

Tutorial

Creating a console —

David & John

by RetroValou

Tools and materials

/01

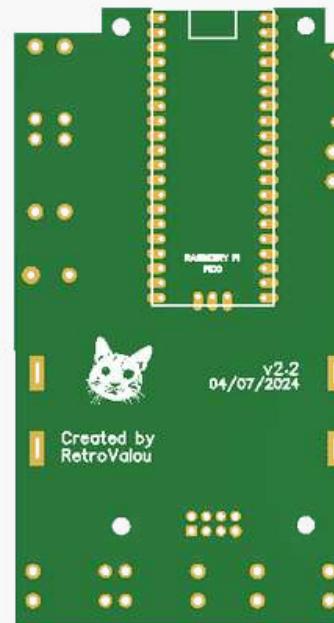
Materials



E-Paper Weaxie WeAct Studio
2.9 - Black-White
([Link Aliexpress](#))



Raspberry Pi Pico
Standard, without pin
([Link kubii](#))



PCB *David&John*
(file Gerber available)
(to be ordered from
[JLCPCB](#) for example)



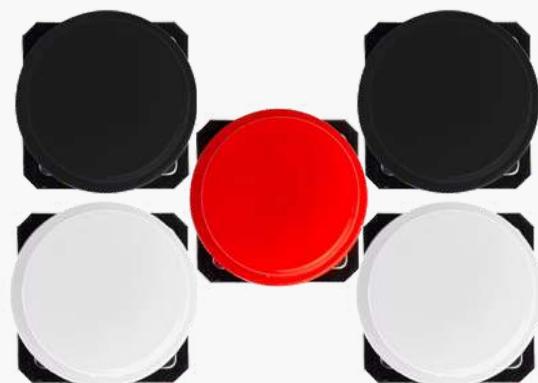
Button Power
3Pin L-type black
([Link Aliexpress](#))



Schottky Diode
1N5817
([Link Aliexpress](#))



Batterie shrapnel
2 Pairs
([Link Aliexpress](#))



Push buttons
5 buttons
([Link Aliexpress](#))



Passive buzzer
([Link Aliexpress](#))



Insert Nut
4 nuts
M3 (OD4.5mm) Length 5mm
([Link Aliexpress](#))



Carbon Screw
4 Screws
ISO7380 M3 6mm
([Link Aliexpress](#))

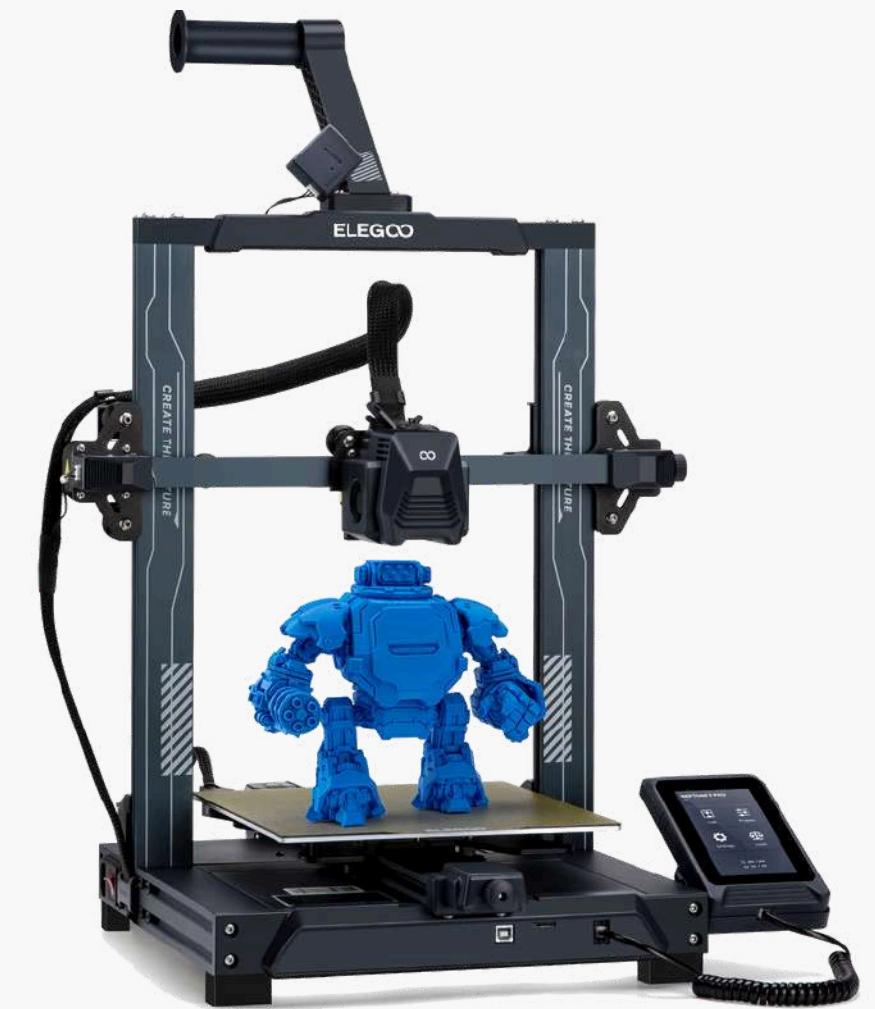
Tools



Soldering iron



Tin



3D printer
Tested on an Elegoo
Neptune 3 Pro



PLA
less than
100g



Micro USB cable
WARNING !
not type C!



Screwdriver

Configurations for PCB and 3D printing

/02

PCB

David&John PCB can be ordered from a custom PCB creation service/site

Result tested with the JLCPCB site

The available Gerber file contains the necessary information for creating the PCB

Important PCB Configurations: thickness: 0.8mm

- Layers: 2 (1 should be OK)
- Via Covering : Untented

Complete configurations (under JLCPCB)

Gerber file:	PCB David V2.1_PCB_PCB David V2.1__20240717102034.zip_Y7	Build Time:	2 days
Base Material:	FR-4	Layers:	2
Dimension:	58.2 mm* 106.3 mm 58.17mm* 106.3mm	PCB Qty:	10
Product Type:	Industrial/Consumer electronics	Different Design:	1
Delivery Format:	Single PCB	PCB Thickness:	0.8
Impedance Control:	no	Layer Sequence:	
PCB Color:	Green	Silkscreen:	White
Material Type:	FR4-Standard TG 135-140	Via Covering:	Untented
Surface Finish:	HASL(with lead)	Deburring/Edge rounding:	No
Outer Copper Weight:	1 oz	Gold Fingers:	No
Flying Probe Test:	Fully Test	Castellated Holes:	no
Edge Plating:	No	Mark on PCB	Order Number
4-Wire Kelvin Test:	No	Paper between PCBs:	No
Appearance Quality:	IPC Class 2 Standard	Confirm Production file:	No
Silkscreen Technology:	Ink-jet/Screen Printing Silkscreen	Package Box:	With JLCPCB logo
Board Outline Tolerance:	±0.2mm(Regular)		

3D printing

**Basic configuration used in Cura 5.6.0
under an Elegoo Neptune 3 Pro
(check that the settings
are activated in Cura!)**

