

Comp24112: Symbolic AI

Lecture 3: Prolog III

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Outline

Flow of control

Accumulators

Conclusion

- Prolog has a special predicate, `not`.
- The goal `not(goal)` succeeds when *goal* fails. Given:

```
parent(sue,noel).  
parent(chris,noel).  
parent(noel,ann).  
parent(ann,dave).
```

- we have the following behaviour
`?- not(parent(sue, noel)).`

No

```
?- not(parent(ann, noel)).
```

Yes

- Note that `not` in Prolog is different to 'not' in English.
- For example, the above program says nothing about Dougal and Zebedee, yet
`?- not(parent(dougal, zebedee)).`

Yes

- In these contexts `not` means 'not as far as I know'.
- `not` is not part of pure logic programming, and has no (clear) declarative meaning

- To think about: What happens with programs like these?

```
p:- not(p).
```

or

```
p:- not(q).
```

```
q:- not(p).
```

- not can be useful in various predicate definitions
- A **set** is like a list except that the order of elements is unimportant, and there are no repeated elements.
- The following predicate computes the union of two sets

```
union([],S,S).
```

```
union([X|S],S1,S2):-
```

```
    member(X,S1),
```

```
    union(S,S1,S2).
```

```
union([X|S],S1,[X|S2]):-
```

```
    not(member(X,S1)),
```

```
    union(S,S1,S2).
```

- It is **not** what you need for the first lab!

- There is a useful predicate `\=` (read **not equal**)
- $X \backslash= Y$ is the same as `not(X= Y)`:

`?- a \= a.`

`no`

`?- a \= b.`

`yes`

- There is a deadly trap involving `not`
- The call
`?- not(parent(X,noel)).`
 will **fail** (given the above program).
- It will not find a value for `X` which is not one of Noel's parents, eg. Ann!

- The same applies to $\backslash=$.
- The call
 $?- X \backslash= a.$
 will always **fail**.
- It will not find a value for X which is not equal to a !

- To understand what is going on with `not`, we need to understand `!`, or 'cut':
 - `!` always succeeds
 - Once an instance of `!` has succeeded, Prolog is committed to all choices made between the matching of the clause containing that instance of `!` and the instance of `!` itself
 - This includes other declarations for proving the same clause. This is very useful as we will now see.

- Example:

```
max1(X,Y,X):- X >= Y.
```

```
max1(X,Y,Y):- X < Y.
```

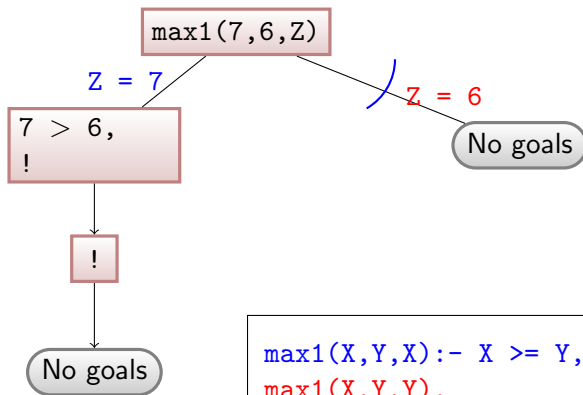
is (well, sort of) equivalent to

```
max1(X,Y,X):- X >= Y,!.
```

```
max1(X,Y,Y).
```

- **Warning: deliberate error.**

- It helps to consider the search tree



```

max1(X,Y,X):- X >= Y,!
max1(X,Y,Y).
  
```

- Why does the program

```
max1(X,Y,X):- X >= Y,!.
```

```
max1(X,Y,Y).
```

contain an error?

