

# Cloth Simulation

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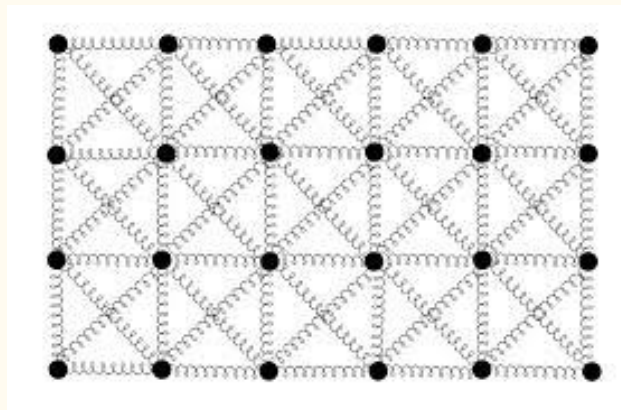
# Mass-spring system

Grid of vertices connected with springs

$$F_{spring} = K_{spring}(|\vec{x}| - l_0)$$

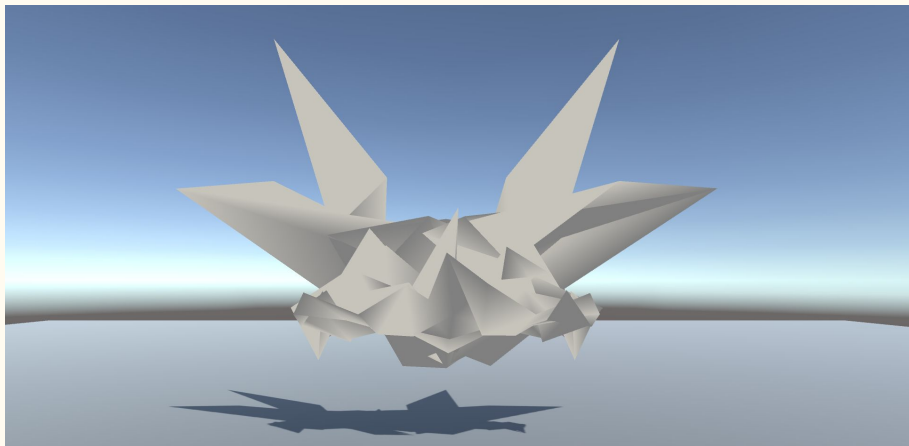
$$F_{damp} = K_{damp} \frac{\vec{v} \cdot \vec{x}}{|\vec{x}|}$$

$$\vec{F} = (F_{spring} + F_{damp}) \frac{\vec{x}}{|\vec{x}|}$$



# Explicit Euler integration

- Everything exploded
- Glitchy mess
- Infinite energy



# Verlet [vɛʁ'le] integration

- Incredibly stable!
- 4th order accurate  $\rightarrow$  as good as Runge-Kutta
- As cheap as Euler
- Does not have velocity terms

$$\vec{x}_{t+\Delta t} = \vec{x}_t + (\vec{x}_t - \vec{x}_{t-\Delta t}) + \vec{F} \frac{\Delta t^2}{m}$$

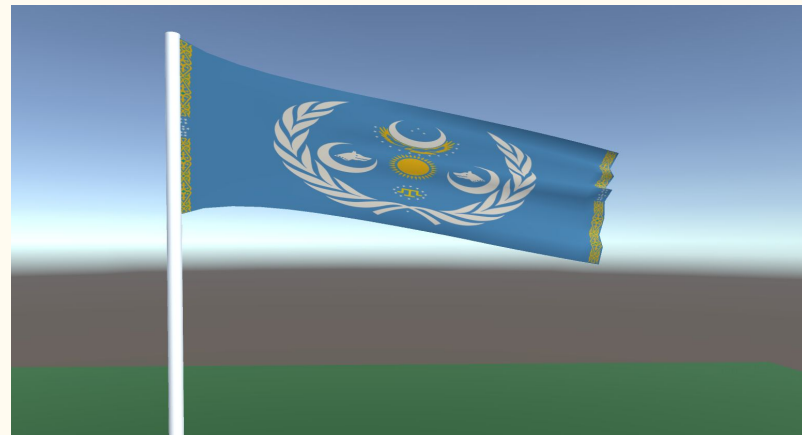
$$\vec{v} = \frac{\vec{x}_t - \vec{x}_{t-\Delta t}}{\Delta t}$$

# Drag and Wind

- Highly scientific
- Totally not a hack

$$\vec{F}_{drag} = -K_{drag}\vec{v}$$

$$\vec{F}_{wind} = \vec{K}_{wind}R_1R_2$$



- $R_1$ : random number in range  $[0.2, 1]$ , renewed every 30 frames
- $R_2$ : random number in range  $[0.8, 1.2]$ , renewed every frame

# Collision

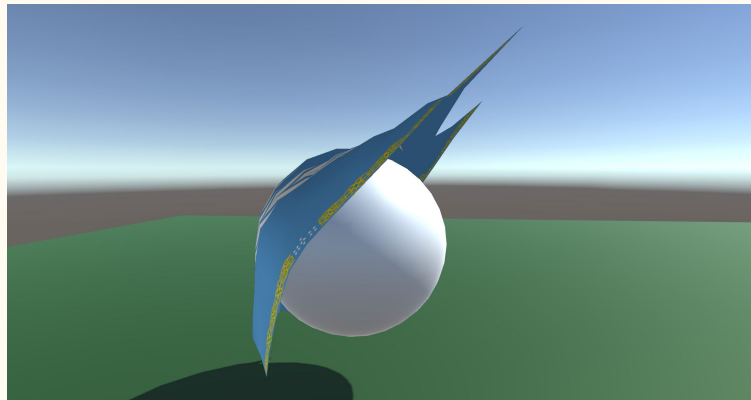
- Ground

$$x_y = \max(\varepsilon, x_y)$$

- Sphere

- If inside sphere
- epsilon: small number to prevent z-fighting and visual glitches

$$\vec{x} = \vec{x}_{sphere} + \frac{\vec{x} - \vec{x}_{sphere}}{|\vec{x} - \vec{x}_{sphere}|} (r + \varepsilon)$$



# Polish

- Unity3D
  - Custom mesh
- Tweakable parameters
- Textures
- ‘Professional’ 3D modeling
- Decades of tweaking