{i=1}^n 2V_i \Delta t (V_{i+1} - V_i(1 - c \Delta t)) \\ &= \sum_{i=1}^n 2V_{i+1} V_i \Delta t - 2V_i^2 \Delta t + 2V_i^2 \Delta t^2 c\end{aligned}$$

Then,  $c^{**}$  satisfies the following :

$$c^{**} \approx \frac{\sum_{i=1}^n V_i (V_i - V_{i+1})}{\Delta t \cdot \sum_{i=1}^n (V_i)^2}$$

## Quadratic variation

We approximate the SDE by its E-M scheme. In particular, we approximate the Itô quadratic variation with the discrete one :

- ▶ Itô process quadratic variation :  $[V]_t = \int_0^t \sigma_s^2 ds$
- ▶ Discrete process quadratic variation :  $[V]_t = \sum_{0 \leq s \leq t} (\Delta V_s)^2$

Then, considering  $\Delta t$  the time between the measurements, we approximate :

$$\theta_0^* \alpha^* \approx \frac{\sum_{i=1}^n (\Delta V_i)^2}{2\Delta t \sum_{i=1}^n (V_i + p_i)(1 - V_i - p_i)}$$

## Estimation of $(\theta_0, \alpha, \varepsilon)$

In this section, we will use the approximation made previously to estimate the parameters  $(\theta_0, \alpha, \varepsilon)$  of the SDE. Let us define  $(\theta_0^*, \alpha^*, \varepsilon^*)$  as their estimators.

If we fix  $\varepsilon$ , we define the forecast error  $\forall i \in 1 \dots n \ V_i = X_i - p_i^\varepsilon$ .

If we also fix  $\theta_0$  and  $\alpha$ , we can define the set of indexes :

$I = \{i \in \{1, \dots, n\} : \text{the LSM estimation will estimate } \theta_0\}$

$J = \{j \in \{1, \dots, n\} : \text{the } \textit{LSM} \text{ estimation will estimate } \frac{\theta_0 \alpha}{\varepsilon}\}$

We will proceed then to approximate these sets in order to estimate our parameters.

## Estimation of $(\theta_0, \alpha, \varepsilon)$

To use the LSM estimation, we assumed that  $\theta_t^\varepsilon = c \in \mathbb{R}^+$ , and we defined  $\theta_t^\varepsilon$  :

$$\theta_t^\varepsilon = \max \left( \theta_0, \frac{\alpha \theta_0 + 2 |\dot{p}_t^\varepsilon|}{2 \min(1 - p_t^\varepsilon, p_t^\varepsilon)} \right)$$

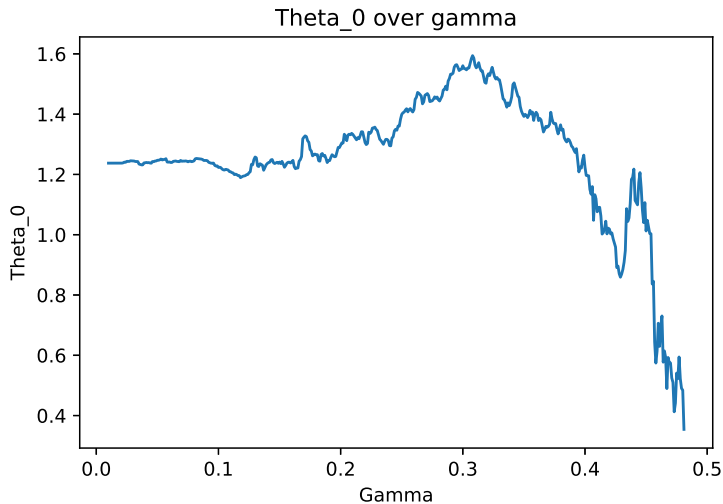
From the definition of  $\theta_t^\varepsilon$  : We have that for  $\varepsilon \ll 1$ , and  $p_t = \varepsilon$  or  $p_t = 1 - \varepsilon$ , the approximation  $\theta_t^\varepsilon \approx \frac{\theta_0 \alpha}{\varepsilon}$  holds. Then, for  $\varepsilon$  small enough,  $J$  can be approximated by the following :

$$J \approx J = \{j \in \{1, \dots, n\} : p_j^\varepsilon \in \{\varepsilon, 1 - \varepsilon\}\}$$

and  $\theta_t^\varepsilon$ , we have that it is more likely that  $\theta_t^\varepsilon = \theta_0$  if  $p_t^\varepsilon \approx \frac{1}{2}$ . Then, we can approximate  $I$  by

$$I \approx \tilde{I} = \{i \in \{1, \dots, n\} : p_i \in (\gamma, 1 - \gamma)\}, \gamma \approx \frac{1}{2}, \gamma < \frac{1}{2}$$

