Chapter 5

dynamic circuits - voltages and current vary as functions of time

- models for time-varying signals (chap. 5)
- models for devices that describe the effects of time-varying signals in circuits (Chap. 67
- 5.1 waveform equation or graph defining a signal as a function of time

NOTATION

up to now we have considered de (direct current) signals which are constants, i.e.

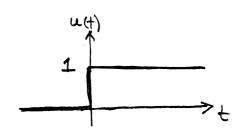
v(t) Vo - oct < 00 noually use uppercase for de quantities

Time-varying quantities are usually represented by lower case V(t)

Reference marks (+,-) for voltage and (-) for current are not THE polarity or direction but the reference forwhat positive means

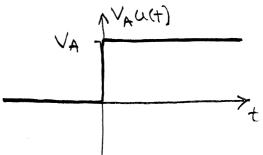
5-2 The Unit Step

$$u(t) = \begin{cases} 0 & t < 0 \\ 1 & t > 0 \end{cases}$$



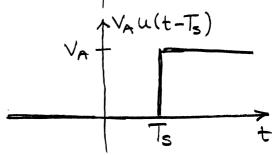
Signals can be scaled

$$V_{A}u(t) = \begin{cases} 0 & t < 0 \\ V_{A} & t \ge 0 \end{cases}$$



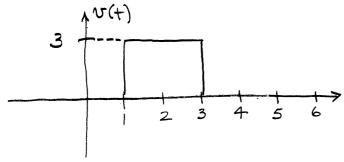
Signals can also be delayed.

$$V_{A}u(t-T_{S}) = \begin{cases} 0 & t < T_{S} \\ V_{A} & t > T_{S} \end{cases}$$

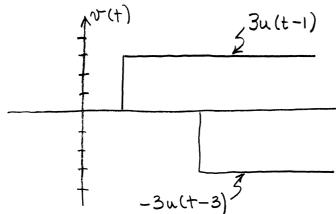


Example 5-1

Express the given pulse waveform in terms of step functions.



Pulses are often called gating functions and are used to turn things on or off.

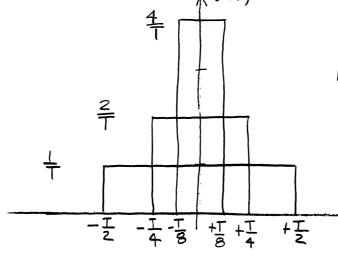


v(t) = 3u(t-1) - 3u(t-3)

The impulse function

Consider the pulse v(t) of unit area centered at t=0

$$v(t) = \frac{1}{T} \left[u(t + \frac{T}{2}) - u(t - \frac{T}{2}) \right]$$



All three functions have unitarea.

$$\frac{4}{7} \times \frac{1}{4} = 1$$

$$2 \times I = 1$$

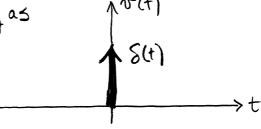
consider the limit as T→0 [the amplitude goes to ∞] mathematically for the unit impulse

$$S(t)=0$$
 for $t\neq 0$

$$\int_{+\infty}^{-\infty} S(x) \, dx = S(t)$$

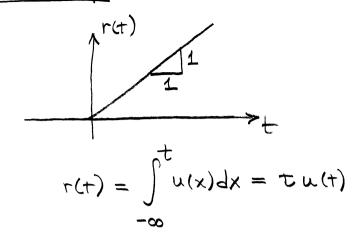
The definition
$$\lim_{t \to 0} \frac{u(t+\frac{T}{2})-u(t-\frac{T}{2})}{T} = \frac{du(t)}{dt}$$

It's shown graphically as



4

The unit ramp



Singularity Functions

S(t), u(t) and r(t) are mathematically related and are often called singularity functions

