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G01R 31/12 (2006.01)

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FIG.1

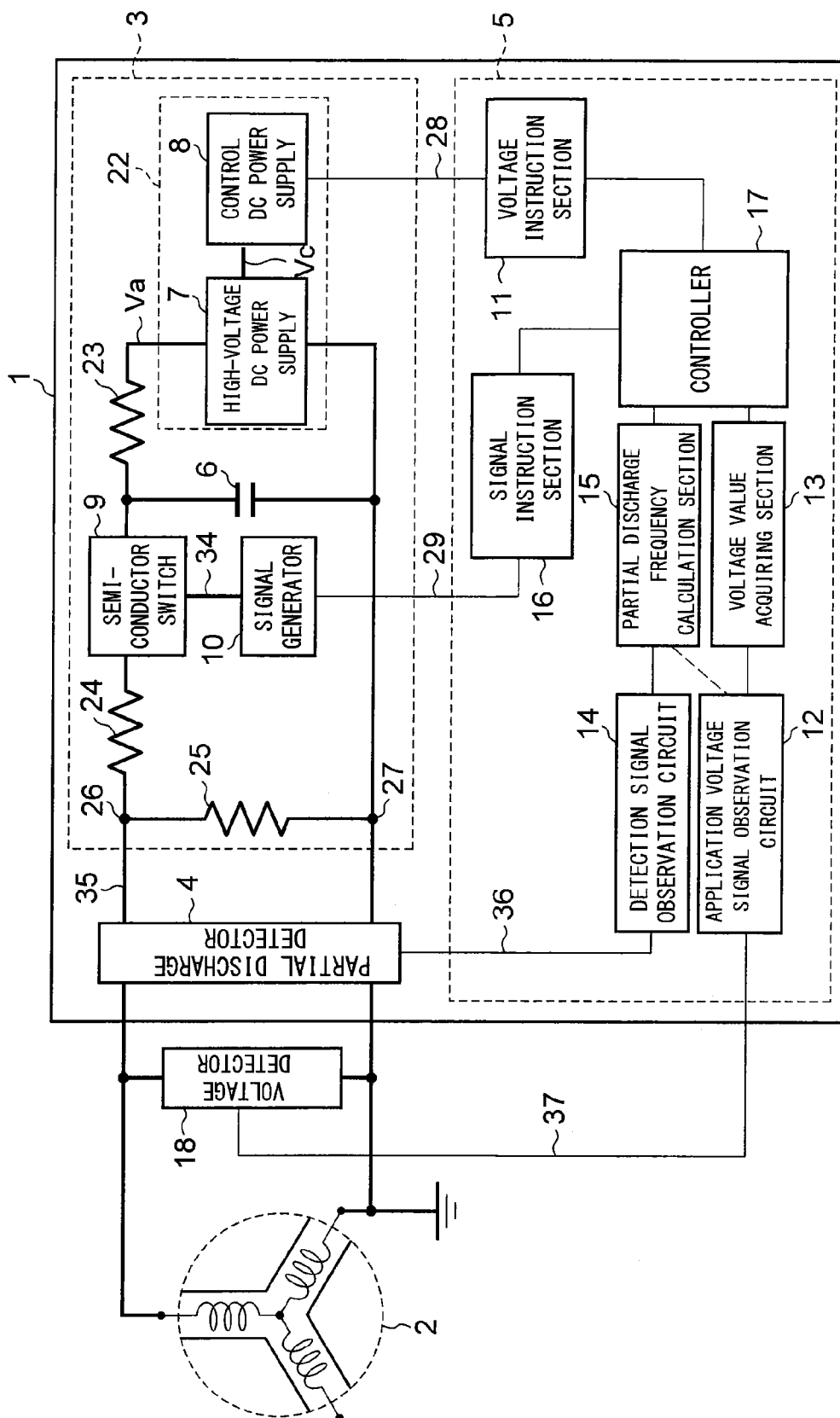


FIG. 2A

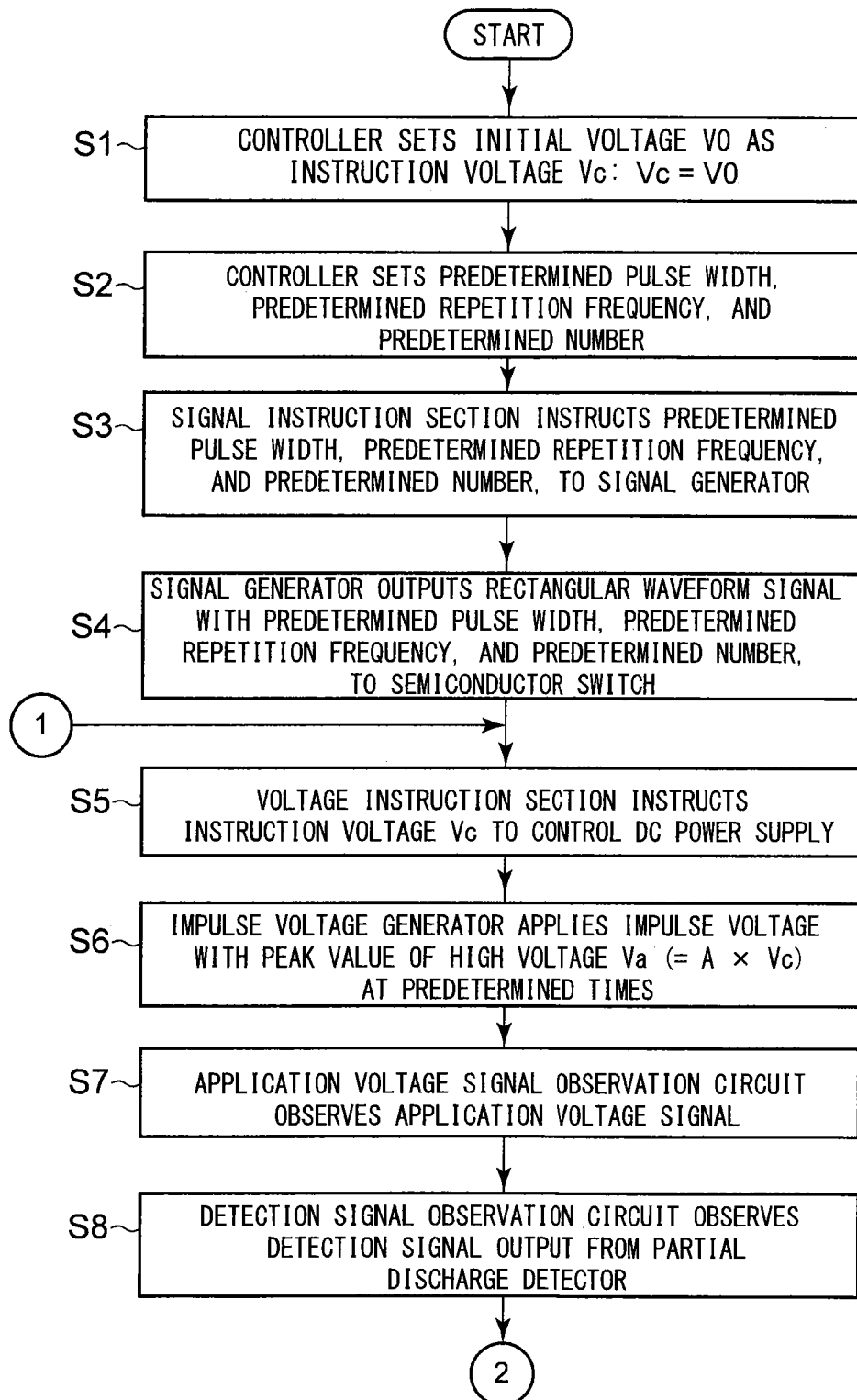


FIG. 2B

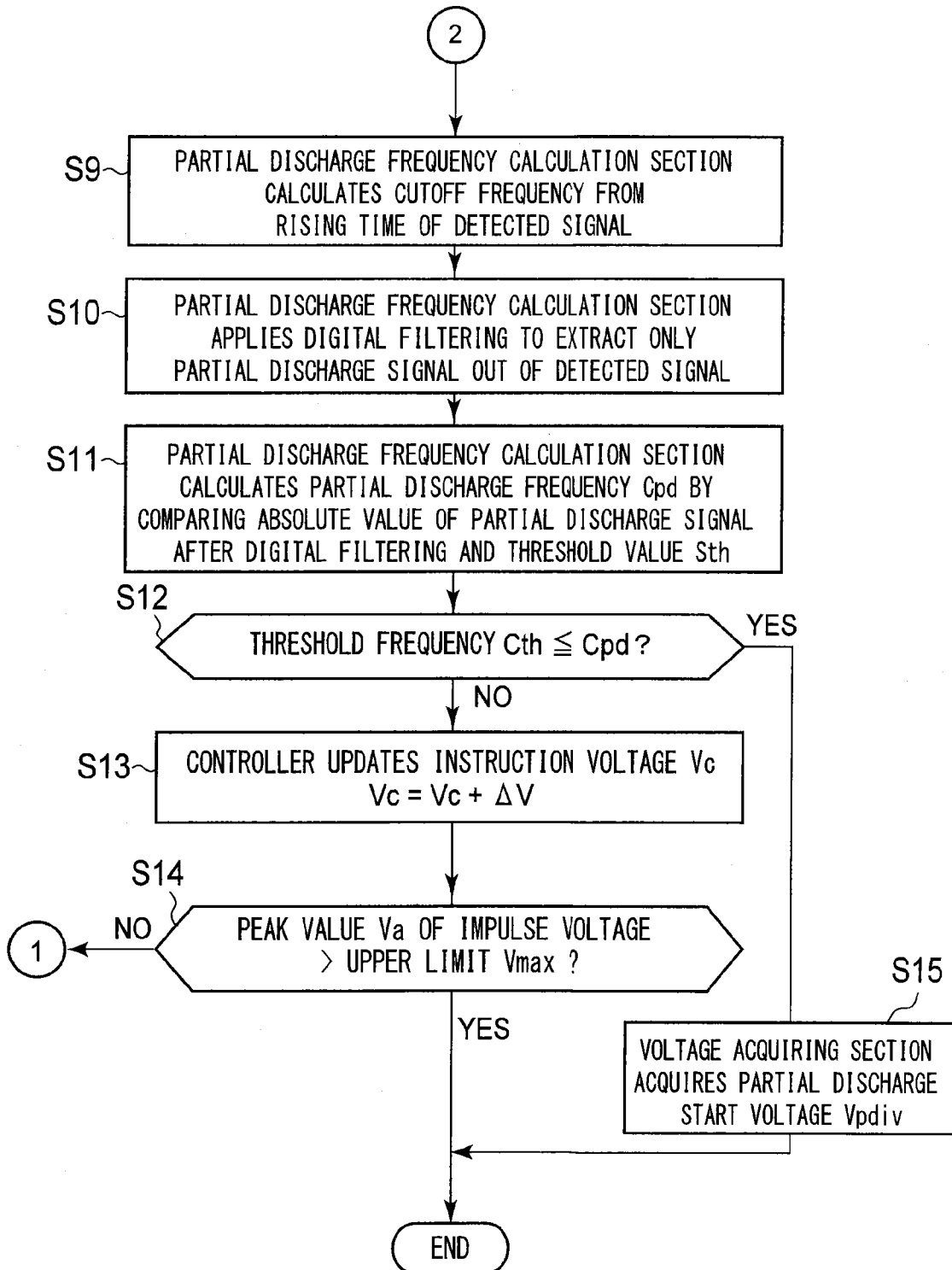


FIG. 3A

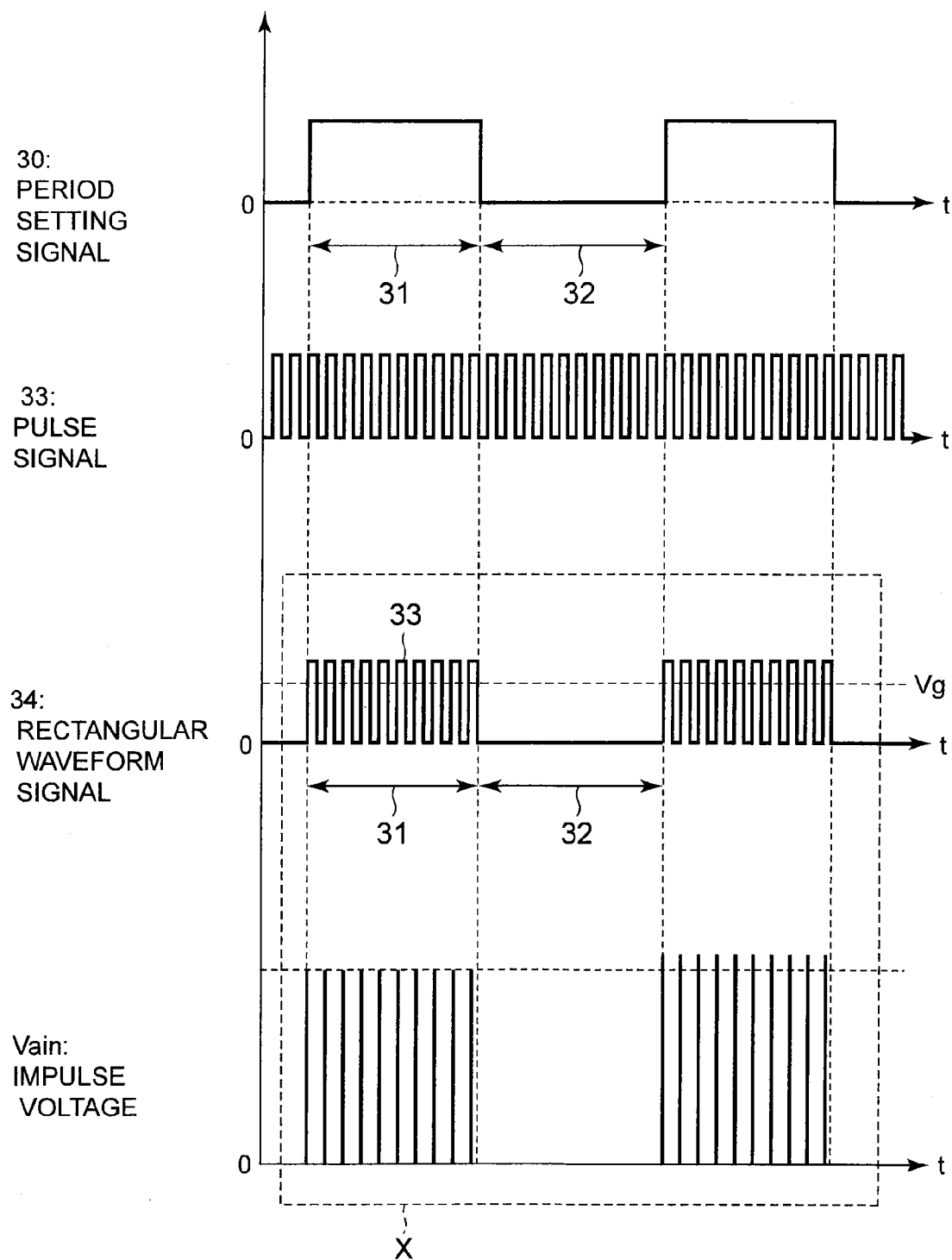
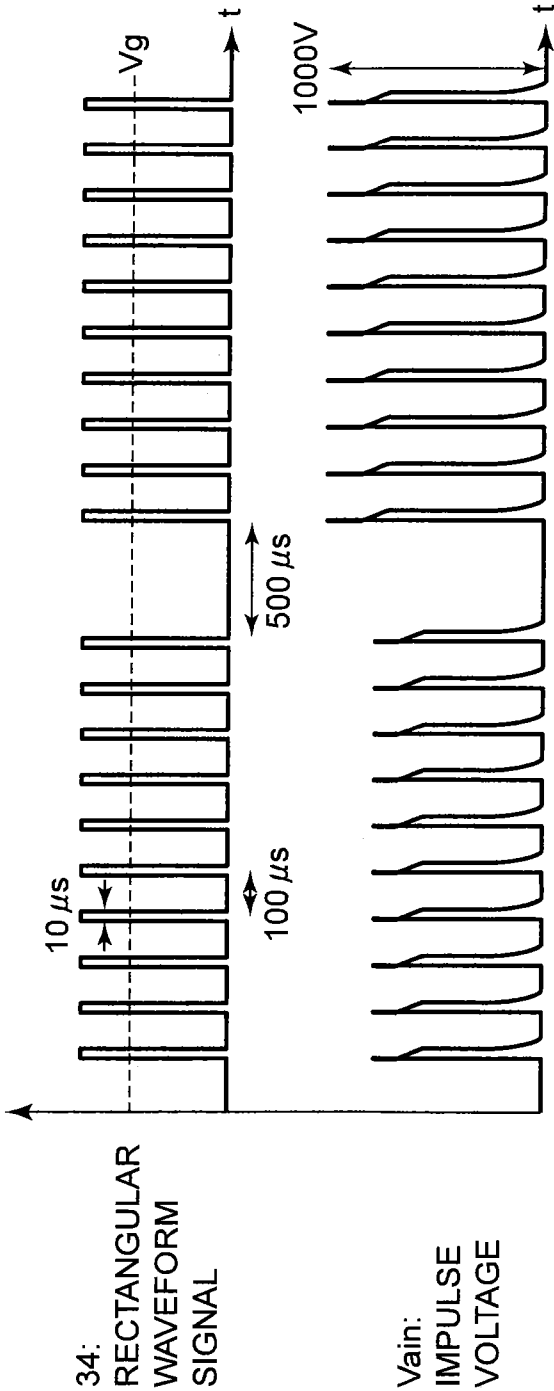


