## The Gervais-Neveu-Felder equation for the Jordanian quasi-Hopf $U_{h;y}(sl(2))$ algebra

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## Abstract

Using a contraction procedure, we construct a twist operator that satisfies a shifted cocycle condition, and leads to the Jordanian quasi-Hopf  $U_{h;y}(sl(2))$  algebra. The corresponding universal  $\mathcal{R}_h(y)$  matrix obeys a Gervais-Neveu-Felder equation associated with the  $U_{h;y}(sl(2))$  algebra. For a class of representations, the dynamical Yang-Baxter equation may be expressed as a compatibility condition for the algebra of the Lax operators.

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Recently a class of invertible maps between the classical sl(2) and the non-standard Jordanian  $U_h(sl(2))$  algebras has been obtained [1]-[3]. The classical and the Jordanian coalgebraic structures may be related [2]-[5] by the twist operators corresponding to these maps. Following the first twist leading from the classical to the Jordanian Hopf structure, it is possible to envisage a second twist leading to a quasi-Hopf quantization of the Jordanian  $U_h(sl(2))$  algebra. By explicitly constructing the appropriate universal twist operator that satisfies a shifted cocycle condition, we here obtain the Gervais-Neveu-Felder (GNF) equation satisfied by the universal  $\mathcal{R}$  matrix of a one-parametric quasi-Hopf deformation of the  $U_h(sl(2))$  algebra.

The GNF equation corresponding to the standard Drinfeld-Jimbo deformed  $U_q(sl(2))$  algebra was studied in the context of Liouville field theory [6], quantization of Kniznik-Zamolodchikov-Bernard equation [7] and the quantization of the Calogero-Moser model in the R matrix formalism [8]. The general construction of the twist operators leading to the GNF equation corresponding to the quasi-triangular standard Drinfeld-Jimbo deformed  $U_q(\mathbf{g})$  algebras and superalgebras were obtained in [9]-[11].

For the sake of completeness, we start by enlisting the general properties of a quasi-Hopf algebra  $\mathcal{A}$  [12]. For all  $a \in \mathcal{A}$  there exist an invertible element  $\Phi \in \mathcal{A} \otimes \mathcal{A} \otimes \mathcal{A}$  and the elements  $(\alpha, \beta) \in \mathcal{A}$ , such that

$$(\mathrm{id} \otimes \triangle) \triangle (a) = \Phi (\triangle \otimes \mathrm{id})(\triangle (a)) \Phi^{-1},$$

$$(\mathrm{id} \otimes \mathrm{id} \otimes \triangle)(\Phi) (\triangle \otimes \mathrm{id} \otimes \mathrm{id})(\Phi) = (1 \otimes \Phi) (\mathrm{id} \otimes \triangle \otimes \mathrm{id})(\Phi) (\Phi \otimes 1),$$

$$(\varepsilon \otimes \mathrm{id}) \circ \triangle = \mathrm{id},$$

$$(\mathrm{id} \otimes \varepsilon) \circ \triangle = \mathrm{id},$$

$$\sum_{r} S(a_{r}^{(1)}) \alpha a_{r}^{(2)} = \varepsilon(a) \alpha,$$

$$\sum_{r} a_{r}^{(1)} \beta S(a_{r}^{(2)}) = \varepsilon(a) \beta,$$

$$\sum_{r} X_{r}^{(1)} \beta S(X_{r}^{(2)}) \alpha X_{r}^{(3)} = 1,$$

$$\sum_{r} S(\bar{X}_{r}^{(1)}) \alpha \bar{X}_{r}^{(2)} \beta S(\bar{X}_{r}^{(3)}) = 1,$$

$$(1)$$

where

$$\triangle (a) = \sum_{r} a_r^{(1)} \otimes a_r^{(2)}, \quad \Phi = \sum_{r} X_r^{(1)} \otimes X_r^{(2)} \otimes X_r^{(3)}, \quad \Phi^{-1} = \sum_{r} \bar{X}_r^{(1)} \otimes \bar{X}_r^{(2)} \otimes \bar{X}_r^{(3)}. \quad (2)$$