Adhesion of the plate
Plate adhesion type: Edge

Up down
Activate stretching Stretch flow: 15%

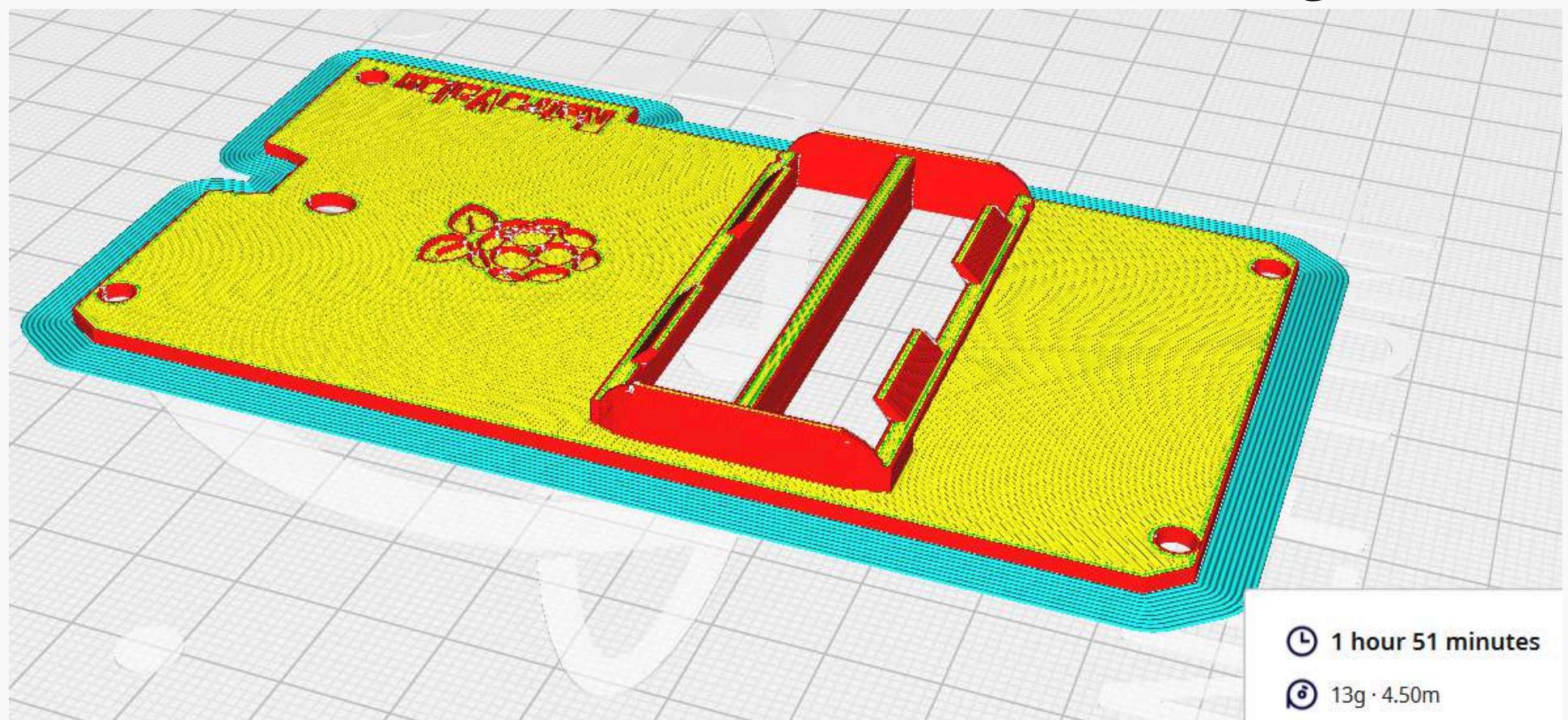
Quality

Layer height: 0.12 mm
Line width: 0.4 mm
Flow Percentage: 105%

Speed

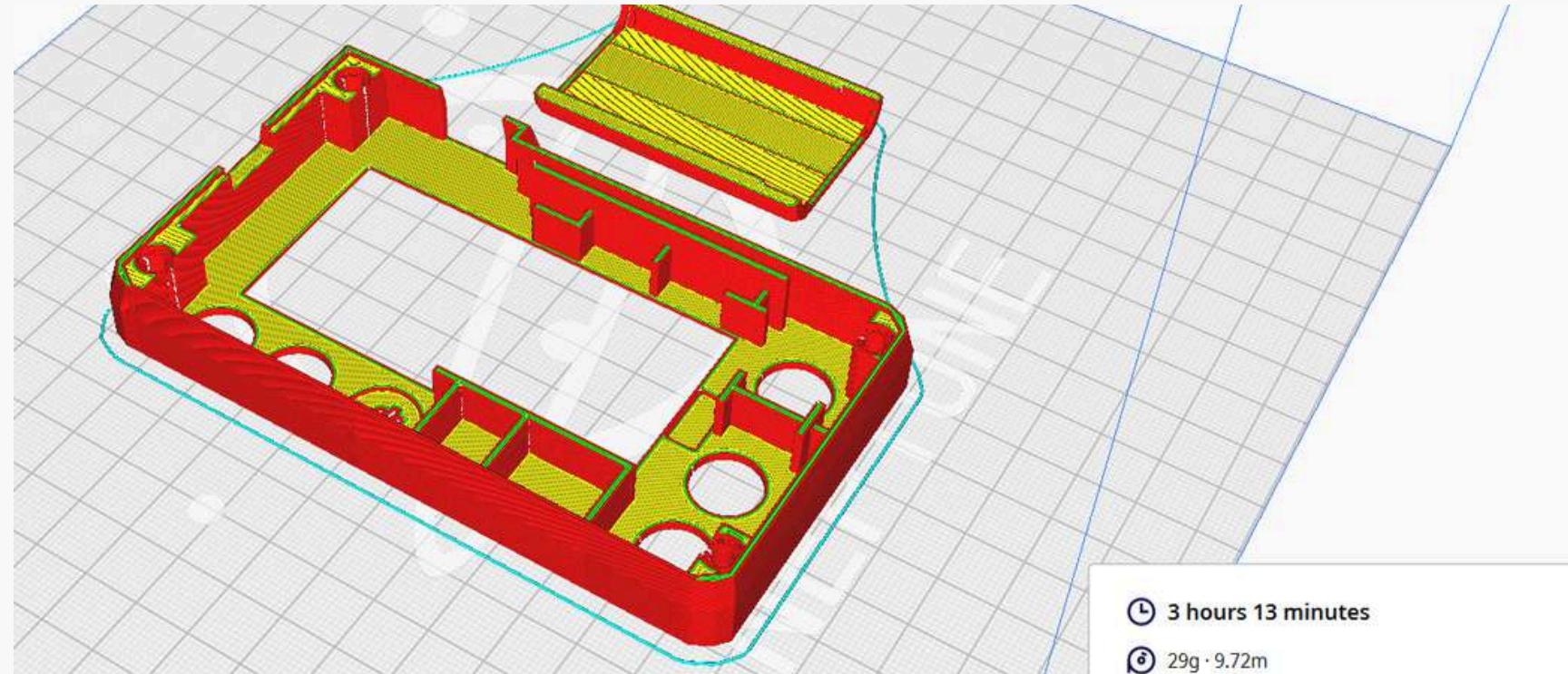
Print Speed: 50 mm/s

Back case configuration



3D printing

Front case and battery cover configuration



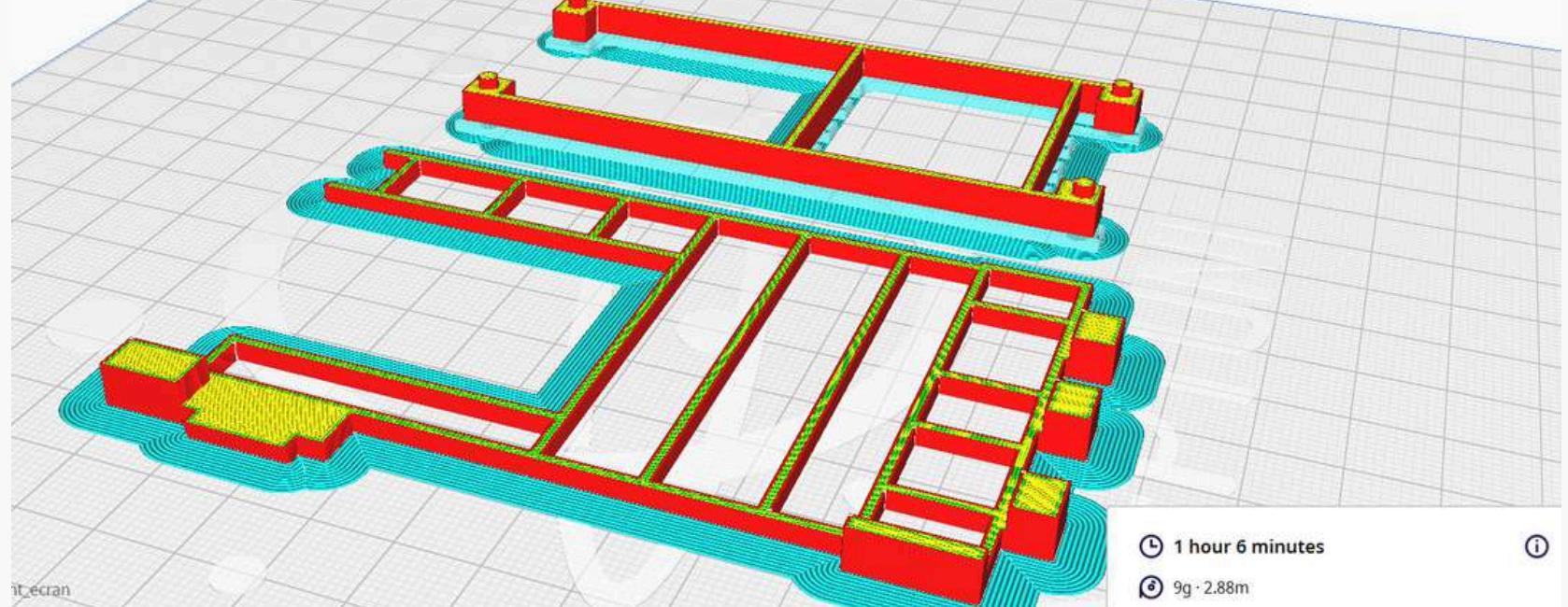
Adhesion of the plate

Type of grip of the deck: Skirt

WARNING ! I advise you to use a little glue for better adhesion to the tray

Adhesion of the plate
Plate adhesion type: Edge

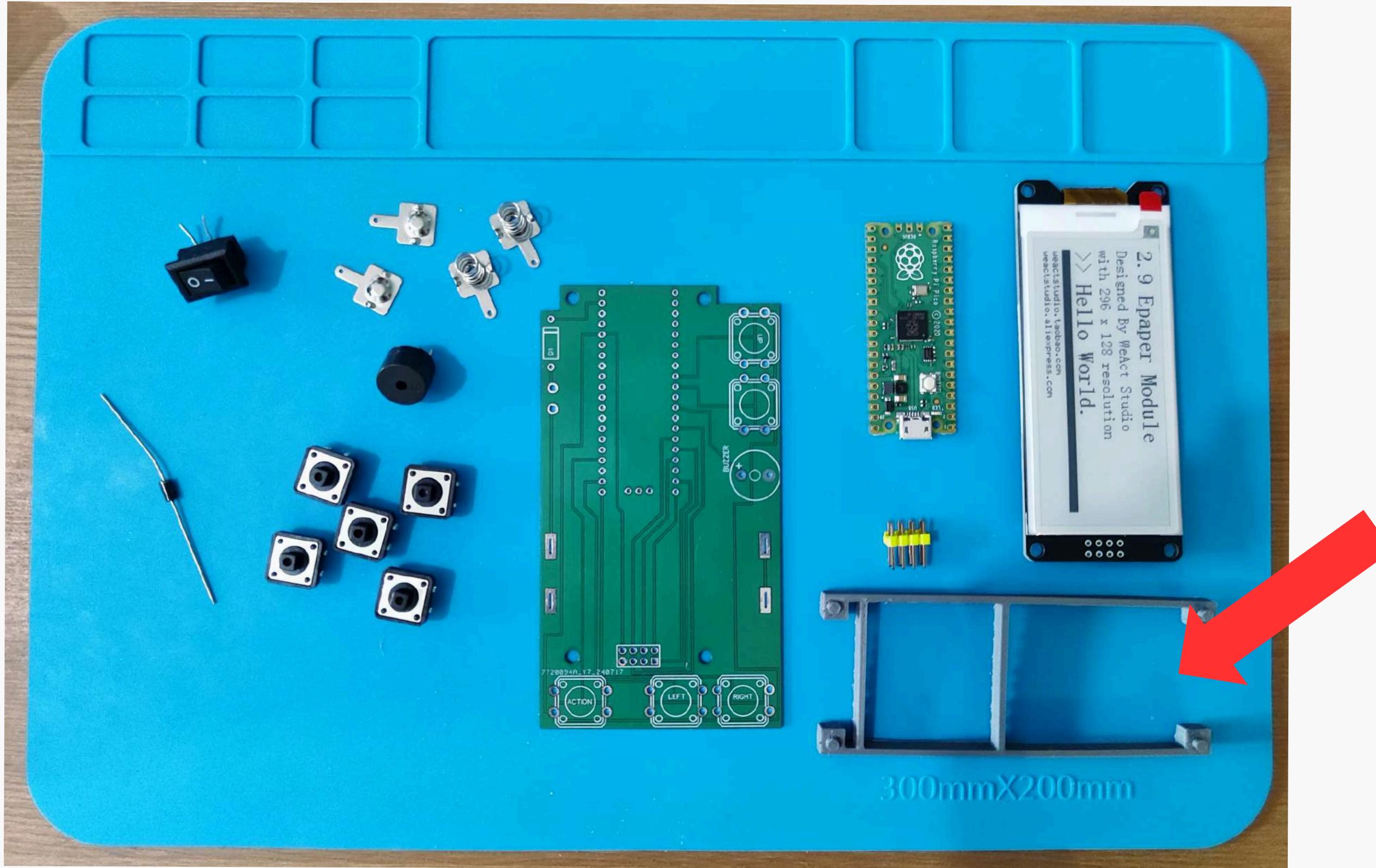
Supports
Generate supports



Soldering the PCB

/03

Materials



You need to print this part before you start soldering!
(Part Maintains Screen)

Materials



**You must also cut one of the pins present
on the power button
(pin most at the edge and on the same side
as the “|” logo)
(WARNING! the button available with the 2
pins on Aliexpress is reversed!)**

Soldering the screen

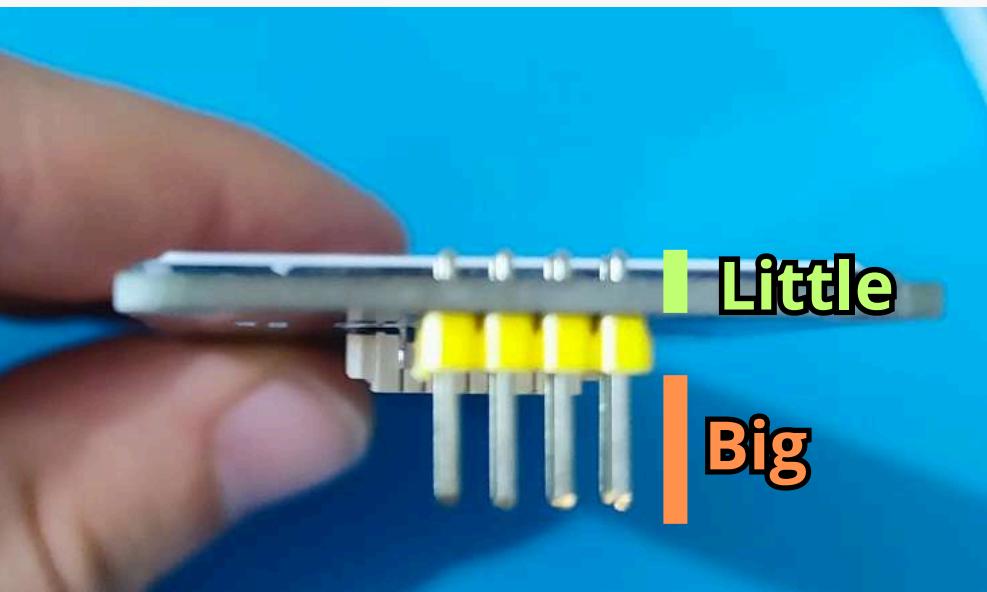
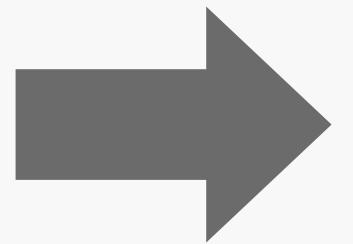
There is no specific order for the steps to follow for welding. You can start by soldering the buttons, the Raspberry pi or the screen.

However, the order defined here is the one that makes it easier to weld

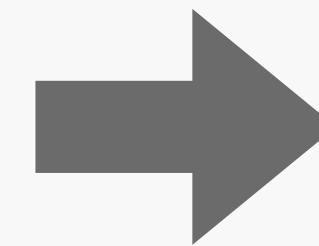
The first step is to solder the screen pins



Included
with the
purchase of
the screen



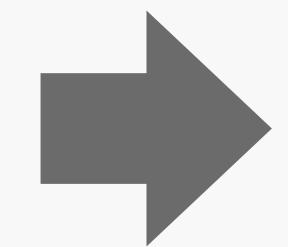
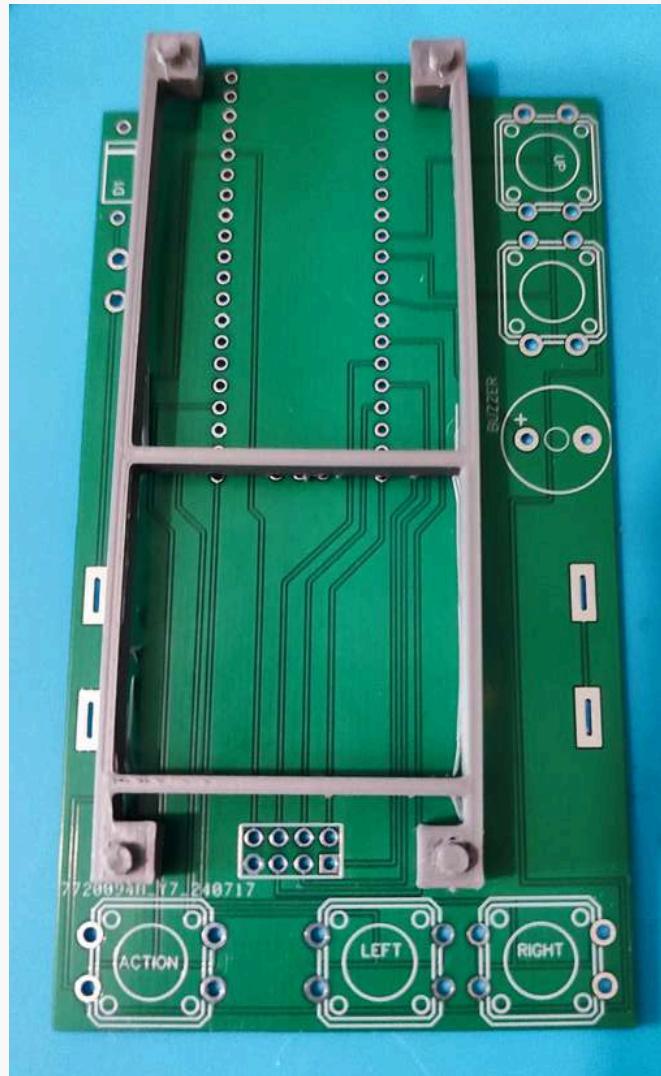
Position the pins so that the
smallest part is the one that fits
into the screen (yellow part on
the back of the screen!)



Solder the 8 Pins
Be careful that none of the
pins are connected
together

Soldering the screen

Side
without
the Cat!



at the end, the screen, PCB and printed part should be like this

Position the printed “screen hold” part on the PCB like this.

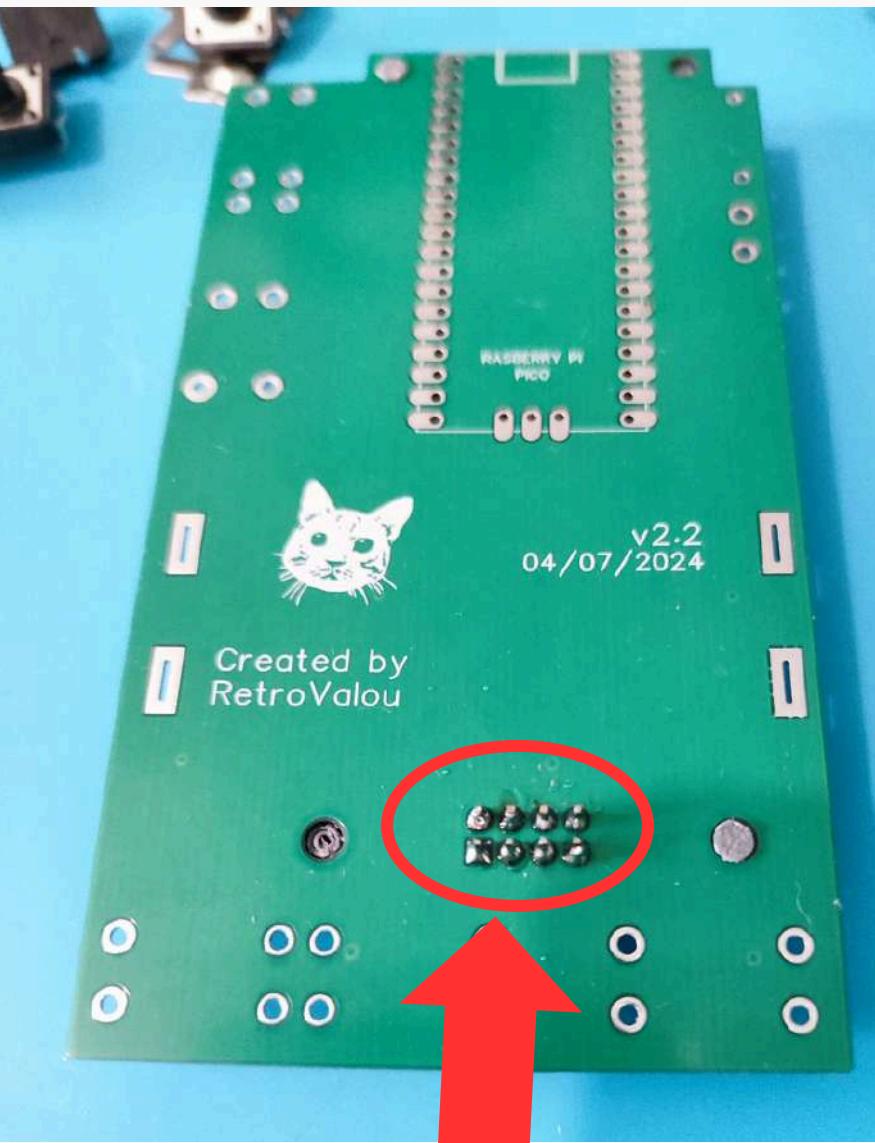
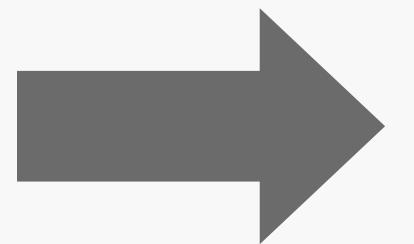
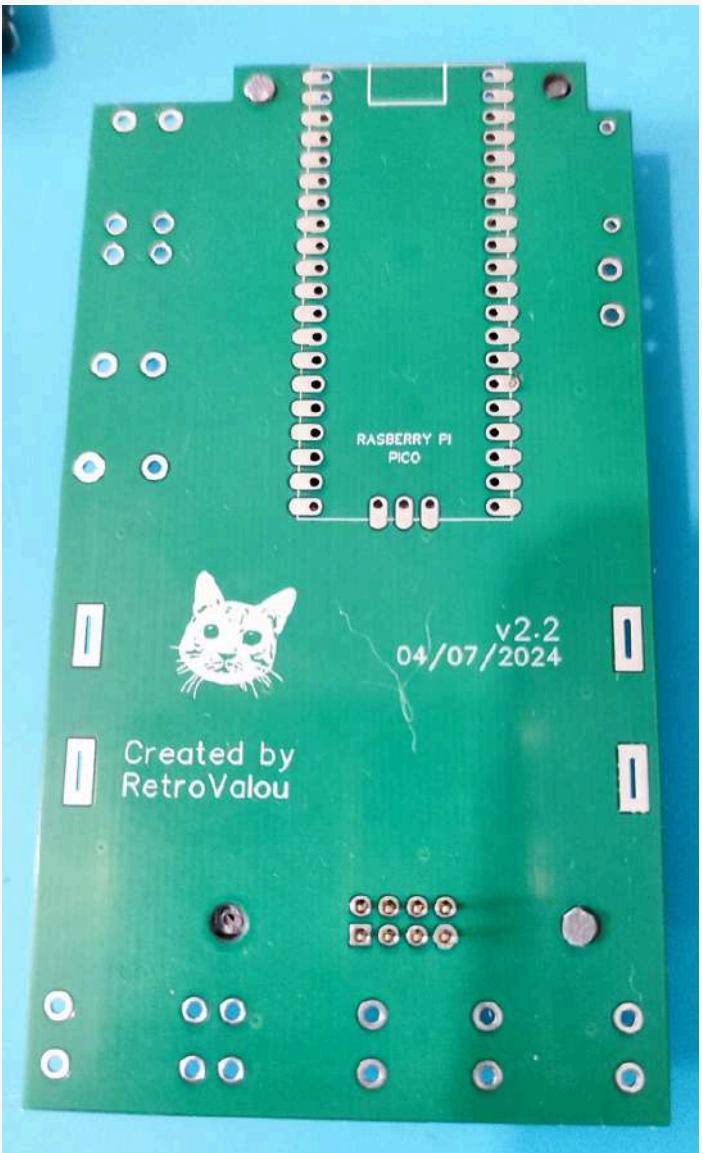
It is used to have the right distance between the screen and the PCB. The rods must fit into the holes of the PCB

Position the screen on the support the rods must fit into the holes of the screen

The pins of the screen must fit into the 8 vias (holes) of the PCB

Soldering the screen

Side with
the Cat!

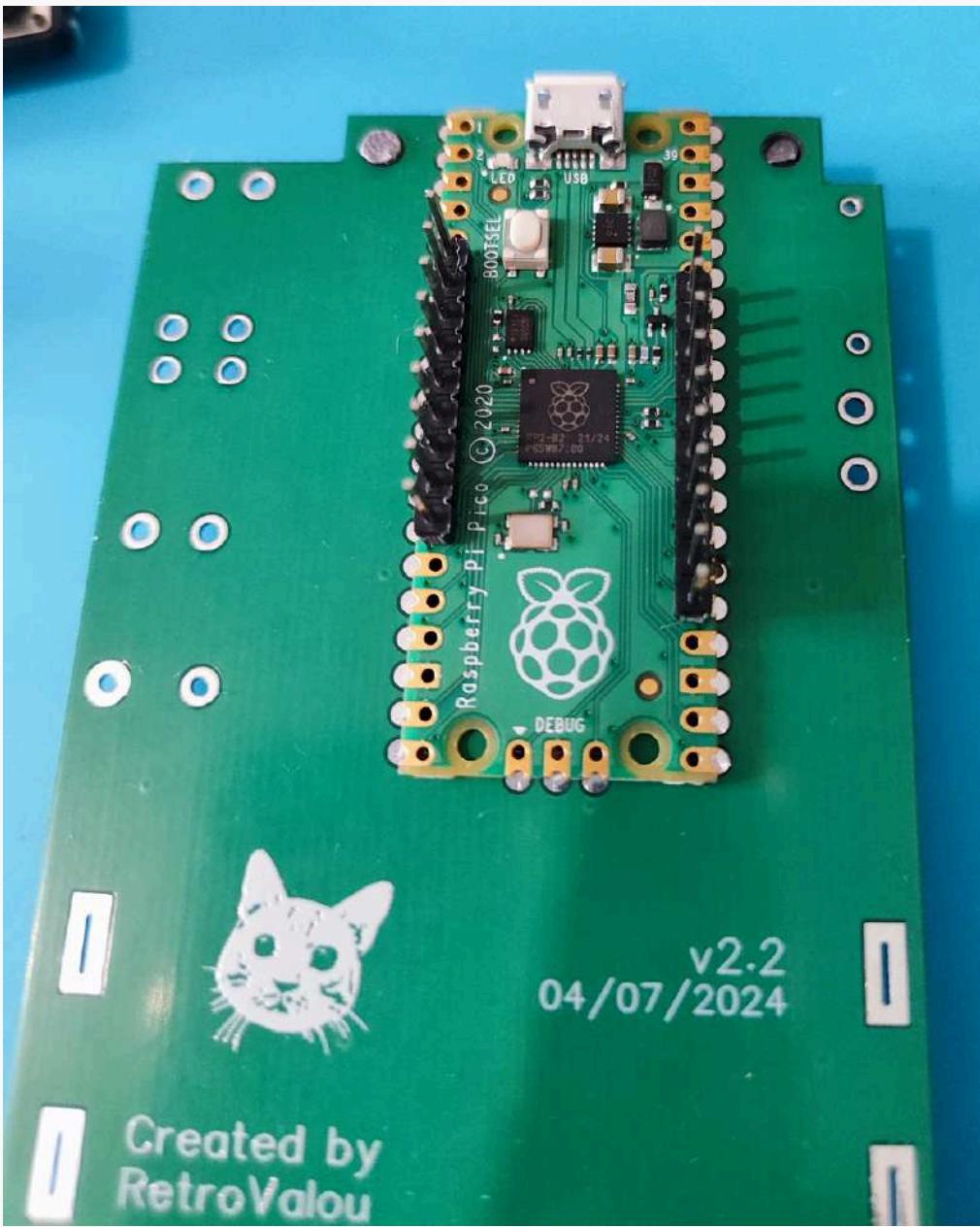


Flip the screen and PCB over. Be careful that the screen, the PCB and the printed part remain fitted!

