Sorting and Computational Complexity

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Steps to Improve Performance

- Use faster Hardware (clock rate, cache, type)
- Write more efficient code (fewer instructions, better CPU utilization, faster instructions)
- Vectorize (explicitly or through compiler)
- Parallelize (MPI, OpenMP, CUDA/OpenCL)
- Use a better algorithm (has the most potential!)
 Question: How do we compare algorithms?
 - Computational complexity (→ Big O notation)
 - Memory use, number and cost of operations



Big O Notation

- For any algorithm the "cost" of it is the sum of the "cost" of multiple parts/steps in it: $f(x) = \sum f_i(x)$
- The "cost" for each part is a positive function $f_i(x)$ of the number of items x being worked on
- Thus we can write that there is a function g(x) for which we can define:

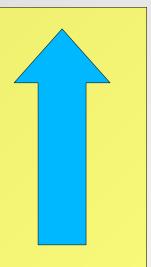
$$f(x)=O(g(x))$$
 for $x \to \infty$
 $f(x) \le M g(x)$ for $x \ge x_0$

with M being a positive number



Typical Scaling Orders

- O(1) constant time
- O(log n) logarithmic time
- O(n) linear time
- O(n log n) quasilinear time
- O(n²) quadratic time
- O(n^c) exponential time
- O(n!) factorial time





Sorting Algorithms

- Sorting: take a sequence of items and order them according to a comparison function in either ascending or descending order
- Comparisons return: smaller, larger, or equal
- Sorting algorithms can be "stable" or "unstable": when the comparison function returns "equal", a "stable" algorithm will leave items in place but an "unstable" algorithm may change order
- Sorting may happen "in place" or may need an additional "holding space"



Factors that Impact Sorting Speed

- Cost of comparison operation (e.g. comparing strings versus integers)
- Cost of swapping data (single number versus complex object)
- Number of comparisons needed
- Number of swaps needed
 - => There are best case, worst case and typical case scenarios to be considered.
- All of those determine the choice of algorithm



Bubble Sort

- Start with first element and compare to next
- If next element is smaller, then swap
- Move to second element and compare to third
- Continue until last but one element
- After that comparison/swap step the last element is sorted (i.e. the largest in the list)
- Repeat from beginning, but no need to compare with last element. Next run skip 2 last elements
- Optimization: if no swaps needed, list is sorted

Bubble Sort Animation

6 5 3 1 8 7 2 4



Insertion Sort

- Copy second element to holding space
- Compare holding space with first element
- If 1st element is larger than hold, move 1st to 2nd and copy held value to 1st,otherwise discard
- First two elements are now sorted
- Take 3rd element and compare with 2nd. Move 2nd to 3rd position if 2nd is larger than hold, move 1st to 2nd if larger than hold. Insert hold.
- Basic idea: move if larger, insert if smaller



Insertion Sort Animation

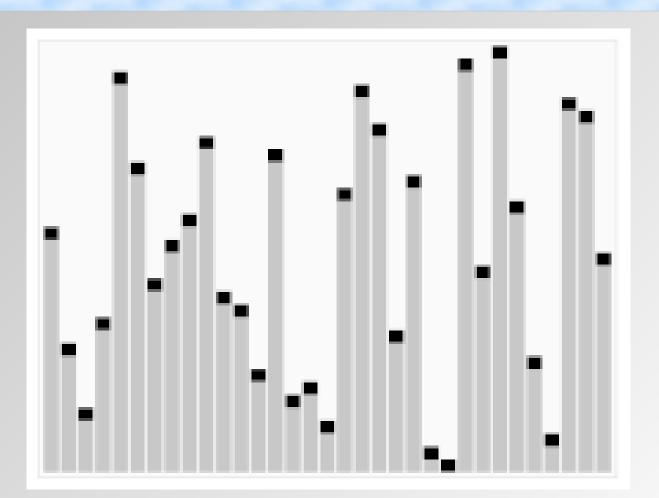
6 5 3 1 8 7 2 4



Quick Sort

- Pick some element from list (=pivot element)
- Now compare to remaining elements and swap them so that all elements larger than the pivot are to the right and smaller are to the left
- The pivot element is now in its final place
- Now apply the same procedure to the sub-lists to the left and the right of the pivot element
- Repeat until sub-list have 0 or 1 elements and thus are automatically sorted





