DESIGN AND FUNCTIONAL SIMULATION OF LAND ROVER FIGO FSM

M.Vivekanandan
Assistant professor
Department of Artificial
Intelligence and
Data Science
Rajalakshmi Institute Of
Technology
vivekanandan.m@ritchennai.
edu.in

O. Pandithurai
Associate Professor
Department of Computer
Science and Engineering,
Rajalakshmi Institute of
Technology
pandics@ritchennai.edu.in

G.Sai Krishnan
Department of mechanical
engineering
Rajalakshmi Institute of
Technology
saikrishnan.g@ritchennai.edu
.in

R Reshma

Artificial Intelligence and Data Science

Rajalakshmi Institute of Technology

Chennai, India

reshma.r.2021.ad@ritchennai.e du.in

J Vishal

Artificial Intelligence and Data Science

Rajalakshmi Institute of Technology

Chennai, India

vishal.j.2021.ad@ritchennai.ed u.in J P Ratish

Artificial Intelligence and Data
Science

Rajalakshmi Institute of Technology

Chennai, India

ratish.j.p.2021.ad@ritchennai.e du.in

Abstract-This paper presents the design *functional* and of **Finite** State simulation a Machine (FSM) for the Land Rover Figo vehicle.[15] By constructing the FSM model and defining the states and transitions, we establish a clear representation of the Land Rover Figo's behaviour.[11] We then simulate the FSM to observe and analyse the vehicle response

under different conditions, allowing us to verify its functionalities and identify areas for improvement. [5] Hence this research contributes to a better understanding of the Land Rover Figo's behaviour, aids in the design of control strategies, and facilitates improvements in performance and reliability.

Keywords: Land Rover Figo FSM, design, functional simulation, computer-aided design, finite element analysis

I. INTRODUCTION:

The design and functional simulation of the Land Rover Figo FSM aims to efficient create model an behaviour the and represents functionality of the Land Rover Figo vehicle. By modelling the FSM, we can simulate the vehicle's behaviour and test its functionality under scenarios different and input conditions, ensuring that the system performs as intended.

- 1. Model Representation:[9] The FSM will provide a clear representation of the Land Rover Figo's operational modes, states, and transitions and will serve as a basis for understanding the vehicle's behaviour and designing appropriate strategies.
- Functionality Simulation;
 [4]Through this, we will be able to evaluate the performance of the Land Rover Figo which includes

- testing the response to user inputs, environmental conditions, and various control algorithms.
- 3. Validation and Optimization:
 The simulated FSM will be
 validated against the expected
 behaviour of the real Land
 Rover Figo which accurately
 represents the vehicle's
 functionalities. Additionally,
 the FSM can be optimized to
 improve performance,
 efficiency, and safety.

II. OBJECTIVE:

The objective of the design and functional simulation of the Land Rover Figo FSM is to achieve the following:

1. Model Representation:
Develop an FSM model that represents the operational modes, control logic, and transitions within the Land Rover Figo system. The model should provide a clear understanding of the vehicle's behaviour and serve as a basis for designing appropriate control strategies.

- 2. Functional Simulation: To evaluate the performance and behaviour of the Land Rover Figo under various scenarios. This includes testing the response to user inputs, environmental conditions, and different control algorithms.
- 3. System Validation: Validate the simulated FSM against the expected behaviour of the actual Land Rover Figo. By comparing the simulated results with real-world observations and measurements, ensure that the model accurately represents the vehicle's functionalities and behaviour.