FIG. 3B



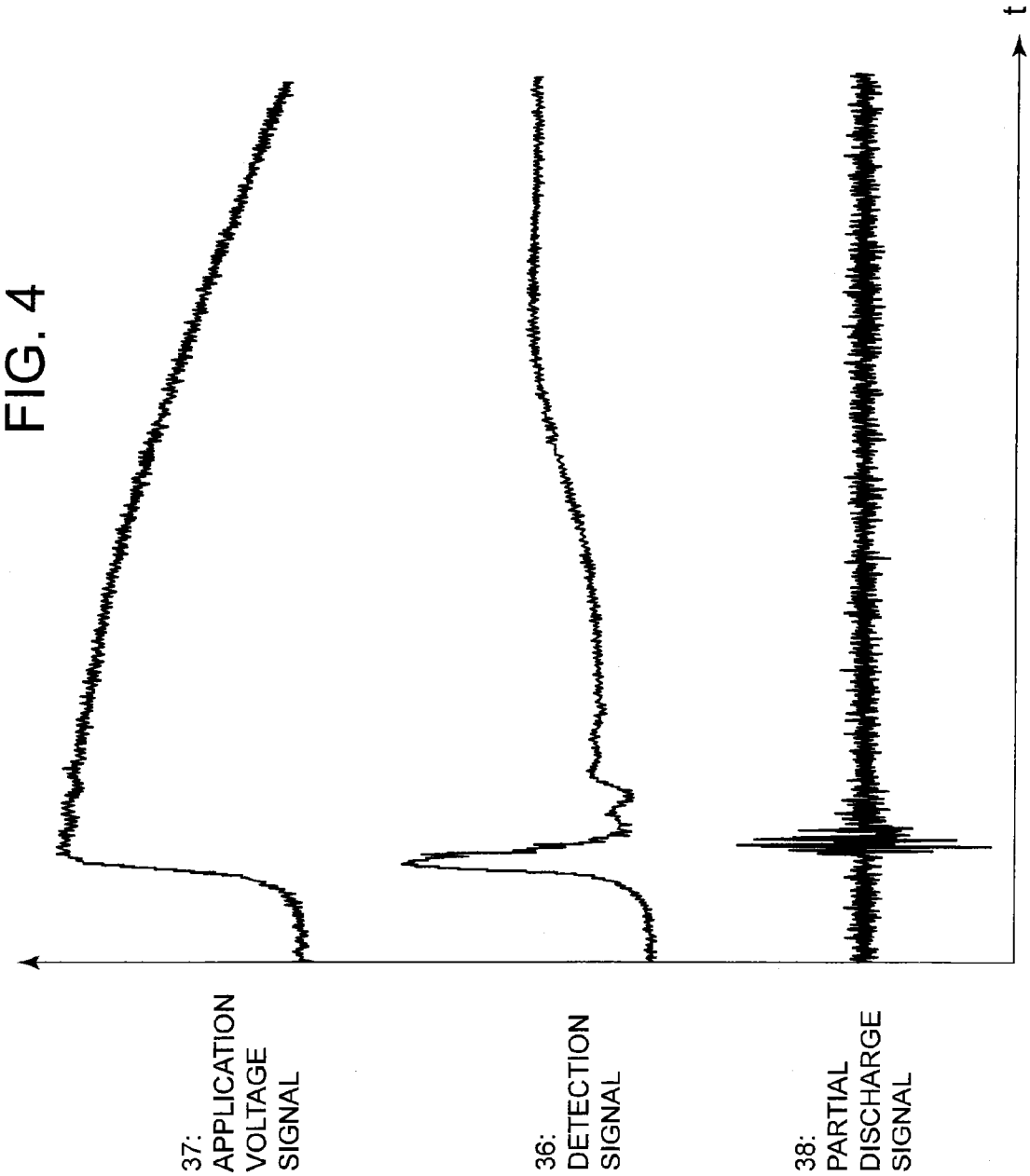


FIG. 5

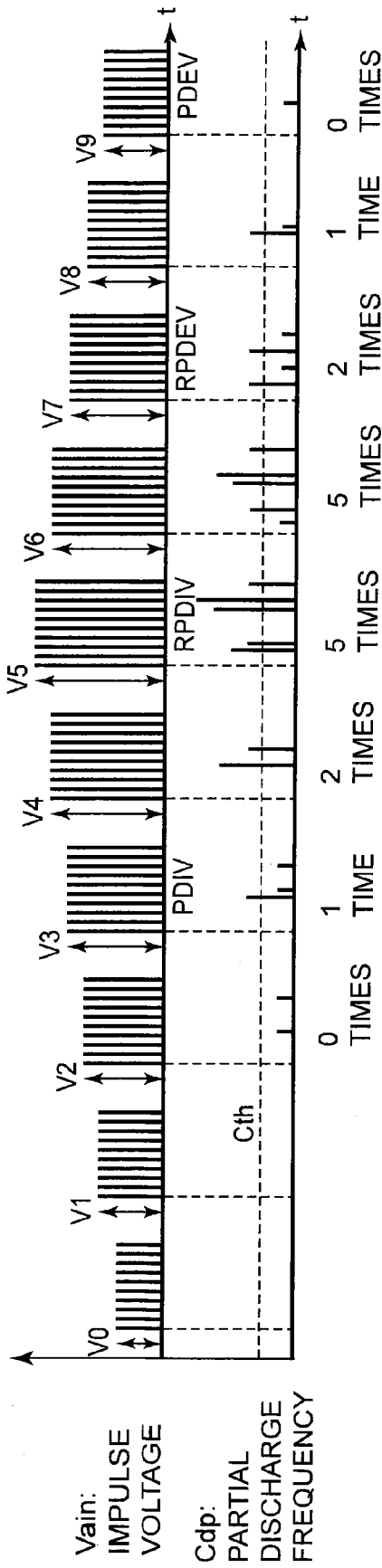


FIG. 6A

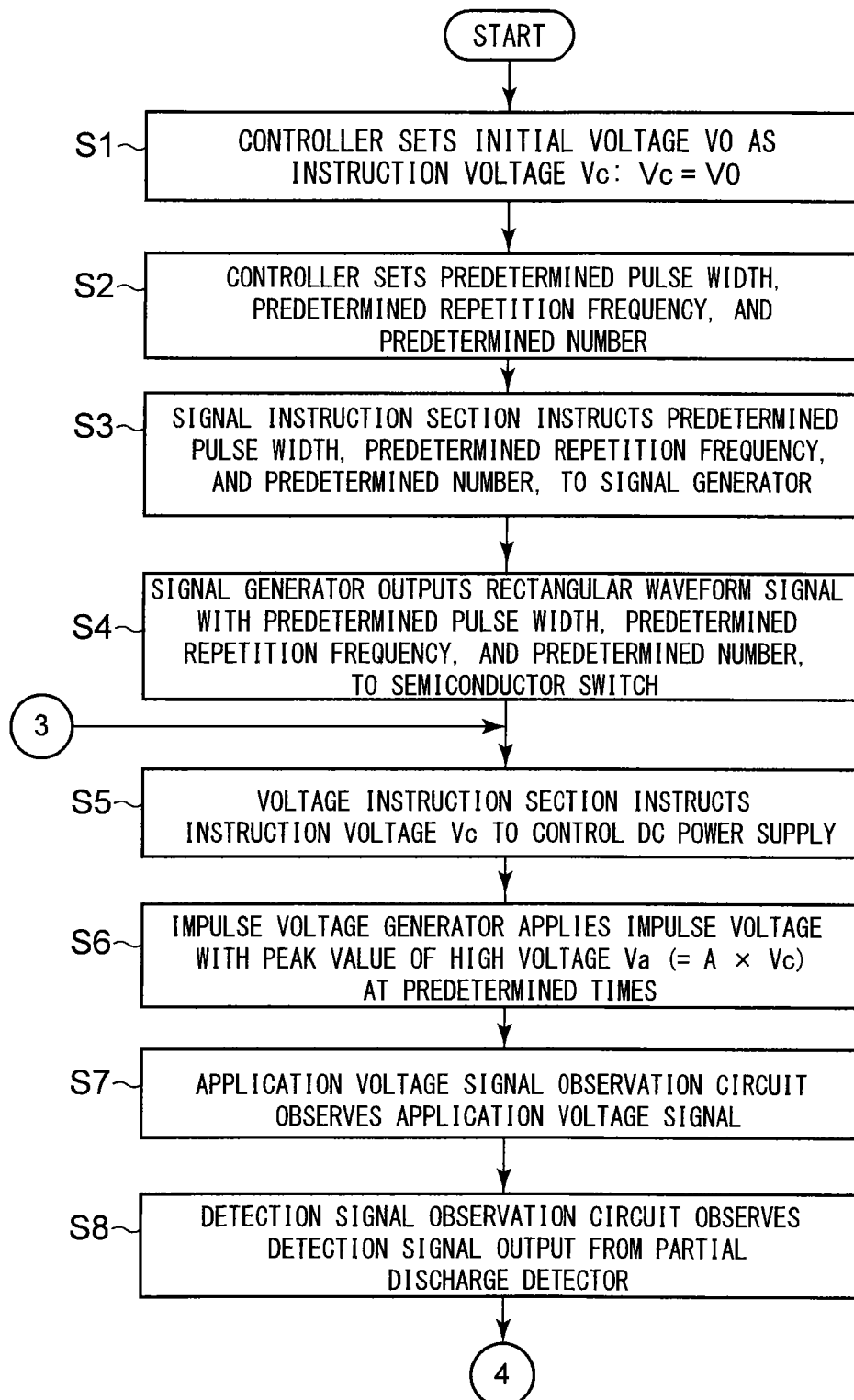


FIG. 6B

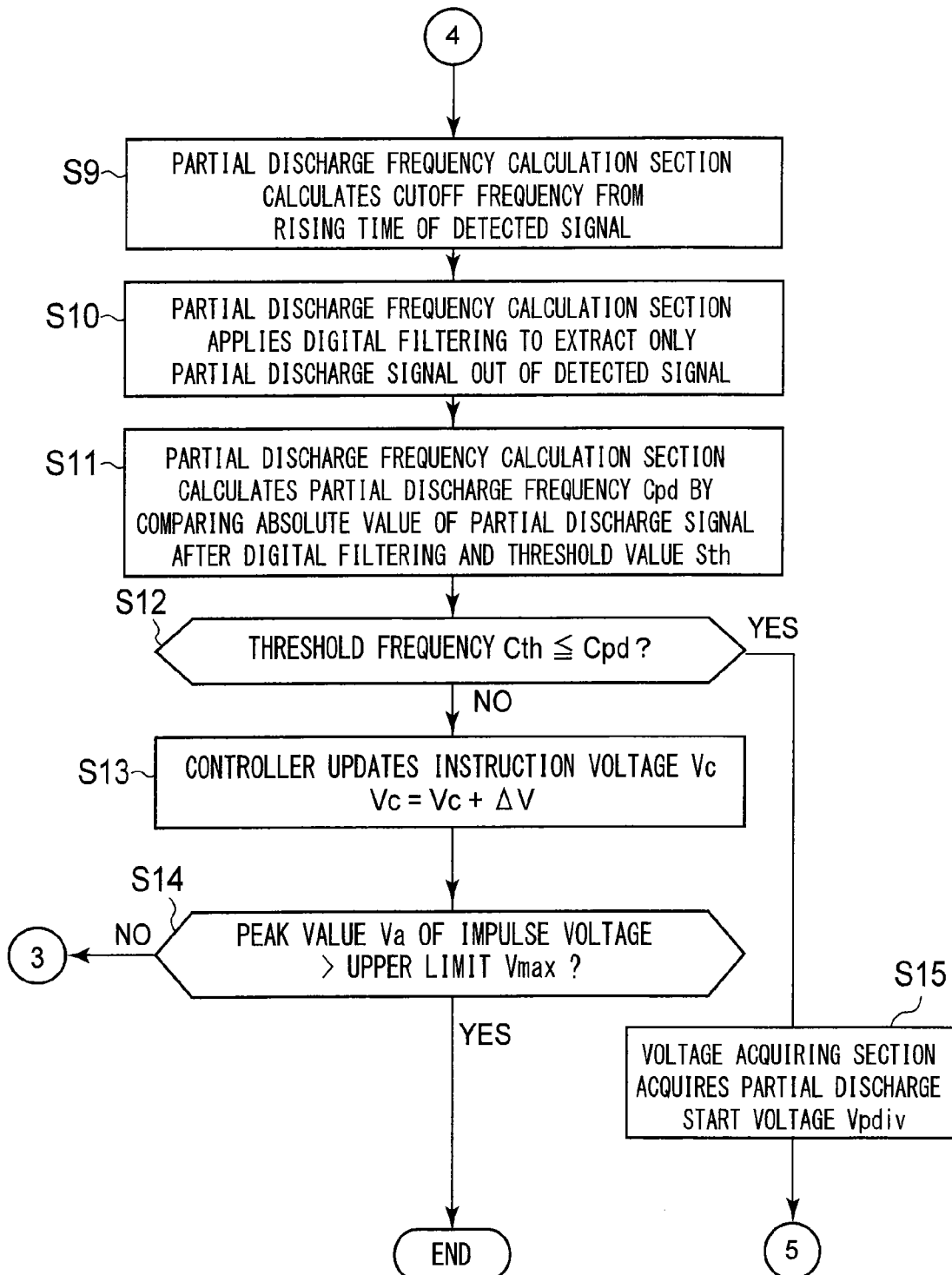


FIG. 6C

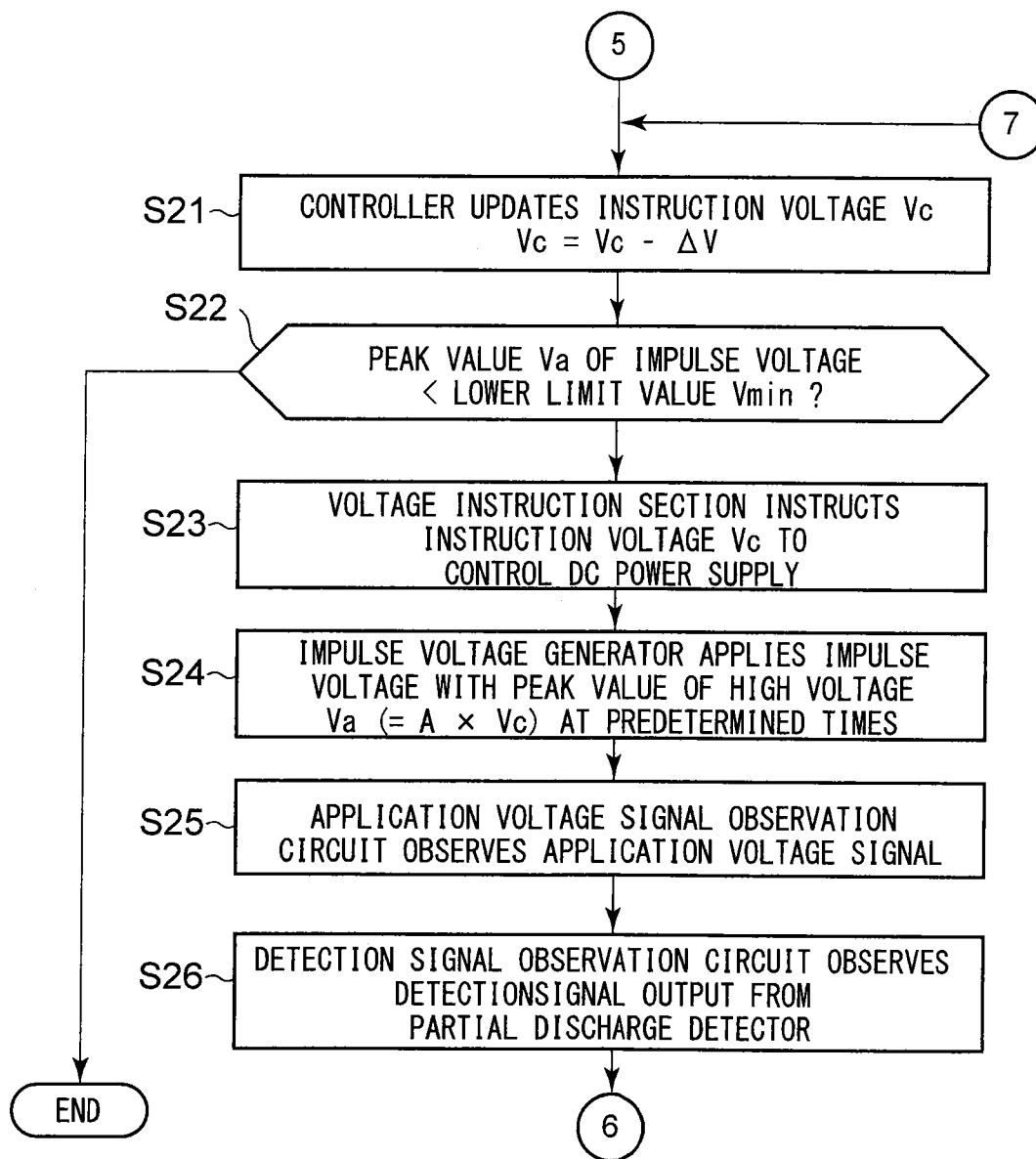


FIG. 6D

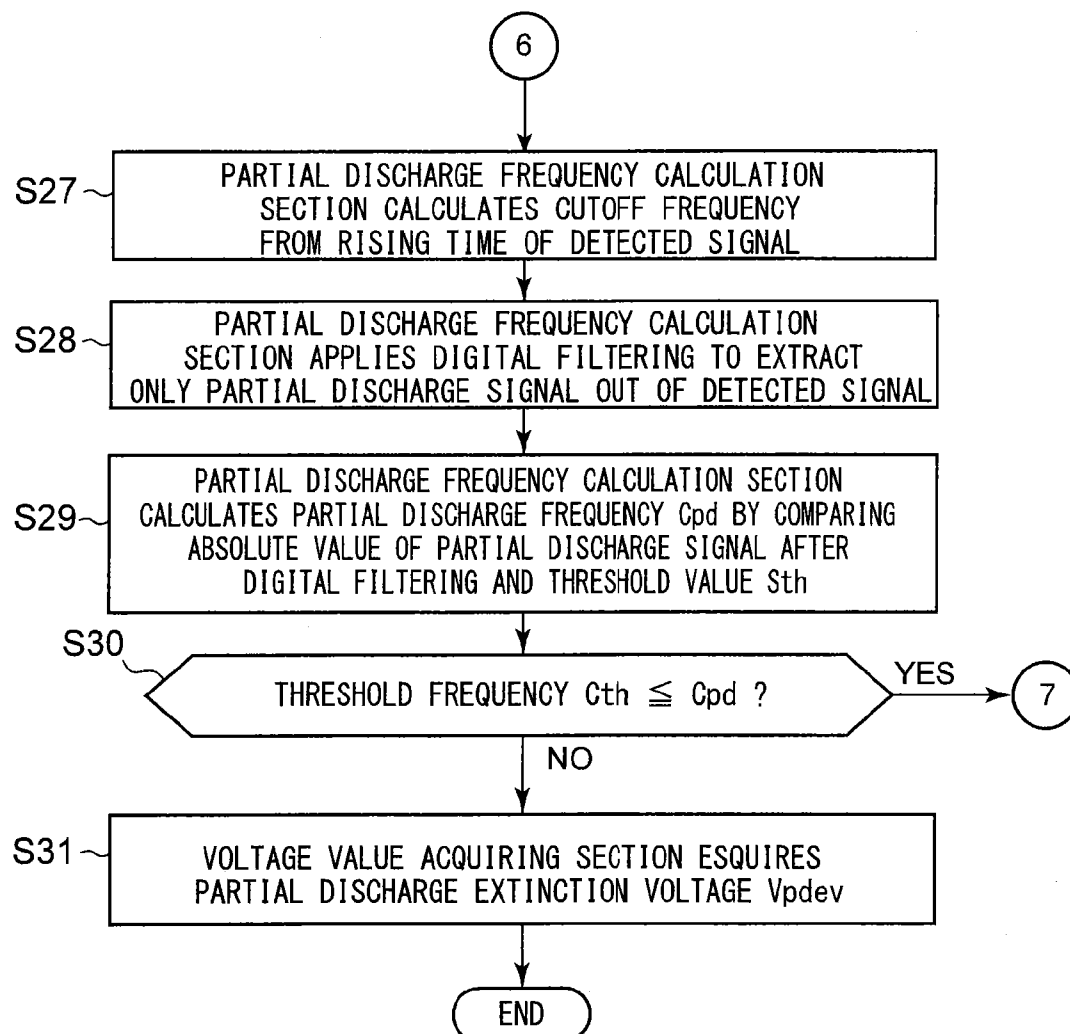


FIG. 7

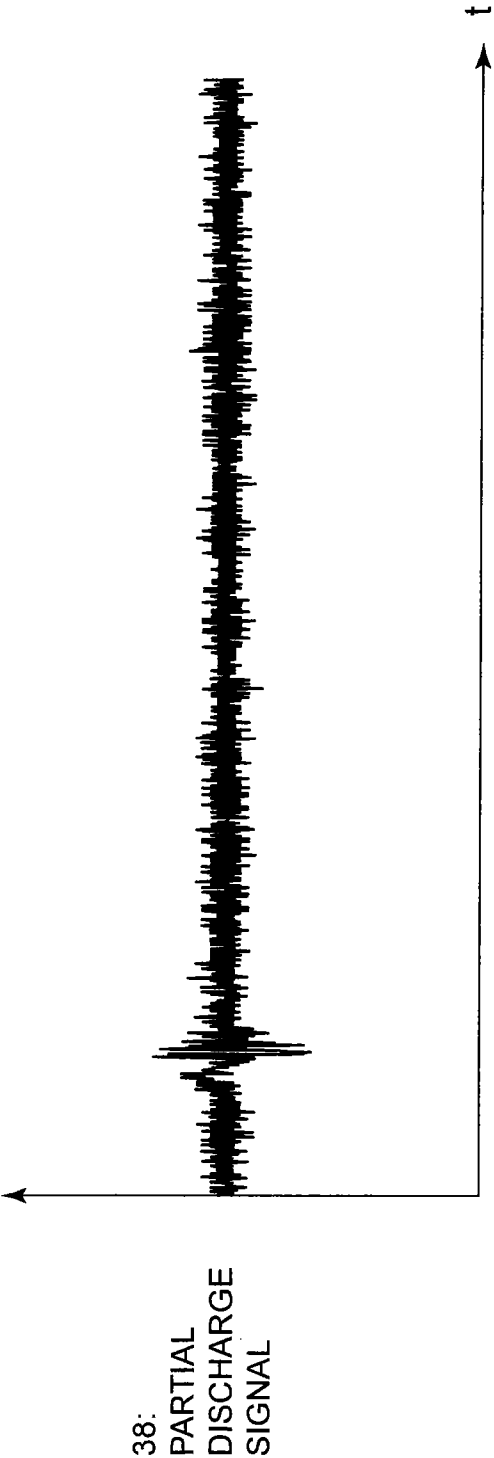


FIG. 8

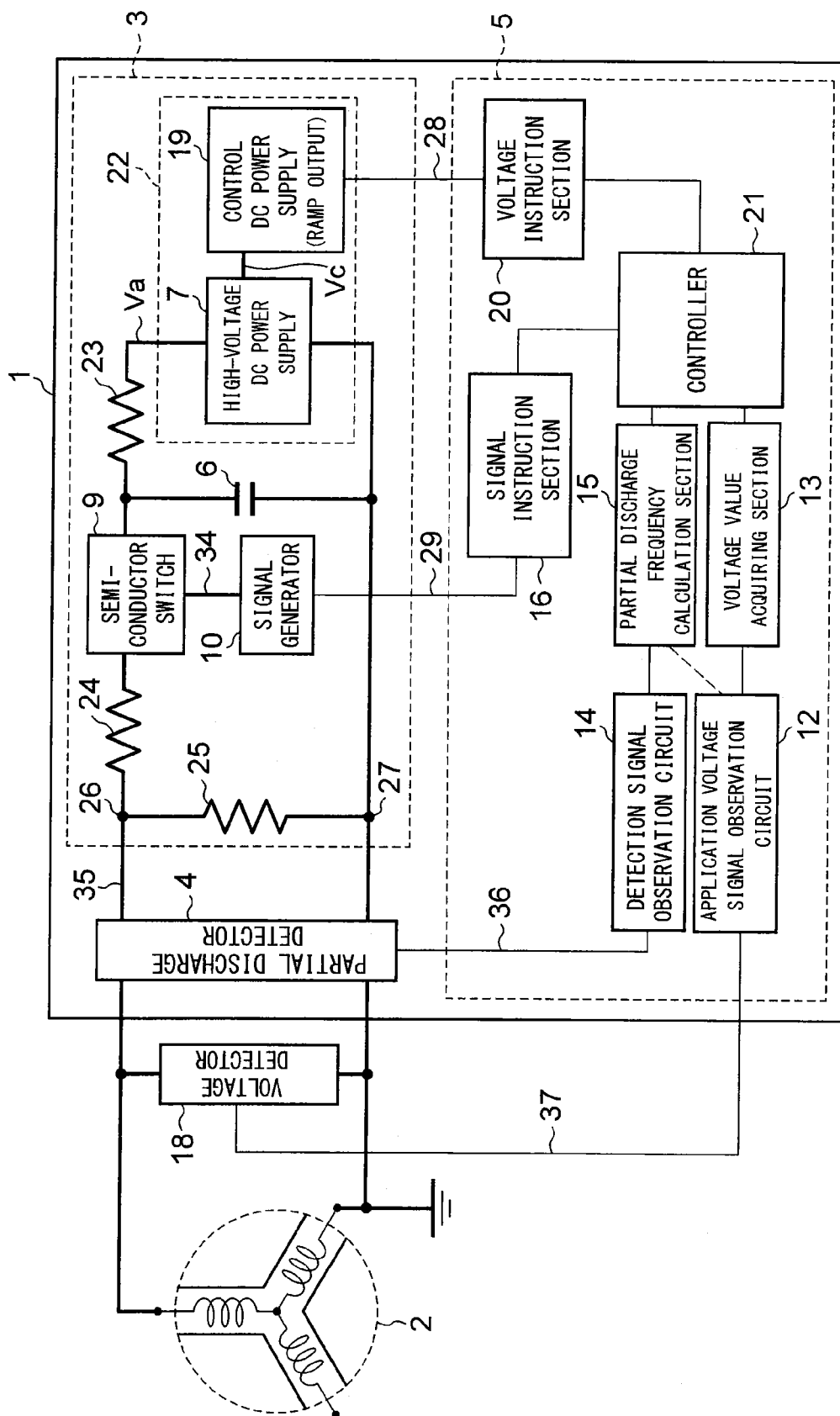


FIG. 9A

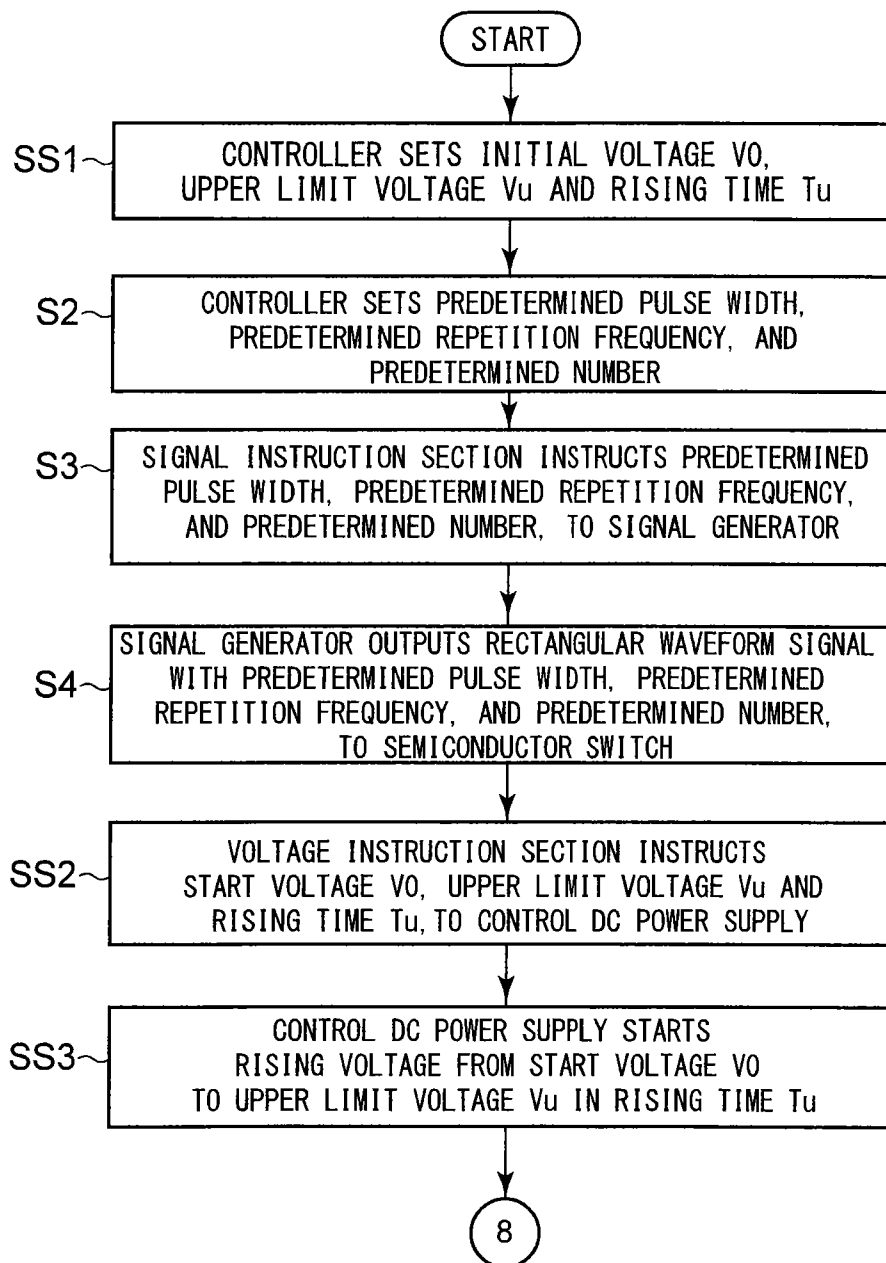


FIG. 9B

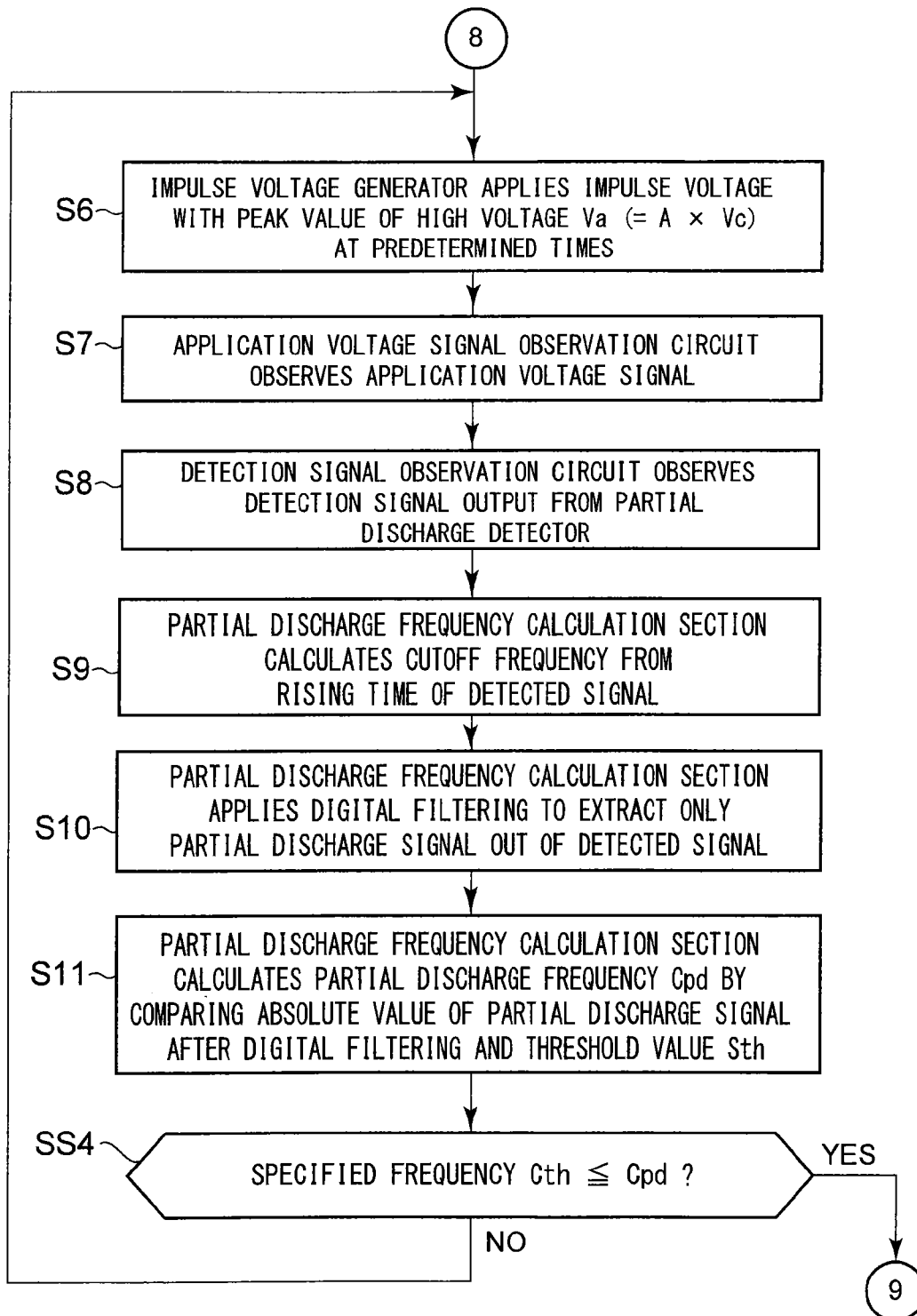


FIG. 9C

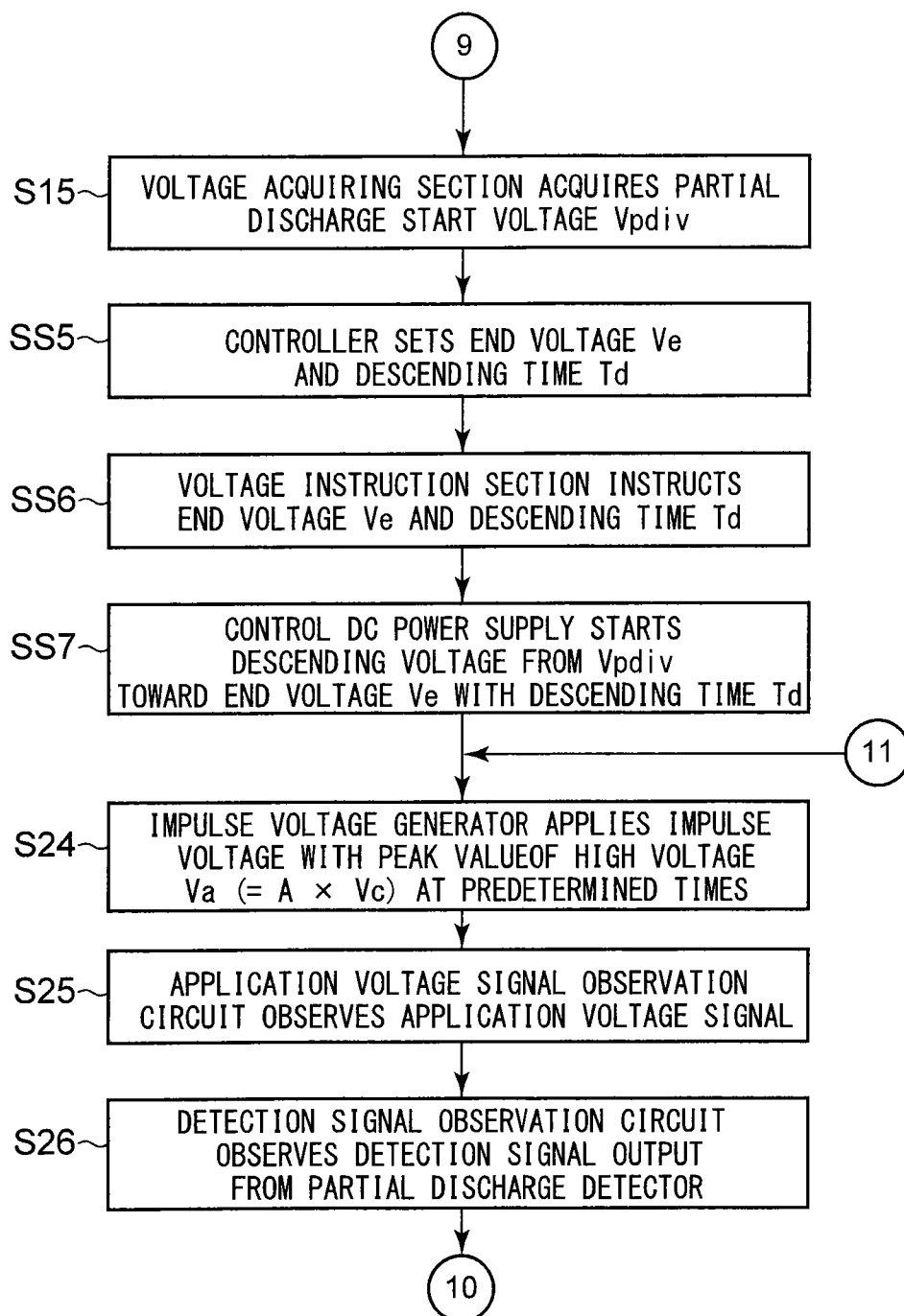


FIG. 9D

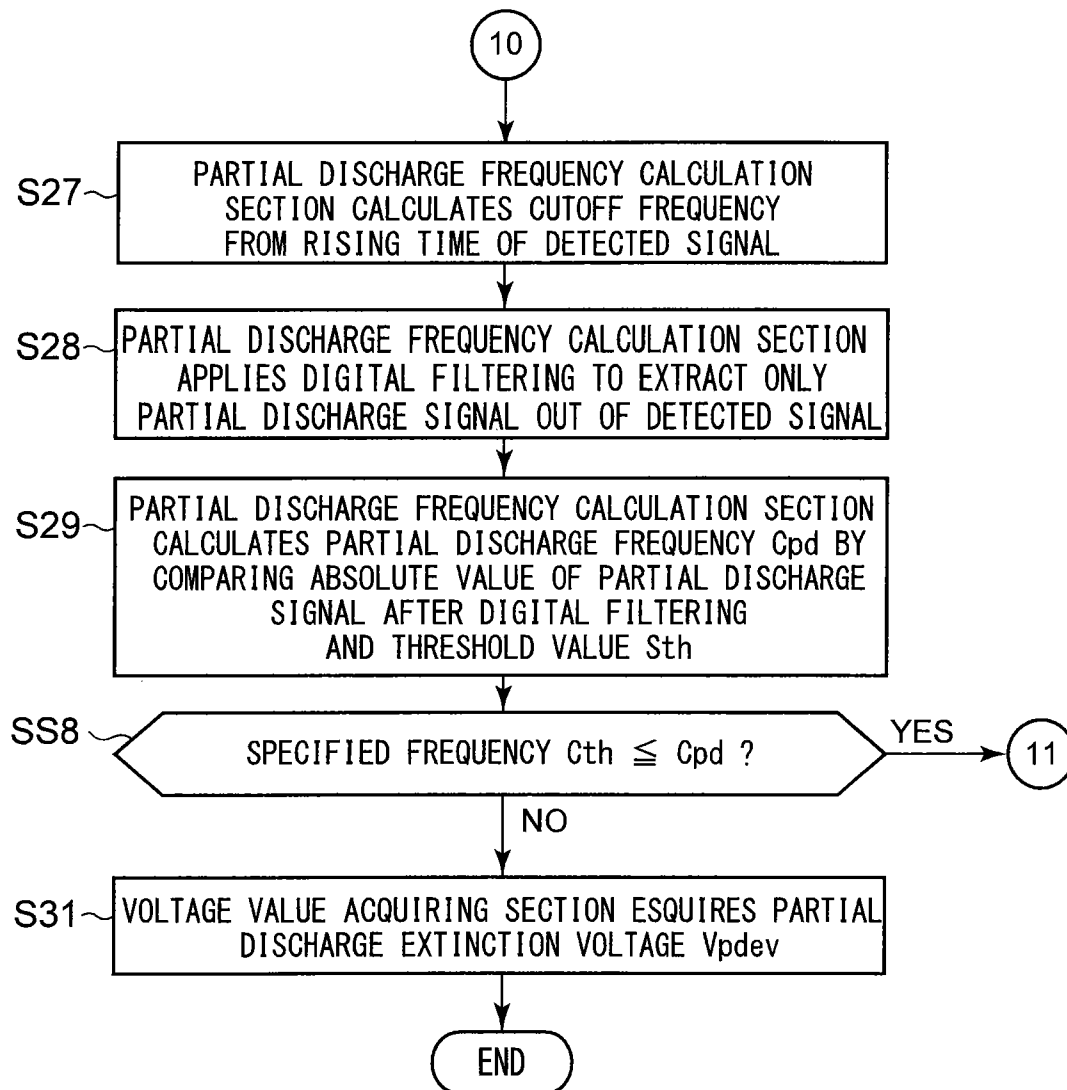


FIG. 10

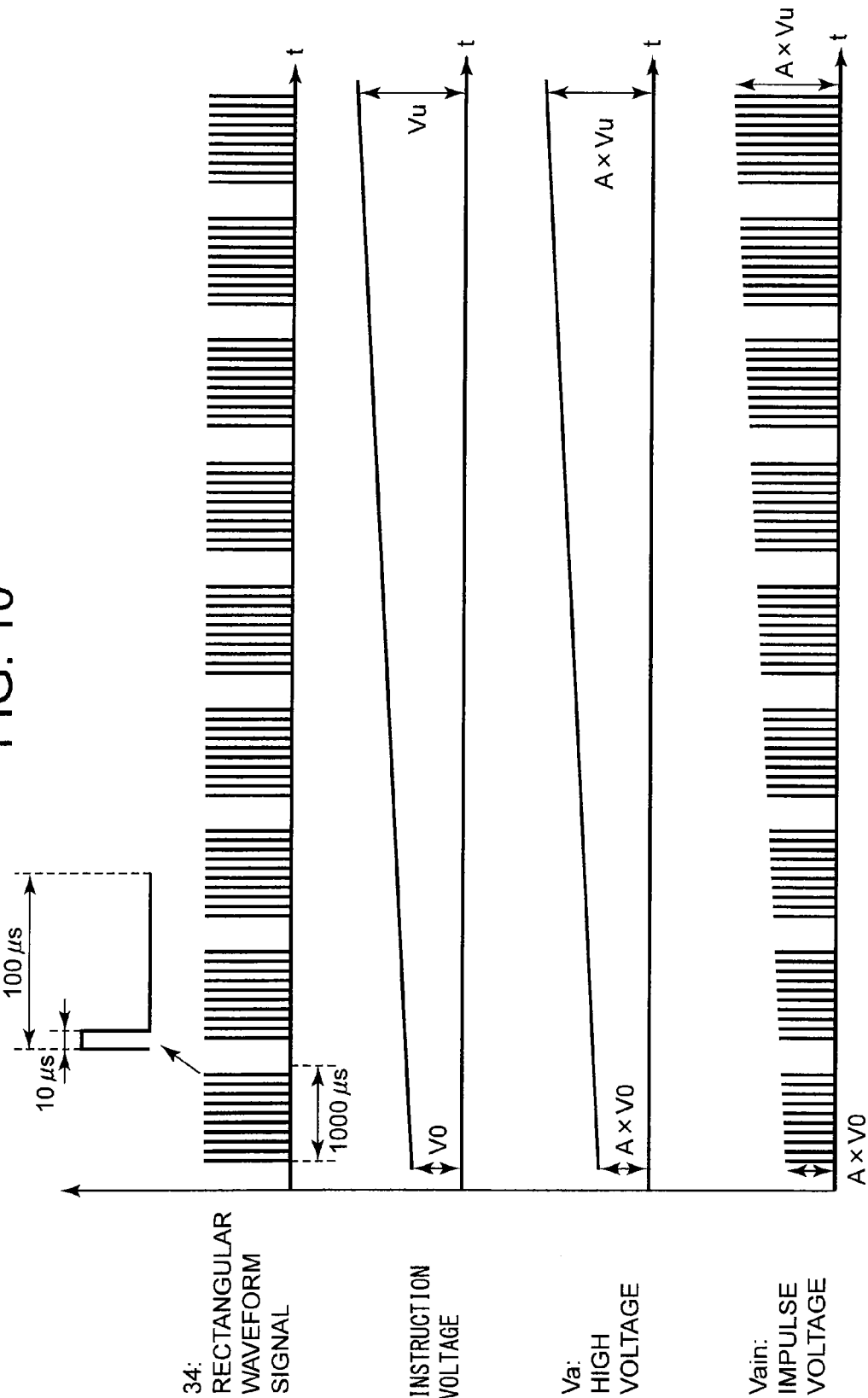


FIG. 11

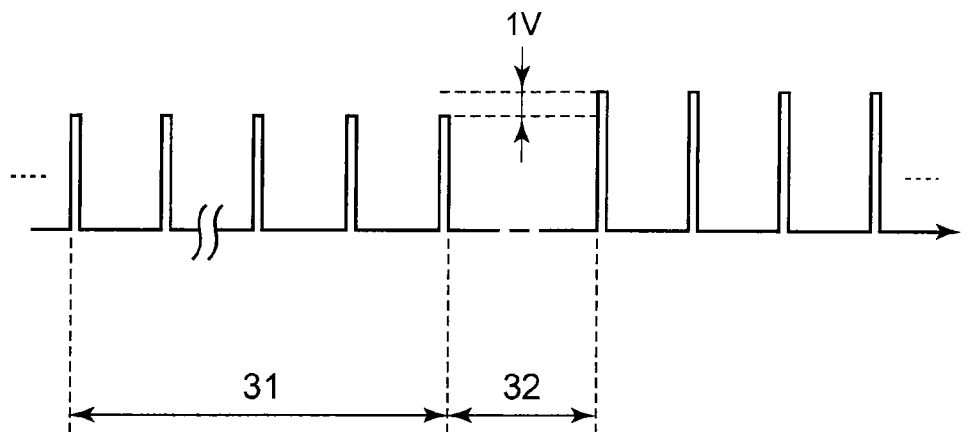
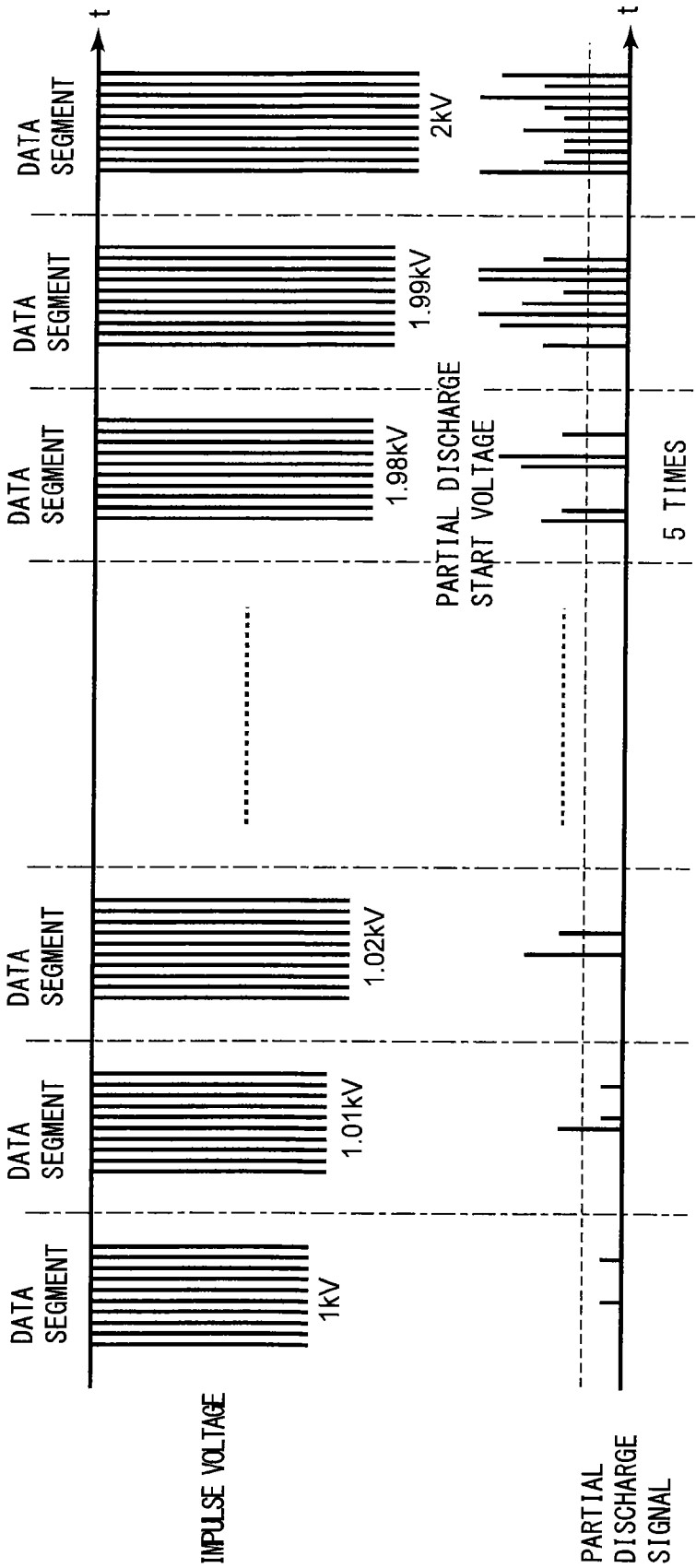


FIG. 12



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PARTIAL DISCHARGE MEASUREMENT SYSTEM AND PARTIAL DISCHARGE MEASUREMENT METHOD BY REPEATED IMPULSE VOLTAGE

TECHNICAL FIELD

The present invention relates to a partial discharge measurement system and a partial discharge measurement method based on repeated impulse voltage.

BACKGROUND ART

It is widely known that when an electric motor is inverter-driven, a surge voltage due to high-speed switching in an inverter is generated to affect insulation of a motor winding. Such a surge voltage is called "inverter surge" and may sometimes reach double or more the rated voltage. When the inverter surge is applied to the motor winding, a partial discharge may occur inside or outside the winding. Such a partial discharge may cause degradation of coating of an enamel wire constituting the winding. Degradation of the coating may lead to insulation breakdown. Thus, there is desired an insulation design of the electric motor that prevents the partial discharge from occurring even when the inverter surge is applied to the winding.

Conventionally, insulation performance of the motor winding is evaluated based on partial discharge characteristics obtained by application of an ordinary alternate voltage, especially, a partial discharge starting voltage. However, a potential distribution in the winding differs between when the ordinary alternate voltage is applied and when the surge voltage is applied. Therefore, the insulation performance of the inverter-driven electric motor is desirably evaluated by application of an impulse voltage simulating the surge voltage. Further, in partial discharge measurement conducted by application of the impulse voltage, voltage changes steeply at rising time (at application start time) of the impulse voltage, so that there is required a different approach from the partial discharge measurement conducted by application of the ordinary alternate voltage.

Non-Patent Document 1 describes a guideline of a partial discharge measurement method that repeatedly applies the impulse voltage in one period. More specifically, Non-Patent Document 1 defines that an impulse voltage applied when a partial discharge frequency, which is the number of the partial discharges, with respect to the number of all the applied impulse voltages (hereinafter, referred to as "number of impulses") reaches a specified frequency or more is regarded as a partial discharge starting voltage, which is called a partial discharge starting voltage in repeated impulse voltage.

Further, Non-Patent Documents 2 and 3 describe a partial discharge measurement method (all-period partial discharge measurement method) that repeatedly applies the impulse voltage for all periods. The following more specifically describes the all-period partial discharge measurement method.

FIG. 12 is a timing chart of the all-period partial discharge measurement method, illustrating an impulse voltage to be applied for each period (data segment in the drawing) to a twist pair sample simulating the winding of the electric motor and a partial discharge signal representing the partial discharge generated in the electric motor to which the impulse voltage is applied. As illustrated in FIG. 12, in the all-period partial discharge measurement method, one period includes a pulse supply period and a pulse pause period following the pulse supply period. In the first period, ten impulse voltages