- Because all arguments might be instantiated:

```
2 ?- max1(3,2,X).
```

```
X = 3 ;
```

No

```
5 ?- max1(3,2,2).
```

Yes

- How do we fix this?
- By delaying the instantiation of the third variable in the first rule:

```
max2(X,Y,Z):- X >= Y,!,X=Z.  
max2(X,Y,Y).
```

- This produces the correct behaviour:

```
18 ?- max1(3,2,2).
```

Yes

```
19 ?- max2(3,2,2).
```

No

- Here is another example of cut:

```
member(X, [X|L]) .
```

```
member(X, [Y|L]) :- member(X, L) .
```

```
one_member(X, [X|L]) :- ! .
```

```
one_member(X, [Y|L]) :- one_member(X, L) .
```

- This is just like ordinary member except that it does not find repeated solutions

- Thus:

```
?- member(a, [a, b, a, c]).
```

```
yes
```

```
?- member(X, [a, b, a, c]).
```

```
X = a ;
```

```
X = b ;
```

```
X = a ;
```

```
X = c ;
```

```
No
```

```
?- one_member(a,[a, b, a, c]).
```

```
Yes
```

```
?- one_member(X,[a, b, a, c]).
```

```
X = a ;
```

```
No
```


- The relationship between `not` and `!:`
- Note that `call(term)` calls *term* as if it were a goal in its own right.

```
?- ancestor(sue,N).
```

```
N = noel
```

Yes

```
?- call(ancestor(sue,N)).
```

```
N = noel
```

Yes

- We can define `not` in terms of `!`.
`not(Goal):- call(Goal), !, fail.`
`not(Goal).`

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- Time to worry about efficiency
- Consider again the definition of `append/3`
`append([X|L1],L2,[X|L3]):-`
`append(L1,L2,L3).`
`append([],L,L).`
- Calls to `append/3` evidently involve a number of goal calls which is **linear** in the first argument.

- Consider again the definition of reverse/2

```
rev1([X|L], L_ans):-
```

```
    rev1(L,L_ans1),
```

```
    append(L_ans1, [X], L_ans).
```

```
rev1([], []).
```

where append/3 is as defined above

- Suppose the list we are reversing has N elements
- For the k th item in the list, we perform an append on the end of an $N - k$ element list.
- This append takes $N - k + 1$ reductions
- So the whole operation takes

$$(N + 1) + N + \dots + 1 = \frac{1}{2}(N + 1)(N + 2)$$

reductions

- That is, it is quadratic in N .
- Although `rev1` is very easy to understand, quadratic behaviour seems unacceptable.

- Here is a better program:

```
rev2(L,L1):-  
    rev_acc(L, [],L1).
```

```
rev_acc([X|L],L_acc,L_ans):-  
    rev_acc(L,[X|L_acc],L_ans).
```

```
rev_acc([],L_acc,L_acc).
```

- In operation:

```
?- rev2([a, b, c, d, e], L).
```

```
L = [e, d, c, b, a]
```

- The middle variable in rev2 is called an **accumulator**

- We can see better what is going on by tracing:

```
call  rev2([a, b, c], _873)
  call  rev_acc([a, b, c], [], _873)
    call  rev_acc([b, c], [a], _873)
      call  rev_acc([c], [b, a], _873)
        call  rev_acc([], [c, b, a], _873)
          exit  rev_acc([], [c, b, a], [c, b, a])
        exit  rev_acc([c], [b, a], [c, b, a])
      exit  rev_acc([b, c], [a], [c, b, a])
    exit  rev_acc([a, b, c], [], [c, b, a])
  exit  rev2([a, b, c], [c, b, a])
```

- Obviously, the number of reductions performed by rev2 is linear in the length of the list.

- Here is another way to think about the same thing.
- Now consider the predicate `append_df1`:
`append_df1(L1/L2,L2/L3,L1/L3) .`
- The time taken to query `append_df1` is constant
- The program clearly appends lists (look at the variable `L`):
`:- append_df1([a, b, c| X]/X, [d, e, f| Y]/Y, U/[])`
`N1 X = [d, e, f], Y = [], U = [a, b, c, d, e, f]`