A quasi-triangular quasi-Hopf algebra is equipped with a universal  $\mathcal{R}$  matrix satisfying

$$\triangle^{op}(a) = \mathcal{R} \triangle(a) \mathcal{R}^{-1}, 
(id \otimes \triangle)(\mathcal{R}) = \Phi_{231}^{-1} \mathcal{R}_{13} \Phi_{213} \mathcal{R}_{12} \Phi_{123}^{-1}, 
(\triangle \otimes id)(\mathcal{R}) = \Phi_{312} \mathcal{R}_{13} \Phi_{132}^{-1} \mathcal{R}_{23} \Phi_{123}.$$
(3)

The algebra is known as triangular if the additional relation

$$\mathcal{R}_{21} = \mathcal{R}^{-1} \tag{4}$$

is satisfied. In a quasi-triangular quasi-Hopf algebra, the universal  $\mathcal{R}$  matrix satisfies quasi-Yang-Baxter equation

$$\mathcal{R}_{12} \Phi_{312} \mathcal{R}_{13} \Phi_{132}^{-1} \mathcal{R}_{23} \Phi_{123} = \Phi_{321} \mathcal{R}_{23} \Phi_{231}^{-1} \mathcal{R}_{13} \Phi_{213} \mathcal{R}_{12}. \tag{5}$$

An invertible twist operator  $\mathcal{F} \in \mathcal{A} \otimes \mathcal{A}$  satisfying the relation

$$(\varepsilon \otimes \mathrm{id})(\mathcal{F}) = 1 = (\mathrm{id} \otimes \varepsilon)(\mathcal{F}) \tag{6}$$

performs a gauge transformation as follows:

$$\Delta_{\mathcal{F}}(a) = \mathcal{F} \Delta(a) \mathcal{F}^{-1},$$

$$\Phi_{\mathcal{F}} = \mathcal{F}_{23}(\mathrm{id} \otimes \Delta)(\mathcal{F}) \Phi(\Delta \otimes \mathrm{id})(\mathcal{F}^{-1})\mathcal{F}_{12}^{-1},$$

$$\alpha_{\mathcal{F}} = \sum_{r} S(\bar{f}_{r}^{(1)}) \alpha \bar{f}_{r}^{(2)},$$

$$\beta_{\mathcal{F}} = \sum_{r} f_{r}^{(1)} \beta S(f_{r}^{(2)}),$$

$$\mathcal{R}_{\mathcal{F}} = \mathcal{F}_{21} \mathcal{R} \mathcal{F}^{-1},$$
(7)

where

$$\mathcal{F} = \sum_{r} f_r^{(1)} \otimes f_r^{(2)}, \qquad \mathcal{F}^{-1} = \sum_{r} \bar{f}_r^{(1)} \otimes \bar{f}_r^{(2)}.$$
 (8)

The Jordanian Hopf algebra  $U_h(sl(2))$  is generated by the elements  $(T^{\pm 1} (= e^{\pm hX}), Y, H)$ , satisfying the algebraic relations [13]

$$[H, T^{\pm 1}] = T^{\pm 2} - 1, \ [H, Y] = -\frac{1}{2} \left( Y(T + T^{-1}) + (T + T^{-1})Y \right), \ [X, Y] = H,$$
 (9)

whereas the coalgebraic properties are given by [13]

$$\Delta (T^{\pm 1}) = T^{\pm 1} \otimes T^{\pm 1}, \ \Delta (Y) = Y \otimes T + T^{-1} \otimes Y, \ \Delta (H) = H \otimes T + T^{-1} \otimes H, 
\varepsilon (T^{\pm 1}) = 1, \quad \varepsilon (Y) = \varepsilon (H) = 0, 
S(T^{\pm 1}) = T^{\mp 1}, \quad S(Y) = -TYT^{-1}, \quad S(H) = -THT^{-1}.$$
(10)

