# **Project Documentation**

## Pi1541 HAT

Project number: 111

Revision: 1

Date: 26.02.2019

#### Pi1541-HAT Rev. 1

### Module description

### Description

The Pi1541 HAT is the required electrical and user interface for the Raspberry Pi (Model 3, 3+ or better) to emulate the Commodore 1541 floppy disk drive in conjunction with Steve White's software project (<a href="https://cbm-pi1541.firebaseapp.com/">https://cbm-pi1541.firebaseapp.com/</a>). This software is a cycle exact, real-time emulation of the 1541. The disk images are stored on the SD-card of the Raspberry Pi and the switches and the display (of the HAT) allow the user to navigate through his disk archive. Since Pi1541 emulates the exact hardware of the 1541, it is compatible to every speed loader, that work with the original disk drive.

This Pi1541 HAT is one of many possible variants. It holds the original I/O-driver configuration of the 1541, which is then adapted to the Raspberry Pi. The user interface consists of an OLED-display, six switches and a piezo buzzer, which resembles the sound of the working stepper motor.

Further on, it is designed to offer a good flexibility. The display can be either connected to a 4 pole receptable on the board or it can be detached and connected with a small piece of ribbon cable. The switches can also be soldered on the PCB or on a little extra PCB (Pi1541-Switch), which also holds two LEDs and is designed for a front panel mount. The two IEC-connectors can be mounted on this PCB or a separate PCB (Pi1541-IEC), which also holds a RESET switch and a barrel connector for a 5V power supply.

#### Pin outs

#### IEC-Bus

J1 and J2 – Lumberg 010599 06, 6p DIN receptables

Pin	Signal
1	/SRQ (not used in this design)
2	GND
3	ATN
4	CLK
5	DATA
6	/RESET

#### IEC Bus (break out board)

X1 – 10p Micro Match receptible, female, vertical, through hole, e.g. MPE Garry 369-1-010

X1 can be assembled instead of J1 and J2

Pin	Signal
1	/SRQ (not used in this design)
2	GND
3	ATN
4	CLK
5	DATA
6	/RESET
7	+5V
8	+5V
9	GND
10	GND

#### Display

M2 - A 0.96" OLED display ( $I^2C$ ) can be connected to the 4p receptable M2 (0.1" pin distance). This connector provides +3.3V supply voltage. It is important to check the pinning of the display. Some might have swapped +3.3V and GND, so inserting those displays will destroy them.

From left to right:

Pin	Signal
1	VCC
2	GND
3	SCL
4	SDA

#### External Display

In case the display is desired to be mounted externally or it is bigger than the footprint (e.g. 1.3") or it has a different pin sequence such as GND, VCC etc. it can be attached to this connector.

X2 – 4p Micro Match receptible, female, vertical, through hole, e.g. MPE Garry 369-1-004

Pin	Signal
1	VCC
2	GND
3	SCL
4	SDA

#### **External Switches**

X3 – 8p Micro Match receptible, female, vertical, through hole, e.g. MPE Garry 369-1-008

Pin	Signal
1	/SW1
2	/SW2
3	/SW3
4	/SW4
5	/SW5
6	LED_OUT (LD1)
7	+3V3
8	GND

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### Raspberry Pi Connector

A 2x20 Pin receptible, assembled on the solder side of the PCB.

Pin	GPIO	Signal	Comment	
1	-	+3.3V	Supply voltage	
2	-	+5V	Supply voltage	
3	SDA	SDA (I <sup>2</sup> C)	I <sup>2</sup> C-Bus (display)	
4	-	+5V	Supply voltage	
5	SCL	SCL (I <sup>2</sup> C)	I <sup>2</sup> C-Bus (display)	
6	-	GND	Ground	
7	4	/SW4_IN	Switch 4, active low	
9	-	GND	Ground	
11	17	/CLK_OUT	/CLK_(output to IEC-Bus driver)	
12	18	/DATA_OUT	/DATA (output to IEC-Bus driver)	
13	27	/SW1_IN	Switch 1, active low	
14	-	GND	Ground	
15	22	/SW2_IN	Switch 2, active low	
16	23	/SW3_IN	Switch 3, active low	
17	-	+3.3V	Supply voltage	
18	24	ATN_IN	ATN (IEC-Bus), 3.3V-level	
20	-	GND	Ground	
22	25	DATA_IN	DATA (IEC-Bus), 3.3V-level	
25	-	GND	Ground	
27	ID_SD	ID_SD	Secondary I <sup>2</sup> C: SDA	
28	IC_SC	ID_SC	Secondary I <sup>2</sup> C: SCL	
29	5	/SW5_IN	Switch 5, active low	
30	-	GND	Ground	
33	13	SND_OUT	Sound/Piezo buzzer	
34	-	GND	Ground	
36	16	LED_OUT	Activity LED	
37	26	CLK_IN	CLK (IEC-Bus), 3.3V-level	
38	20	/RESET_IN	/RESET (IEC-Bus), 3.3V-level	
39	-	GND	Ground	