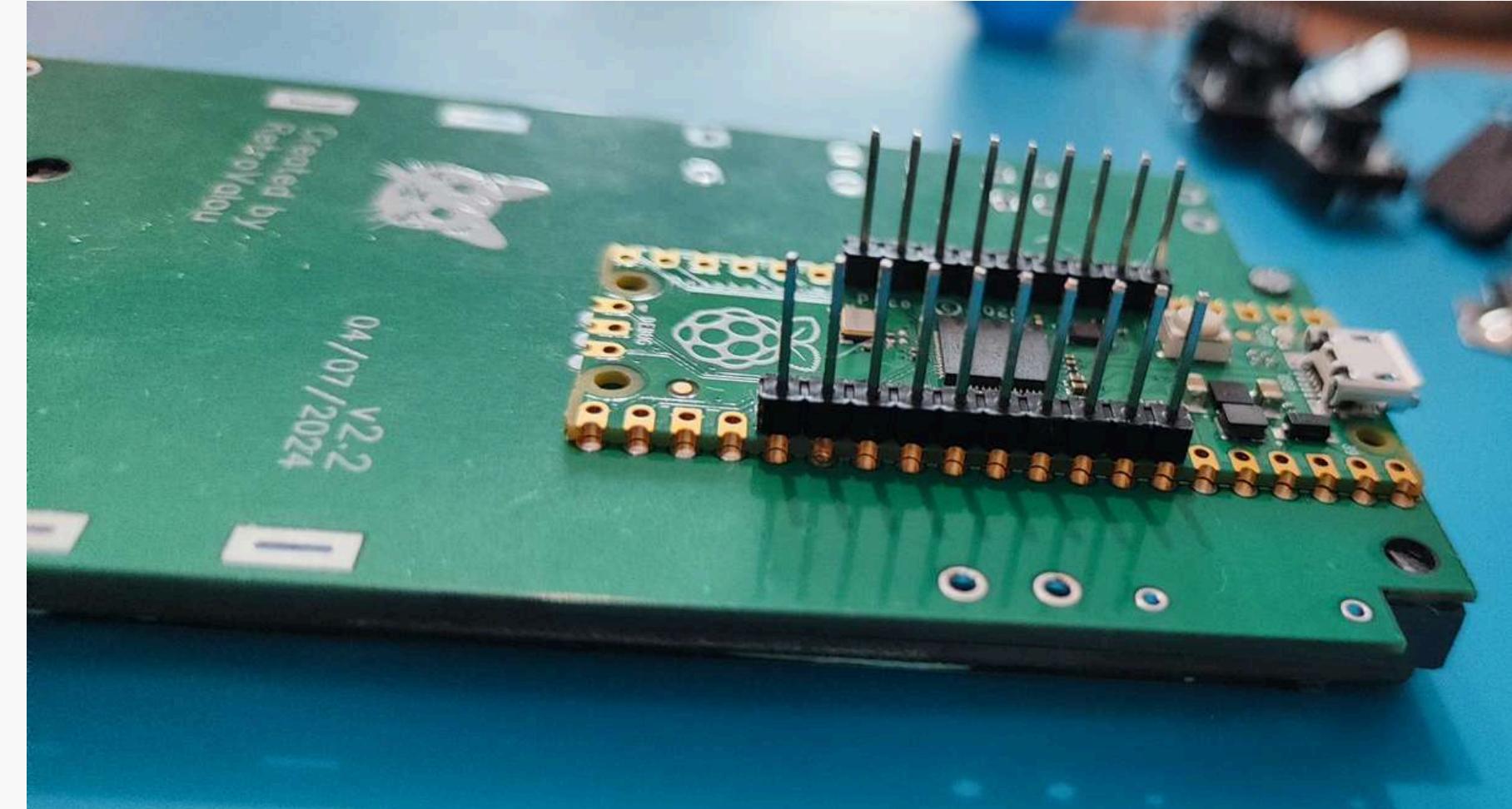
Solder the 8 Pins Be careful that none of the pins are connected together

Soldering the Raspberry PI Pico

Side with
the Cat!



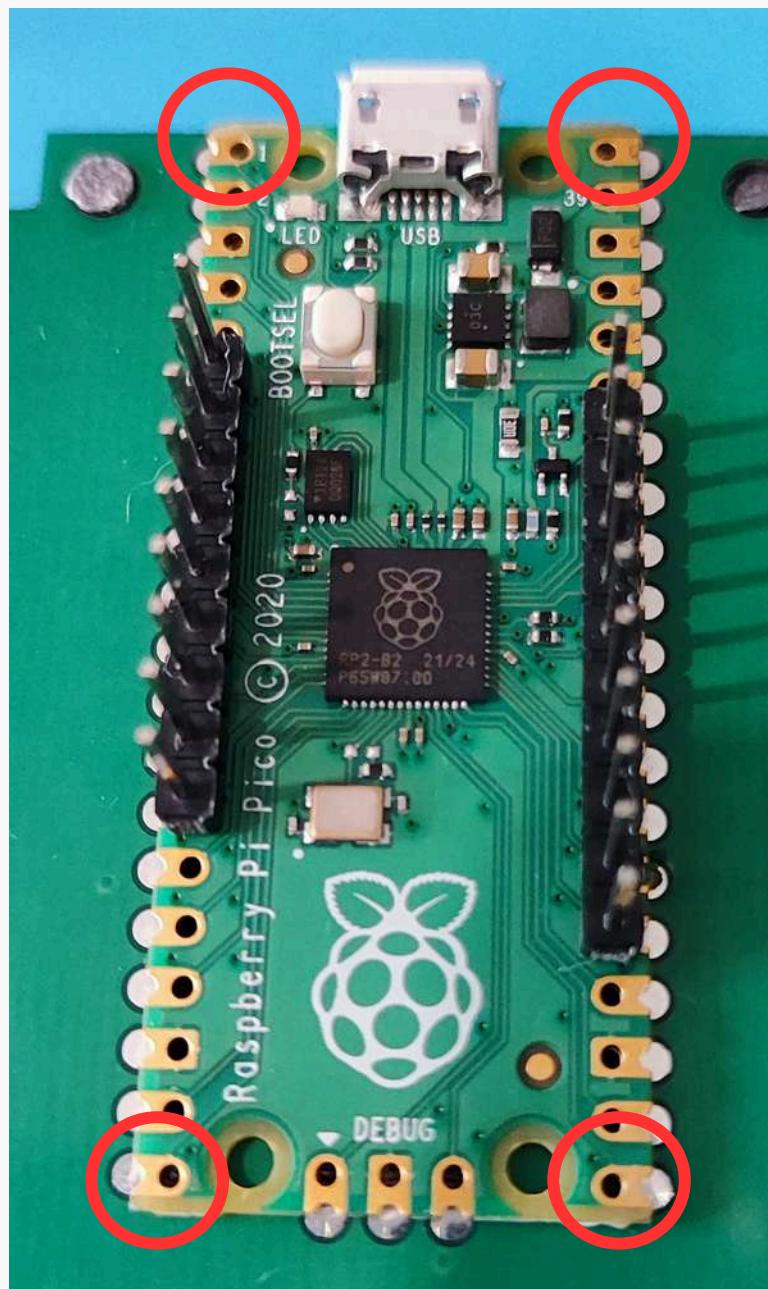
For this step, the easiest way to position and hold the Raspberry Pi during soldering is to use a row of standard pins found for example with the PI



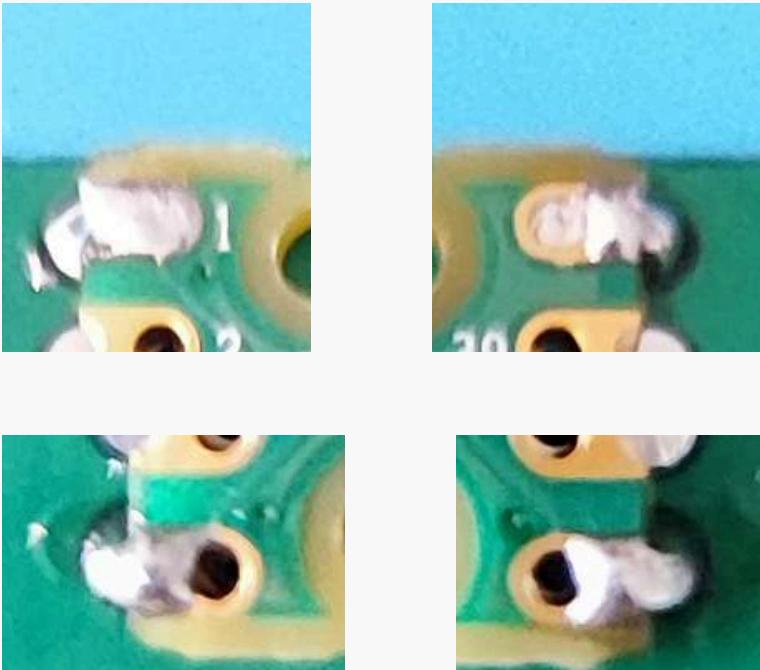
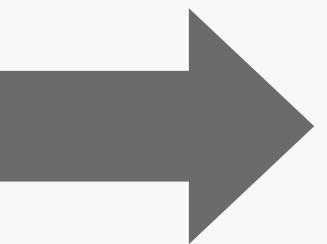
Use the shortest part of the pins to prevent them from touching the soldered screen.

WARNING ! we are not going to solder the pins, they are only used to hold them during soldering. They are not obligatory but strongly recommended

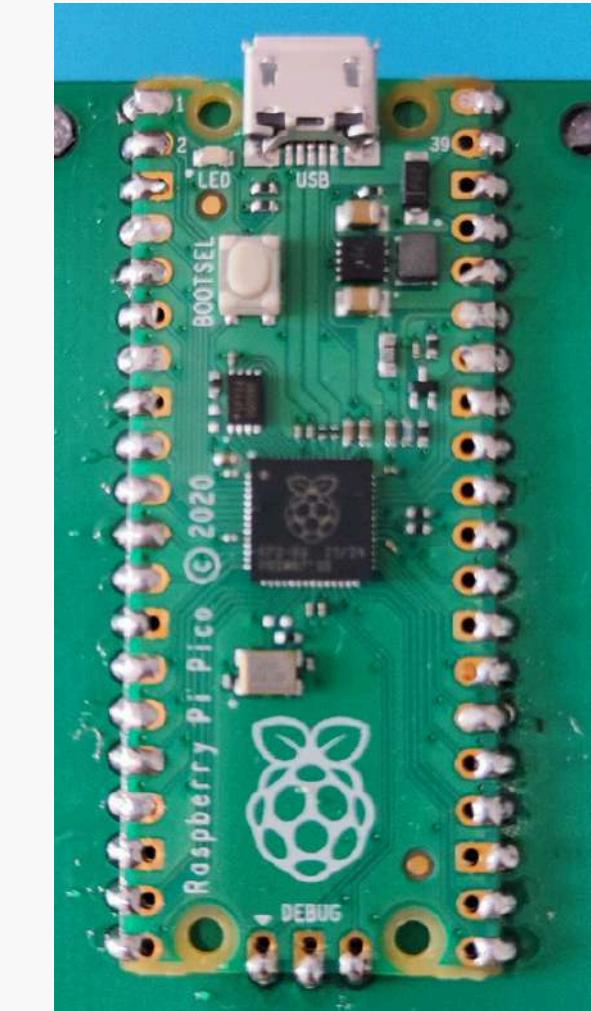
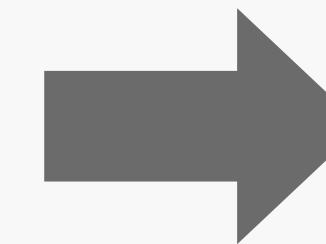
Soldering the Raspberry PI Pico



First solder the 4 pins in the corners so that the Raspberry pi is held by the PCB



The tin must be present on the side of the Raspberry PI and in contact with the copper part which protrudes from the PCB



You can remove the rows of pines serving as aids.

Solder the rest of the pins to the PCB. Technically, not all pins are necessary but it's better to solder them all for strength!

Soldering the buttons

Side
without
the Cat!

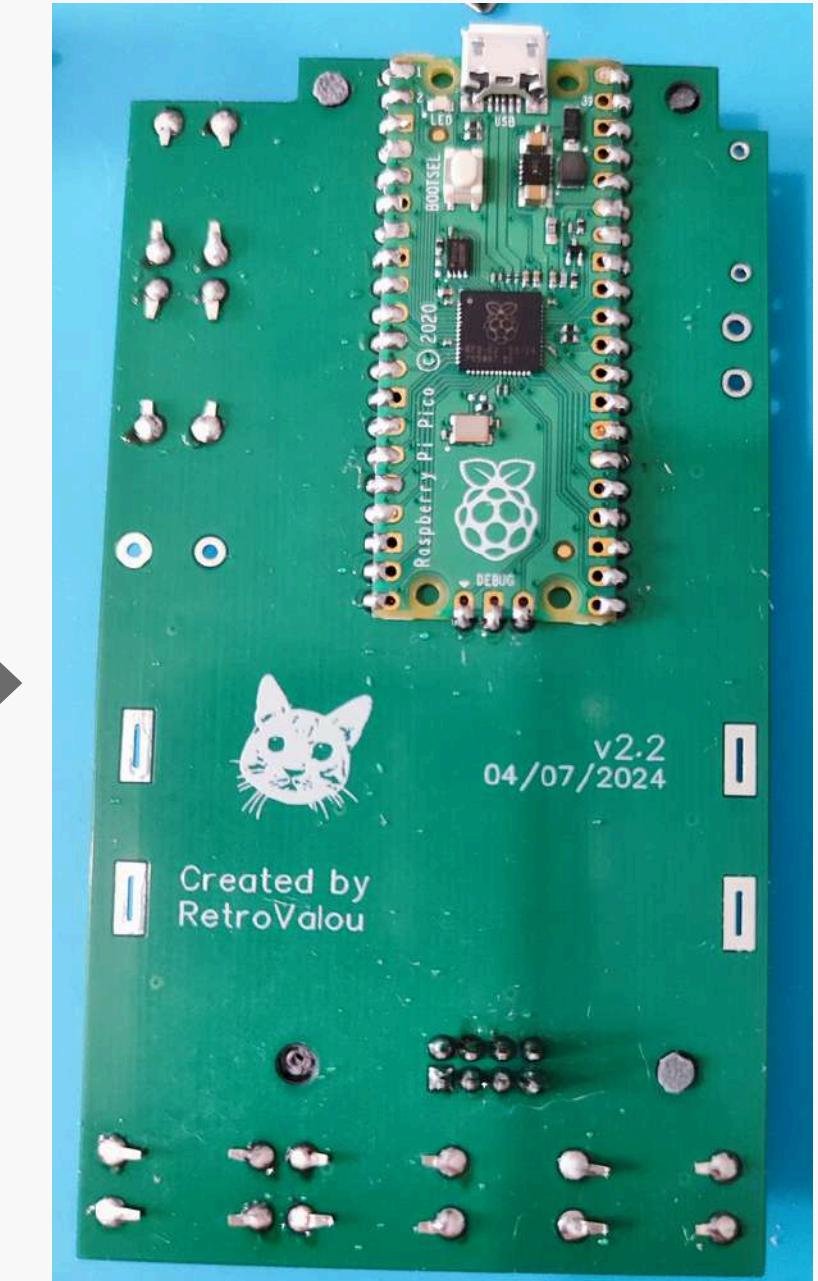


Position the 5 buttons on the PCB like this. The direction of the buttons does not matter

Side with the Cat!



To make soldering easier, I advise you to slightly bend the button pins. This allows the buttons to fit on the PCB without soldering!



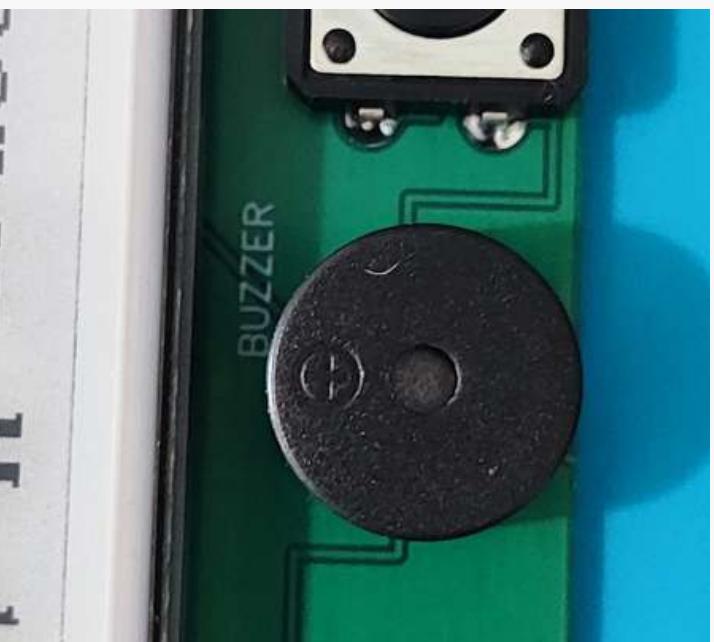
Solder the 5 buttons

Buzzer soldering



Position the buzzer
on the PCB like this.