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are applied during the pulse supply period (e.g., 20 ms) and application of the impulse voltage is stopped during the pulse pause period (e.g., 100 ms). Subsequently, in the second period, ten 10 V boosted impulse voltage are applied during the pulse supply period, and application of the impulse voltage is stopped during the pulse pause period. Such processing is repeated for all periods until a starting value (e.g., 1 kV) of a peak value of the impulse voltage reaches a stop value (e.g., 2 kV).

In the all-period partial discharge measurement method, in all the periods, an applied voltage signal representing the impulse voltage and the above-mentioned partial discharge signal are stored in a memory. Thereafter, an operator verifies, on a per-period basis, whether or not the partial discharge frequency is a specified frequency or more (e.g., five or more) and defines, as the partial discharge starting voltage, the impulse voltage applied to the twist pair sample in a period in which the partial discharge frequency first reaches a specified frequency or more. That is, in the all-period partial discharge measurement method, application of the impulse voltage and measurement of the partial discharge are continuously performed for all periods from the start of the application of the impulse voltage to stop thereof, and the partial discharge starting voltage is derived after completion of the measurement.

Further, in Non-Patent Document 2, a voltage increment of the impulse voltage to be boosted every period is set to be 10 V. Further, in one period, an interval between one impulse voltage and the subsequent impulse voltage in the pulse supply period is set to be 20 ms, and the pulse pause period is set to be 100 ms. The above settings are based on the specification of an impulse voltage generator to be used and cannot be set arbitrarily by a user.

PRIOR ART DOCUMENTS

Non-Patent Documents

Non-Patent Document 1: IEC 61934TS

Non-Patent Document 2: Institute of Electrical Engineers of Japan "40th Symposium on Electric and Electronic Insulating Materials and Applications in System D-1" August 2009

Non-Patent Document 3: Institute of Electrical Engineers of Japan "40th Symposium on Electric and Electronic Insulating Materials and Applications in System P-7" August 2009

SUMMARY OF THE INVENTION

Problems to be Solved by the Invention

An object of the present invention is to provide a partial discharge measurement system based on repeated impulse voltage, capable of allowing a user to set an arbitrary impulse voltage and reducing user's work.

Means for Solving the Problems

According to the present invention, there is provided a partial discharge measurement system based on repeated impulse voltage, the system comprising: a DC power supply that outputs high voltage as a voltage obtained by multiplying an instruction voltage by a set factor; a signal generator that generates a pulse signal representing a predetermined pulse width and a predetermined pulse repetition frequency, and superimposes a period setting signal whose one period

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includes a pulse supply period and a pulse pause period following the pulse supply period and the pulse signal on each other to generate a rectangular waveform signal in which a predetermined number of the pulse signals are generated only in the pulse supply period; a semiconductor switch that charges a capacitive element with the high voltage from the DC power supply when a voltage value of the rectangular waveform signal is lower than a preset voltage threshold, while applies an impulse voltage having a peak value equal to a value of the high voltage from the capacitive element to an object to be measured when the voltage value of the rectangular waveform signal is equal to or higher than the voltage threshold; a signal instruction section that outputs, to the signal generator, a square wave instruction signal in which the predetermined pulse width, the predetermined pulse repetition frequency, and the predetermined number are set; a voltage instruction