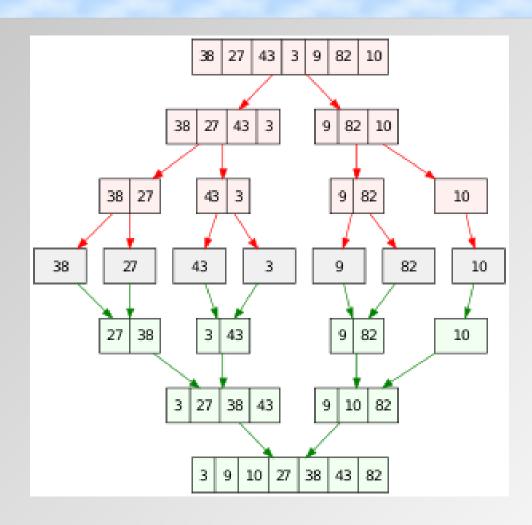


Merge Sort (Top Down)

- Split list in two parts of equal size +/- 1
- Continue until sub-lists are of size 1 or 2 size 1 is sorted, size 2 do comparison and swap
- Now take sub-lists and merge into new list:
 - Compare head of each list and select smaller
 - Copy to new list, move head to next element
 - Compare heads of sub-lists again and copy until one of the two sub-lists is out of elements; add remaining elements of other list to merged list
- Now merge larger lists until back at top



Merge Sort Schema (Top Down)





Merge Sort (Bottom Up)

- Compare items in pairs: 1 and 2, 3 and 4, 5 and 6 etc.
 and swap if not in correct order
- Now apply merge procedure as in top down version to two neighboring sub-lists (the rightmost list may be shorter or of length 0)
- Continue doubling the size of the sub-lists and merging them until merging the full list
- Merge sort needs a holding space of the size of the entire list to merge into
- Top down version simple to implement with recursion, but then it needs 1 copy of the list per recursion level



Merge Sort Animation (Bottom Up)





Properties of Sort Algorithms

Algorithm	Best Case	Worst Case	Typical	Memory Usage
Bubble Sort	O(n) comparisons O(1) swaps	O(n²) comparisons O(n²) swaps	O(n²) comparisons O(n²) swaps	O(n) + O(1)
Insertion Sort	O(n) comparisons O(1) swaps	O(n²) comparisons O(n²) swaps	O(n²) comparisons O(n²) swaps	O(n) + O(1)
Quick Sort	O(n log n)	O(n ²)	O(n log n)	2*O(n)
Merge Sort	O(n log n)	O(n log n)	O(n log n)	2*O(n) / c*O(n)
Heap Sort	O(n log n)	O(n log n)	O(n log n)	O(n) + O(1)
Shell Sort	O(n log n)	O(n ²)	$O(n \log n) \leftrightarrow O(n2)$	O(n) + O(1)

Stable Algorithms: Merge sort, Insertion sort, Bubble sort Merge sort is easily parallelizable: Operate on n parallel sub-lists Final merges on n, n/2, n/4, n/8 etc. parallel tasks



Further Optimizations

- If copying or moving data around would be expensive (large/complex objects):
 - Create and sort a list of pointers to the objects
 - Create and sort a list of indices instead of the data.
 This would also allow to have differently ordered lists in case there would be multiple properties that could be used for comparing.
- Since well scaling algorithms have more overhead, small chunks of the data could be pre-sorted with insertion/bubble sort and then further sorted with merge sort → hybrid sort

Fun with Sorts

Check out:

https://www.youtube.com/watch?v=kPRA0W1kECg



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