Side without the Cat!

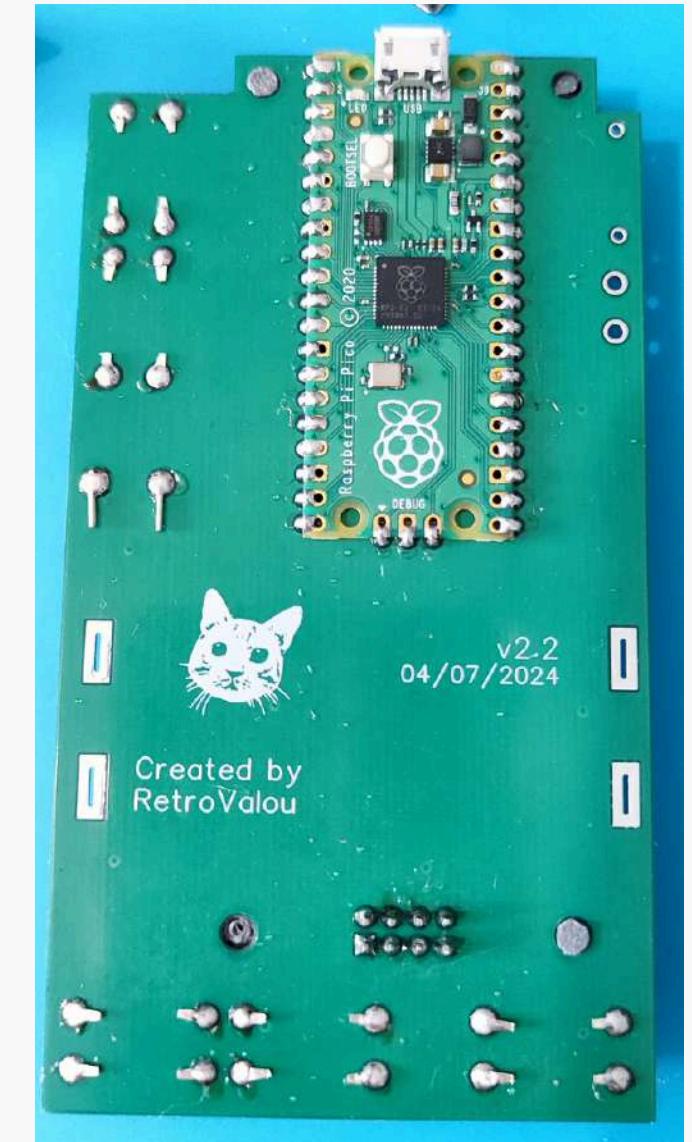


The (+) present on
the buzzer must be
on the screen side

Side with the Cat!

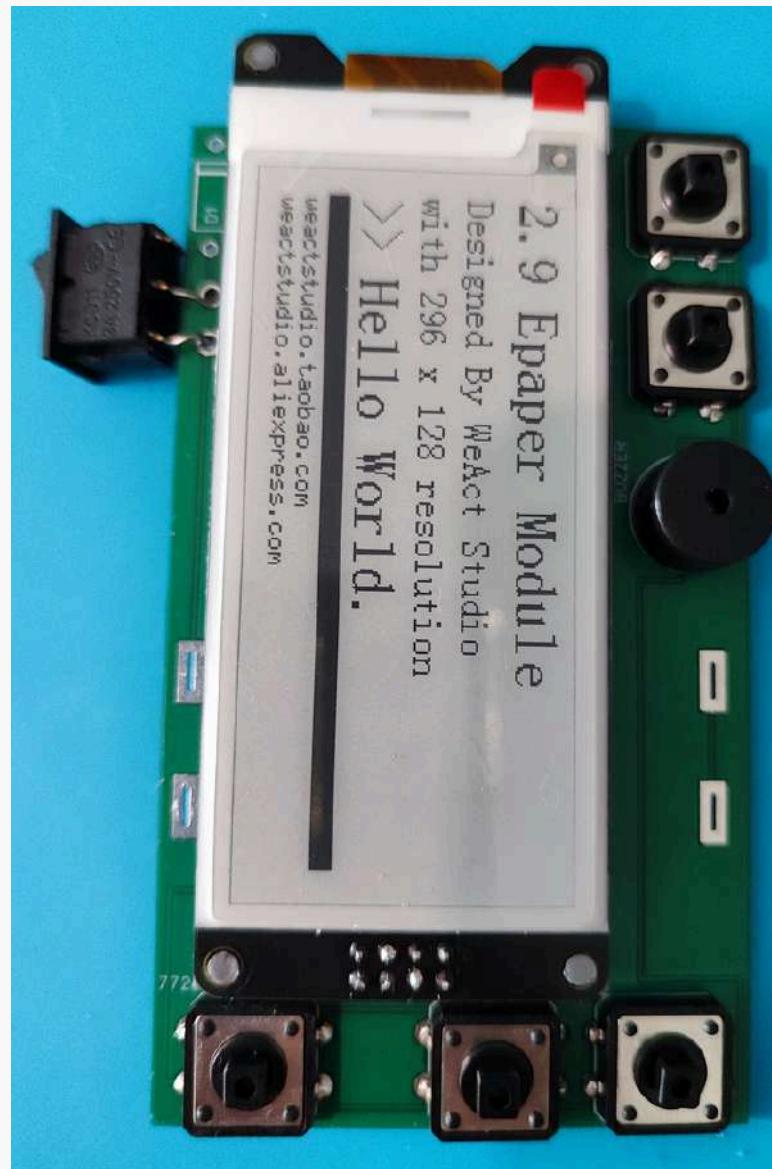


To make soldering easier, I advise
you to slightly bend the buzzer pins.
**WARNING ! They must be folded
downwards otherwise they risk
getting in the way during
assembly.**

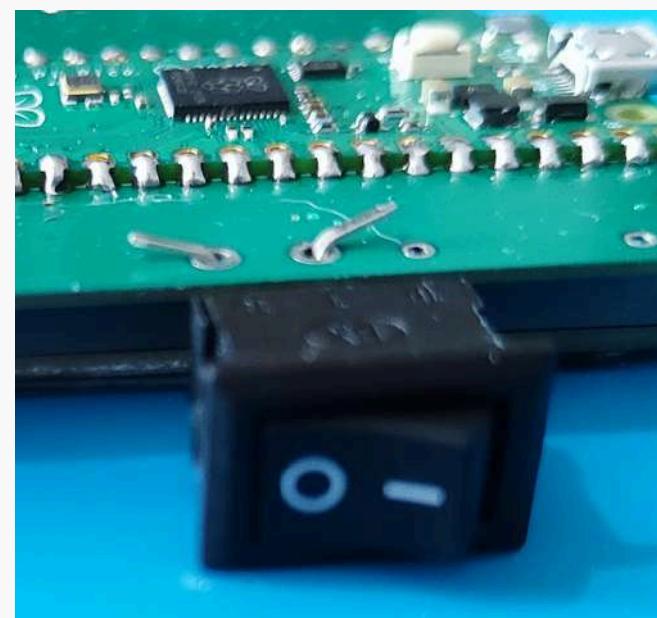


Solder the buzzer

Soldering the Power button



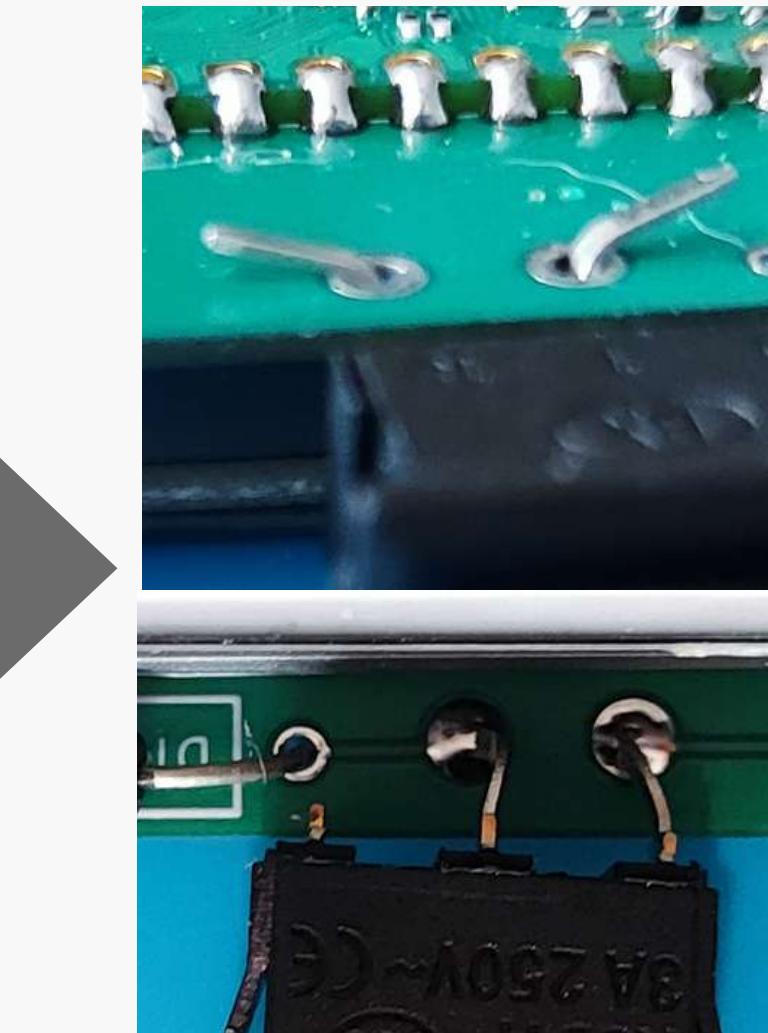
**Side
without
the Cat!**



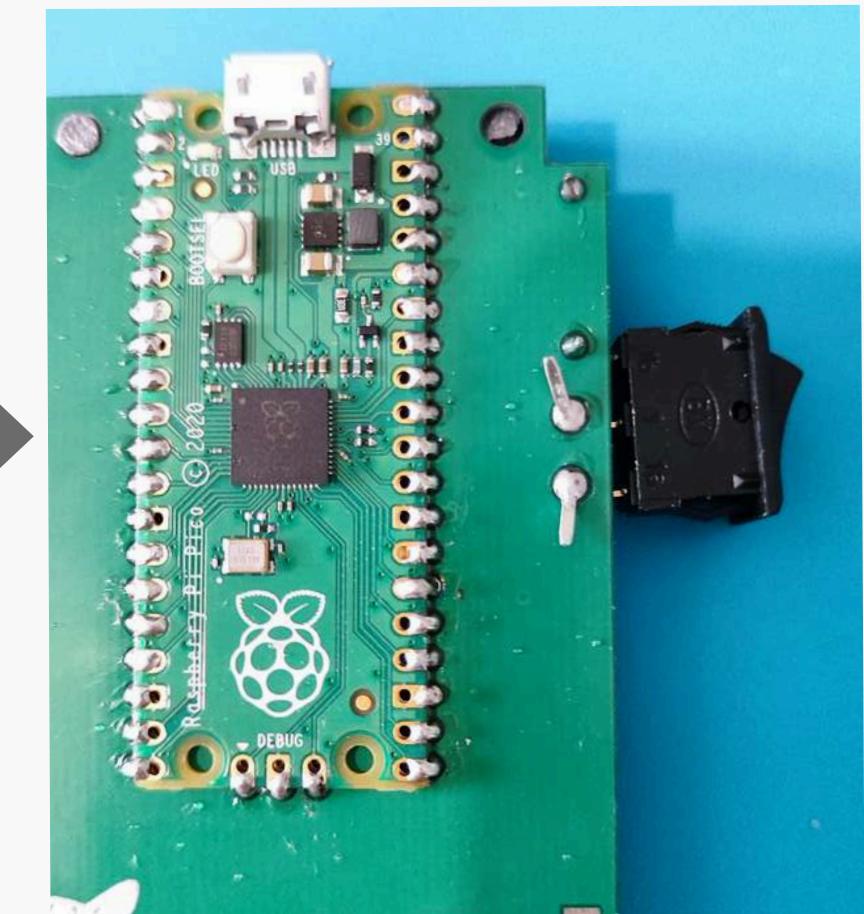
**Side with
the Cat!**

Position the Power
Button like this

Make the button
flush with the cat
side PCB



To make soldering easier, I
advise you to slightly bend
the pins of the power buttons
on both sides of the PCB



Solder the Power button

Diode soldering

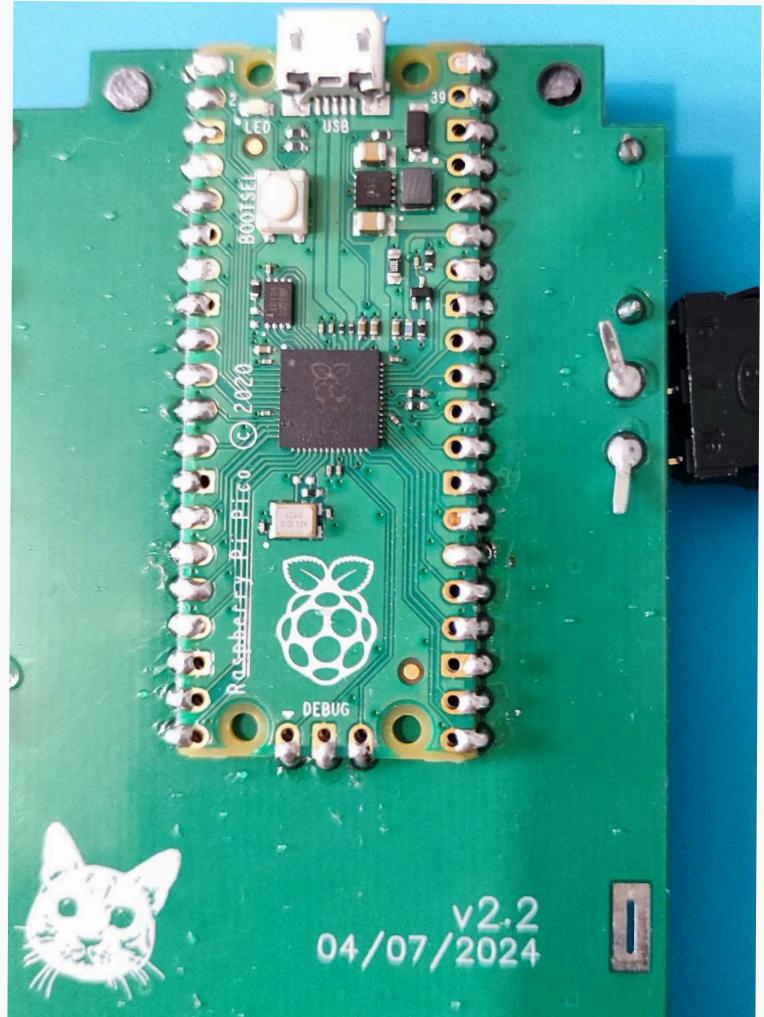
Side without the Cat!



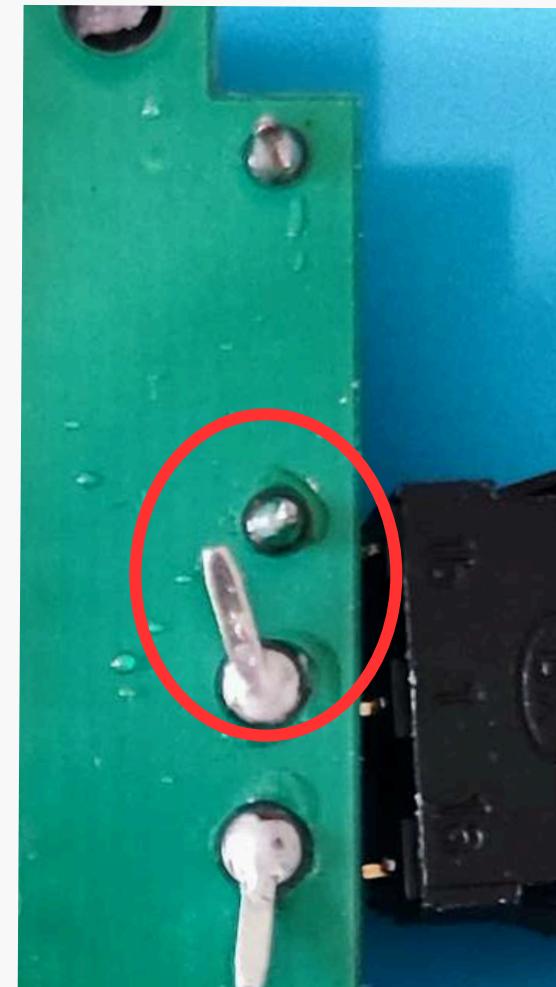
Position the diode
like this

The gray line of the
diode must be
upwards (opposite
the Power button)

Side with the Cat!