The universal  $\mathcal{R}_h$  matrix of the triangular Hopf algebra  $U_h(sl(2))$  is given in a convenient form [14] by

$$\mathcal{R}_h = \exp(-hX \otimes TH) \exp(hTH \otimes X). \tag{11}$$

An invertible nonlinear map of the generating elements of the  $U_h(sl(2))$  algebra on the elements of the classical U(sl(2)) algebra plays a pivotal role in the present work. The map reads [2]

$$T = \tilde{T}, \quad Y = J_{-} - \frac{1}{4} h^{2} J_{+} (J_{0}^{2} - 1), \quad H = (1 + (hJ_{+})^{2})^{1/2} J_{0},$$
 (12)

where  $\tilde{T} = hJ_+ + (1 + (hJ_+)^2)^{1/2}$ . The elements  $(J_{\pm}, J_0)$  are the generators of the classical sl(2) algebra

$$[J_0, J_+] = \pm 2 J_+, \qquad [J_+, J_-] = J_0.$$
 (13)

The twist operator specific to the map (12), transforming the trivial classical U(sl(2)) coproduct structure to the non-cocommuting coproduct properties (10) of the Jordanian  $U_h(sl(2))$  algebra, has been obtained [3], [4] as a series expansion in powers of h. The transforming operator between the two above-mentioned antipode maps has been obtained [4] in a closed form.

Our present derivation of the GNF equation corresponding to the Jordanian  $U_h(sl(2))$  algebra closely parallels the description in [8]. These authors obtained the solutions of the GNF equation in the case of the standard Drinfeld-Jimbo deformed quasi-Hopf  $U_{q;x}(sl(2))$  algebra by constructing the universal twist operator depending on a parameter x:

$$\mathcal{F}(x) = \sum_{k=0}^{\infty} (-1)^k \frac{(q-q^{-1})^k}{[k]_q!} x^{2k} q^{k(k+1)/2} \left[ \prod_{l=1}^k \left( 1 \otimes 1 - x^2 q^{2l} \ 1 \otimes q^{2\mathcal{J}_0} \right)^{-1} \right] \times q^{\frac{k}{2}\mathcal{J}_0} \mathcal{J}_+^k \otimes q^{\frac{3k}{2}\mathcal{J}_0} \mathcal{J}_-^k,$$
(14)

where  $[n]_q = (q^n - q^{-n})/(q - q^{-1})$ . The generators of the  $U_q(sl(2))$  algebra satisfies [12] the relations

$$q^{\mathcal{J}_0} \mathcal{J}_{\pm} q^{-\mathcal{J}_0} = q^{\pm 2} \mathcal{J}_{\pm}, \quad [\mathcal{J}_+, \mathcal{J}_-] = [\mathcal{J}_0]_q.$$
 (15)

A key ingredient in our method is the contraction technique developed in  $\ [2]$ , where a matrix G

$$G = E_q(\eta \mathcal{J}_+) \otimes E_q(\eta \mathcal{J}_+), \quad \eta = \frac{h}{q-1}$$
 (16)

performs a similarity transformation on the universal  $\mathcal{R}_q$  matrix of the  $U_q(sl(2))$  algebra [12]. The twisted exponential  $E_q(\chi)$  reads

$$E_q(\chi) = \sum_{n=0}^{\infty} \frac{\chi^n}{[n]_q!}.$$
(17)