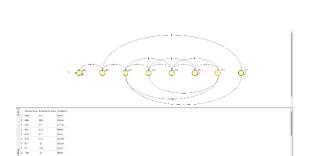
III. OUTCOMES:

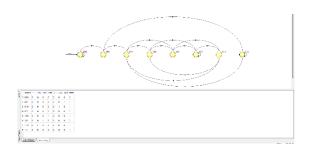
The design and functional simulation of the Land Rover Figo FSM can yield several important outcomes including:

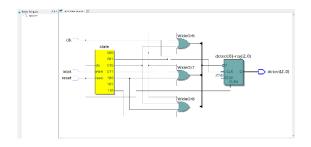
1. Enhanced Understanding: The FSM model and simulation results provide a deeper understanding of the Land Rover Figo's behaviour, operational modes, and

- control logic. This improved understanding aids in identifying system strengths, weaknesses, and opportunities for improvement.
- 2. Validated Functionalities: By validating the simulated FSM against real-world observations and measurements, the accuracy and reliability of the model's functionalities are confirmed. It helps to ensure that the simulated FSM accurately represents the behaviour of the actual Land Rover Figo.
- 3. Performance Evaluation:
 Functional simulations allow
 for the evaluation of the Land
 Rover Figo's performance
 under various scenarios, user
 inputs, and environmental
 conditions.
- 4. Optimization Opportunities:
 The analysis of simulated behaviour and performance can reveal opportunities for optimizing the Land Rover Figo system. This may include refining control strategies, adjusting operational modes to improve the vehicle's overall performance.

- 5. Decision Support: The FSM model and simulation outcomes provide valuable insights for decision-making processes related to system design, control strategies, and overall vehicle improvements.
- 6. Future Development: The outcomes of the design and functional simulation can guide future development efforts for the Land Rover Figo or similar vehicles.









IV. CHALLENGES:

The design and functional simulation of the Land Rover Figo FSM may encounter several challenges, including:

Complexity of the System:
 The Land Rover Figo is a complex vehicle with numerous operational modes, control logic, and interactions between subsystems.
 Capturing this complexity accurately in the FSM model can be challenging, requiring a

- thorough understanding of the vehicle's architecture and behaviour
- 2. Availability of Detailed Specifications: Access to detailed specifications, control algorithms, and system behaviour information for the Land RoverFigo. Without comprehensive documentation or cooperation from the manufacturer, it is difficult to represent the vehicle's functionalities and transitions in the FSM model.
- 3. Modelling and Abstraction:
 Choosing appropriate levels of abstraction in the FSM model is crucial. Finding the right balance between capturing essential details and maintaining a manageable model size can be challenging.
- 4. Data Collection and
 Validation: Obtaining reliable
 data on the vehicle's
 behaviour, performance, and
 responses to various scenarios
 requires access to appropriate
 testing facilities,
 instrumentation, and testing
 protocols
- 5. System Integration and Verification: Integrating the

simulated FSM model with other vehicle systems, such as the control software or sensors, can be challenging. Ensuring seamless communication and interaction between the FSM and the rest of the system requires careful integration and thorough verification to guarantee consistent behaviour.

V. ARCHITECTURE:

The architecture for the design and functional simulation of the Land Rover Figo FSM involves several key components and stages. Here is a high-level overview of the architecture:

- 1. Requirements Analysis: The first step is to analyse the requirements for the Land Rover Figo FSM. This involves understanding the operational modes, control logic, and desired functionalities of the vehicle.
- 2. FSM Modelling: This involves defining the states, transitions, and control logic

- that represent the Land Rover Figo's behaviour.
- 3. Simulation Environment: It is to simulate the behaviour of the FSM model. This includes software tools or frameworks that support FSM simulation and provides the necessary infrastructure for running the simulations and analysing the results.
- 4. Input Generation: It simulates user interactions, environmental conditions, or other external factors that affect the Land Rover Figo's behaviour.
- 5. Performance Evaluation: The results are analysed to evaluate the performance of the Land Rover Figo FSM. This includes assessing factors such as response times, efficiency, safety, and adherence to desired behaviours.
- 6. Optimization and
 Enhancement: The simulation
 outcomes are utilized to
 identify opportunities for
 optimization and enhancement
 of the Land Rover Figo
 system. This may involve
 refining control strategies,

adjusting operational modes, or improving overall system performance.