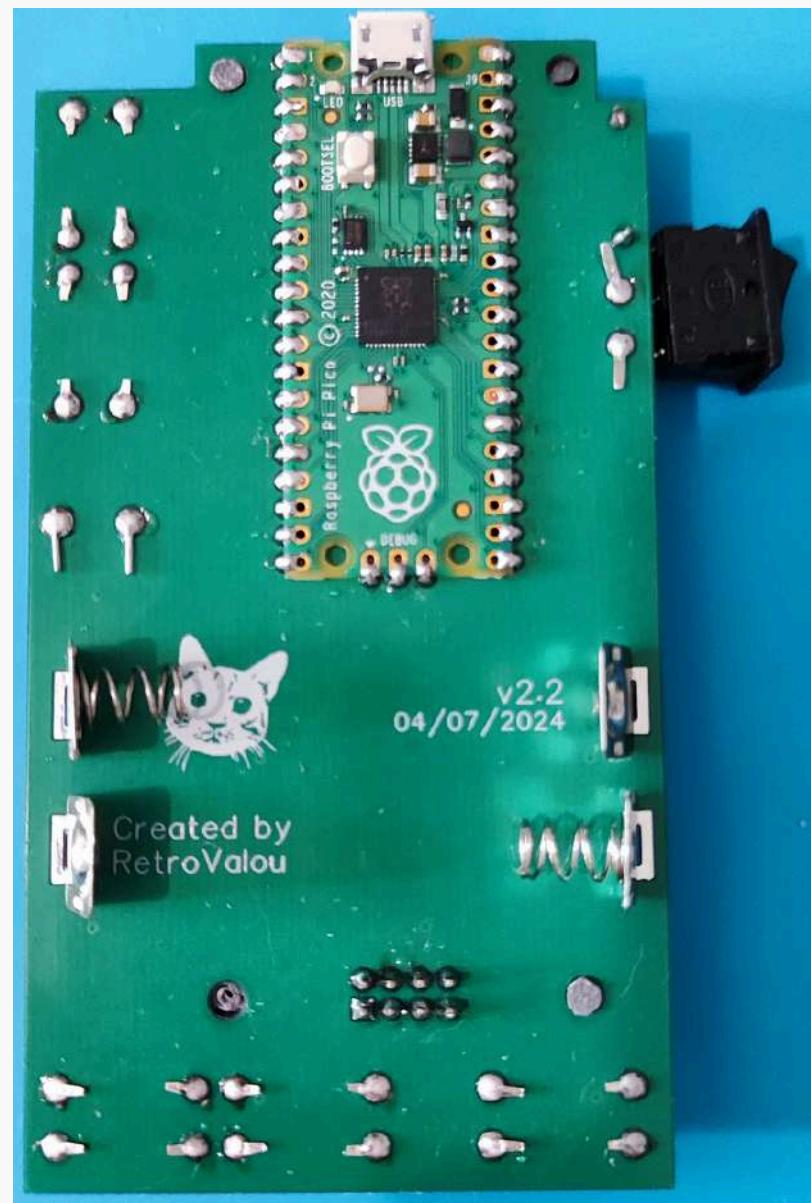


Solder the diode
and cut the pins to
shorten them

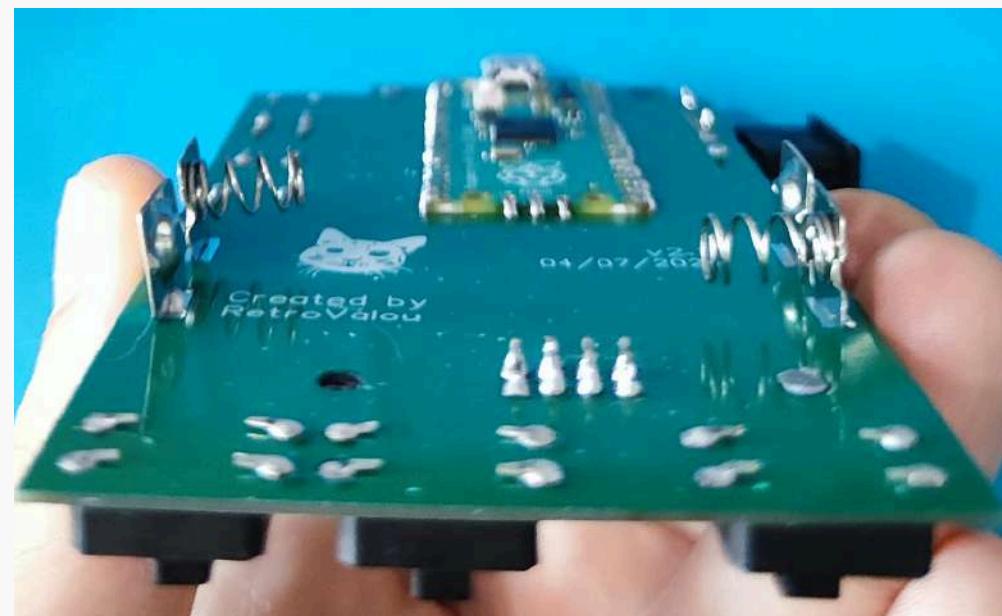


Normally, there is no risk if the pin
of the diode and the power button
are in contact here (the pins are
already connected by the PCB!)

Soldering contacts for batteries



Side
with the
Cat!



the battery contacts should be positioned like this

WARNING ! Respect the spring and non-spring contacts



Side
without
the Cat!

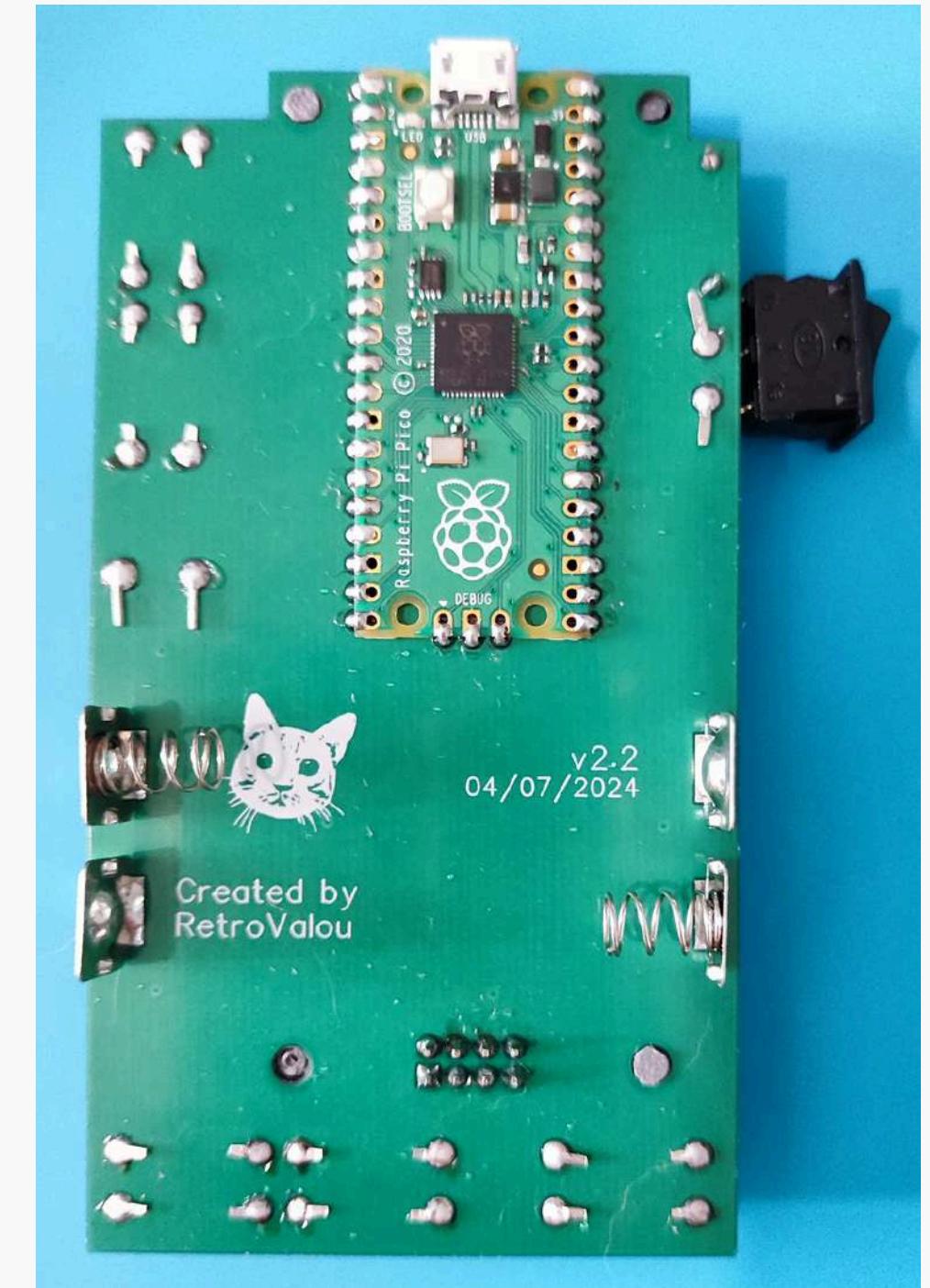
The contacts must be as straight as possible

Solder the contacts on the catless side.
This part is the hardest. Unfortunately I don't have
much advice to give =(

You can lightly solder on the other side if that
makes it easier for you to solder on the screen side

Finish!

**Bravo !
you have finished
soldering the David &
John console PCB!**



Loading the software

/04

Prerequisites



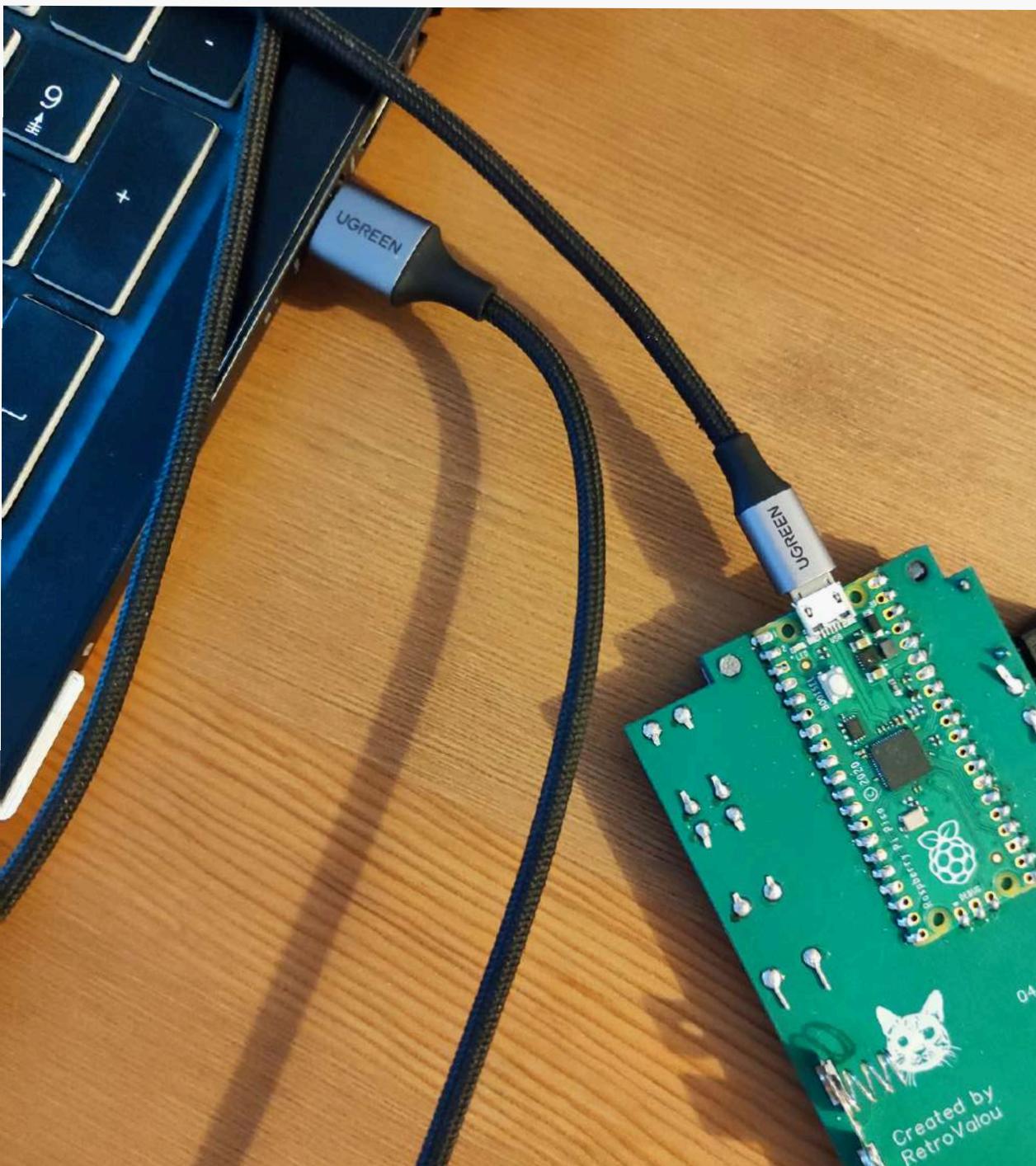
Micro USB cable to connect to the Raspberry PI Pico

Software allowing you to read a Raspberry PI Pico under Micro-
Python Software I use: Thonny (does not require installation)



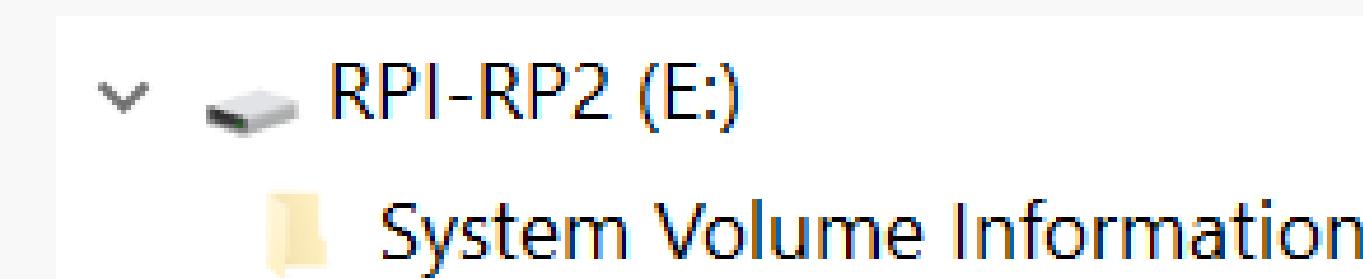
Micro Python Software for Rasberry PI Pico Available
in the given files or on the official Micro Python
website

Loading Micro Python



The tutorial is carried out under Windows with Tonny

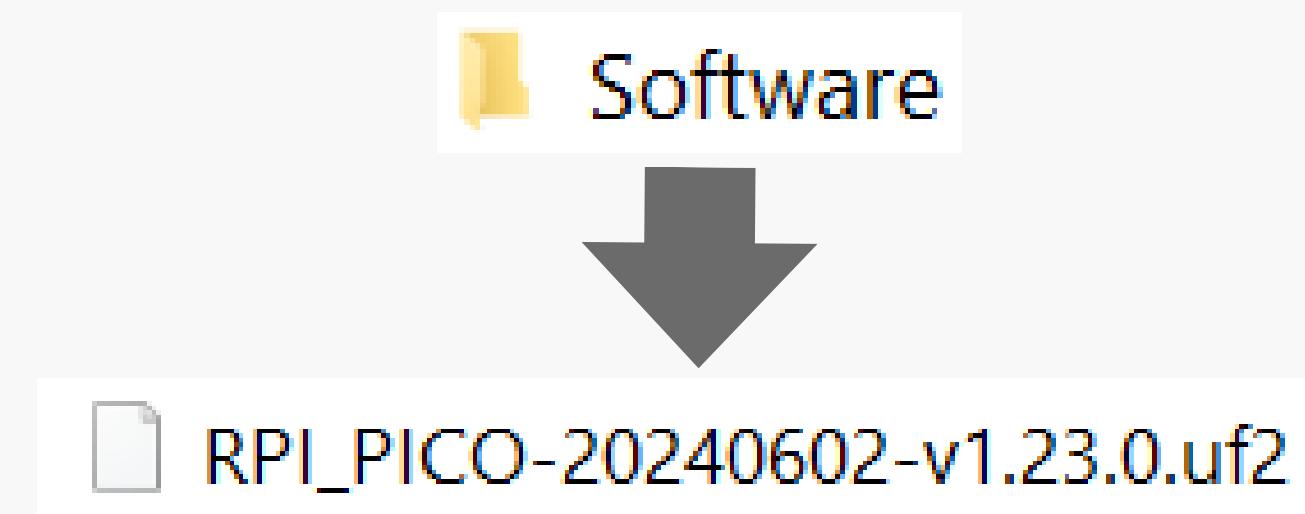
Connect the console to your computer using the MicroUSB cable on the Raspberry PI Pico port



The Raspberry PI should appear as
a new drive

Loading Micro Python

In the Software folder attached to this tutorial or on the Micro Python official website, you will find the following file



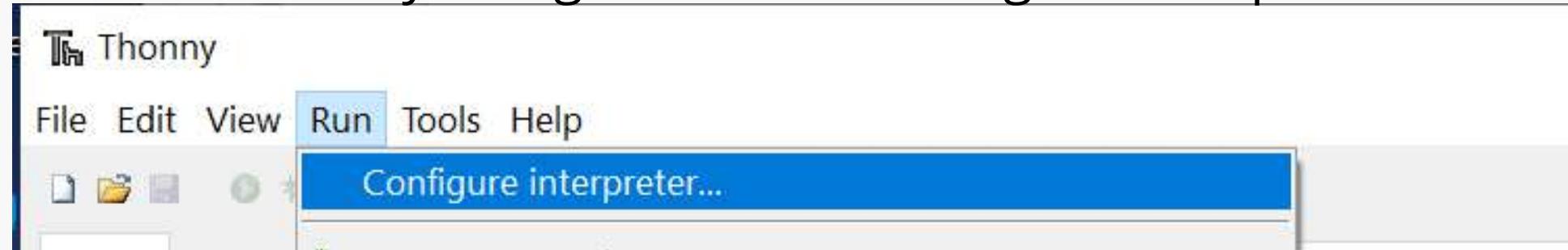
Copy it to the Root of the Raspberry PI Pico

Nom	Modifié le	Type	Taille
System Volume Information	01/08/2024 08:40	Dossier de fichiers	
INDEX.HTM	05/09/2008 16:20	Firefox HTML Docu...	1 Ko
INFO_UF2.TXT	05/09/2008 16:20	Document texte	1 Ko
RPI_PICO-20240602-v1.23.0.uf2	03/07/2024 18:13	Fichier UF2	645 Ko

