

**UNIVERSITY OF BARISHAL**  
 Department of Computer Science and Engineering  
 1<sup>st</sup> Year 2<sup>nd</sup> Semester Final Examination 2022  
 Course Code: EEE-1207  
 Course Title: *Basic Mechanical Engineering*

Time: 03 Hours

Marks: 60

- 1(a). Determine the tension in each cord used to support the 120-kg crate shown in Figure. 06
- 1(b). If cable  $AB$  is subjected to a tension of 750 N, determine the tension in cables  $AC$  and  $AD$  and the magnitude of the vertical force  $F$ . 06

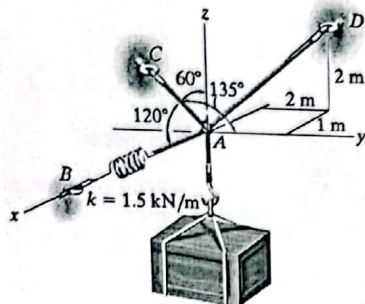


Figure for Q. No. 1(a).

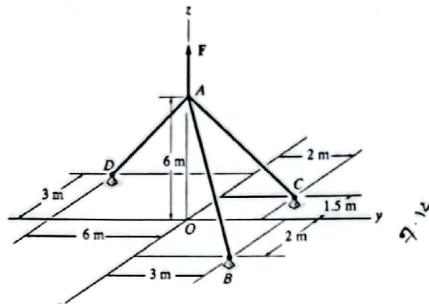


Figure for Q. No. 1(b).

- 2(a). The connected bar  $BC$  is used to increase the lever arm of the crescent wrench as shown. If a clockwise moment of  $M_A = 125 \text{ Nm}$  is needed to tighten the bolt at  $A$  and the force  $F = 210 \text{ N}$ , determine the required extension  $d$  in order to develop this moment. 06
- 2(b). Replace the loading on the frame by a single resultant force. Specify where its line of action intersects member  $AB$ , measured from  $A$ . 06

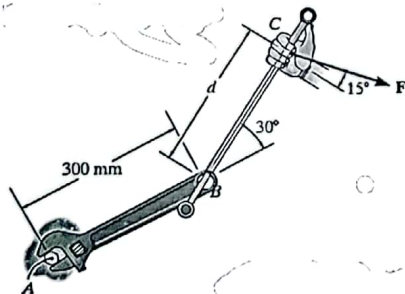


Figure for Q. No. 2(a)

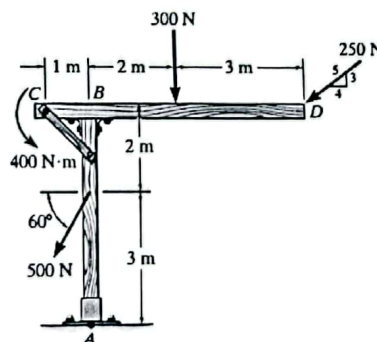


Figure for Q. No. 2(b)

- 3(a). Determine the force in member  $EB$  of the roof truss shown in figure. Indicate whether the member is in tension or compression. 06
- 3(b). A pulley and two loads are connected by inextensible cords as shown. Load  $A$  has a constant acceleration of  $310 \text{ mm/s}^2$  and an initial velocity of  $250 \text{ mm/s}$ , both directed upward. Determine (a) the number of revolutions executed by the pulley in 3s, (b) the velocity and position of load  $B$  after 3s, (c) the acceleration of point  $D$  on the rim of the pulley at  $t = 0$ . 06

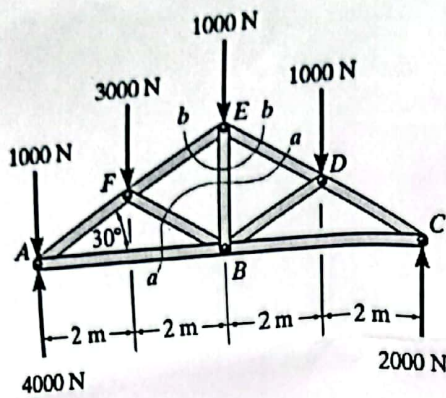


Figure for Q. No. 3(a).

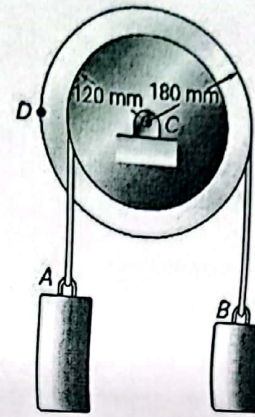


Figure for Q. No. 3(b).

- 4(a). What is meant by Robot? Why robots are used in different industries and places? 04
- 4(b). Write down the basic components of a Robotic system. Also, state the main function of each of the components. 04
- 4(c). How can you classify the Robot manipulators? Describe them shortly. 04
- 5(a). What is sensor? Describe the mechanism of the following sensors with their applications:  
i) Ultrasonic distance sensor ii) Infrared distance sensor and iii) Laser range sensor. 06
- 5(b). Define and describe the forward kinematics and inverse kinematics. 03
- 5(c). Write down the characteristics of Actuator systems. Also discuss about robot axis. 03
- 6(a). What are the differences between SI engine and CI engine? 02
- 6(b). Write down functions of the following terms: 02  
i) Crankshaft, ii) Piston, iii) Flywheel, iv) Connecting rod
- 6(c). Write down the operational sequence of four cycles of an IC Engine with appropriate sketch. 04
- 6(d). Write short notes on the following terms: 04  
i) Detonation, ii) Swept volume, iii) Compression ratio, and iv) Scavenging.
- 7(a). What is refrigeration? Explain the purpose and application of refrigeration. Also write down the properties of a good refrigerant? 03
- 7(b). Define energy? Distinguish between conventional and non-conventional sources of energy. Also discuss the present electrical energy situation in Bangladesh 06
- 7(c) Define: i) Brake power, ii) Specific fuel consumption. 03
- 8(a). Define human comfort. What are the factors that affect comfort air conditioning? Also write down the classification of air-conditioning system. 04
- 8(b). Describe the vapor absorption refrigeration system with neat sketches. 05
- 8(c). Explain the terms i) COP, ii) Tonne of refrigeration and iii) Refrigeration cycle 03

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