section that outputs, to the DC power supply, a voltage instruction signal in which an initial voltage is set as the instruction voltage in a first period of the rectangular waveform signal and sets in the voltage instruction signal, in second and subsequent periods, a voltage obtained by adding a predetermined increment voltage lower than the initial voltage to the instruction voltage in the immediately previous period as the instruction voltage; a detection signal observation circuit that observes a detection signal based on a partial discharge generated in the object to be measured to which the impulse voltages are applied; a partial discharge frequency calculation section that counts the number of inputs of the detection signal on a per period basis as a partial discharge frequency; an application voltage signal observation circuit that observes an application voltage signal representing the impulse voltage to be applied to the object to be measured; and a voltage value acquiring section that sets, in a period in which the partial discharge frequency first becomes equal to or more than a specified frequency, a peak value of a voltage represented by the application voltage signal from the application voltage observation circuit as a partial discharge starting voltage.

According to the present invention, there is provided a measurement device for a partial discharge measurement system based on repeated impulse voltage, the system including: a DC power supply that outputs high voltage as a voltage obtained by multiplying an instruction voltage by a set factor; a signal generator that generates a pulse signal representing a predetermined pulse width and a predetermined pulse repetition frequency and superimposes a period setting signal whose one period includes a pulse supply period and a pulse pause period following the pulse supply period and the pulse signal on each other to generate a rectangular waveform signal in which a predetermined number of the pulse signals are generated only in the pulse supply period; and a semiconductor switch that charges a capacitive element with the high voltage from the DC power supply when a voltage value of the rectangular waveform signal is lower than a preset voltage threshold, while applies an impulse voltage having a peak value equal to a value of the high voltage from the capacitive element to an object to be measured when the voltage value of the rectangular waveform signal is equal to or higher than the voltage threshold, the measurement device comprising: a signal instruction section that outputs, to the signal generator, a square wave instruction signal in which the predetermined pulse width, the predetermined pulse repetition frequency, and the predetermined number are set; a voltage instruction section that outputs, to the DC power supply, a voltage instruction signal in which an initial voltage is set as the instruction voltage in a first period of the rectangular waveform signal and sets in the voltage instruction signal, in sec-

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ond and subsequent periods, a voltage obtained by adding a predetermined increment voltage lower than the initial voltage to the instruction voltage in the immediately previous period as the instruction voltage; a detection signal observation circuit that observes a detection signal based on a partial discharge generated in the object to be measured to which the impulse voltages are applied; a partial discharge frequency calculation section that counts the number of inputs of the detection signal on a per period basis as a partial discharge frequency; an application voltage signal observation circuit that observes an application voltage signal representing the impulse voltage to be applied to the object to be measured; and a voltage value acquiring section that sets, in a period in which the partial discharge frequency first becomes equal to or more than a specified frequency, a peak value of a voltage represented by the application voltage signal from the application voltage observation circuit as a partial discharge starting voltage.