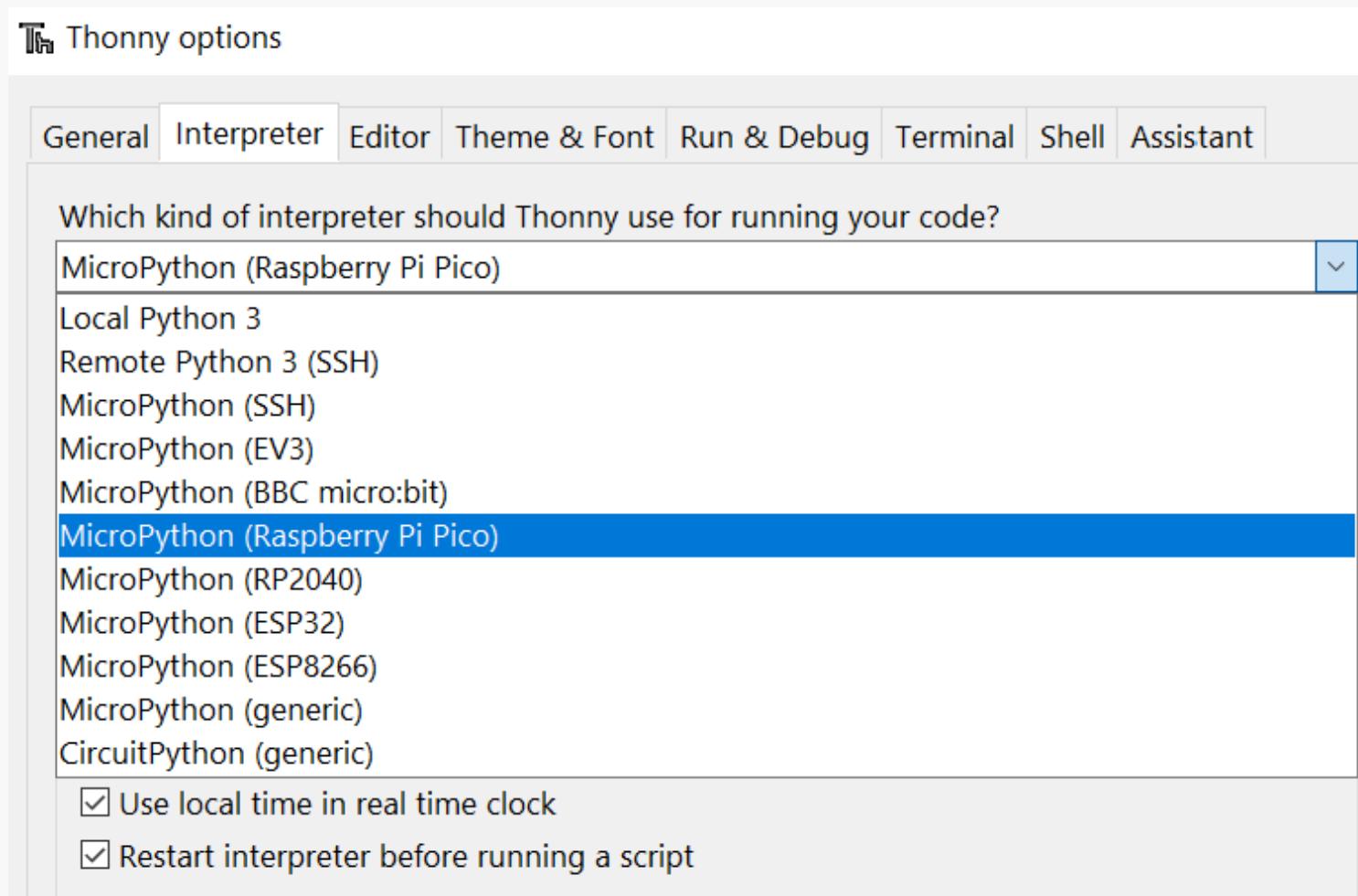
The reader should screw up and disappear from readers

Loading the Software

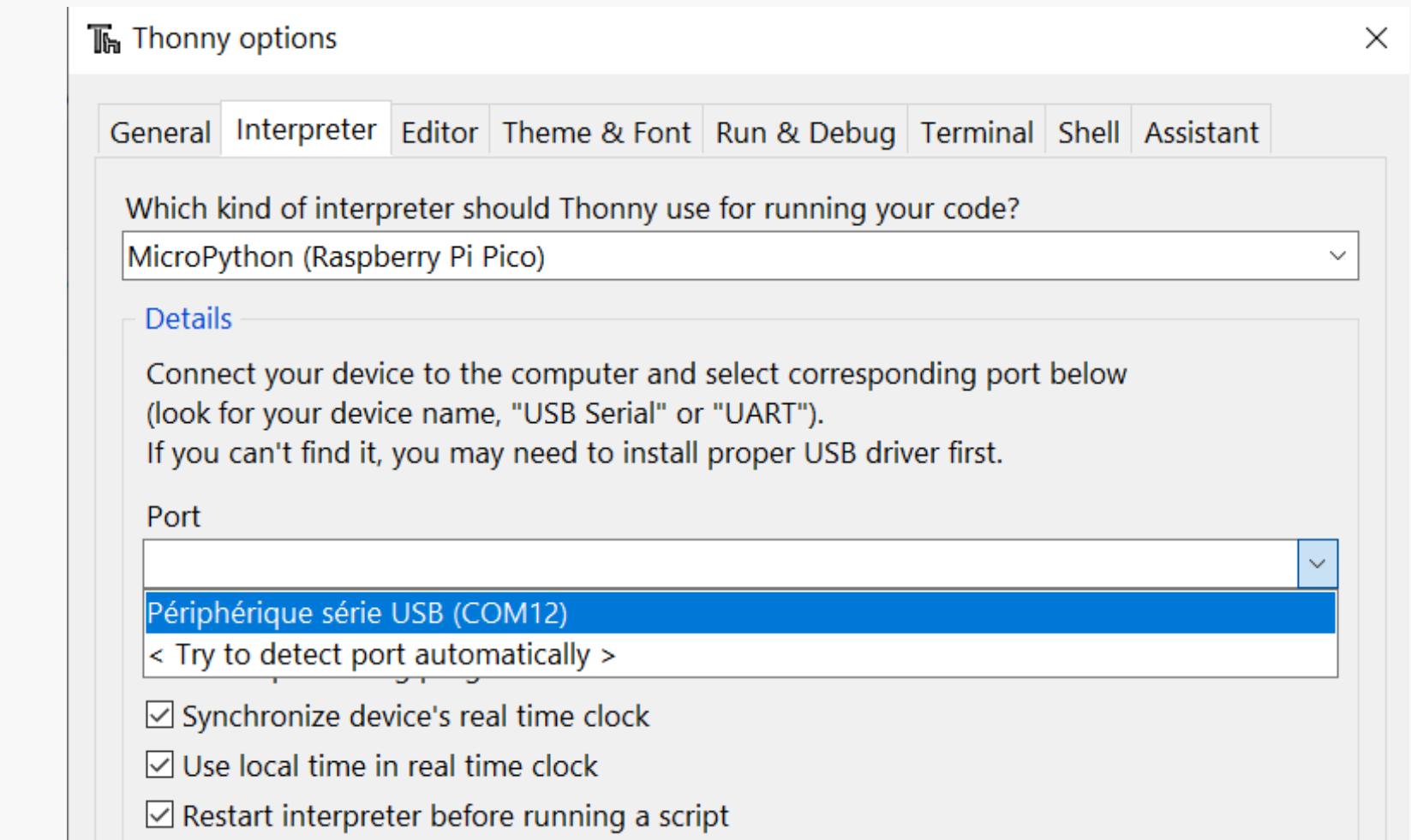
Launch Tonny and go to Run -> Configure interpreter



A window appears

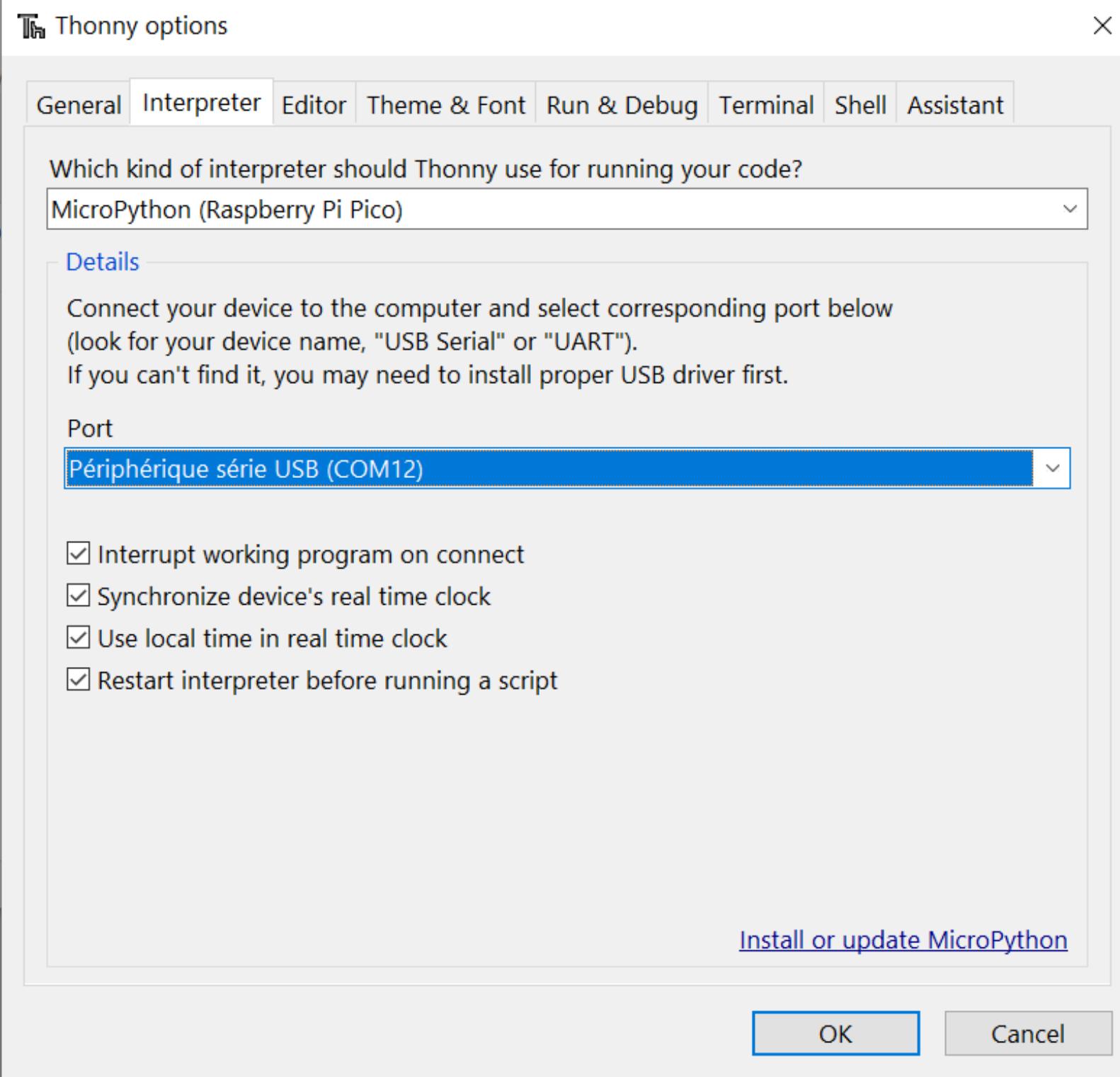


select in the first box MicroPython (Raspberry PI Pico)