VI. HARDWARE:

Intel Quartus Prime Lite is a powerful integrated development environment and design software suite specially designed for FGPA (Field-Programmable Gate Array) and CPLD (Complex Programmable Logic Device).

The Quartus Prime Lite provides comprehensive tools and functions that enable users to design, simulate, analyse and program FPGA and CPLD devices. With Quartus Prime Lite, users can create their own designs using various methods such as schematic input, hardware annotations such as VHDL or Verilog. One of the main features of Quartus Prime Lite is its integration and optimization.

It also provides simulation tools that allow users to verify the performance and functionality of their designs prior to implementation. The Quartus Prime Lite includes debugging and analysis features such as a waveform viewer, real-time analysis tools, and interactive debugging capabilities. After the compilation is complete, Quartus Prime Lite will help generate programming files for the target device. The

Intel Quartus Prime Lite provides a comprehensive and user-friendly environment for FPGA and CPLD design and implementation. Its powerful architecture, optimization, and integration with the Intel FPGA family make it a valuable tool for digital logic designers.

VII. CONCLUSION:

In conclusion, the design and functional simulation of the Land Rover Figo FSM is a critical process that aims to enhance our understanding of the vehicle's behaviour, validate its functionalities, performance and identify opportunities for optimization. The simulation outcomes help us make informed decisions regarding system design,

control strategies, and optimization efforts.

The design and functional simulation process also involves the validation of the simulated FSM against real-world observations and measurements. The outcomes of the design and functional simulation process provide valuable insights and benefits. These outcomes contribute to the overall goal of improving the Land Rover Figo's design, functionality, efficiency, and user experience.

Hence the design and functional simulation of the Land Rover Figo FSM play a crucial role in shaping the future development of the vehicle, ensuring its continued success and delivering an exceptional driving experience to its users.

VIII. REFERENCE:

[1].https://www.intel.com/content/www/us/en/programmable/customertraining/webex/Verilog/presentation_html5.html

[2].https://www.intel.com/content/www/us/en/docs/programmable/683082/22-

1/systemverilog-state-machine-coding-example.html

[3]. "Finite State Machine Modelling and Simulation of Automobile Control System"

Author: Zhang Junqi et al

[4]. "Finite State Machine Modelling and Simulation of Automobile Control System"

Author: Abrial, Jean-Raymond et al., 2010

[5]. D Brand, P Zafiropulo - Journal of the ACM (JACM), 1983 - dl.acm.org

[6]. Kadeghe G Fue, Edward M Barnes, Wesley M Porter, Glen C Rains

2019 ASABE Annual

International Meeting, 1, 2019

[7]. Carsten Schradin, Brigitte Schradin, Goegap Nature Reserve, Succulent Karoo

people 5 (7), 8

[8]. David Allen Blubaugh, Steven D Harbour, Benjamin Sears, Michael J Findler Intelligent Autonomous Drones with Cognitive Deep Learning: Build AI-Enabled Land Drones with the Raspberry Pi 4, 217-255, 2022

[9]. Alexandre Petrenko, Nina Yevtushenko

IEEE Transactions on Computers 54 (9), 1154-1165, 2005

[10]. GA Bohoris, C Vamvalis, W Trace, K Ignatiadou

Journal of Quality in Maintenance Engineering 1 (4), 3-16, 1995

[11]. F Wagner, R Schmuki, T Wagner, P Wolstenholme - 2006 books.google.com

[12]. Ashly Pinnington, Geraldine Hammersley

Employee Relations 19 (5), 415-429, 1997

[13]. Oluwamayokun Adetoro, Abhishek Das, Rui Cardoso

Journal of Physics: Conference Series 734 (2), 022002, 2016

[14]. CM Freeman, AP Gaylard

7th MIRA International Conference on Vehicle Aerodynamics, 22-23, 2008

[15]. D Lee, <u>M Yannakakis</u> - Proceedings of the IEEE, 1996 - ieeexplore.ieee.org