The transforming matrix G is singular in the  $q \to 1$  limit. The transformed  $R_h^{j_1;j_2}$  matrix for an arbitrary  $(j_1;j_2)$  represention

$$R_h^{j_1;j_2} = \lim_{q \to 1} \left[ G^{-1} R_q^{j_1;j_2} G \right] \tag{18}$$

is, however, nonsingular and coincide, on account of the map (12), with the result obtained directly from the expression (11) of the universal  $\mathcal{R}_h$  matrix. In the above contraction process the following two identities play a crucial role:

$$(E(\eta \mathcal{J}_{+}))^{-1} q^{\alpha \mathcal{J}_{0}/2} E(\eta \mathcal{J}_{+}) = \mathcal{T}_{(\alpha)} q^{\alpha \mathcal{J}_{0}/2},$$

$$(E(\eta \mathcal{J}_{+}))^{-1} \mathcal{J}_{-} E(\eta \mathcal{J}_{+}) = -\frac{\eta}{q - q^{-1}} (\mathcal{T}_{(1)} q^{\mathcal{J}_{0}} - \mathcal{T}_{(-1)} q^{-\mathcal{J}_{0}}) + \mathcal{J}_{-},$$
(19)

where  $\mathcal{T}_{(\alpha)} = (E(\eta \mathcal{J}_+))^{-1} E(q^{\alpha} \eta \mathcal{J}_+)$ . In the  $q \to 1$  limit, it may be proved [2]

$$\lim_{q \to 1} \mathcal{T}_{(\alpha)} = \tilde{T}^{\alpha} = T^{\alpha}. \tag{20}$$

The second equality in (20) follows from the map (12).

Using the contraction scheme discussed above we now obtain an one-parametric twist operator  $\mathcal{F}_h(y) \in U_h(sl(2)) \otimes U_h(sl(2))$ , which satisfies a shifted cocycle condition. The twist operator  $\mathcal{F}_h(y)$  gauge transforms à la (7) the Jordanian Hopf algebra

 $U_h(sl(2))$  to a quasi-Hopf  $U_{h;y}(sl(2))$  algebra and the transformed universal  $\mathcal{R}_h(y)$  matrix satisfies the corresponding GNF equation. To this end we first compute

$$\tilde{\mathcal{F}}(y) = \lim_{q \to 1} (G^{-1} \mathcal{F}(x)G)_{x^2 = y(q-1)},$$
 (21)

where  $\mathcal{F}(x)$  is given by (14).

A new feature here is the reparametrization described by

$$y = \frac{x^2}{q-1},\tag{22}$$

which is necessary for obtaining nonsingular result in the  $q \to 1$  limit. In (22) we assume that  $x \to 0$  in the  $q \to 1$  in such a way that y remains finite. Following the above procedure in the said limit we obtain

$$\tilde{\mathcal{F}}(y) = \sum_{k=0}^{\infty} \frac{(hy)^k}{k!} \left( \tilde{T} J_+ \right)^k \otimes \left( \tilde{T}^3 (\tilde{T} - \tilde{T}^{-1}) \right)^k. \tag{23}$$

The rhs of (23) is interpreted on account of the map (12) as an element of  $U_h(sl(2)) \otimes U_h(sl(2))$ . Identifying this in the above sense with the twist operator  $\mathcal{F}_h(y) = \tilde{\mathcal{F}}(y)$  we now obtain the crucial result

$$\mathcal{F}_h(y) = \exp\left(\frac{y}{2}\left(1 - T^2\right) \otimes \left(T^2 - T^4\right)\right). \tag{24}$$

The above twist operator  $\mathcal{F}_h(y)$  satisfies the property (6). Following the arguments in [8] we express  $\mathcal{F}_h(y)$  as a shifted coboundary

$$\mathcal{F}_h(y) = \Delta(\mathcal{M}(y)) \left( 1 \otimes \mathcal{M}^{-1}(y) \right) \left( \mathcal{M}^{-1}(y T_{(2)}^4) \otimes 1 \right), \tag{25}$$

where the expression for the boundary reads

$$\mathcal{M}(y) = \exp\left(\frac{y}{2}(1 - T^2)\right). \tag{26}$$

The operator  $\mathcal{F}_h(y)$  given by (24) satisfies the following shifted cocycle condition

$$(1 \otimes \mathcal{F}_h(y)) \left[ (\mathrm{id} \otimes \triangle) \, \mathcal{F}_h(y) \right] = \left( \mathcal{F}_h(y \, T_{(3)}^4) \otimes 1 \right) \left[ (\triangle \otimes \mathrm{id}) \, \mathcal{F}_h(y) \right]. \tag{27}$$