## **Jumpers**

JP1 and JP2 are smd jumpers (to be bridged by a 0603 resistor/ $0\Omega$ ). The I<sup>2</sup>C bus for the display can be selected. For a proper function, they should both be bridged between 1-2. This selects the primary I<sup>2</sup>C-bus.

### **Switches**

Switch	Function
SW1 (left)	Select/Reset
SW2	Move Up/Previous Disk
SW3	Move Down/Next Disk
SW4	Exit Folder
SW5 (right)	Insert Disk

SW6 is a RESET switch for the IEC-Bus

### Configuration

The configuration of the software can be found in the root directory of the micro SD-card (options.txt). It has to be edited before powering up the Raspberry Pi for the first time.

Since there are input and output drivers, for the bidirectional IEC-Bus signals signal, the parameter has to be set in the following way:

```
splitIECLines = 1
```

There is a buzzer acting as a sound device for resembling the working stepper motor of the real drive:

```
SoundOnGPIO = 1
```

```
SoundOnGPIODuration = 70 // Length of buzz in micro seconds
SoundOnGPIOFreq = 900 // Frequency of buzz in Hz
```

The I<sup>2</sup>C-Bus for the display requires this configuration:

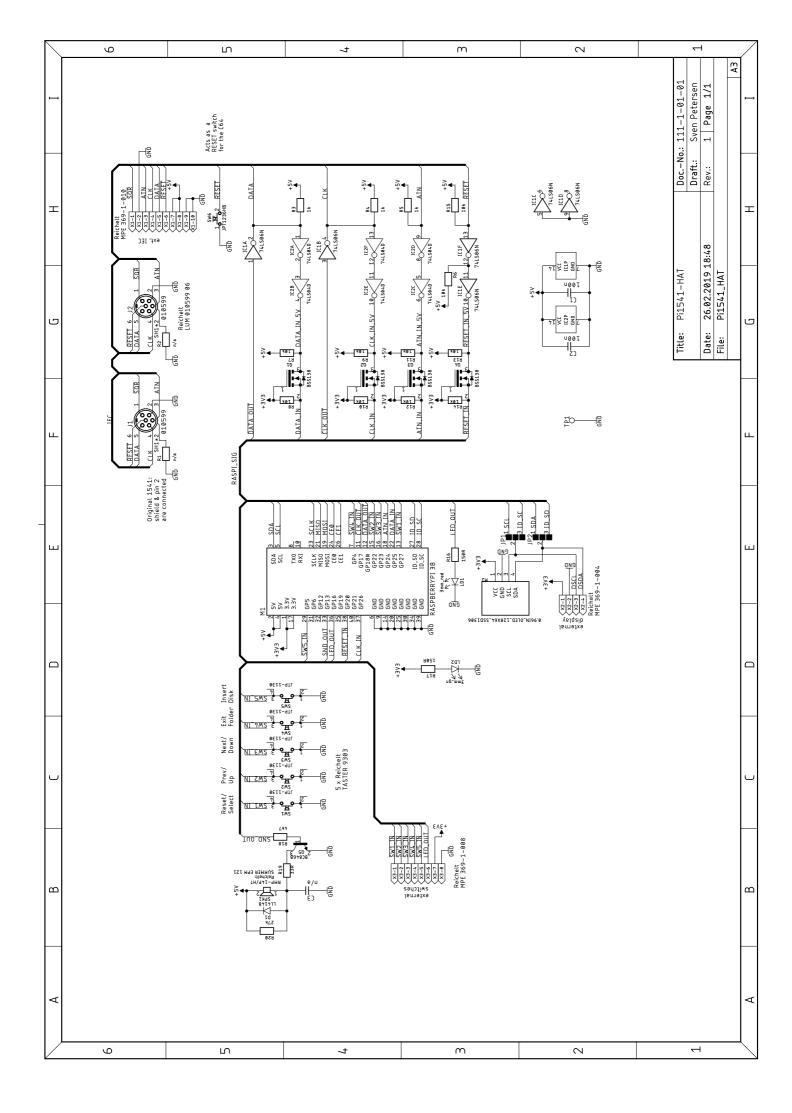
```
i2cBusMaster = 1 //SDA - pin 3 SCL - pin 5
```

More information about the configuration and setup can be found on the Pi1541 project website mentioned above. It is highly recommended to read the instructions there before setting up the SD card.