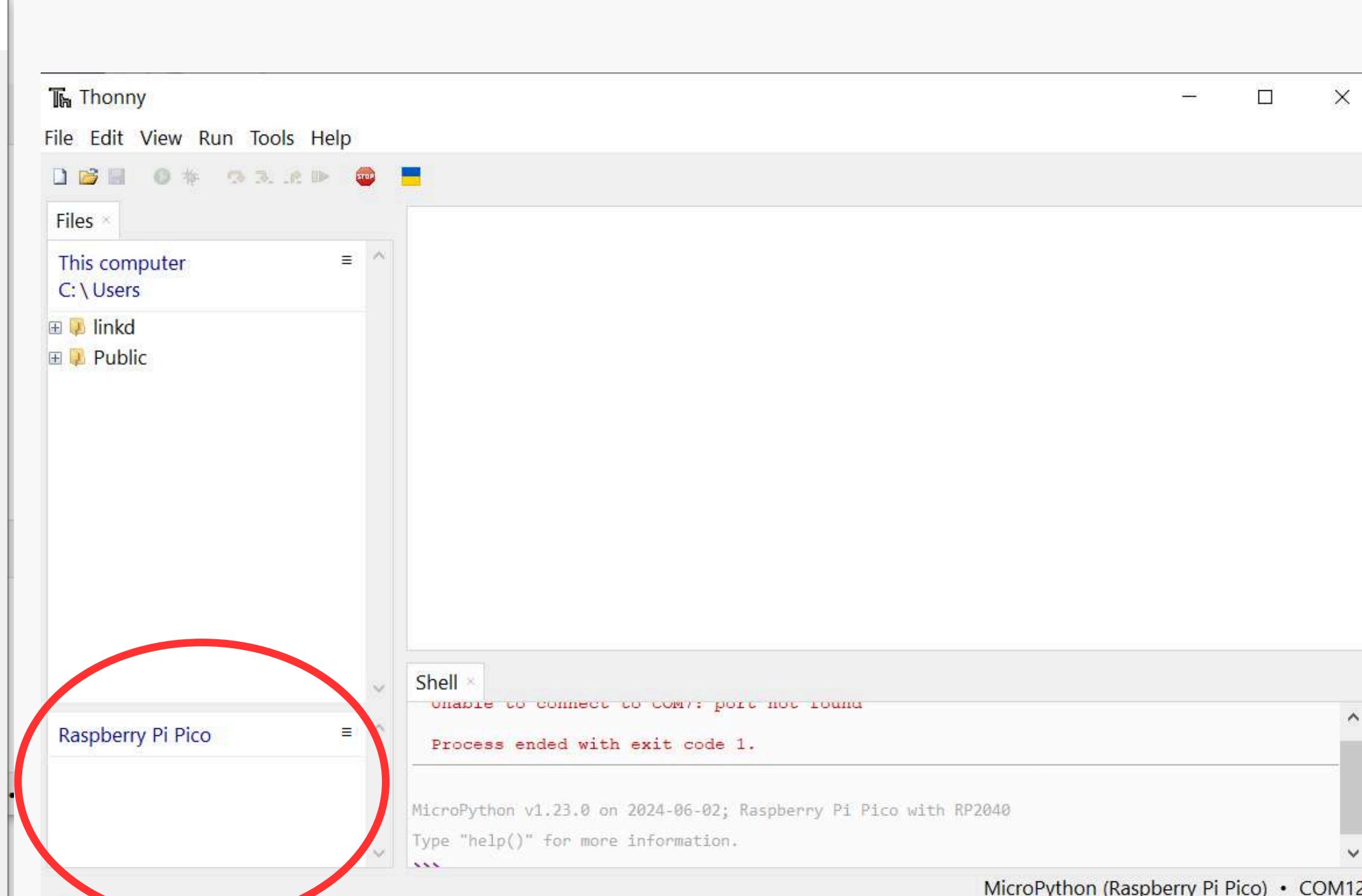


select in the second box your USB device corresponding to the Raspberry PI

Loading the Software



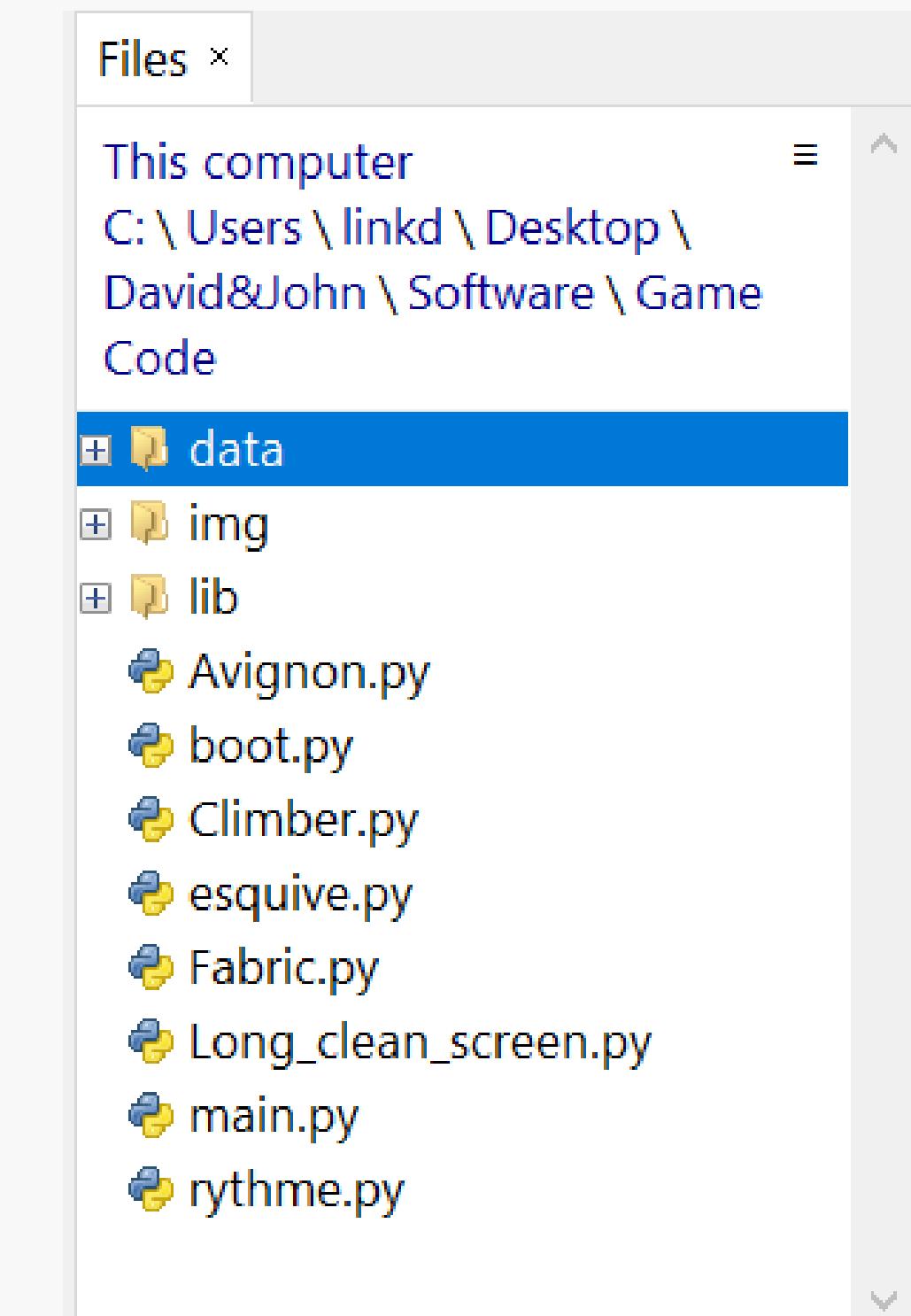
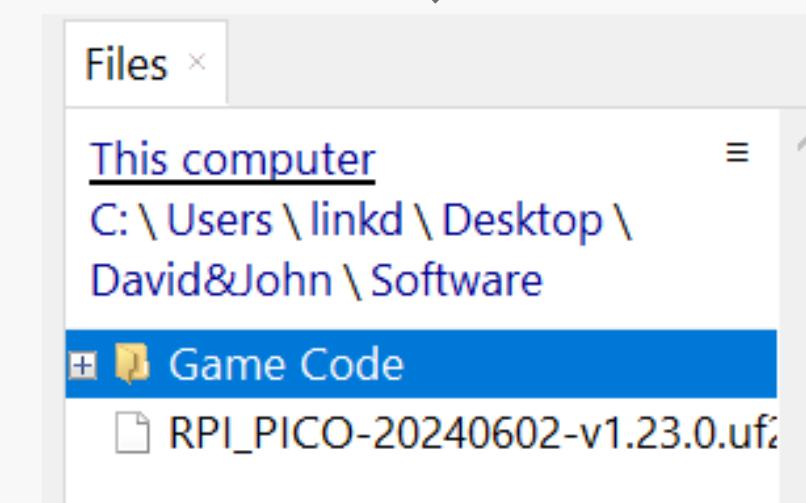
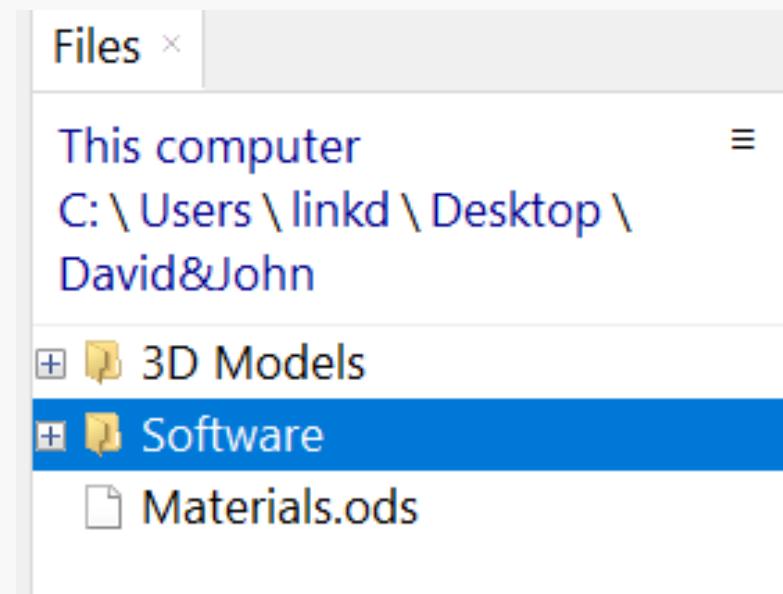
Click OK



The Raspberry PI Pico should appear

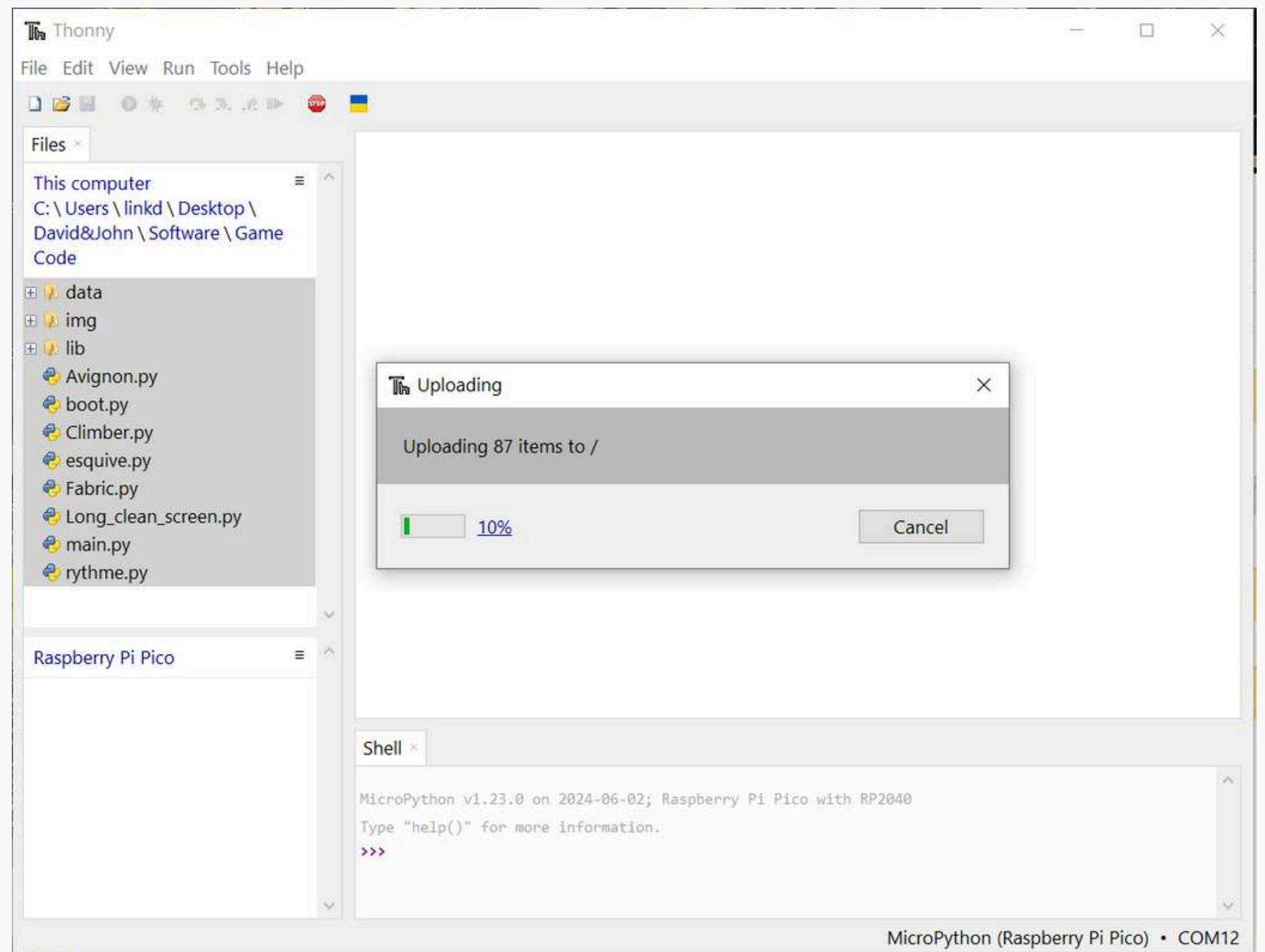
Loading the Software

In the File window go to Software -> Game Code

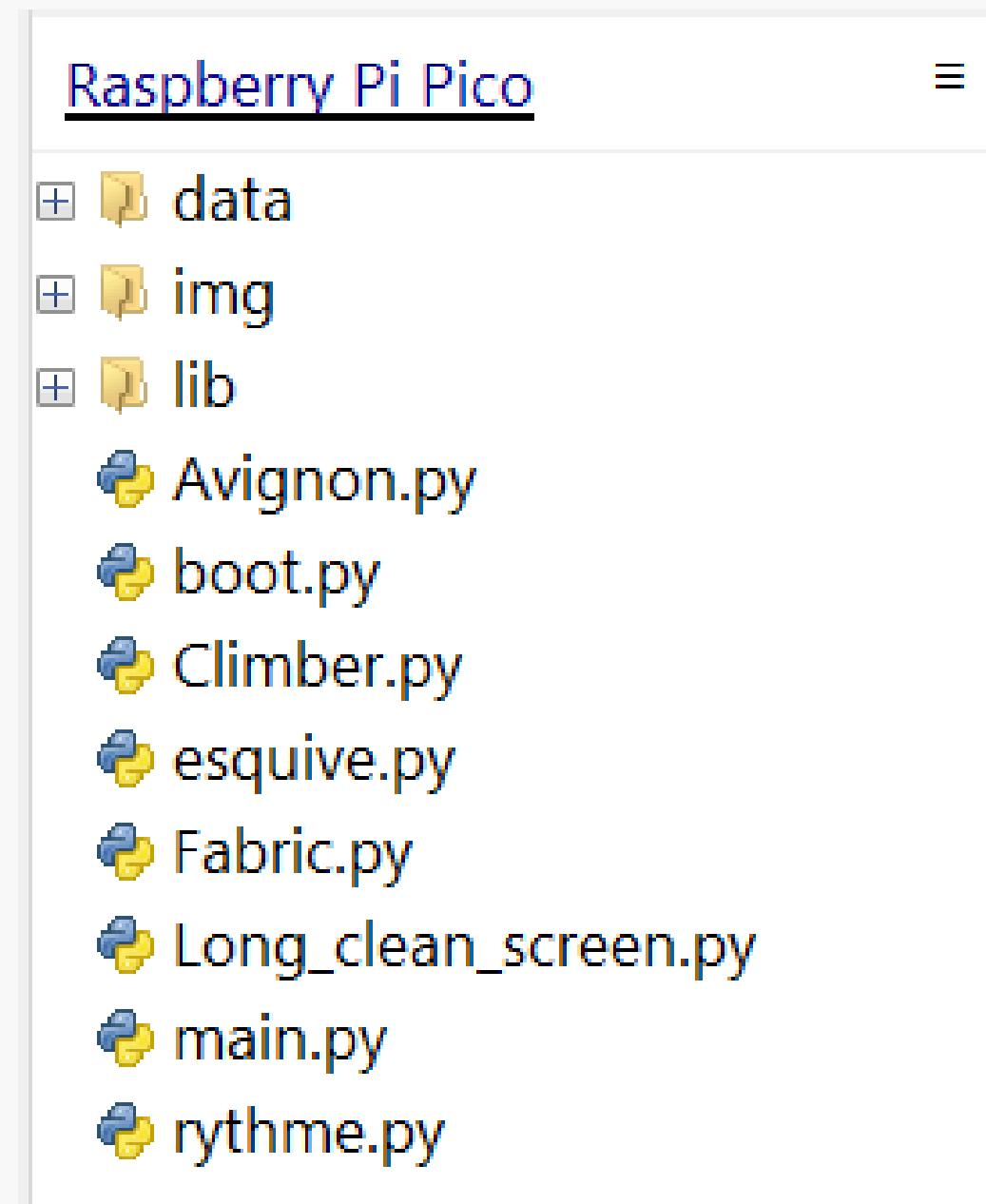


Loading the Software

Select all files, right click and select “Update to /”



The files are completely copied to the Raspberry PI PICO!



Loading the Software



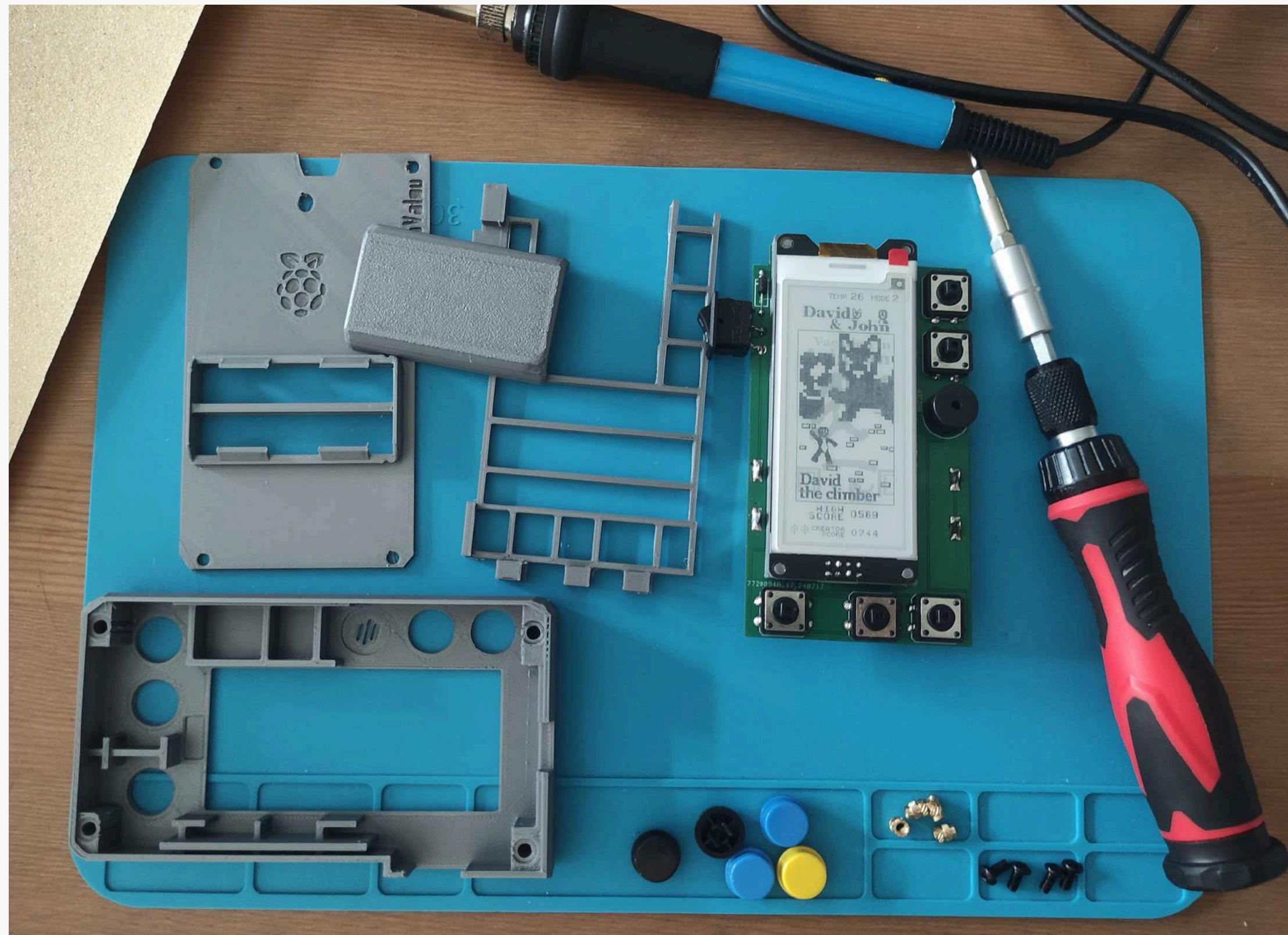
Exit Tonny, unplug and plug back in the Raspberry Pi Pico.
The console should start!

**WARNING ! Test if all the components work correctly
(the sound, the 5 buttons, the batteries) and repair /
resolder / change the components if one of them is
defective
(for example, in this tutorial the buzzer was defective!)**

Case assembly

/05

Materials



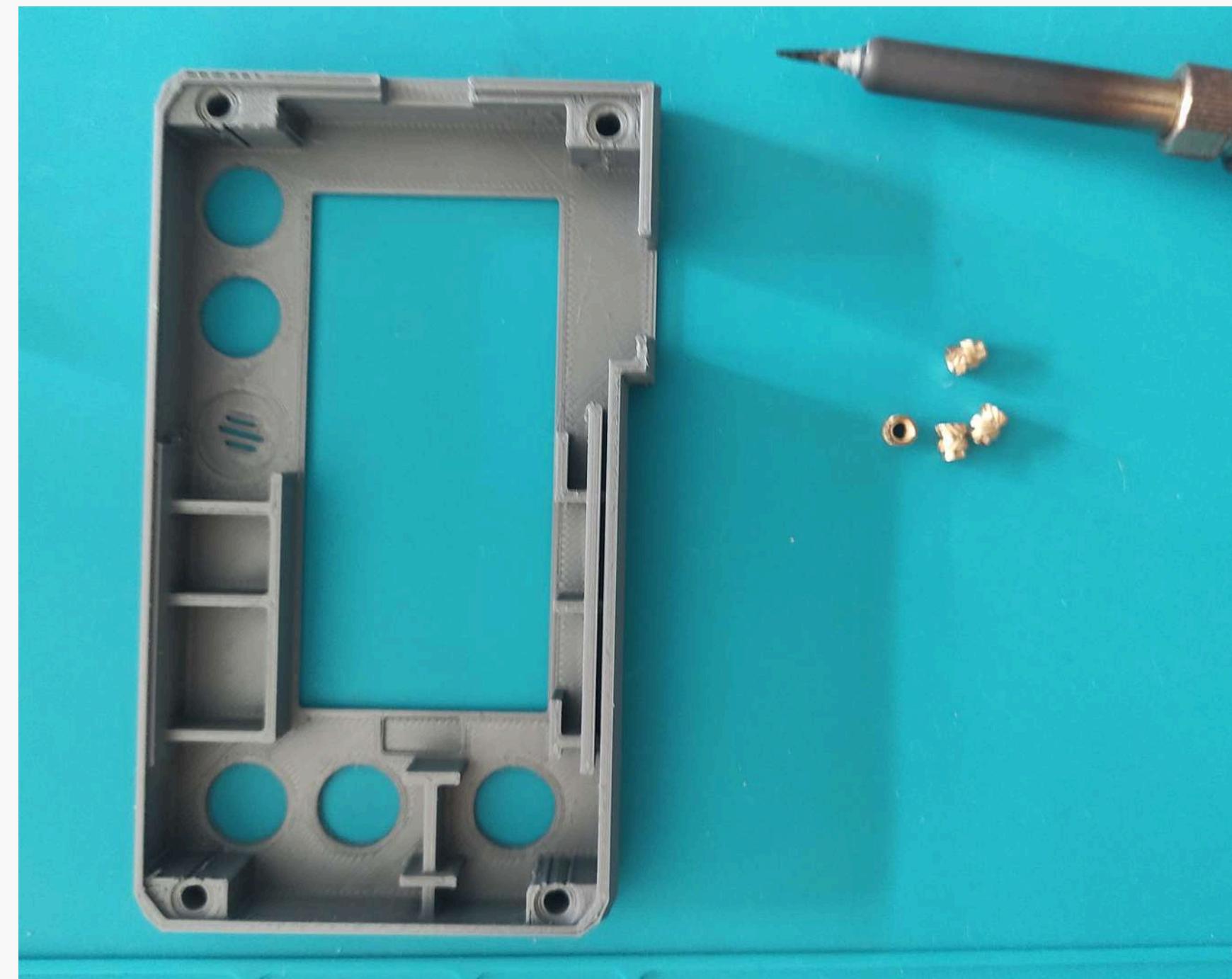
case assembly

/05

Preparing the front case



I advise you to lightly sand the button holes so that they can fit perfectly.



