The original pb

(3)
$$\begin{cases} \min_{x} \frac{1}{2} \|r - \alpha x\|_{2}^{2} \\ \text{s.t.} \\ \|x\|_{1} \leq \gamma \end{cases}$$

Regularized seg of pbs.

$$(g_k)$$
: $\begin{cases} \min_{1 \le k} \frac{1}{2} \|r - g_{\times}\|_2^2 \\ \sin_{1 \le k} \frac{1}{2} \|x\|_{1/k} \le \gamma \end{cases}$

$$||x||_{1K} = \sum_{i=1}^{N} |x_i|_{K}$$

where x = (x1,...; xp) T

$$|x_i|_k = \frac{1}{k} \left[\ln \left(1 + e^{-kx_i} \right) + \ln \left(1 + e^{-kx_i} \right) \right]$$

(Px) convex and differentiable

Denote (2/x, 1/x) optimal sol

to Pk)

Note his derives from the Lagrangia and the KKT conditions

Objective. Prove that

(xx, x) = (x, x)

optimal sol

to (3)

The solution

(xi, i'k) to (3k) sonveys

as know to (xi, i') of (9)

Some techniquel requiremeds

LIM Is reliant upon equality constrained pb.

Prop (3k) reduce to) min & 11r - Øx112 S.t.

121/Kn = 2

provided that $2 < \frac{\|\phi^T - \|_2}{\|\phi^T \phi\|_2} = \frac{2n\ln(\nu)}{k}$

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 $N_2 = 15$, magnitude = ± 2

We are interested in (Pk) $||x^*||_{1,K} = 31,94...$ at K = 374 donc

prenons: y = 30 et

See the behaviour.

equality - constraint in not valid - check n = 31, ... in res (Sx) and in 13) direct methods

2=30 in (Ph) and direct methods

Dynamics for (P_k) $\frac{dx}{dt} = \varphi^T(r - \varphi_X) - \lambda \nabla_x ||x||_{1/k}$ $\frac{d\lambda}{dt} = ||x||_{k,1} - 2$

k = 35 H; 2 = 2 Valus. $(-) \circ k$, $8 \rightarrow \circ k$ $|| \times ||_{\mathbf{k},1} \circ k$.

intest: m, I evaluate

Nx*11, K=1 -> 374

at k=355 -> it becomes inf.

Then is the appropriate k

is k=374 and 2=31,94...

For this 2 -> we have good results in direct muethods.

 $\begin{aligned}
\nabla_{\mathbf{x}} \|\mathbf{x}\|_{\mathbf{1},\mathbf{K}} &\in \mathbf{R}^{N} \\
\mathbf{Const} \|\mathbf{x}\|_{\mathbf{1},\mathbf{K}} &= \sum_{i=1}^{N} |\mathbf{x}_{i}|_{\mathbf{K}} \\
&= \sum_{j=1}^{N} |\mathbf{x}_{i}|_{\mathbf{K}} \\
&= \frac{e^{\mathbf{K}\mathbf{x}_{i}}}{1 + e^{\mathbf{K}\mathbf{x}_{i}}} \\
&= \frac{e^{-\mathbf{K}\mathbf{x}_{i}}}{1 + e^{-\mathbf{K}\mathbf{x}_{i}}}
\end{aligned}$

$$\frac{dx}{dt} = \left(\frac{dx_1}{dt} - \frac{dx_n}{dt}\right)^T$$

$$\frac{dx}{dt} \in \mathbb{R}$$