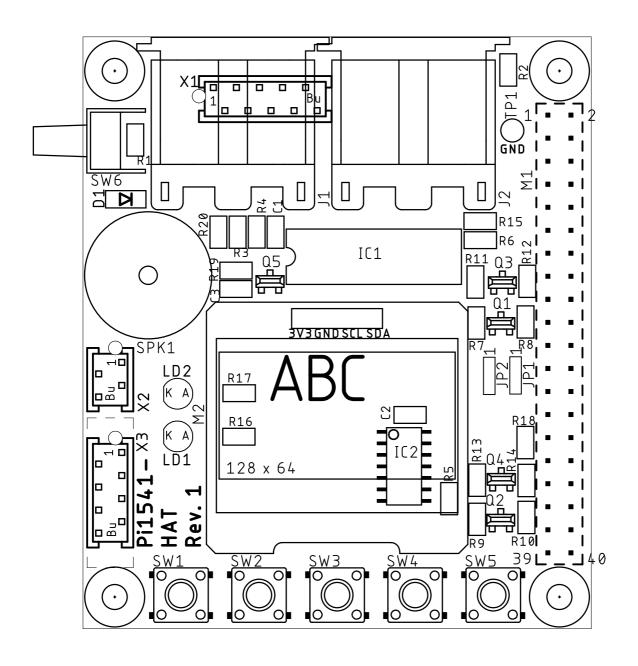
### Revision history

Rev.  $0 \rightarrow \text{Rev. } 1$ 

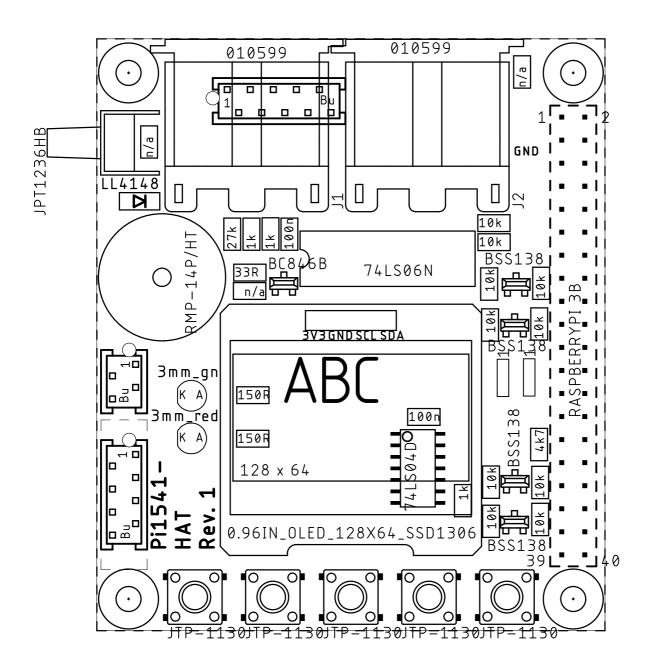
- R20 added, due to the SND\_OUT being High during idle
- X1 became 10p to enable a power supply being connected on the external IEC-Board
- Added TP1 as a ground connection for measurement