First, we will place the inserts in the 4 holes of the front case

Preparing the front case



Place the insert like this on the tip of the hot soldering iron



Push it into one of the holes in the front case.

Do this until the edge is at the edge of the plastic (To prevent the insert from falling during the operation, hold the shell on its side)



Preparing the front case

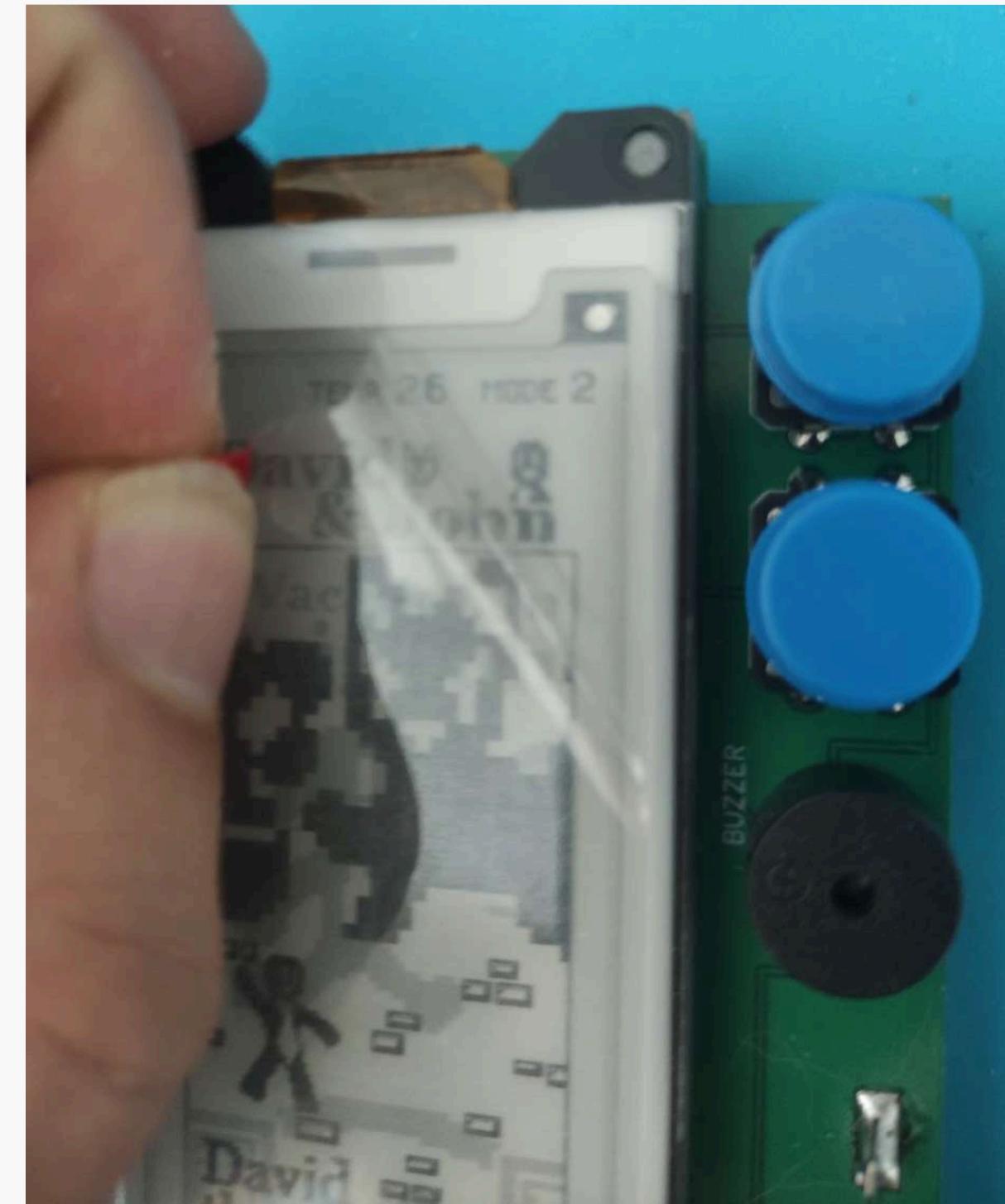


Repeat the action for the
other holes

Inserting the PCB into the case

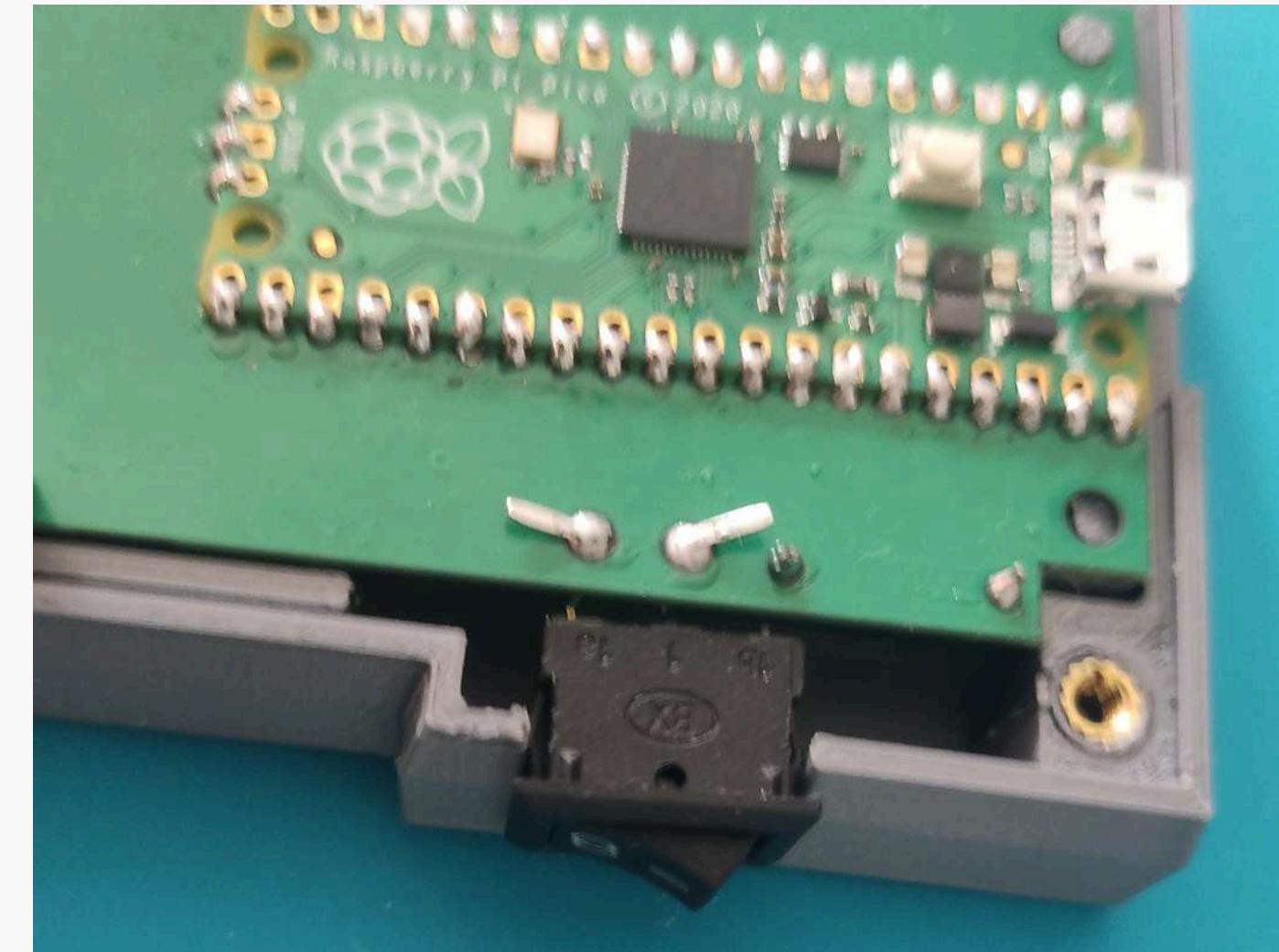
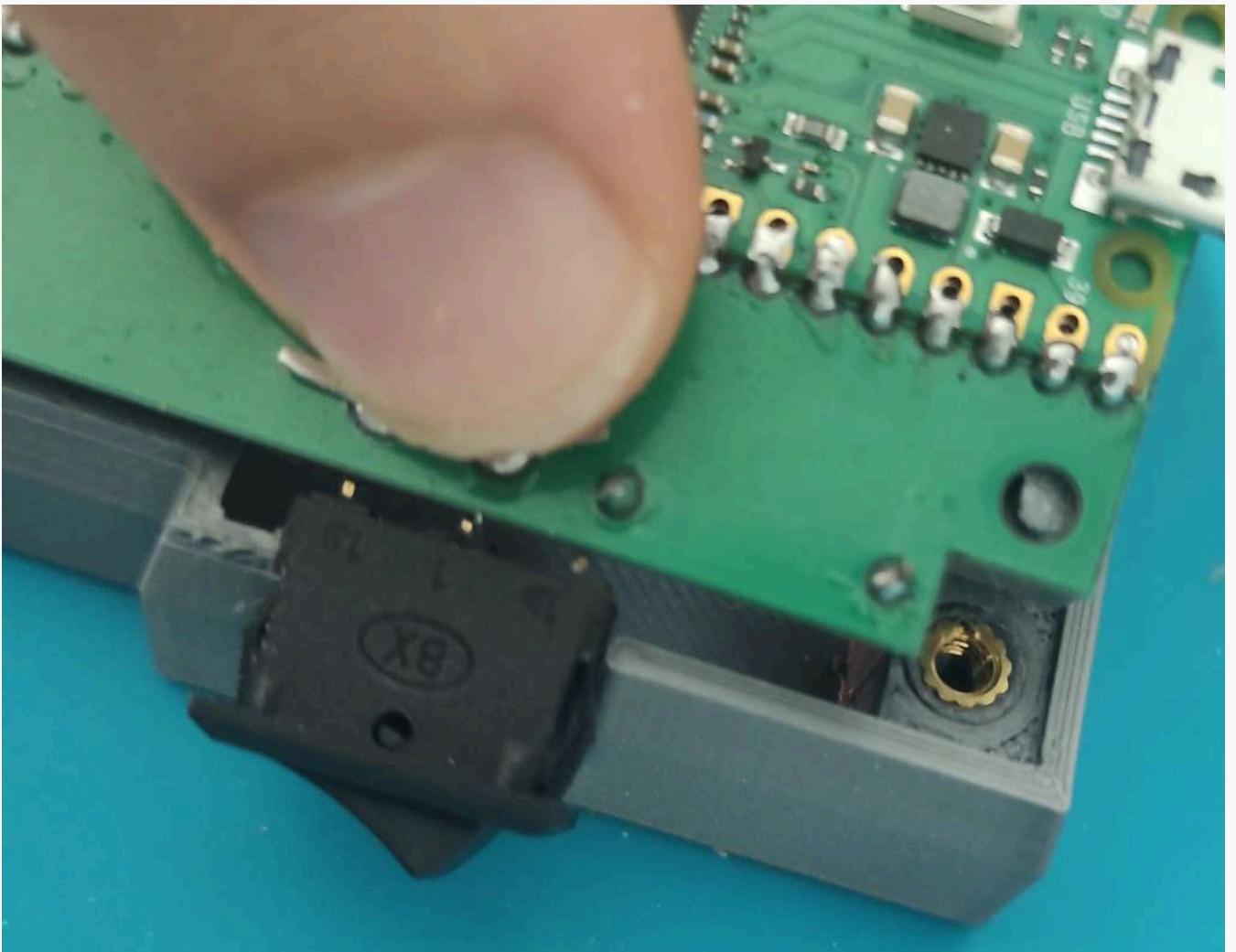


Place the button caps



Remove the film from the screen

Inserting the PCB into the case



To insert the PCB, start by inserting the power button from the outside of the case

Inserting the PCB into the case



Insert the rest of the card until it is completely seated in the front case

Inserting the PCB into the case

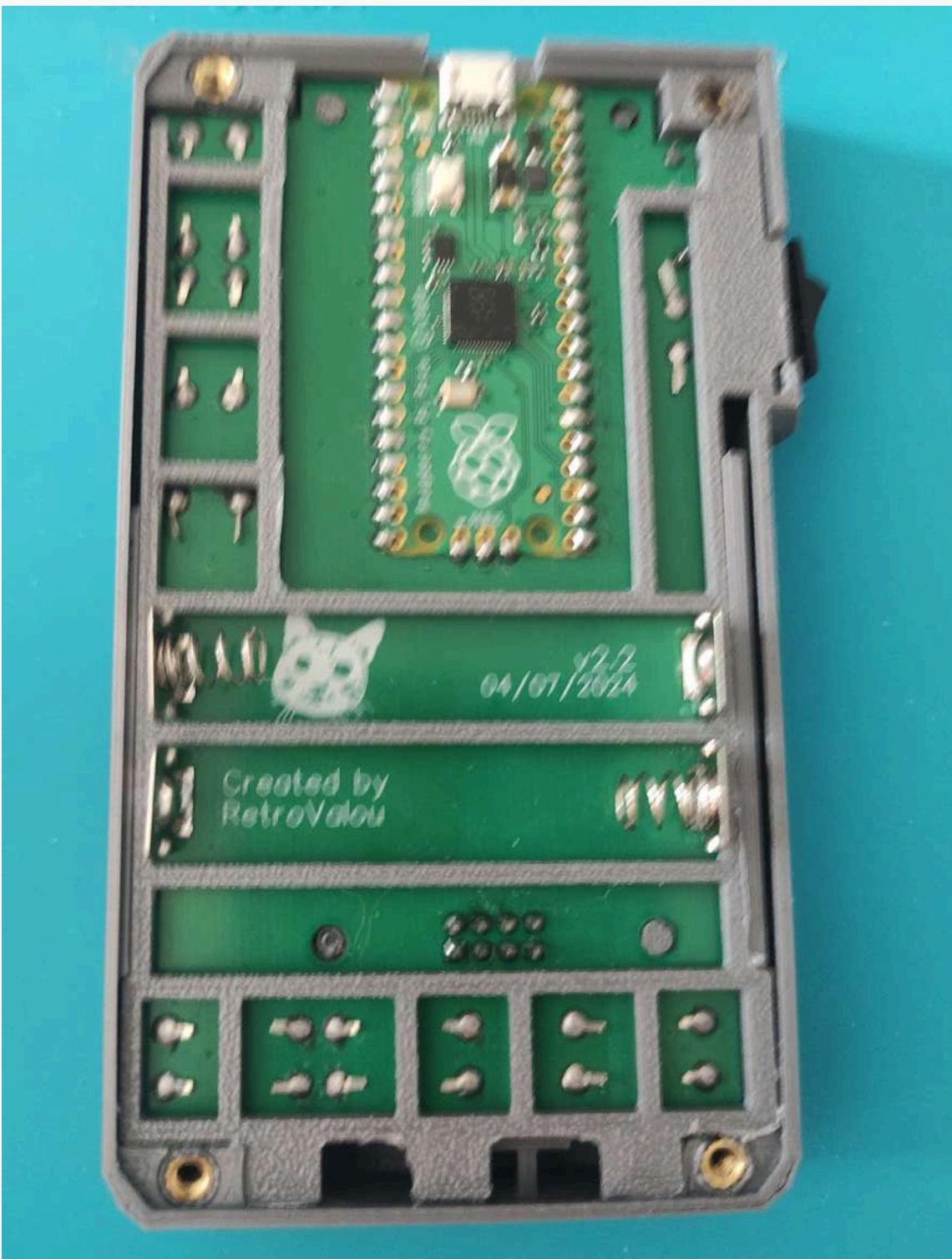


Insert the rest of the card until it is completely seated in the front cover



Check that the buttons click correctly.
If not, remove the PCB and sand button's holes

Assembly of the rest of the case



Insert the PCB holder



Then fit the rear case

Assembly of the rest of the case



Screw in the remaining 3 screws



Insert the batteries

Assembly of the rest of the case



Slide the battery cover into place

END



The console is completely finished!

THANK YOU !
and good
game!

/06