On the Uncertainty of Wind Power Generation continuous report

Waleed Alhaddad

September 2, 2019

Base Model

Moments approach with a Beta proxy. The SDE is given by

$$dV_t = - heta_t V_t \ dt + \sqrt{2 heta_t lpha(V_t + p_t)(1 - V_t - p_t)} \ dW_t$$
 $V_0 = v_0$

(1)

and the moments by,

$$\begin{split} \frac{dm_1(t)}{dt} &= -m_1(t)\theta_t \implies m_1(t_2) = V_{t_1}e^{-\int_{t_1}^{t_2}\theta_t \ dt} \\ \frac{dm_2(t)}{dt} &= -m_2(t)\theta(1+\alpha) + \alpha\theta m_1(t)((1-p_t-p_t^2)) + 2 \\ &\implies m_2(t_2) = v_{t_1}^2e^{-(1+\alpha)\int_{t_1}^{t_2}\theta_t \ dt} \\ &+ \alpha\int_{t_1}^{t_2} \left(\theta_s m_1(s)(1-p_s-p_s^2) + 2\right)e^{-(1+\alpha)\int_{t_1}^{t_2-s}\theta_u \ du} \ ds \end{split}$$

solving for the moments numerically

We discretize and integrate numerically step-by-step using Euler,

$$m_{1,i+1} = v_i \ e^{-\theta_i \Delta t}$$
 $m_{2,i+1} = \frac{v_i^2 + 2\Delta t v_i \alpha \theta_i p_i (1 - p_i) (1 - 2p_i) \alpha \theta_i p_i^2 (1 - p_i)^2}{1 + 2\Delta t (\theta_i + \alpha \theta_i p_i (1 - p_i))}$

Proposed Mini-Batch Stochastic Gradient Descent

We have the following beta log-likelihood,

$$\ell(\theta_0, \alpha | \{V_{i,j}\}) = \sum_{j=1}^{M} \sum_{i=1}^{N} (s_1 - 1) \log \left(\frac{V_{j,i+1} + 1}{2}\right) + (s_2 - 1) \log \left(1 - \frac{V_{j,i+1} + 1}{2}\right) - \log (2B(s_1, s_2))$$

where $B(\cdot,\cdot)$ is the Beta function and

$$s_1 = -\frac{(m_1+1)(m_1^2 + m_2 - m_1^2 - 1)}{2(m_2 - m_1^2)} \tag{2}$$

$$s_2 = \frac{(m_1 - 1)(m_1^2 + m_2 - m_1^2 - 1)}{2(m_2 - m_1^2)} \tag{3}$$

We optimize the likelihood using Nelder-Mead Method which is a derivative-free method for non-linear objectives.

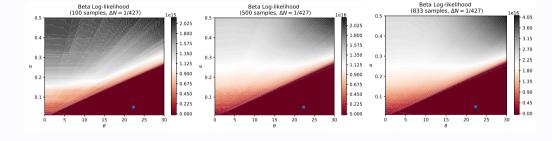


Figure 1: Likelihood evaluation with different number of sample paths. Optimal point $(\theta_0^*, \alpha^*) = (22.33, 0.049)$ shown in blue obtained using Nelder-Mead optimization method.

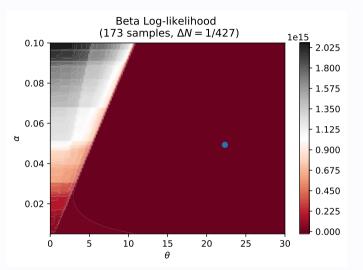


Figure 2: Likelihood evaluation with 173 paths. Optimal point $(\theta_0^*, \alpha^*) = (22.33, 0.049)$ shown in blue obtained using Nelder-Mead optimization method.