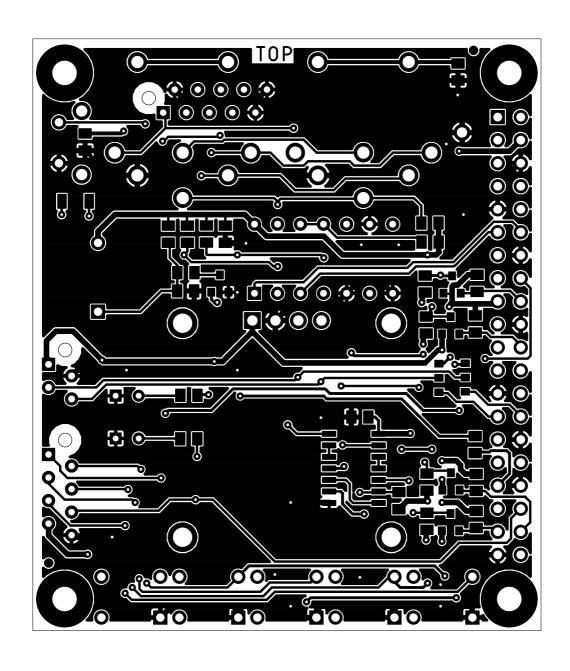
Sven Petersen	DocNo.: 111-2-01-01	
2019	<b>Cu:</b> 35µm	Cu-Layers: 2
Pi1541_HAT		
27.02.2019 13:04		Rev.: 1
placement component side		



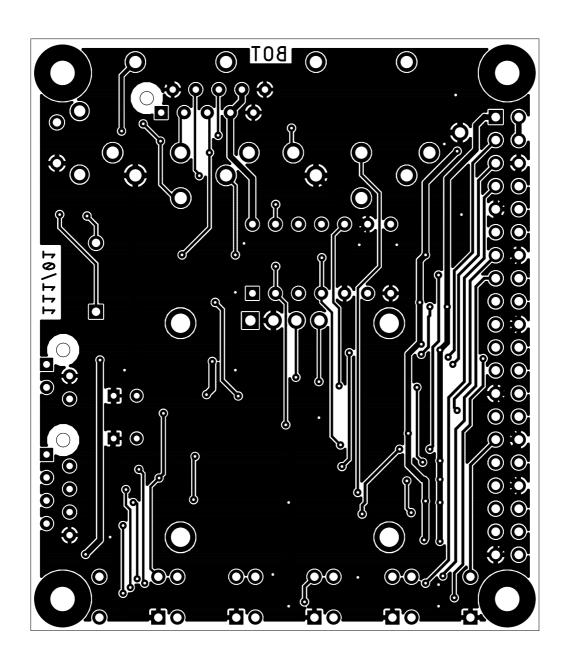
Sven Petersen	DocNo.: 111-2-01-01	
2019	<b>Cu:</b> 35μm	Cu-Layers: 2
Pi1541_HAT		
27.02.2019 10:13		Rev.: 1
placement component side		



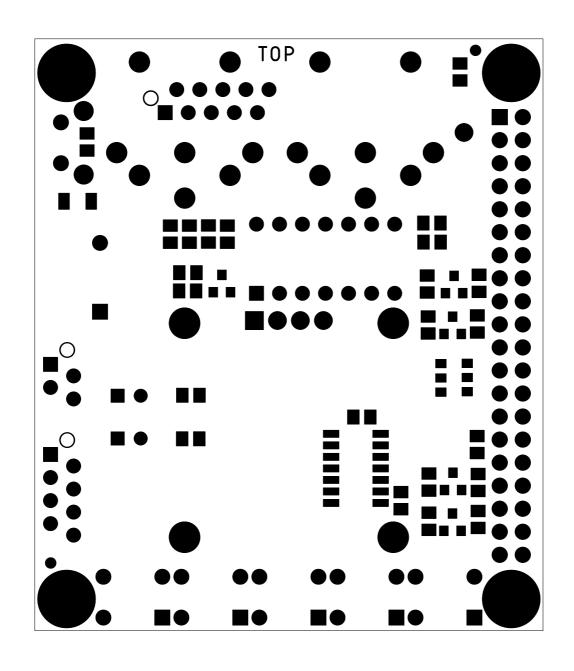
Sven Petersen	DocNo.: 111-2-01-01		
2019	Cu: 35µm	Cu-Layers: 2	
Pi1541_HAT			
27.02.2019 10:13		Rev.: 1	
top			



