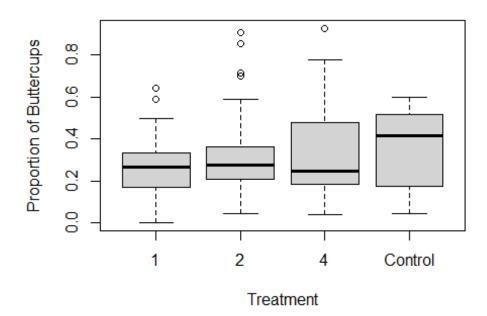
Assignment5Mrkdwn

2023-05-10

Observer should be included as a random effect because different observers may introduce variance into the data due to factors such as the step size of the observer or their interpretation of what is meant by a weed being "exactly" at the tip of their shoe.

A binomial distribution is appropriate because it allows us to model the proportion of successes (steps with butter cup present) out of the total number of steps. This allows us to find the probability of finding a buttercup after each step.



```
mod1 <- glmer(y ~ Trt + Farm + (1|Observer), data = data, family = binomial)</pre>
mod2 \leftarrow glmer(y \sim Trt + (1|Observer) + (1|Farm), data = data, family =
binomial)
mod3 <- glmer(y ~ Trt + (1|Observer) + (1|Farm:Plot),data = data, family =</pre>
binomial)
anova(mod1, mod2, mod3)
## Data: data
## Models:
## mod2: y ~ Trt + (1 | Observer) + (1 | Farm)
## mod3: y ~ Trt + (1 | Observer) + (1 | Farm:Plot)
## mod1: y ~ Trt + Farm + (1 | Observer)
        npar
                       BIC logLik deviance Chisq Df Pr(>Chisq)
                AIC
## mod2
           6 482.23 498.16 -235.12
                                      470.23
## mod3
           6 478.51 494.44 -233.26
                                      466.51 3.7174 0
           9 477.48 501.36 -229.74
                                      459.48 7.0362 3
## mod1
                                                          0.07075 .
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
summary(mod1) #Best model
## Generalized linear mixed model fit by maximum likelihood (Laplace
     Approximation) [glmerMod]
## Family: binomial ( logit )
## Formula: y ~ Trt + Farm + (1 | Observer)
##
      Data: data
##
##
                       logLik deviance df.resid
        AIC
                 BIC
##
      477.5
               501.4
                       -229.7
                                  459.5
                                              96
##
## Scaled residuals:
        Min
                  10
                       Median
                                     3Q
                                             Max
## -2.37497 -0.88004 0.02078 0.67377
                                         3.02819
##
## Random effects:
                         Variance Std.Dev.
## Groups
             Name
## Observer (Intercept) 0.04433 0.2105
## Number of obs: 105, groups: Observer, 5
##
## Fixed effects:
               Estimate Std. Error z value Pr(>|z|)
## (Intercept) -1.30669
                           0.18257
                                     -7.157 8.24e-13 ***
## Trt2
                0.15889
                           0.12930
                                     1.229
                                              0.2191
## Trt4
                                      1.701
                0.21855
                           0.12847
                                              0.0889 .
## TrtControl
                0.22587
                           0.15760
                                      1.433
                                              0.1518
                                     0.968
## FarmB
                0.19313
                           0.19957
                                              0.3332
## FarmF
                           0.20704 -1.504
                                              0.1326
               -0.31136
## FarmR
               -0.39467
                           0.21223 - 1.860
                                              0.0629 .
## FarmS
                0.05252
                           0.19425
                                     0.270
                                              0.7869
```

```
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## Correlation of Fixed Effects:
             (Intr) Trt2
                          Trt4 TrtCnt FarmB FarmF FarmR
##
## Trt2
             -0.356
## Trt4
             -0.355 0.525
## TrtControl -0.300 0.427 0.430
             -0.598 -0.004 -0.009
## FarmB
                                 0.006
## FarmF
## FarmR
             -0.567 -0.021 -0.022 -0.002 0.723
             -0.555 -0.015 -0.020 -0.011 0.707
                                               0.679
## FarmS
             -0.605 -0.012 -0.016 -0.006 0.767 0.736 0.720
```

Model 1 which includes observer as a random effect and treatment and farm as fixed effects is the best model. This is because it has the lowest AIC meaning it has the best tradeoff between goodness of fit and model complexity.

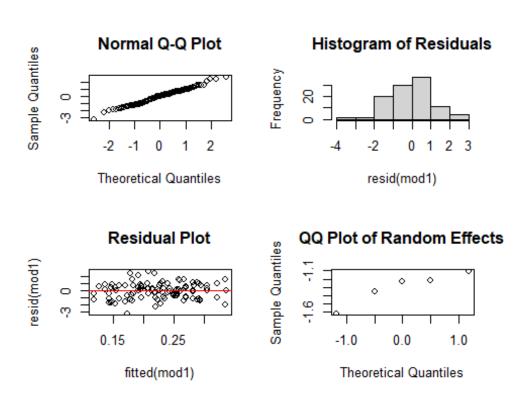
The scaled residuals look good because the median is close to 0 (0.0208) and the 1st and 3rd quartile are reasonably symetric.

The random effect coefficient of 0.044 suggests there are differences between observers when determining if a buttercup is found at the end of a step. This introduces variance into our data which we need to account for.

The fixed effects all have insignificant p-values. This means there is no significant difference between treatments in each farm. The regression equation is log odds of finding buttercup = -1.307 + (0.159 x trt2) + (0.219 x trt4) + (0.226 x control) + (0.193 x farmB) + (-0.311 x farmF) + (-0.395 x farmR) + (0.053 x farmS).

my overall conclusion is that there is no significant difference between treatments in the farms. Our original plot did not show a clear difference between the groups. This observation was backed up by generalised linear mixed effects models coefficients.

```
par(mfrow=c(2,2))
qqnorm(resid(mod1), main="Normal Q-Q Plot")
hist(resid(mod1), main="Histogram of Residuals")
plot(fitted(mod1), resid(mod1), main = "Residual Plot")
abline(0,0, col='red')
qqnorm(coef(mod1)$Observer[,1], main="QQ Plot of Random Effects")
```



The residuals appear to be normally distributed as the residuals can be fit to a straight line in our Normal Q-Q plot and create a bell curve shape in our Histogram of Residuals. The residuals are scattered above and bellow 0 in the Residual plot so we can assume there is constant variance between the residuals.

The points in the QQ Plot of Random Effects can be fit to a striaght line. This menas we can assume our random effects are normally distributed.