Following (7) the transformed coproduct property may now be read as

$$\Delta_y(a) = \mathcal{F}_h(y) \ \Delta(a) \ \mathcal{F}_h^{-1}(y) \quad \text{for all } a \in U_{h;y}(sl(2)). \tag{28}$$

It may now be shown that the shifted cocycle condition is a consequence of the following shifted coassociativity property:

$$(\mathrm{id} \otimes \triangle_y) \circ \triangle_y(a) = \left(\triangle_{y\,T^4_{(3)}} \otimes \mathrm{id}\right) \circ \triangle_y(a). \tag{29}$$

Following (7) the gauge-transformed universal  $\mathcal{R}_h(y)$  matrix for the Jordanian quasi-Hopf  $U_{h;y}(sl(2))$  algebra reads

$$\mathcal{R}_h(y) = \mathcal{F}_{h\ 21}(y)\,\mathcal{R}_h\,\mathcal{F}_h^{-1}(y). \tag{30}$$

The coassociator  $\Phi(y)$  corresponding to the Jordanian quasi-Hopf  $U_{h,y}(sl(2))$  algebra may be obtained for the above construction of the twist operator obeying the shifted cocycle condition (27). Using (7), (24) and (27) we obtain

$$\Phi(y) = \mathcal{F}_{h \ 12}(y \, T_{(3)}^4) \, \mathcal{F}_{h \ 12}^{-1}(y) 
= \exp \left[ -\frac{y}{2} (1 - T^2) \otimes (T^2 - T^4) \otimes (1 - T^4) \right].$$
(31)

The elements  $\alpha(y)$  and  $\beta(y)$ , characterizing the antipode map of the  $U_{h;y}(sl(2))$  algebra may be similarly obtained from (7), (10) and (24):

$$\alpha(y) = \exp\left[\frac{y}{2}(1-T^2)^2\right], \qquad \beta(y) = \exp\left[-\frac{y}{2}(1-T^{-2})^2\right].$$
 (32)

Using the guage transformation property of the universal  $\mathcal{R}$  matrix in (7) and our construction (24) of the twist operator, we now discuss the GNF equation associated with the Jordanian quasi-Hopf  $U_{h;y}(sl(2))$  algebra. The relations (7), (24) and (31) lead to the transformation property

$$\mathcal{R}_{h \ 12} \left( y \, T_{(3)}^4 \right) = \Phi_{213}(y) \, \mathcal{R}_{h \ 12} \left( y \right) \Phi_{123}^{-1}(y). \tag{33}$$

Now the quasitriangularity property of  $U_{h;y}(sl(2))$  algebra implies via (3), (31) and (33) the following relations:

$$(id \otimes \triangle_{y}) \mathcal{R}_{h}(y) = \mathcal{F}_{h \ 23}(y) \mathcal{F}_{h \ 23}^{-1} \left( y \, T_{(1)}^{4} \right) \mathcal{R}_{h \ 13}(y) \mathcal{R}_{h \ 12} \left( y \, T_{(3)}^{4} \right),$$

$$(\triangle_{y} \otimes id) \mathcal{R}_{h}(y) = \mathcal{R}_{h \ 13} \left( y \, T_{(2)}^{4} \right) \mathcal{R}_{h \ 23}(y) \mathcal{F}_{h \ 12} \left( y \, T_{(3)}^{4} \right) \mathcal{F}_{h \ 12}^{-1}(y). \tag{34}$$

