```
/* Binary Encodings */
/* STACK */
* END 00000000 | 4-bit base address | 4-bit multiplier | 16-bit offset field
 * PUSH 00000001 | 4-bit base address | 4-bit multiplier | 16-bit offset field
 * P0P
        00000010 | 4-bit base address | 4-bit multiplier | 16-bit offset field
 * ADD
        00000011 | 4-bit base address | 4-bit multiplier | 16-bit offset field
        00000100 | 4-bit base address | 4-bit multiplier | 16-bit offset field
 * MUL
 * PIMM 00000101 | 24-bit immediate field
/* ACCUMULATOR */
 * END
       00000000 | 4-bit base address | 4-bit multiplier | 16-bit offset field
 * LOAD 00000001 | 4-bit base address | 4-bit multiplier | 16-bit offset field
       00000010 | 4-bit base address | 4-bit multiplier | 16-bit offset field
        00000011 | 4-bit base address | 4-bit multiplier | 16-bit offset field
 * MUL
        00000100 | 4-bit base address | 4-bit multiplier | 16-bit offset field
 * LIMM 00000101 | 24-bit immediate field
/* ANALYSIS */
 * To accomodate 140 instructions we need 8 bits for the opcode
* For the address, since we only have 32 bits, we'll have to come up with some
kind of way to construct a target address
 * Here we have a 4 bit field to choose between 16 different base addresses,
which will be registers
 * In our case we can speciify the different areas of memory here (for example,
0000 will be address of user text, 0001 user data, etc...)
* We can use a multiplier which will multiply the base address by 2 to the
power of the value we load into this 4-bit field, considerably extending the
range of addresses we can reach
 From there we can specify a simple 16-bit offset immediate field
 * We have two new instructions, PUSH IMMEDIATE (PIMM) and LOAD IMMEDIATE (LIMM)
which have a 8 bit opcode and 24-bit immediate field
```

## /\* Example of how accumulator code would break down to binary

.text

main:			OPCODE	Base	MULT	Address Offset	Hex
LOAD	Α	#	00000001	0001	0000	00000000000000001	01100001
MUL	Χ	#	00000100	0001	0000	00000000000000000	04100000
MUL	Χ	#	00000100	0001	0000	0000000000000000	04100000
ST0	Α	#	00000010	0001	0000	0000000000000001	02100001
LOAD	В	#	00000001	0001	0000	00000000000000002	01100002
MUL	Χ	#	00000100	0001	0000	0000000000000000	04100000
ST0	В	#	00000010	0001	0000	00000000000000002	02100002
LOAD	С	#	00000001	0001	0000	0000000000000003	01100003
ADD	Α	#	00000011	0001	0000	00000000000000001	03100001
ADD	В	#	00000011	0001	0000	00000000000000002	03100002
ST0	ANS	#	00000010	0001	0000	0000000000000004	02100004
END		#	00000000	0000	0000	000000000000000000	00000000

.data

		Binary	Hex
A: 7	#	000000000000000000000000000000111	00000007
B: 5	#	000000000000000000000000000000000000101	00000005
X: 3	#	000000000000000000000000000000011	0000003
C: 4	#	000000000000000000000000000000000000000	00000004
ANS: 0	#	000000000000000000000000000000000000000	0000000

The base for most of the commands corresponds to the data section where the operands are held. The multipler is simply zero.

Then we find the address offset by looking at the order of the data section variables.

\*/

\* In the hex we could give our file a simple format to know when the different sections are.

\* We'll denote .text with T and .data with D. We will also specify how many bytes are in each section

\* T|30|01100001|04100000|04100000|02100001|01100002|04100000|02100002|01100003| 03100001 | 03100002 | 02100004 | 00000000 |

\* D|14|00000003|00000007|00000005|000000004|00000000|

 $^{\star}$  Here we have T and D to denote our sections. Afterwards, we have the number of bytes in hex (30 would be 48 bytes).

\* Then we have our stream of instructions.

\* Here in total we have 68 (decimal) bytes

.text

main:	OPCODE	Base MULT	Address Offset	Hex				
PUSH C	# 00000001	0001   0000	00000000000000003	01100003				
PUSH B	# 00000001	i 0001 i 0000 i	0000000000000000000002	01100002				
PUSH X	# 0000001	0001   0000	0000000000000000	01100000				
MUL	# 00000100	j 0000 j 0000 j	0000000000000000	04000000				
PUSH X	# 0000001	0001   0000	0000000000000000	01100000				
PUSH X	# 0000001	0001   0000	0000000000000000	01100000				
MUL	# 00000100	0000   0000	0000000000000000	04000000				
PUSH A	# 0000001	0001 0000	0000000000000001	01100001				
MUL	# 00000100	0000   0000	0000000000000000	04000000				
ADD	# 00000011	0000   0000	0000000000000000	03000000				
ADD	# 00000011	0000   0000	00000000000000000	03000000				
POP ANS	# 00000010	0001   0000	0000000000000004	02100004				
END	# 00000000	0000   0000	0000000000000000	0000000				
.data								
		Binary	Hex					
X: 3	# 00000000	# 000000000000000000000000000011   00000003						
A: 7	# 00000000	000000000000000000000000000000000000000						
B: 5	# 00000000	# 0000000000000000000000000000101   00000005						
C: 4	# 00000000	000000000000000000000000000000000000000	00000100   00000004					
ANS: 0	# 00000000	000000000000000000000000000000000000000	00000000   00000000					

The base for many commands corresponds to the data section where the operands are held. The multipler is simply zero.

Then we find the address offset by looking at the order of the data section variables. Commands like MUL, ADD, and END

only need the opcode as they will use the stack pointer register to perform the arithmetic.

\*/

\* In the hex we could give our file a simple format to know when the different sections are.

- \* We'll denote .text with T and .data with D. This will be followed by a byte to specify how many bytes are in each section.
- \* T|34|01100003|01100002|01100000|04000000|01100000|01100000|04000000|01100001|04000000|03000000|02100004|00000000|
  - \* D|14|00000003|00000007|00000005|00000004|000000000|
- $^{*}$  Here we have T and D to denote our sections. Afterwards, we have the number of bytes in hex (34 would be 52 bytes).
  - \* Then we have our stream of instructions.
  - \* Here in total we have 72 (decimal) bytes

\*/