According to the present invention, there is provided a measurement method for a partial discharge measurement system based on repeated impulse voltage, the system including: a DC power supply that outputs high voltage as a voltage obtained by multiplying an instruction voltage by a set factor; a signal generator that generates a pulse signal representing a predetermined pulse width and a predetermined pulse repetition frequency, and superimposes a period setting signal whose one period includes a pulse supply period and a pulse pause period following the pulse supply period and the pulse signal on each other to generate a rectangular waveform signal in which a predetermined number of the pulse signals are generated only in the pulse supply period; and a semiconductor switch that charges a capacitive element with the high voltage from the DC power supply when a voltage value of the rectangular waveform signal is lower than a preset voltage threshold, while applies an impulse voltage having a peak value equal to a value of the high voltage from the capacitive element to an object to be measured when the voltage value of the rectangular waveform signal is equal to or higher than the voltage threshold, the measurement method comprising steps of: outputting, to the signal generator, a square wave instruction signal in which the predetermined pulse width, the predetermined pulse repetition frequency, and the predetermined number are set; outputting, to the DC power supply, a voltage instruction signal in which an initial voltage is set as the instruction voltage in a first period of the rectangular waveform signal, and setting in the voltage instruction signal, in second and subsequent periods, a voltage obtained by adding a predetermined increment voltage lower than the initial voltage to the instruction voltage in an immediately previous period as the instruction voltage; observing, using a detection signal observation circuit, a detection signal based on a partial discharge generated in the object to be measured to which the impulse voltages are applied; counting the number of inputs of the detection signal on a per period basis as a partial discharge frequency; observing, using an application voltage signal observation circuit, an application voltage signal representing the impulse voltage to be applied to the object to be measured; and setting, in a period in which the partial discharge frequency first becomes equal to or more than a specified frequency, a peak value of a voltage represented by the application voltage signal from the application voltage observation circuit as a partial discharge starting voltage.

Advantage of the Present Invention

According to the present invention, the user can set an arbitrary impulse voltage and the user's work can be reduced.

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BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a block diagram illustrating a schematic configuration of a partial discharge measurement system according to a first embodiment.

FIG. 2A is a flowchart illustrating a measurement procedure of a partial discharge starting voltage V_{pdiv} .

FIG. 2B is a flowchart illustrating the measurement procedure of the partial discharge starting voltage V_{pdiv} .

FIG. 3A is a timing chart illustrating a period setting signal 30, a pulse signal 33, and a rectangular waveform signal 34 which are generated by a signal generator, and an impulse voltage V_{ain} generated by a semiconductor switch.

FIG. 3B is an enlarged view of a part X of FIG. 3A.

FIG. 4 is a timing chart illustrating waveforms of an application voltage signal 37, a detection signal 36, and a partial discharge signal 38 obtained by applying digital filtering to the detection signal 36.

FIG. 5 is a timing chart illustrating an impulse voltage V_{ain} and a partial discharge frequency C_{pd} on a per period basis.

FIG. 6A is a flowchart illustrating a measurement procedure of a partial discharge starting voltage V_{pdiv} and a partial discharge extinction voltage V_{pdev} .

FIG. 6B is a flowchart illustrating a measurement procedure of the partial discharge starting voltage V_{pdiv} and the partial discharge extinction voltage V_{pdev} .