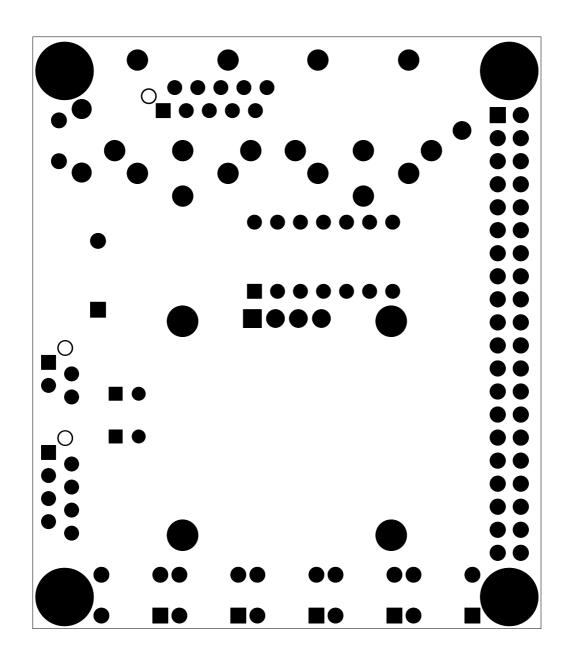
Sven Petersen	DocNo.: 111-2-01-01		
2019	Cu: 35µm	Cu-Layers: 2	
Pi1541_HAT			
27.02.2019 10:13		Rev.: 1	
bottom			



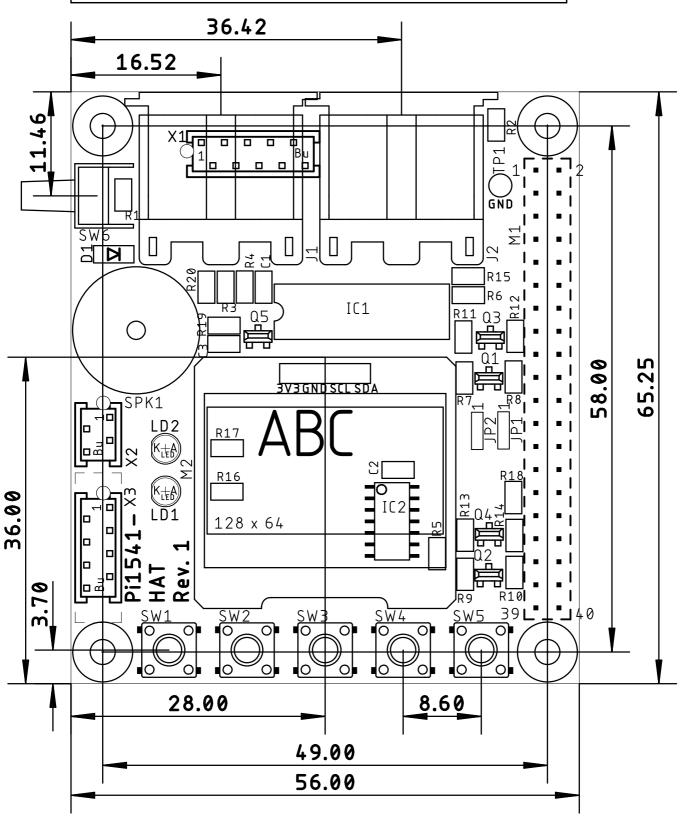
Sven Petersen	DocNo.: 111-2-01-01		
2019	Cu: 35µm	Cu-Layers: 2	
Pi1541_HAT			
27.02.2019 10:13		Rev.: 1	
stopmask component side			



Sven Petersen	DocNo.: 1	11-2-01-01
2019	Cu: 35µm	Cu-Layers: 2
Pi1541_HAT		
27.02.2019 10:13		Rev.: 1
stopmask solder side		



Sven Petersen	DocNo.: 1	11-2-01-01
2019	Cu: 35µm	Cu-Layers: 2
Pi1541_HAT		
27.02.2019 13:04		Rev.: 1
placement component	side mea	sures



#### Pi1541-HAT Rev. 1

### Functional Description

J1 and J2 are the IEC-Bus connectors for the Commodore computers. X1 can be assembled instead of J1 and J2 to make use of an external IEC-Bus PCB.

SW6 is an IEC-Bus RESET switch.

IC1A is the bus driver for the IEC-Bus DATA signal. R3 is the required 1k pull-up-resistor. Since DATA is a bi-directional signal, there is an input stage (IC2A and IC2B), too. This circuit resembled the original 1541 input circuitry. The input signals are inverted twice (which is not required, since the Pi1541 can be configured to use inverted input signals). Q1 in conjunction with R7 and R8 is acting as a 5V/3.3V level shifter. This is a common level shifter circuit as suggested for I<sup>2</sup>C-bus level shifting by NXP.