## Estimation of $\theta_0^*$



We estimate  $\theta_0^* = 1.25$

## Estimation of $\alpha^*$

With the previous approximation made of the quadratic variation we can estimate  $\theta_0 * \alpha^* = 0.094$  therefore, with our given estimation of  $\theta_0$  we find that :  $\alpha^* = 0.08$

## Estimation of $\varepsilon^*$

Now that we have an approximated value of  $\theta_0\alpha$ , if we can estimate  $\frac{\theta_0\alpha}{\varepsilon}$ , then we can estimate  $\varepsilon$ . We showed previously that for  $\varepsilon \ll 1$ , the LSM estimation using indexes from  $J$  is an estimator for  $\frac{\theta_0\alpha}{\varepsilon} =: k$

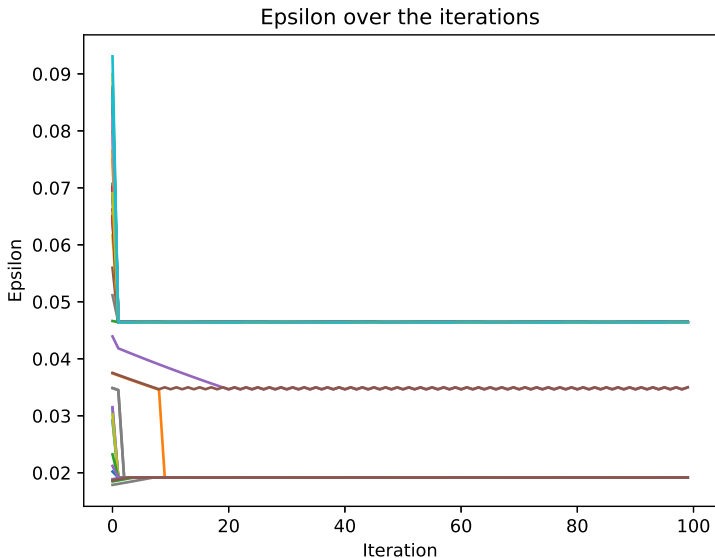
The goal is to find values for  $\varepsilon$  that satisfy  $\varepsilon \ll 1$ . For that we start by randomly choosing a small initial value for  $\varepsilon$  (that we will call  $\varepsilon_0$ ), and iterating we aim to converge to some local minimum. We proceed with the following steps :

- ▶ We sample  $\varepsilon_0$  from  $U[0.01, 0.1]$  and load  $\varepsilon \leftarrow \varepsilon_0$
- ▶ We create  $\tilde{J}$  and use the LSM estimation to find  $k$ .
  - ▶ If  $k < \theta_0^*$ , then the assumption  $\theta_t^\varepsilon = c \in \mathbb{R}^+$  is wrong and we reduce the value of  $\varepsilon$ , i.e.,  $\varepsilon \leftarrow \varepsilon * 0.999$ .
  - ▶ If  $k \geq \theta_0^*$ , we load  $\varepsilon \leftarrow \frac{\theta_0^*\alpha^*}{k}$  ( we allow a maximum relative change of 1%).

We repeat this step 100 times.

- ▶ We repeat steps 1 and 2, 50 times.

## Estimation of $\varepsilon^*$



We can see from the plots that  $\varepsilon^* = 0.018$  is a good approximation.



## Conclusion

To conclude, the estimations of the SDE parameters that we found are :  $(\theta_0^*, \alpha^*, \varepsilon^*) = (1.25, 0.08, 0.018)$ .

The code computing this process can be found in the file '*Wind<sub>p</sub>project;ntial<sub>g</sub>uess.ipynb*'.