FIG. 6C is a flowchart illustrating a measurement procedure of the partial discharge starting voltage V_{pdiv} and the partial discharge extinction voltage V_{pdev} .

FIG. 6D is a flowchart illustrating a measurement procedure of the partial discharge starting voltage V_{pdiv} and the partial discharge extinction voltage V_{pdev} .

FIG. 7 is a timing chart illustrating a waveform of a partial discharge signal 38 obtained by applying digital differential processing to a detection signal 36 of FIG. 4.

FIG. 8 is a block diagram illustrating a schematic configuration of a partial discharge measurement system according to a second embodiment.

FIG. 9A is a flowchart illustrating a measurement procedure of the partial discharge starting voltage V_{pdiv} and the partial discharge extinction voltage V_{pdev} .

FIG. 9B is a flowchart illustrating a measurement procedure of the partial discharge starting voltage V_{pdiv} and the partial discharge extinction voltage V_{pdev} .

FIG. 9C is a flowchart illustrating a measurement procedure of the partial discharge starting voltage V_{pdiv} and the partial discharge extinction voltage V_{pdev} .

FIG. 9D is a flowchart illustrating a measurement procedure of the partial discharge starting voltage V_{pdiv} and the partial discharge extinction voltage V_{pdev} .

FIG. 10 is a timing chart illustrating the rectangular waveform signal 34, instruction voltage of the ramp output, high voltage V_a , and impulse voltage V_{ain} .

FIG. 11 is a timing chart illustrating an example in which predetermined number of impulse voltage V_{ain} is applied by boosting it by 1 V after 1 V.

FIG. 12 is a timing chart of an all-period partial discharge measurement method, illustrating an impulse voltage to be applied for each period (data segment in the drawing) to an electric motor (e.g., between phases of a winding) and a partial discharge signal representing the partial discharge generated in the electric motor to which the impulse voltage is applied.

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EMBODIMENTS FOR CARRYING OUT THE INVENTION

Hereinafter, embodiments of a partial discharge measurement system based on repeated impulse voltage according to the present invention will be described with reference to the drawings.

(First Embodiment)

FIG. 1 is a block diagram illustrating a schematic configuration of a partial discharge measurement system according to a first embodiment. A partial discharge measurement system 1 illustrated in FIG. 1 applies repeated impulse voltage to an electric motor 2 which is an object to be measured to measure a partial discharge in the repeated impulse voltage. The partial discharge measurement system 1 includes an impulse voltage generator 3, a partial discharge detector 4, a measurement device 5, and a voltage detector 18.

The impulse voltage generator 3 includes a capacitor 6 as a capacitive element, a DC power supply 22, a semiconductor switch 9, a signal generator 10, resistive elements 23 to 25, and output terminals 26 and 27. The DC power supply 22 includes a high-voltage DC power supply 7 and a control DC power supply 8.

An output of the high-voltage DC power supply 7 is connected to a first electrode of the capacitor 6. A second electrode 2 of the capacitor 6 has the same potential as that of the output terminal 27. More specifically, the output terminal 27 is grounded. An output of the control DC power supply 8 is connected to an input port (not illustrated) of the high-voltage DC power supply 7.

The resistive element 23 is provided between the output of the high-voltage DC power supply 7 and the first electrode of the capacitor 6. The resistive element 25 is provided between the output terminals 26 and 27. For example, a section between phases (e.g., U and V phases) of a winding of the electric motor 2 is provided as a load for supplying an impulse voltage V_{ain} . The load is not limited to the illustrated section between phases of the winding of the electric motor 2 but may be other sections between phases or a section between the winding and the iron core of the electric motor 2.

The semiconductor switch 9 includes a first terminal (not illustrated) connected to the first electrode of the capacitor 6, a second terminal (not illustrated) connected to the output terminal 26, and a gate terminal (not illustrated). The resistive element 24 is provided between the second terminal of the semiconductor switch 9 and the output terminal 26. An output of the signal generator 10 is connected to the gate terminal of the semiconductor switch 9.

The control DC power supply 8 receives a voltage instruction signal 28 from the measurement device 5 and outputs an instruction voltage V_c set in the voltage instruction signal 28 to the high-voltage DC power supply 7. The instruction voltage V_c is a voltage input to the input port of the high-voltage DC power supply 7 so as to control a value of voltage output from the high-voltage DC power supply 7.

The high-voltage DC power supply 7 outputs, as a high voltage V_a , a voltage obtained by multiplying the instruction voltage V_c output from the control DC power supply 8 by a set factor A.

A period setting signal is set in the signal generator 10. One period of the period setting signal includes a pulse supply period and a pulse pause period following the pulse supply period. The signal generator 10 receives a square wave instruction signal 29 from the measurement device 5 and generates a pulse signal representing a predetermined pulse width and a predetermined pulse repetition frequency set in the square wave instruction signal 29. The signal generator 10

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superimposes the period setting signal and pulse signal on each other to generate a rectangular waveform signal **34** in which a predetermined number of pulse signals set in the square wave instruction signal **29** are generated only in the pulse supply period of the period setting signal. Details of the period setting signal, pulse signal, and rectangular waveform signal **34** will be described later.

The semiconductor switch **9** is turned ON when a voltage value to be supplied to the gate electrode is equal to or higher than a preset voltage threshold to connect the first and second terminals. More specifically, the semiconductor switch **9** charges the capacitor **6** with the high voltage V_a from the high-voltage DC power supply **7** when a voltage value of the rectangular waveform signal **34** is lower than the voltage threshold; while it applies an impulse voltage V_{in} having a peak value equal to a value of the high voltage V_a from the capacitor **6** to the electric motor **2** when the voltage value of the rectangular waveform signal **34** is equal to or higher than the voltage threshold.

The voltage detector **18** detects the impulse voltage V_{in} to be applied to the electric motor **2** (section between phases of the winding of the electric motor **2**, in the above example) provided between the output terminals **26** and **27** and outputs an application voltage signal **37** representing the impulse voltage V_{in} to the measurement device **5**.

The partial discharge detector **4** detects the partial discharge generated in the electric motor **2** to which the impulse voltage V_{in} is applied, and outputs a detection signal **36** based on the partial discharge to the measurement device **5**. For example, as the partial discharge detector **4**, there may be adopted any configurations that detect a physical quantity generated with the partial discharge, such as one detecting a current flowing in the winding of the electric motor **2** by a CT (Current Transformer) and one detecting an electromagnetic wave around the winding of the electric motor **2** by an antenna.

The measurement device **5** is realized by a personal computer in which, for example, Windows® is installed as an OS (Operating System). The measurement device **5** includes various application programs to be described later running thereon and is provided with an interface for inputting/outputting a signal from/to an external device. With this configuration, the measurement device **5** can perform a function as an oscilloscope that displays an input signal on a screen as a waveform or a function for controlling measurement of the partial discharge.

The measurement device **5** includes a voltage instruction section **11**, an application voltage signal observation circuit **12**, a voltage value acquiring section **13**, a detection signal observation circuit **14**, a partial discharge frequency calculation section **15**, a signal instruction section **16**, and a controller **17**.

The constituent elements of the measurement device **5** other than the application voltage signal observation circuit **12** and the detection signal observation circuit **14**, that is, the voltage instruction section **11**, the voltage value acquiring section **13**, the partial discharge frequency calculation section **15**, the signal instruction section **16**, and the controller **17** are each constituted by hardware or software. For example, when each constituent element is constituted by software, it can be realized by a computer program.

The voltage instruction section **11** controls operation of the control DC power supply **8** through a communication interface for performing communication such as RS-232C so as to apply the impulse voltage V_{in} having the same voltage level to the electric motor **2**. More specifically, for controlling the control DC power supply **8**, the controller **17** generates the

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voltage instruction signal **28** in which an initial voltage is set as the instruction voltage V_c in a first period (corresponding to a first period of the rectangular waveform signal **34**) of the period setting signal, and the voltage instruction section **11** outputs the voltage instruction signal **28** to the control DC power supply **8**. Further, in second and subsequent periods, the controller **17** sets, in the voltage instruction signal **28**, a voltage obtained by adding a predetermined increment voltage that is lower than the initial voltage to the instruction voltage V_c in the immediately previous period as a new instruction voltage V_c , and the voltage instruction section **11** outputs the voltage instruction signal **28** to the control DC power supply **8**.

The signal instruction section **16** controls operation of the signal generator **10** through a communication interface for performing communication such as RS-232C so as to apply a predetermined number of the impulse voltages V_{in} having a predetermined pulse width and a predetermined repetition frequency to the electric motor **2**. More specifically, for controlling the signal generator **10**, the controller **17** generates the square wave instruction signal **29** in which a predetermined pulse width, a predetermined pulse repetition frequency, and a predetermined number are set, and the signal instruction section **16** outputs the square wave instruction signal **29** to the signal generator **10**.

The application voltage signal observation circuit **12** observes the application voltage signal **37** output from the voltage detector **18**. The application voltage signal **37** is transferred to the voltage value acquiring section **13**.

The voltage value acquiring section **13** acquires a value (peak value) of the voltage applied to the electric motor **2** based on the transferred application voltage signal **37**. More specifically, the voltage value acquiring section **13** receives the application voltage signal **37** from the application voltage signal observation circuit **12** in a period in which the partial discharge frequency first reaches a specified frequency or more and acquires a peak value (value of the high voltage V_a) of the voltage represented by the application voltage signal **37**, and the controller **17** sets the voltage peak value as a partial discharge starting voltage.

The detection signal observation circuit **14** observes the detection signal **36** output from the partial discharge detector **4**. The detection signal **36** is then transferred to the partial discharge frequency calculation section **15**.

The partial discharge frequency calculation section **15** inputs thereto the detection signal **36** observed by the detection signal observation circuit **14**, and counts, on a per period basis, an input frequency of the detection signal **36** as a frequency of occurrence of the partial discharge (partial discharge frequency). More specifically, the partial discharge frequency calculation section **15** applies, e.g., digital filtering to the detection signal **36** observed by the detection signal observation circuit **14** to remove unnecessary signal component, thereby extracting only a signal (partial discharge signal) representing the partial discharge. After that, the partial discharge frequency calculation section **15** evaluates an absolute value of the peak value of the partial discharge signal using a predetermined discharge determination threshold, and counts, on a per period basis, the partial discharge frequency based on the evaluation result. In this manner, the partial discharge frequency calculation section **15** counts the number of times that the partial discharge signal is extracted on a per period basis as the partial discharge frequency.

As described above, according to the partial discharge measurement system **1**, a predetermined number of impulse voltages V_{in} having the same peak value, a predetermined pulse width, and a predetermined repetition frequency are

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applied to the electric motor 2, and the frequency of occurrence of the partial discharge is counted every time the predetermined number of impulse voltages are applied. After that, the controller 17 raises stepwise the peak value of the impulse voltage V_{in} through the voltage instruction section 11. Then, when the partial discharge frequency calculation section 15 counts the occurrence of the partial discharge by a specified frequency, the controller 17 regards the voltage at that time as the partial discharge starting voltage.

FIGS. 2A and 2B are each a flowchart illustrating a measurement procedure of a partial discharge starting voltage V_{pdiv} . FIG. 3A is a timing chart illustrating a period setting signal 30, a pulse signal 33, and a rectangular waveform signal 34 which are generated by the signal generator 10 and impulse voltage V_{in} generated by the semiconductor switch 9. FIG. 3B is an enlarged view of a part X of FIG. 3A.

The controller 17 initializes the instruction voltage V_c for indicating the peak value of the impulse voltage generator 3 to an initial voltage V_0 . More specifically, in a first period (corresponding to a first period of the rectangular waveform signal 34) of the period setting signal, the controller 17 generates the voltage instruction signal 28 in which the initial voltage is set as the instruction voltage V_c (step S1).

Then, the controller 17 generates the square wave instruction signal 29 in which a predetermined pulse width (e.g., 10 μ s), a predetermined repetition frequency (e.g., 10 kHz), and a predetermined number (e.g., 10) which are parameters of the impulse voltage V_{in} output from the impulse voltage generator 3 (step S2). The signal instruction section 16 outputs the square wave instruction signal 29 to the signal generator 10 (step S3). The signal generator 10 outputs the rectangular waveform signal 34 having the predetermined pulse width, predetermined repetition frequency, and predetermined number set in the square wave instruction signal 29 (step S4).

The above-mentioned step S4 will be described more specifically.

The period setting signal 30 as illustrated in FIG. 3A is set in the signal generator 10. One period of the period setting signal 30 includes a pulse supply period 31 and a pulse pause period 32 following the pulse supply period 31. The signal generator 10 receives the square wave instruction signal 29 from the measurement device 5, and generates the pulse signal 33 as illustrated in FIG. 3A. The pulse signal 33 represents the predetermined pulse width and predetermined pulse repetition frequency which are set in the square wave instruction signal 29. The pulse repetition frequency is higher than a frequency of the period setting signal 30. The signal generator 10 superimposes the period setting signal 30 and the pulse signal 33 on each other to generate the rectangular waveform signal 34 as illustrated in FIG. 3A. In the rectangular waveform signal 34, a predetermined number of pulse signals 33 set in the square wave instruction signal 29 are generated in only the pulse supply period 31.

Then, the voltage instruction section 11 outputs the voltage instruction signal 28, in which the instruction voltage V_c is set, to the control DC power supply 8 (step S5). At this time, the high-voltage DC power supply 7 outputs the high voltage V_a which is a voltage obtained by multiplying the instruction voltage V_c set in the voltage instruction signal 28 by a set factor A (A is e.g., 3000). As a result, the capacitor 6 is charged with the high voltage V_a . The semiconductor switch 9 repeats ON and OFF based on the rectangular waveform signal 34 output from the signal generator 10 and, thereby, the impulse voltage V_{in} is generated from the charged voltage of the capacitor 6 and is then applied to the electric motor 2 (step S6).

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The above-mentioned step S6 will be described more specifically.

The semiconductor switch 9 is turned OFF when the voltage value of the rectangular waveform signal 34 is lower than a voltage threshold V_g and charges the capacitor 6 with the high voltage V_a from the high-voltage DC power supply 7. On the other hand, the semiconductor switch 9 is turned ON when the voltage value of the rectangular waveform signal 34 is equal to or higher than the voltage threshold V_g and applies the impulse voltage V_{in} as illustrated in FIG. 3A from the capacitor 6 to the electric motor 2. As illustrated in FIG. 3B, the impulse voltage V_{in} has a peak value equal to the value of the high voltage V_a , and the rising time thereof is very short.

Then, the application voltage signal observation circuit 12 observes the application voltage signal 37 output from the voltage detector 18 (step S7). Then, the detection signal observation circuit 14 observes the detection signal 36 output from the partial discharge detector 4 (step S8).

FIG. 4 is a timing chart illustrating waveforms of the application voltage signal 37, the detection signal 36, and the partial discharge signal 38 obtained by applying the digital filtering to the detection signal 36. The partial discharge is generated when a high voltage is applied to a contact portion of enamel wires constituting the winding of the electric motor 2 and, therefore, it is often generated especially in the vicinity of the peak of the impulse voltage V_{in} (application voltage signal 37). When the impulse voltage V_{in} is applied, current flows in the winding of the electric motor 2, and a winding current signal is superimposed on the detection signal 36. When the winding current signal is superimposed on the detection signal 36, the partial discharge starting voltage cannot be measured accurately. To cope with this, an approach that extracts only the partial discharge signal by making the detection signal pass through a filter circuit is widely employed. However, frequency components of the winding current signal and partial discharge signal vary depending on measurement conditions such as a size of the electric motor 2 and a wiring length, so that the filter circuit is provided as needed.

Thus, the partial discharge frequency calculation section 15 calculates an approximate frequency band of the detection signal 36 using a generally-known relational expression between a signal rising time and a frequency band. Assuming that the rising time of the detection signal 36 transferred from the detection signal observation circuit 14 is T_{ri} , and the frequency band thereof is F_{cut} , the frequency band F_{cut} is calculated by $F_{cut}=0.35/T_{ri}$. In the present embodiment, a frequency ten times the frequency band F_{cut} is calculated as a cutoff frequency of the digital filtering (step S9).