Using the transformation property (33) we may now recast the quasi Yang-Baxter equation (5) as the GNF equation associated with the Jordanian quasi-Hopf  $U_{h;y}(sl(2))$  algebra:

$$\mathcal{R}_{h \ 12}(y) \, \mathcal{R}_{h \ 13}\left(y \, T_{(2)}^{4}\right) \, \mathcal{R}_{h \ 23}(y) = \mathcal{R}_{h \ 23}\left(y \, T_{(1)}^{4}\right) \, \mathcal{R}_{h \ 13}(y) \mathcal{R}_{h \ 12}\left(y \, T_{(3)}^{4}\right). \tag{35}$$

We now briefly consider the solutions of the above GNF equation (35). Using the universal  $\mathcal{R}_h(y)$  matrix (30), the twist operator  $\mathcal{F}_h(y)$  in (24) and the map (12) of the generators of the  $U_h(sl(2))$  algebra on the corresponding classical elements, we may construct solutions of the GNF equation (35). As illustrations we describe the representations  $R_h(y)$  for the  $\frac{1}{2} \otimes j$  and the  $1 \otimes j$  cases. A (2j+1) dimensional representation of the classical sl(2) algebra (13)

$$J_{+}|jm\rangle = (j-m)(j+m+1)|jm+1\rangle, \qquad J_{-}|jm\rangle = |jm-1\rangle,$$
  
 $J_{0}|jm\rangle = m|jm\rangle,$  (36)

now, via the map (12), immediately furnishes the corresponding (2j+1) dimensional representation of the  $U_h(sl(2))$  algebra (9). For the  $j=\frac{1}{2}$  case, the generators remain undeformed. For the j=1 case, we list the representation of  $U_h(sl(2))$  below.

$$(j=1)$$

$$X = \begin{pmatrix} 0 & 2 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix}, \quad Y = \begin{pmatrix} 0 & \frac{1}{2}h^2 & 0 \\ 1 & 0 & -\frac{3}{2}h^2 \\ 0 & 1 & 0 \end{pmatrix},$$

$$H = \begin{pmatrix} 2 & 0 & -4h^2 \\ 0 & 0 & 0 \\ 0 & 0 & -2 \end{pmatrix}.$$

$$(37)$$

Using the above representations in the expression (30) of the universal  $\mathcal{R}_h(y)$  matrix, we obtain

$$R_h^{\frac{1}{2};j}(y) = \begin{pmatrix} T & -hH + \frac{1}{2}h(T - T^{-1})(1 + 2y(1 - T^4)) \\ 0 & T^{-1} \end{pmatrix}$$
(38)

and

$$R_h^{1;j}(y) = \begin{pmatrix} T^2 & A & B \\ 0 & 1 & C \\ 0 & 0 & T^{-2} \end{pmatrix}, \tag{39}$$

where

$$A = -2hTH - 2hy(1 - T^{2})(1 - T^{4}),$$

$$B = -2h^{2} \left[ T^{2} - T^{-2} - 2TH(1 - T^{-2}) - (TH)^{2}T^{-2} \right] - 4h^{2}y(1 - T^{2})(1 + 4T^{-2} - T^{4})$$

$$-4h^{2}yTH(1 - T^{2})(T^{2} - T^{-2}) + 2h^{2}y^{2}(T - T^{-1})^{2}(1 - T^{4})^{2},$$

$$C = -2h(1 - T^{-2} + THT^{-2}) + 2hy(1 - T^{2})(T^{2} - T^{-2}).$$
(40)

From (38) it follows that the  $R_h^{\frac{1}{2},\frac{1}{2}}$  matrix for the fundamental (1/2; 1/2) case does not depend on the parameter y. The  $R_h(y)$  matrices for the higher representations, however, nontrivially depend on y. The  $R_h(y)$  matrices satisfy an "exchange symmetry" between the two sectors of the tensor product spaces:

$$\left(R_h^{j_1;j_2}(y)\right)_{km,ln} = \left(R_{-h}^{j_2;j_1}(y)\right)_{mk,nl}.$$
(41)