by integration
$$u(t) = \int_{-\infty}^{\infty} S(x) dx$$

$$r(t) = \int_{-\infty}^{\infty} u(x) dx$$

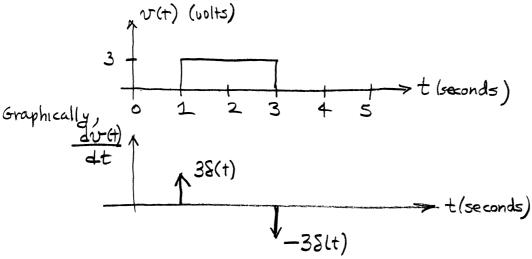
by differentiation

$$u(t) = \frac{dr(t)}{dt}$$

$$S(t) = \frac{du(t)}{dt}$$

Example 5-2

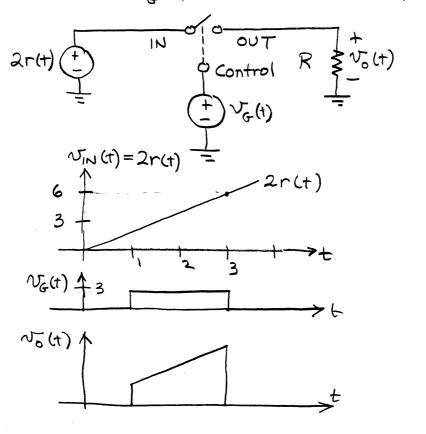
Calculate and sketch the derivative of v(t).



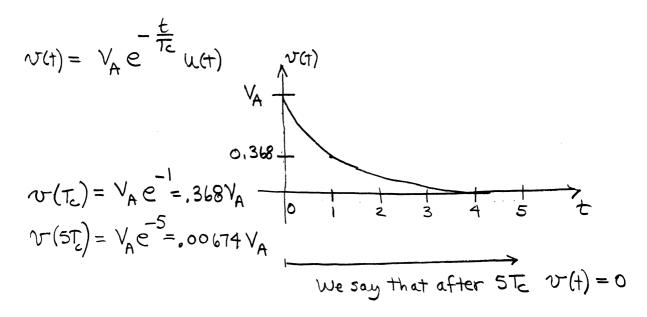
mathematically, v(t) = 3u(t-1) - 3u(t-3) $\frac{dv(t)}{dt} = 3S(t-1) - 3S(t-3)$

Example 5-3

Consider an ideal electronic switch whose input 15 a ramp 2r(t). Find the switch output $v_0(t)$ for the gate function $v_6(t) = 3u(t-1) - 3u(t-3)$



5-3 The Exponential Waveform



Properties of exponential waveforms

Consider
$$v(t)$$
 for $t > 0$

$$v(t) = V_A e^{-\frac{t}{T_c}}$$

$$v(t + \Delta t) = V_A e^{-\frac{t}{T_c}} = V_A e^{-\frac{\Delta t}{T_c}} = e^{-\frac{\Delta t}{T_c}}$$

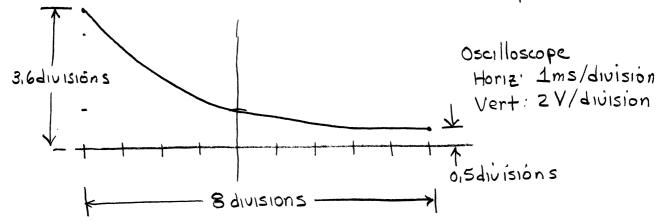
$$\frac{v(t + \Delta t)}{v(t)} = \frac{V_A e^{-\frac{t}{T_c}} e^{-\frac{\Delta t}{T_c}}}{V_A e^{-\frac{t}{T_c}}} = e^{-\frac{\Delta t}{T_c}}$$

$$\frac{v(t + \Delta t)}{v(t)} = \frac{V_A e^{-\frac{t}{T_c}} e^{-\frac{\Delta t}{T_c}}}{V_A e^{-\frac{t}{T_c}}} = e^{-\frac{\Delta t}{T_c}}$$
Independent of t, V_A

$$\frac{dv(t)}{dt} = V_A \left(-\frac{1}{T_c}\right) e^{-\frac{t}{T_c}} = -\frac{v(t)}{T_c}$$
This is called the slope property.

Example 5-6

Consider the oscilloscope measurement of an exponential waveform. Determine the time constant of the exponential.



You can readily find To from the decrement property of the exponential

$$\frac{\sqrt{(1+\Delta t)}}{\sqrt{(t)}} = e^{-\frac{\Delta t}{\tau}}$$

Take the log of both sides and solve for Te

$$l_{m}\left(\frac{v(t+\Delta t)}{v(t)}\right) = -\frac{\Delta t}{T_{c}}$$

$$T_{c} = \frac{-\Delta t}{\ln\left(\frac{v(t+\Delta t)}{v(t)}\right)} = \frac{\Delta t}{\ln\left[\frac{v(t)}{v(t+\Delta t)}\right]}$$