- We are interested in structures of the form

$$[x_1, \dots, x_i, x_{i+1}, \dots, x_n] / [x_{i+1}, \dots, x_n]$$

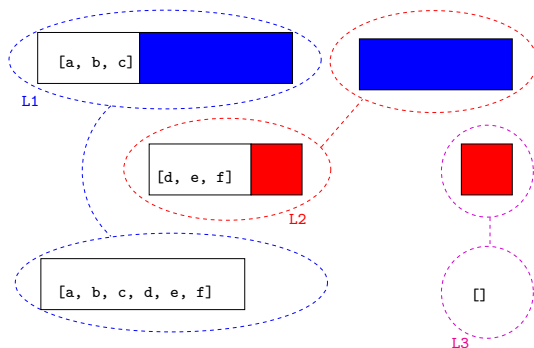
- This represents the list

$$[x_1, \dots, x_i]$$

i.e. the difference between the two lists.

- We are particularly interested in difference lists such as $[a, b, c \mid X] / X$.
- Such data-structures are said to be **incomplete**

- The following picture illustrates what is going on with a call to the goal `append_df1([a,b,c|X]/X,[d,e,f|Y]/Y,U/[])` given the program `append_df1(L1/L2,L2/L3,L1/L3)`.



- We can also write a fast list-reverse program using difference lists

```
rev3(L,L1):-
    rev_dfl(L,L1/[]).
```

```
rev_dfl([X|L],L_ans/L_ans_tail):-
    rev_dfl(L,L_ans/[X|L_ans_tail]).
```

```
rev_dfl([],L_ans_tail/L_ans_tail).
```

- This is just like rev1, except that the method of appending used in append_dfl has been 'built in' to the definition

- The program certainly works:

```
?- rev3([1, 2, 3], L)
```

```
L = [3, 2, 1]
```

```
call rev3([1, 2, 3], _897)
call rev_df1([1, 2, 3], _897/[])
call rev_df1([2, 3], _897/[1])
call rev_df1([3], _897/[2, 1])
call rev_df1([], _897/[3, 2, 1])
exit rev_df1([], [3, 2, 1]/[3, 2, 1])
exit rev_df1([3], [3, 2, 1]/[2, 1])
exit rev_df1([2, 3], [3, 2, 1]/[1])
exit rev_df1([1, 2, 3], [3, 2, 1]/[])
exit rev3([1, 2, 3], [3, 2, 1])
```

- If this looks unfamiliar, it shouldn't.

```

rev3(L,L1):-
    rev_dfl(L,L1/[]).
rev_dfl([X|L],L_ans/L_ans_tail):-
    rev_dfl(L,L_ans/[X|L_ans_tail]).
rev_dfl([],L_ans_tail/L_ans_tail).

```

```

rev2(L,L1):-
    rev_acc(L,[],L1).
rev_acc([X|L],L_acc,L_ans):-
    rev_acc(L,[X|L_acc],L_ans).
rev_acc([],L_acc,L_acc).

```

- As a final example, recall
`factorial(0,1).`

```
factorial(N,F):-  
    N > 0,  
    N1 is N - 1,  
    factorial(N1,F1),  
    F is N * F1.
```

- The Prolog interpreter has to store the program state on the stack before making each recursive call.

- Here is an alternative using a numerical accumulator:

```
factorial2(N,F):-  
    factorial2_acc(N,1,F).  
  
factorial2_acc(N,Acc,F):-  
    Acc1 is Acc * N,  
    N1 is N - 1,  
    factorial2_acc(N1,Acc1,F).  
  
factorial2_acc(0,Acc,Acc).
```

- The Prolog interpreter can forget about the program state on the stack before making each recursive call.

- These two programs require the same number of calls as each other
- Nevertheless, the second is more efficient
- This is because Prolog does not need to keep a stack of the factorial2-goals, and can reclaim the space taken up by each.
- This space reclamation is handled by the Prolog compiler, and is called **tail-recursion optimization**.

Outline

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- Summary:
 - Negation: `not` and `\=`
 - Flow of control: the cut !
 - Accumulators
 - Incomplete data structures: difference lists
- What should I do next?
 - Revise Chh. 6, 10 of *Learn Prolog Now!*.
 - Read Introduction and Chh. 1,5 of *Representation and inference for natural Language* for next lecture.