In the remaining part of the present work we recast the Jordanian GNF equation (35) as a compatibility condition for the algebra of L operators. Using a new parametrization  $y = \exp(z)$ , we perform a translation

$$\mathcal{R}_{h \ 12}(z) \to \mathcal{R}_{h \ 12}(z - 2h X_{(3)})$$
 (42)

to express (35) in a symmetric form

$$\mathcal{R}_{h \ 12}(z - 2hX_{(3)}) \,\mathcal{R}_{h \ 13}(z + 2hX_{(2)}) \,\mathcal{R}_{h \ 23}(z - 2hX_{(1)}) 
= \mathcal{R}_{h \ 23}(z + 2hX_{(1)}) \,\mathcal{R}_{h \ 13}(z - 2hX_{(2)}) \,\mathcal{R}_{h \ 12}(z + 2hX_{(3)}).$$
(43)

This is equivalent to the Jordanian GNF equation (35) for the class of representations  $\varrho_{j_1;j_2}$  satisfying the property

$$\varrho_{j_1;j_2}\left(\left[\left(X_{(k)}+X_{(l)}\right)\partial_z,\mathcal{R}_{h\ kl}(z)\right]\right)=0. \tag{44}$$

Adopting the procedure in [8] we here use the following construction of the Lax operator for the  $U_{h;y}(sl(2))$  algebra

$$L_{13}(z) = \exp\left[-2h\left(2X_{(1)} + X_{(3)}\right)\partial_z\right] \mathcal{R}_{h \ 13}(z) \exp\left[2h X_{(3)} \partial_z\right],\tag{45}$$

where the subscript 3 denotes the quantum space. For the representations satisfying (44) the relation (43) may be expressed in a Lax martix form

$$R_{h,12}^{j_1;j_2}(z-2hX_{(3)})L_{13}(z)L_{23}(z) = L_{23}(z)L_{13}(z)R_{h,12}^{j_1;j_2}(z+2hX_{(3)}). \tag{46}$$

As illustrations we note that the representations  $R_h^{\frac{1}{2};1}(z)$ ,  $R_h^{1;\frac{1}{2}}(z)$  and  $R_h^{1;1}(z)$  obtained from (38) and (39) satisfy the requirement (44).

To summarize, here we have constructed the Jordanian quasi-Hopf  $U_{h;y}(sl(2))$  algebra by explicitly obtaining the relevant twist operator via a contraction method. In the contraction method used here we start with the standard Drinfeld-Jimbo deformed quasi-Hopf  $U_{q;x}(sl(2))$  algebra and use a suitable similarity transformation followed by a  $q \to 1$  limiting process. An important point here is that the reparametrization as obtained in (22) is essential for obtaining a nonsingular twist operator for the  $U_{h;y}(sl(2))$  algebra in the  $q \to 1$  limit. Our contraction method has an advantage in that it furnishes the dynamical quantities for the Jordanian quasi-Hopf  $U_{h;y}(sl(2))$  algebra from the corresponding quantities of the standard

Drinfeld-Jimbo deformed quasi-Hopf  $U_{q;x}(sl(2))$  algebra. The present twist operator associated with the  $U_{h;y}(sl(2))$  algebra satisfies a shifted cocycle condition. The universal  $\mathcal{R}_h(y)$  matrix satisfies the GNF equation associated with the  $U_{h;y}(sl(2))$  algebra. For a special class of representations, the GNF equation may be recast as a compatibility condition of the L operators. As an extension of the present work, a similar formalism may be developed to describe a quasi-Hopf quantization of the coloured Jordanian deformed gl(2) algebra considered in [15], [16], [4]. A similar construction of the twist operators associated with the quasi-Hopf deformation of the Jordanian  $sl_h(N)$  algebra may also be attempted following the discussion in [2].

## Acknowledgments:

One of us (RC) wishes to thank A. J. Bracken for a kind invitation to the University of Queensland, where part of this work was done.

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