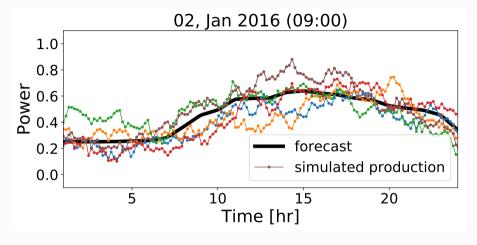


Figure 3: Example 24hr simulation paths with the optimal parameters $(\theta_0^*, \alpha^*) = (22.33, 0.049)$

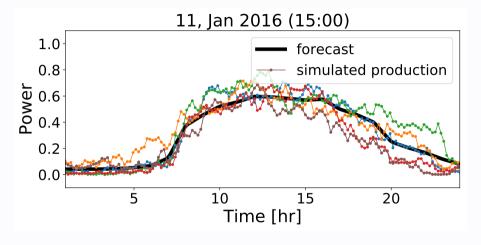


Figure 4: Example 24hr simulation paths with the optimal parameters $(\theta_0^*, \alpha^*) = (22.33, 0.049)$

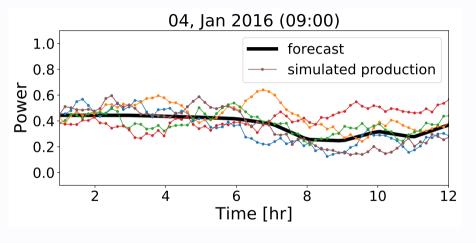


Figure 5: Example 12hr simulation paths with the optimal parameters $(\theta_0^*, \alpha^*) = (22.33, 0.049)$

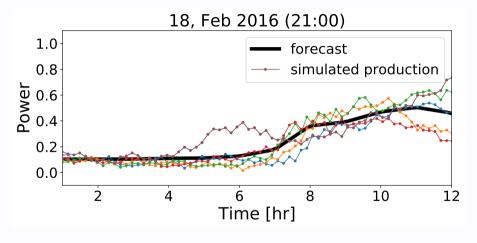


Figure 6: Example 12hr simulation paths with the optimal parameters $(\theta_0^*, \alpha^*) = (22.33, 0.049)$

Proposed Mini-Batch Stochastic Gradient Descent

Let B be the mini-batch size and η the learning rate. We iterate from an initial guess $\Theta_0 = (\theta_0, \alpha)^T$ in the following way,

$$\Theta = \Theta - \eta \nabla \ell(\Theta; V_{1:B,1:N}) \tag{4}$$

until an accuracy threshold is reached. Note that $V_{1:B,1:N}$ is a mini-batch of size B of complete sample paths. The components of the gradient $\nabla \ell = (\frac{\partial \ell}{\partial \theta_0}, \frac{\partial \ell}{\alpha})^T$ are given by,

$$\frac{\partial \ell}{\partial \theta_0} = \frac{\partial \ell}{\partial s_1} \frac{\partial s_1}{\partial m_1} \frac{\partial m_1}{\partial \theta_t} \frac{\partial \theta_t}{\partial \theta_0} + \frac{\partial \ell}{\partial s_1} \frac{\partial s_1}{\partial m_2} \frac{\partial m_2}{\partial \theta_t} \frac{\partial \theta_t}{\partial \theta_0} + \frac{\partial \ell}{\partial s_2} \frac{\partial s_2}{\partial m_1} \frac{\partial m_1}{\partial \theta_t} \frac{\partial \theta_t}{\partial \theta_0} + \frac{\partial \ell}{\partial s_2} \frac{\partial s_2}{\partial m_2} \frac{\partial m_2}{\partial \theta_t} \frac{\partial \theta_t}{\partial \theta_0}$$

$$\frac{\partial \ell}{\partial \alpha} = \frac{\partial \ell}{\partial s_1} \frac{\partial s_1}{\partial m_2} \frac{\partial m_2}{\partial \alpha} + \frac{\partial \ell}{\partial s_2} \frac{\partial s_2}{\partial m_2} \frac{\partial m_2}{\partial \alpha} + \frac{\partial \ell}{\partial s_2} \frac{\partial s_2}{\partial m_2} \frac{\partial m_2}{\partial \alpha}$$

Proposed Mini-Batch Stochastic Gradient Descent

We run into an issue here because the term $\frac{\partial \theta_t}{\partial \theta_0}$ is undefined as θ_t is non-differentiable and given by,

$$heta_t = \max\left(heta_0, rac{|\dot{p}|}{\min(p, 1-p)}
ight)$$

We can either regularize or continue to use the Nelder-Mead optimization method which is derivative-free. Is it possible to use mini-batches with Nelder-Mead?