Converting the oscilloscope waveform to measured values

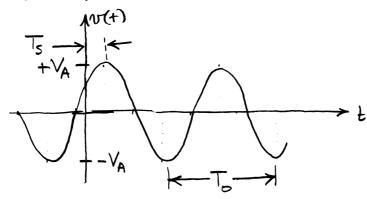
$$vr(+) = 3.6 \, \text{div} \times 2 \, \frac{\text{Volts}}{\text{division}} = 7.2 \, \text{volts}$$

$$w(t+\Delta t) = 0.5 \, \text{div} \times 2 \, \frac{\text{Volts}}{\text{division}} = 1 \, \text{uolt}$$

$$\Delta t = 8 \, \text{div} \times \frac{1 \, \text{ms}}{\text{div}} = 8 \, \text{milliseconds}$$

$$T_{c} = \frac{\Delta t}{\ln \left[\frac{v(t)}{v(t+\Delta t)} \right]} = \frac{8 \times 10^{-3}}{\ln \left[\frac{7.2}{i} \right]} = \frac{8 \times 10^{-3}}{1.9741} = 4.0525 \times 10^{-3}$$
 seconds

5-4 The sinusoidal waveform



$$v(t) = V_A \cos \left[2\pi \left(\frac{t - T_S}{T_O} \right) \right]$$
we will typically use cosines

VA - amplitude

Instead of To we often use the phase angle \$

$$v(t) = V_A \cos \left[2\pi \frac{t}{T_0} + \phi\right]$$

$$\phi = -2\pi \frac{T_s}{T_o}$$

cyclic frequency $f_0 = \frac{1}{T_0}$

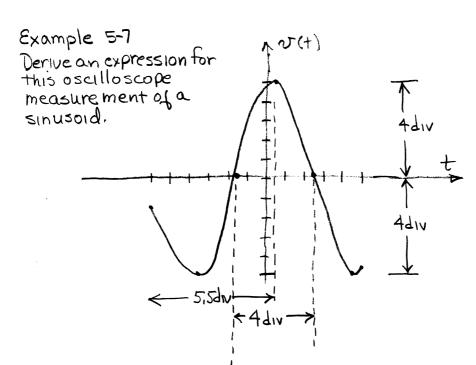
angular frequency $\omega_0 = 2\pi f_0 = \frac{2\pi}{T_0}$

If
$$v(t) = V_A \cos\left[2\pi \left(\frac{t-T_S}{T_o}\right)\right]$$
 Then $v(t) = V_A \cos\left[\frac{2\pi t}{T_o} - \frac{2\pi T_S}{T_o}\right]$
Using $\cos(x+y) = \cos x \cos y - \sin x \sin y$ $+\phi$

$$v(t) = V_A \cos \phi \cos\left(\frac{2\pi t}{T_o}\right) - V_A \sin \phi \sin\left(\frac{2\pi t}{T_o}\right)$$

$$v(t) = a\cos\left(\frac{2\pi t}{T_0}\right) + b\sin\left(\frac{2\pi t}{T_0}\right) \qquad a,b = \text{Fourier coefficients}$$

$$v_A = \sqrt{a^2 + b^2} \qquad \frac{b}{a} = \frac{-v_A \sin\phi}{v_A \cos\phi} \Rightarrow \phi = \tan^{-1}\left(\frac{-b}{a}\right)$$



Oscilloscope:

Vertical: 5V/div

Horiz: Oilms/div

amplitude
$$V_A = 4 div \times \frac{5V}{div} = 20 volts$$

period
$$T_0 = 8 \text{ div} \times \frac{0.1 \text{ ms}}{\text{div}} = 0.8 \text{ ms}$$

oscilloscope measurement is 1 cycle

To determine To you need to define the time origin. Use the left-hand edge as our time origin.

Ts is the location of the nearest positive peak.

The closest positive peak to the origin is actually to the left of the origin. The positive peak we measured is actually one cycle AFTER the actual nearest peak.

$$T_0 + T_5 = 5.5 \, \text{div} \times 0.1 \, \text{mS} = 0.55 \, \text{mS}$$

$$T_s = 0.55 \, \text{ms} - T_0 = 0.55 \, \text{ms} - 0.8 \, \text{ms} = -0.25 \, \text{mS}$$

1.
$$v(t) = V_A \cos \left[2\pi \left(\frac{t - I_S}{I_O} \right) \right] = 20 \cos \left[2\pi \left(\frac{t + .00025}{.0008} \right) \right]$$

This can also be expressed in alternative forms.