A definition of the cutoff frequency will be described more specifically.

Assuming that the rising time T_{ri} of the detection signal 36 is about 290 ns, the frequency band F_{cut} is about 1.2 MHz. The partial discharge signal has a frequency band at least one digit higher than the frequency band F_{cut} . Thus, in the present embodiment, 10 MHz which is a frequency ten times the frequency band F_{cut} (1.2 MHz) is defined as the cutoff frequency.

The partial discharge frequency calculation section 15 applies the digital filtering to the detection signal 36 based on the cutoff frequency (step S10).

In the digital filtering, data obtained by multiplying a plurality of consecutive data in a signal data string by filter coefficients calculated based on the cutoff frequency, respectively, are added to each other to thereby calculate one new data. For example, assume that the data string of the detection signal 36 is set as P (0), P (1), P (2), . . . , P (n-1), the number

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of consecutive data in the data string of the detection signal **36** is set to three, the three consecutive data is set as $P(j-1)$, $P(j)$, and $P(j+1)$, and data string of the filter coefficient is set as $F(0)$, $F(1)$, $F(2)$, $F(n-1)$. In this case, the new data $D(j)$ is calculated by $D(j) = \{P(j-1) \times F(j-1)\} + \{P(j) \times F(j)\} + \{P(j+1) \times F(j+1)\}$ (where, j is 1, . . . , $n-3$).

The partial discharge signal **38** illustrated in FIG. 4 is obtained by applying the digital filtering to the detection signal **38** based on the cutoff frequency 10 MHz. As illustrated in FIG. 4, the detection signal **36** (in this case, the partial discharge signal **38**) after digital filtering is a signal from which the winding current signal, which is an unnecessary signal component, has been removed and has only a signal component caused in response to generation of the partial discharge.

The partial discharge frequency calculation section **15** counts the occurrence frequency of the partial discharge based on the partial discharge signal **38** after digital filtering as follows. The partial discharge frequency calculation section **15** compares an absolute value of the peak value of the partial discharge signal **38** after digital filtering and a discharge determination threshold S_{th} (step **S11**). The partial discharge signal **38** after digital filtering often exhibits an attenuation vibration waveform of a high frequency. Thus, which one of a positive side peak value and a negative side peak value becomes larger in the partial discharge signal **38** after digital filtering cannot be determined. Therefore, even when such a partial discharge signal **38** and discharge determination threshold S_{th} which is a fixed value are compared, it is difficult to accurately determine occurrence of the partial discharge. Thus, the partial discharge frequency calculation section **15** compares the absolute value of the partial discharge signal **38** after digital filtering and discharge determination threshold S_{th} . When the partial discharge signal **38** exceeds the discharge determination threshold S_{th} as a result of the comparison, the partial discharge frequency calculation section **15** determines that a partial discharge has occurred. In this manner, the partial discharge frequency calculation section **15** counts a partial discharge frequency C_{pd} which is the occurrence frequency of the partial discharge.

Then, the controller **17** compares the partial discharge frequency C_{pd} transferred from the partial discharge frequency calculation section **15** and a specified frequency C_{th} (step **S12**). In the present embodiment, the specified frequency C_{th} is set to "5" which is $\frac{1}{2}$ of the above-mentioned predetermined number "10". When the partial discharge frequency C_{pd} is less than the specified frequency C_{th} ("NO" in step **S12**), the controller **17** updates the instruction voltage V_c (step **S13**). More specifically, the controller **17** sets, in the voltage instruction signal **28**, a voltage obtained by adding a predetermined increment voltage ΔV to the instruction voltage V_c in the immediately previous period as a new instruction voltage V_c . The predetermined increment voltage ΔV is set lower than the initial voltage V_0 , and the instruction voltage V_c is set to a voltage higher by the predetermined increment voltage ΔV (e.g., 0.03 V) than the instruction voltage V_c in the immediately previous period ($V_c = V_c + \Delta V$).

Then, the controller **17** determines whether or not a voltage obtained by multiplying the updated instruction voltage V_c by the set factor A , i.e., high voltage V_a , exceeds an upper limit value V_{max} (step **S14**). This step **S14** is provided for preventing an endless loop which may occur when, for example, the partial discharge frequency C_{pd} does not become equal to or more than the specified frequency C_{th} for some cause, such as a fault, even when the high voltage V_a continues to be increased. Thus, the V_{max} should be set to a voltage sufficiently higher than an ordinarily expected partial

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discharge starting voltage. When the high voltage V_a exceeds the upper limit voltage V_{max} ("YES" in step **S14**), this routine is ended. On the other hand, when the high voltage V_a is equal to or lower than the upper limit voltage V_{max} ("NO" in step **S14**), the voltage instruction section **11** outputs, in step **S5**, the voltage instruction signal **28** in which the instruction voltage V_c is set to the control DC power supply **8**, and processing of step **S6** and subsequent steps are executed once again.

On the other hand, when the partial discharge frequency C_{pd} is equal to or more than the specified frequency C_{th} ("YES" in step **S12**), the voltage value acquiring section **13** receives the voltage value applied to the electric motor **2**, i.e., the application voltage signal **37** from the application voltage signal observation circuit **12**, acquires the peak value (value of the high voltage V_a) of the voltage represented by the application voltage signal **37**, and transfers the peak value to the controller **17** (step **S15**). As described above, the voltage value acquiring section **13** acquires the peak value of the voltage from the application voltage signal **37** in the period in which the partial discharge frequency C_{pd} first becomes equal to or more than the specified frequency C_{th} . The controller **17** sets the peak value of the voltage as the partial discharge starting voltage V_{pdv} and ends this routine.

According to the partial discharge measurement of the present embodiment based on the above-mentioned processing, the impulse voltage V_{ain} is applied to the electric motor **2** according to a repeated pattern in which the peak value of the impulse voltage V_{ain} is increased stepwise by voltage $A \times \Delta V$ every time the ten impulse voltages V_{ain} have been applied until the partial discharge frequency C_{pd} becomes equal to or more than the specified frequency C_{th} ("YES" in step **S12**).

FIG. 5 is a timing chart illustrating the impulse voltage V_{ain} and partial discharge frequency C_{pd} on a per period basis. In FIG. 5, assuming that an amplification factor (the above-mentioned factor A) by the high DC voltage is 3000, an initial value of the instruction voltage V_c is V_0 (e.g., 0.4 V), and the predetermined increment voltage ΔV is, e.g., 0.03 V, a boosting range of a voltage to be applied is 90 V ($=3000 \times 0.03$ V), and the high voltage V_a after m -th update is represented as $V_m (=A \times V_c)$. As illustrated in FIG. 5, in a period during which the instruction voltage V_c is V_0 to V_4 , that is, in a period during which the impulse voltage V_{ain} is 1200 V ($3000 \times V_0$) to 1520 V ($3000 \times V_4$), the partial discharge frequency C_{pd} is less than the specified frequency C_{th} . Note that in a period $PDIV$ during which the instruction voltage is V_3 , the partial discharge frequency C_{pd} is first counted. In a period $RPDIV$ during which the instruction voltage V_c is V_5 , that is, in a period during which the impulse voltage V_{ain} is 1610 V ($3000 \times V_5$), the partial discharge frequency C_{pd} is equal to or more than the specified frequency C_{th} . In this period $RPDIV$, it is determined that the partial discharge starting voltage V_{pdv} has occurred, and the boost of the impulse voltage V_{ain} is stopped.

After calculation of the partial discharge starting voltage V_{pdv} in this manner, it is possible to measure also a partial discharge extinction voltage. In this case, the voltage instruction section **11** controls the control DC power supply **8** and signal generator **10** such that the impulse voltage V_{ain} is applied to the electric motor **2** according to a repeated pattern in which the peak value of the impulse voltage V_{ain} is reduced stepwise every time a predetermined number of the impulse voltages V_{ain} having the same peak value have been applied.

FIGS. 6A to 6D are flowcharts each illustrating a measurement procedure of the partial discharge starting voltage V_{pdv} and partial discharge extinction voltage V_{pdev} .

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In the flowcharts of FIGS. 6A to 6D, the processing from step S1 to step S15 is the same as that illustrated in the flowcharts of FIGS. 2A and 2B. After step S15, the controller 17 updates the instruction voltage V_c (step S21). More specifically, the controller 17 sets, in the voltage instruction signal 28, a voltage obtained by subtracting the predetermined voltage ΔV from the instruction voltage V_c in the immediately previous period as a new instruction voltage V_c . That is, the new instruction voltage V_c is set to a voltage lower by the predetermined increment voltage (e.g., 0.03 V) than the instruction voltage V_c in the immediately previous period ($V_c = V_c - \Delta V$).

Then, the controller 17 determines whether or not a voltage obtained by multiplying the updated instruction voltage V_c by the set factor A, i.e., high voltage $V_a (= A \times V_c)$ falls below a lower limit value V_{min} (step S22). This step S22 is provided for a similar reason as in step S15 of FIG. 2B. Thus, the V_{min} should be set to a voltage sufficiently lower than the ordinary expected partial discharge extinction voltage. When the high voltage V_a falls below the lower limit voltage V_{min} ("YES" in step S22), this routine is ended. On the other hand, when the high voltage V_a is equal to or higher than the lower limit voltage V_{min} ("NO" in step S22), the voltage instruction section 11 outputs the voltage instruction signal 28 in which the instruction voltage V_c is set to the control DC power supply 8 (step S23). After that, processing from step S24 to step S29 which is similar to that from step S6 to step S11 illustrated in FIGS. 2A and 2B is executed.

Then, the controller 17 compares the specified frequency C_{th} and partial discharge frequency C_{pd} (step S30). When the partial discharge frequency C_{pd} is equal to or more than the specified frequency C_{th} ("YES" in step S30), the processing flow returns to step S21.

On the other hand, when the partial discharge frequency C_{pd} is less than the specified frequency C_{th} ("NO" in step S30), the voltage value acquiring section 13 receives the voltage value applied to the electric motor 2, i.e., the application voltage signal 37 from the application voltage signal observation circuit 12, acquires the peak value (value of the high voltage V_a) of the voltage represented by the application voltage signal 37, and transfers the peak value to the controller 17 (step S31). As described above, the voltage value acquiring section 13 acquires the peak value of the voltage from the application voltage signal 37 in a period in which the partial discharge frequency C_{pd} first becomes less than the specified frequency C_{th} after the period $RPDIV$ in which the partial discharge starting voltage V_{pdv} is calculated. The controller 17 sets the peak value of the voltage as the partial discharge extinction voltage V_{pdev} and ends this routine.

As illustrated in FIG. 5, in a period $RPDEV$ in which the instruction voltage V_c is V_7 , that is, the impulse voltage V_{ain} is 1430 V ($3000 \times V_7$), the partial discharge frequency C_{pd} is less than the specified frequency C_{th} . Further, in a period $PDEV$ in which the instruction voltage V_c is V_9 , that is, the impulse voltage V_{ain} is 1250 V ($3000 \times V_9$), the partial discharge frequency C_{pd} is not counted.

As described above, the partial discharge measurement system 1 according to the present embodiment applies to the electric motor 2 a predetermined number of impulse voltages V_{ain} having a predetermined pulse width and a predetermined repetition frequency, and calculates the partial discharge frequency C_{pd} , every time the impulse voltages are applied. A user can perform various partial discharge measurement works, such as measurement of the partial discharge starting voltage V_{pdv} and the partial discharge extinction voltage V_{pdev} by using the partial discharge frequency C_{pd} and the like acquired by the partial discharge measurement

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system 1. As described above, according to the partial discharge measurement system 1 of the present embodiment, it is possible to reduce works that the user performs such a work (e.g., reading of a meter or displayed numerical values) that may affect measurement accuracy. As a result, highly accurate partial discharge measurement can be performed.

In the measurement of the partial discharge starting voltage V_{pdv} , boost of the impulse voltage V_{ain} is stopped when it is determined that the partial discharge frequency C_{pd} is equal to or more than the specified frequency C_{th} . Further, in the measurement of the partial discharge extinction voltage V_{pdev} , the application of the impulse voltage V_{ain} is stopped when it is determined that the partial discharge frequency C_{pd} is less than the specified frequency C_{th} . With the above configuration, a time required for the partial discharge measurement can be reduced. Further, application of an excessive voltage to the winding of the electric motor 2 to be measured can be suppressed to thereby prevent the object to be measured from suffering damage due to overloading.

The measurement device 5 observes the application voltage signal 37 or detection signal 36 every time a predetermined number of the impulse voltages V_{ain} having the same peak value is applied. The impulse voltage generator 3 can change the pulse width, repetition frequency, and the number of the impulse voltages V_{ain} to be applied, thereby reducing the amount of memory necessary for observing the application voltage signal 37 or detection signal 36, which can in turn reduce a time required for the partial discharge frequency calculation section 15 to perform data processing.

The partial discharge frequency calculation section 15 calculates a frequency band of the winding current signal included in the detection signal 36 from the rising time Tri of the detection signal 36 observed by the detection signal observation circuit 14 and applies digital filtering to the detection signal using the calculated frequency as the cutoff frequency to remove the winding current signal included in the detection signal 36 and then counts the occurrence frequency of the partial discharge. This can enhance measurement accuracy of the partial discharge starting voltage V_{pdv} . Further, even when parameters that contribute to the frequency of the detection signal 36, such as a load and a wiring length, are changed, it is unnecessary to use a new filter.

In the present embodiment, the cutoff frequency used in the digital filtering is calculated every time the detection signal 36 is measured; however, it is no longer necessary to newly calculate the cutoff frequency after it is once determined. Alternatively, the cutoff frequency may be calculated from the rising time of the detection signal 36 that is measured before measurement of the partial discharge starting voltage V_{pdv} or the cutoff frequency may be determined from a frequency spectrum result obtained through Fourier transform processing.

Further, in the present embodiment, the parameters, such as the initial voltage V_0 , predetermined pulse width, predetermined repetition frequency, and predetermined number, which are set in the above-mentioned steps S1 and S2 may be input by the user on a screen of the measurement device 5.

Further, in the present embodiment, the above-mentioned step S9 may be replaced by the following processing. The partial discharge frequency calculation section 15 receives the application voltage signal 37 observed by the application voltage signal observation circuit 12, calculates the frequency band F_{cut} according to $F_{cut} = 0.35 / Tri$ wherein Tri is the rising time of the application voltage signal 37, and sets the obtained F_{cut} as the cutoff frequency for use in the digital filtering. A flow of a signal from the application voltage signal observa-

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tion circuit 12 to partial discharge frequency calculation section 15 at this time is denoted by a dashed line of FIG. 1.

For example, in FIG. 4, the rising time (300 ns) of the application voltage signal 37 and rising time (290 ns) of the detection signal 36 are nearly equal to each other. Therefore, the frequency band F_{cut} becomes about 1.2 MHz irrespective of whether the frequency band F_{cut} is calculated from the rising time (about 290 ns) of the detection signal 36 or rising time of the application voltage signal 37. The partial discharge signal has a frequency band of at least one digit higher than the frequency band F_{cut} , so that 10 MHz which is a frequency ten times the frequency band F_{cut} (1.2 MHz) can be defined as the cutoff frequency.

Further, in the present embodiment, the above-mentioned steps S9 and S10 may be replaced by the following processing. That is, the partial discharge frequency calculation section 15 may apply digital differential processing to the detection signal 36 transferred from the detection signal observation circuit 14.

In the digital differential processing, one new data by calculating a difference between first and second data constituting a signal data string is obtained. For example, assuming that the data string of the detection signal 36 is set as $P(0)$, $P(1)$, $P(2)$, ..., $P(n-1)$, the new data string is set as $D(0)$, $D(1)$, $D(2)$, ..., $D(n-1)$, and a sampling frequency is set as T_s , the new data $D(k)$ is calculated by $D(k) = \{P(k) - P(k-1)\} / T_s$ (where, k is 1, ..., $n-1$). The division by T_s need not be performed. Further, to improve accuracy, the data $D(k)$ may be calculated by $D(k) = \{P(k+1) - P(k-1)\} / 2 T_s$ (where, k is 1, ..., $n-2$).