The circuit for the CLK signal of the IEC-bus is the same. ATN and /RESET do not have an output stage. The input stage of the /RESET signal is making use of the 74LS06 (IC1). Thus, the pull-up-resistor R6 is required.

M1 is the Raspberry Pi connector.

LD1 is the activity LED. LD2 is the power LED.

Both jumpers JP1 and JP2 should be jumpered 1-2 to drive the display M2 with the primary  $I^2C$ -Bus of the Raspberry Pi.

A 0.96" OLED-Display can be connected to M3. In case a 1.3" display is used, the LED and the switches cannot be populated anymore and an external Pi1541-Switch board is required.

The display can also be connected to the MicroMatch connector X2.

SW1 to SW5 are the user interface for navigating through the directories of the disk archive on the SD-card.

Q5 is driving the piezo buzzer. D1 is acting as a protection, since piezo crystals are generating a voltage, when they are moved/compressed. R20 is required, since the idle level of the SND\_OUT signal is HIGH. C3 can be used for sound shaping and additional protection.

TP1 is a ground connection for measurement/debugging.

Pi1541-HAT Rev. 1 Bill of Material Rev. 1.0

Pos.	Qty Value	Footprint	RefNo.	Comment
_	1 111-2-01-01	2 Layer	PCB Rev. 1	2 layer, Cu 35µ, HASL, 56.0mm × 65.25mm, 1.6mm FR4
2	1 369-1-008	MICMA08B	X3	MicroMatch MPE, e.g. Reichelt MPE 369-1-008
က	1 372-1-008		(X3)	option: MicroMatch MPE, e.g. Reichelt MPE 372-1-008
4	1 0.96IN_OLED_128X64_SS	OLED_0.96_SSD	M2	0.96" OLED Display 128x64, controller: SSD1306 or
	D1306	1306		1.3" OLED Display 128x64, controller SH1106
2	1 115-1-004		(M2)	option: MPE Garry, e.g. Reichelt MPE 115-1-004
9	2 010599	10599	ال 11, 12	Lumberg, e.g. Reichelt 010599 06
7	3 100n	0805	C1, C2, C3	
∞	10 10k	0805	R6, R7, R8, R9, R10, R11, R12,	
			R13, R14, R15	
6	2 150R	0805	R16, R17	
10	3 1k	0805	R3, R4, R5	
11	1 33R	0805	R19	
12	1 3mm_gn	3MM	LD2	LED 3mm, green
13	1 3mm_red	3MM	LD1	LED 3mm, red
14	1 74LS04D	SO-14	IC2	
15	1 74LS06N	DIL-14	IC1	
16	1 BC846B	SOT23	Q5	
17	4 BSS138	SOT23	Q1, Q2, Q3, Q4	
18	2 JMP_0603	CP3P	JP1, JP2	Jumper, default: 0R/0603 (1-2)
19	2 OR	0903	(JP1), (JP2)	
20	1 JPT1236HB	JTP_1236HB	SW6	Namae Electronics, e.g. Reichelt TASTER 3305B
21	5 JTP-1130	JTP-1130	SW1, SW2, SW3, SW4, SW5	Namae Electronics, e.g. Reichelt TASTER 9303
22	1 LL4148	SOD80C	D1	Diode
23	1 369-1-004	MICMA04B	X2	MicroMatch MPE, e.g. Reichelt MPE 369-1-004
24	1 372-1-004		(X2)	option: MicroMatch MPE, e.g. Reichelt MPE 372-1-004
25	1 369-1-010	MICMA06B	X1	MicroMatch MPE, e.g. Reichelt MPE 369-1-010
26	1 372-1-010		(X1)	option: MicroMatch MPE, e.g. Reichelt MPE 372-1-010
27	1 RASPBERRYPI 3B		M1	Raspberry Pi 3B or better

27.02.2019 19:11 Doc.No.: 111-5-01-01.0

Pi1541-HAT Rev. 1 Bill of Material Rev. 1.0

Pos.	Qty Value	Footprint	RefNo.	Comment
28	1 MPE 094-2-040		(M1)	MPE, e.g. Reichelt MPE 094-2-040
29	1 RMP-14P/HT	RMP-14P/HT	SPK1	KM, e.g. Reichelt SUMMER EPM 121
30	1 4k7	0805	R18	
31	2 dnp	0805	R1, R2	option OR, not placed
32	1 27k	0805	R20	