FIG. 7 is a timing chart illustrating a waveform of the partial discharge signal 38 obtained by applying the digital differential processing to the detection signal 36 of FIG. 4. A change of the partial discharge signal 38 is steeper than a change of the winding current signal. Thus, in the present embodiment, by performing the digital differential processing, a signal waveform similar to a signal waveform that has been subjected to the digital filtering can be obtained at a partial discharge generation portion, thereby allowing detection of the partial discharge. As described above, the partial discharge frequency calculation section 15 can count the occurrence frequency of the partial discharge after applying the digital differential processing to the detection signal 36.

(Second Embodiment)

A partial discharge measurement system according to a second embodiment will be described focusing on only differences from the first embodiment. Parts that are not particularly described are the same as those in the first embodiment.

FIG. 8 is a block diagram illustrating a schematic configuration of the partial discharge measurement system according to the second embodiment.

The DC power supply 22 of the impulse voltage generator 8 includes, in place of the control DC power supply 8, a control DC power supply 19. The measurement device 5 includes, in place of the voltage instruction section 11 and controller 17, a voltage instruction section 20 and a controller 21, respectively. The control DC power supply 19 is a power supply that can output a ramp voltage, and the voltage instruction section 20 outputs a voltage instruction signal 28 in which a ramp voltage according to a predetermined pulse repetition frequency is set as the above-mentioned instruction voltage V_c to the control DC power supply 19.

FIGS. 9A to 9D are flowcharts each illustrating a measurement procedure of the partial discharge starting voltage V_{pdiv} and partial discharge extinction voltage V_{pdev} .

The controller 21 generates the voltage instruction signal 28 in which a start voltage V_0 same as the initial voltage V_0

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of the first embodiment, an upper limit voltage V_u , and a rising time T_u are set (step SS1). Processing from step S2 to step S4 is the same as that illustrated in the flowcharts of FIGS. 2A and 6A. Then, the voltage instruction section 20 outputs the voltage instruction signal 28 in which the start voltage V_0 , the upper limit voltage V_u , and the rising time T_u are set to the control DC power supply 19 (step SS2). As a result, the control DC power supply 19 starts boosting the initial voltage V_0 toward the upper voltage V_u with the rising time T_u (step SS3).

Processing from step S6 to step S11 is the same as that illustrated in the flowcharts of FIGS. 2A, 2B and 6A, 6B.

Then, the controller 21 compares the specified frequency C_{th} and the partial discharge frequency C_{pd} transferred from the partial discharge frequency calculation section 15 (step SS4). When the partial discharge frequency C_{pd} is less than the specified frequency C_{th} ("NO" in step SS4), the processing flow returns to step S6. On the other hand, when the partial discharge frequency C_{pd} is equal to or more than the specified frequency C_{th} ("YES" in step SS4), the processing flow proceeds to step S15, where the controller 21 sets the voltage value calculated by the voltage value acquiring section 13 as the partial discharge starting voltage V_{pdiv} .

Then, the controller 21 generates the voltage instruction signal 28 in which an end voltage V_e and a descending time T_d are set (step SS5). The voltage instruction section 20 outputs the voltage instruction signal 28 in which the end voltage V_e and descending time T_d are set to the control DC power supply 19 (step SS6). The control DC power supply 19 starts descending the voltage V_{pdiv} toward the end voltage V_e with the descending time T_d (step SS7).

Hereinafter, processing from step S6 to step S11 is the same as that illustrated in the flowcharts of FIGS. 2A and 2B.

Then, the controller 21 compares the specified frequency C_{th} and partial discharge frequency C_{pd} (step SS8). When the partial discharge frequency C_{pd} is equal to or more than the specified frequency C_{th} ("YES" in step SS8), the processing flow returns to step S6. On the other hand, when the partial discharge frequency C_{pd} is less than the specified frequency C_{th} ("NO" in step SS8), the controller 21 sets the voltage value acquired by the voltage acquisition section 13 as the partial discharge extinction voltage V_{pdev} in step S31 of FIG. 9D.

FIG. 10 is a timing chart illustrating the rectangular waveform signal 34, the instruction voltage of the ramp output, the high voltage V_a , and the impulse voltage V_{ain} .

A voltage obtained by multiplying an output voltage of the control DC power supply 19 by a factor A (A is e.g., 3000) is output from the high-voltage DC power supply 7, and the semiconductor switch 9 repeats ON and OFF based on the rectangular waveform signal 34. As a result, the impulse voltage V_{ain} of the ramp output is generated in the impulse voltage generator 3. According to the partial discharge measurement based on the above processing, assuming that the amplification factor of the high-voltage DC power supply 7 is 3000, the start voltage V_0 of the ramp voltage output from the control DC power supply 19 is 0.3 V, the upper voltage V_u is 0.7 V, and the rising time is 12 sec, the impulse voltage to be applied to the electric motor 2 is increased at 100 V/sec. Assuming that the pulse width of one impulse voltage V_{ain} is 10 μ s, repetition frequency is 10 kHz, and ten impulse voltages V_{ain} are grouped into one block, a time required from the start of the one block to the end thereof is 1 msec, and a boosting voltage in 1 msec is 0.1 V. Since the start voltage which is the minimum voltage applied to the electric motor 2 is 900 V, the boosting voltage of 0.1 V in one block is sufficiently smaller than 900 V and can be negligible. Thus, even

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in a configuration in which the control DC power supply 19 outputs the ramp voltage, a predetermined number of impulse voltages V_{ain} having substantially the same peak value can be applied. Further, assuming that a time interval between one block (including ten pulses) and the next block is set to, e.g., 10 msec, the impulse voltage V_{ain} is boosted at 1 V in 10 msec. As a result, it is possible to apply a predetermined number of the impulse voltages V_{ain} having substantially the same peak value as illustrated in FIG. 11 to the electric motor 2 while boosting the impulse voltage by 1 V.

As described above, in the partial discharge measurement system according to the present embodiment, control is performed such that the ramp voltage rising in a predetermined rising time is output from the control DC power supply 19, and the pulse width, the repetition frequency, and the predetermined number of the impulse voltage V_{ain} is controlled by the output signal of the signal generator 10, so that it is possible to finely set a rising width between a predetermined number of the impulse voltages V_{ain} having the same peak value and a predetermined number of the impulse voltages in the next block having the same peak value. The finely setting the rising width of the voltage allows the partial discharge starting voltage V_{pdiv} or partial discharge extinction voltage V_{pdev} to be measured more accurately.

While certain embodiments have been described, these embodiments have been presented by way of example only, and are not intended to limit the scope of the inventions. Indeed, the novel embodiments described herein may be embodied in a variety of other forms; furthermore, various omissions, substitutions and changes in the form of the embodiments described herein may be made without departing from the spirit of the inventions. The accompanying claims and their equivalents are intended to cover such forms or modifications as would fall within the scope and spirit of the inventions.

EXPLANATION OF REFERENCE NUMERALS

1: partial discharge measurement system
 2: electric motor (object to be measured)
 3: impulse voltage generator
 4: partial discharge detector
 5: measurement device
 6: capacitor
 7: high-voltage DC power supply
 8: control DC power supply
 9: semiconductor switch
 10: signal generator
 11: voltage instruction section
 12: application voltage signal observation circuit
 13: voltage value acquiring section
 14: detection signal observation circuit
 15: partial discharge frequency calculation section
 16: signal instruction section
 17: controller
 18: voltage detector
 19: control DC power supply
 20: voltage instruction section
 21: controller
 22: DC power supply
 23: resistive element
 24: resistive element
 25: resistive element
 26: output terminal
 27: output terminal
 28: voltage instruction signal
 29: square wave instruction signal

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30: period setting signal
 31: pulse supply period
 32: pulse pause period
 33: pulse signal
 34: rectangular waveform signal
 36: detection signal
 37: application voltage signal
 38: partial discharge signal

What is claimed is:

1. A partial discharge measurement system based on repeated impulse voltage, the system comprising:
 - a DC power supply that outputs high voltage as a voltage obtained by multiplying an instruction voltage by a set factor;
 - a signal generator that generates a pulse signal representing a predetermined pulse width and a predetermined pulse repetition frequency, and superimposes a period setting signal whose one period includes a pulse supply period and a pulse pause period following the pulse supply period and the pulse signal on each other to generate a rectangular waveform signal in which a predetermined number of the pulse signals are generated only in the pulse supply period;
 - a semiconductor switch that charges a capacitive element with the high voltage from the DC power supply when a voltage value of the rectangular waveform signal is lower than a preset voltage threshold, while applies an impulse voltage having a peak value equal to a value of the high voltage from the capacitive element to an object to be measured when the voltage value of the rectangular waveform signal is equal to or higher than the voltage threshold;
 - a signal instruction section that outputs, to the signal generator, a square wave instruction signal in which the predetermined pulse width, the predetermined pulse repetition frequency, and the predetermined number are set;
 - a voltage instruction section that outputs, to the DC power supply, a voltage instruction signal in which an initial voltage is set as the instruction voltage in a first period of the rectangular waveform signal and sets in the voltage instruction signal, in second and subsequent periods, a voltage obtained by adding a predetermined increment voltage lower than the initial voltage to the instruction voltage in the immediately previous period as the instruction voltage;
 - a detection signal observation circuit that observes a detection signal based on a partial discharge generated in the object to be measured to which the impulse voltages are applied;
 - a partial discharge frequency calculation section that counts the number of inputs of the detection signal on a per period basis as a partial discharge frequency;
 - an application voltage signal observation circuit that observes an application voltage signal representing the impulse voltage to be applied to the object to be measured; and
 - a voltage value acquiring section that sets, in a period in which the partial discharge frequency first becomes equal to or more than a specified frequency, a peak value of a voltage represented by the application voltage signal from the application voltage signal observation circuit as a partial discharge starting voltage.
2. The partial discharge measurement system based on repeated impulse voltage, according to claim 1, wherein the partial discharge frequency calculation section applies digital filtering to the detection signal to remove an

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unnecessary signal component from the detection signal so as to extract only a partial discharge signal representing the partial discharge, and counts, on a per period basis, the number of times that the partial discharge signal is extracted as the partial discharge frequency.

3. The partial discharge measurement system based on repeated impulse voltage, according to claim 2, wherein the partial discharge frequency calculation section calculates a cutoff frequency for use in digital filtering based on a rising time of the detection signal, and applies the digital filtering to the detection signal based on the calculated cutoff frequency.

4. The partial discharge measurement system based on repeated impulse voltage, according to claim 1, wherein the partial discharge frequency calculation section applies digital filtering to the application voltage signal to remove an unnecessary signal component from the application voltage signal so as to extract only a partial discharge signal representing the partial discharge, and counts, on a per period basis, the number of times that the partial discharge signal is extracted as the partial discharge frequency.

5. The partial discharge measurement system based on repeated impulse voltage, according to claim 4, wherein the partial discharge frequency calculation section calculates a cutoff frequency for use in digital filtering based on a rising time of the application voltage signal, and applies the digital filtering to the application voltage signal based on the calculated cutoff frequency.

6. The partial discharge measurement system based on repeated impulse voltage, according to claim 2, wherein the partial discharge frequency calculation section applies digital differential processing to the detection signal to remove the unnecessary signal component from the detection signal so as to extract only the partial discharge signal.

7. The partial discharge measurement system based on repeated impulse voltage according to claim 1, wherein in a period after a period in which the partial discharge starting voltage is acquired by the voltage value acquiring section, the voltage instruction section outputs, to the DC power supply, the voltage instruction signal in which a voltage obtained by subtracting the predetermined voltage from the instruction voltage in the immediately previous period as the instruction voltage, and the voltage value acquiring section acquires, as a partial discharge extinction voltage, a peak value of a voltage represented by the application voltage signal from the application voltage signal observation circuit in a period in which the partial discharge frequency first becomes less than the specified frequency after the period in which the partial discharge starting voltage is acquired.

8. The partial discharge measurement system based on repeated impulse voltage according claim 1, wherein the DC power supply is a power supply that can output a ramp voltage, and

the voltage instruction section outputs, to the DC power supply, the voltage instruction signal in which a ramp voltage according to the predetermined pulse repetition frequency is set as the instruction voltage.

9. A measurement device for a partial discharge measurement system based on repeated impulse voltage, the system including: a DC power supply that outputs high voltage as a voltage obtained by multiplying an instruction voltage by a set factor; a signal generator that generates a pulse signal representing a predetermined pulse width and a predetermined pulse repetition frequency and superimposes a period

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setting signal whose one period includes a pulse supply period and a pulse pause period following the pulse supply period and the pulse signal on each other to generate a rectangular waveform signal in which a predetermined number of the pulse signals are generated only in the pulse supply period; and a semiconductor switch that charges a capacitive element with the high voltage from the DC power supply when a voltage value of the rectangular waveform signal is lower than a preset voltage threshold, while applies an impulse voltage having a peak value equal to a value of the high voltage from the capacitive element to an object to be measured when the voltage value of the rectangular waveform signal is equal to or higher than the voltage threshold,

the measurement device comprising:

a signal instruction section that outputs, to the signal generator, a square wave instruction signal in which the predetermined pulse width, the predetermined pulse repetition frequency, and the predetermined number are set;

a voltage instruction section that outputs, to the DC power supply, a voltage instruction signal in which an initial voltage is set as the instruction voltage in a first period of the rectangular waveform signal and sets in the voltage instruction signal, in second and subsequent periods, a voltage obtained by adding a predetermined increment voltage lower than the initial voltage to the instruction voltage in the immediately previous period as the instruction voltage;

a detection signal observation circuit that observes a detection signal based on a partial discharge generated in the object to be measured to which the impulse voltages are applied;

a partial discharge frequency calculation section that counts the number of inputs of the detection signal on a per period basis as a partial discharge frequency;

an application voltage signal observation circuit that observes an application voltage signal representing the impulse voltage to be applied to the object to be measured; and

a voltage value acquiring section that sets, in a period in which the partial discharge frequency first becomes equal to or more than a specified frequency, a peak value of a voltage represented by the application voltage signal from the application voltage observation circuit as a partial discharge starting voltage.

10. A measurement method for a partial discharge measurement system based on repeated impulse voltage, the system including: a DC power supply that outputs high voltage as a voltage obtained by multiplying an instruction voltage by a set factor; a signal generator that generates a pulse signal representing a predetermined pulse width and a predetermined pulse repetition frequency, and superimposes a period setting signal whose one period includes a pulse supply period and a pulse pause period following the pulse supply period and the pulse signal on each other to generate a rectangular waveform signal in which a predetermined number of the pulse signals are generated only in the pulse supply period; and a semiconductor switch that charges a capacitive element with the high voltage from the DC power supply when a voltage value of the rectangular waveform signal is lower than a preset voltage threshold, while applies an impulse voltage having a peak value equal to a value of the high voltage from the capacitive element to an object to be measured when the voltage value of the rectangular waveform signal is equal to or higher than the voltage threshold,

the measurement method comprising steps of:
outputting, to the signal generator, a square wave instruction signal in which the predetermined pulse width, the predetermined pulse repetition frequency, and the predetermined number are set; 5
outputting, to the DC power supply, a voltage instruction signal in which an initial voltage is set as the instruction voltage in a first period of the rectangular waveform signal, and setting in the voltage instruction signal, in second and subsequent periods, a voltage obtained by adding a predetermined increment voltage lower than the initial voltage to the instruction voltage in an immediately previous period as the instruction voltage; 10
observing, using a detection signal observation circuit, a detection signal based on a partial discharge generated in the object to be measured to which the impulse voltages are applied; 15
counting the number of inputs of the detection signal on a per period basis as a partial discharge frequency;
observing, using an application voltage signal observation circuit, an application voltage signal representing the impulse voltage to be applied to the object to be measured; and 20
setting, in a period in which the partial discharge frequency first becomes equal to or more than a specified frequency, a peak value of a voltage represented by the application voltage signal from the application voltage observation circuit as a partial discharge starting voltage. 25

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