
What If Without the Conformal Prediction?

Jing LIANG

Industrial Engineering and Decision Analytics
Hong Kong University of Science and Technology
jliangcd@connect.ust.hk

Abstract

To be continued...

1 Introduction

With the growing use of machine learning in risk-sensitive domains such as medical diagnosis and financial risk management, aggregate metrics such as average accuracy are no longer sufficient. Conventional learning algorithms such as neural networks, support vector machines, and decision trees typically provide only point predictions and do not offer calibrated measures of uncertainty. In practice, decision-makers require not only accurate predictions but also a principled assessment of their reliability.

Conformal prediction addresses this need by constructing, for each new input X_{n+1} , a prediction set

$$C_\alpha(X_{n+1}) \subseteq \mathcal{Y},$$

where \mathcal{Y} denotes the label space and $\alpha \in (0, 1)$ is the target miscoverage level. The goal is to ensure the finite-sample, distribution-free validity guarantee

$$\mathbb{P}(Y_{n+1} \in C_\alpha(X_{n+1})) \geq 1 - \alpha,$$

for the unknown true label Y_{n+1} , assuming only that the data $(X_i, Y_i)_{i=1}^{n+1}$ are exchangeable.

To achieve this, conformal prediction defines a *nonconformity score*

$$V_i = V(X_i, Y_i), \quad i = 1, \dots, n,$$

which measures how atypical an example (X_i, Y_i) is relative to the others. A candidate label y for the new input X_{n+1} is evaluated via its test-time score $V(X_{n+1}, y)$ and included in the prediction set whenever it does not exceed the appropriate empirical quantile of the calibration scores.

If conformal prediction did not exist, what we would lose is not merely an algorithm but a critical meta-methodology: a systematic framework that decouples uncertainty quantification from model design through the construction of nonconformity scores. The impact would extend beyond the disappearance of a single technique, altering the fundamental paradigm for developing uncertainty-aware predictive systems.

2 Background and Need

With the rapid development of artificial intelligence and its widespread deployment across society, both industry and government agencies are increasingly adopting AI-based decision-support systems and agentic task-execution systems. These systems are typically built upon predictive machine learning models, which generate predictions or recommended actions through supervised learning tasks[1].

At the same time, AI technologies are accelerating their penetration into high-risk domains such as medical diagnosis, biometrics, face recognition, nuclear fusion, and industrial diagnostics[2]. In these settings, model failures can lead to severe medical, ethical, economic, or safety consequences. As a result, society and regulatory bodies have raised expectations regarding the reliability, fairness, transparency, and accountability of AI systems, thereby driving the development of Trustworthy AI (TAI).

Within the TAI framework, uncertainty quantification (UQ) plays a central role in ensuring reliability. The goal of UQ is to characterize and evaluate various sources of uncertainty in predictive models, providing reliable and calibrated confidence information[3]. This enables decision-makers to understand the trust boundaries of model outputs and make robust decisions accordingly.

Traditional UQ approaches face structural limitations that constrain their effectiveness in high-risk applications. Bayesian methods, such as Bayesian neural networks, provide probabilistic predictions but rely heavily on strong prior assumptions and the correctness of the model specification; inference is also computationally expensive for large-scale models. Frequentist methods, such as bootstrapping or dropout-based UQ, estimate uncertainty through resampling or approximate inference but typically lack distribution-free, finite-sample guarantees. They also become unstable under distribution shift and incur high computational costs.

Consequently, traditional UQ methods generally fail to provide instance-wise, distribution-free guarantees of validity.

Conformal prediction, however, offers a systematic solution. It provides verifiable, finite-sample validity guarantees for each individual instance without requiring any distributional assumptions, enabling precise quantification of predictive uncertainty.

3 Conformal Prediction

3.1 Historical Development

The theoretical origins of conformal prediction were established in the late 1990s and early 2000s by Vladimir Vovk, Alex Gammerman, and Glenn Shafer[4, 5, 6]. Unlike traditional parametric statistics or Bayesian inference, the methodology arises from the frameworks of algorithmic randomness and game-theoretic probability[6, 7]. Its objective is to construct distribution-free predictive guarantees for machine learning that remain valid for finite samples. Within this paradigm, predictions produce sets of plausible labels rather than single point estimates, and the size of these sets adapts to model uncertainty, thereby providing a direct quantification of predictive reliability.

The foundational contribution to the field is the work that establishes the theoretical basis of conformal prediction [6]. A more recent overview is provided by the monograph “Conformal prediction for reliable machine learning: theory, adaptations and applications” [2].

Recent developments in conformal prediction have focused on three main areas: improving the validity concept, enhancing computational efficiency, and expanding application scope[8].

3.2 Conformal Prediction Framework

Vovk’s work introduces full conformal prediction or transductive conformal prediction [6]. The central idea is that, given a training set and a new test instance, each possible label for the test instance is tentatively paired with the training data to compute a nonconformity score, and the label is included in the prediction set based on its rank among these scores. Because this procedure becomes computationally expensive as the dataset grows, subsequent research has proposed more efficient variants, most notably split conformal prediction[9], which is now widely used. This subsection will focus on split conformal prediction and its technical details, and illustrate the overall conformal framework.

3.2.1 Split Conformal Prediction

Recall the target of conformal prediction : given i.i.d. data $(X_i, Y_i)_{i=1}^n$ with $X_i \in \mathcal{X}$, $Y_i \in \mathcal{Y}$ and a target miscoverage level $\alpha \in (0, 1)$, conformal prediction attempts to construct, for each new input

X_{n+1} , a prediction set

$$C_\alpha(X_{n+1}) \subseteq \mathcal{Y}$$

such that the coverage rate guarantee

$$\mathbb{P}(Y_{n+1} \in C_\alpha(X_{n+1})) \geq 1 - \alpha$$

holds for any underlying distribution, assuming only exchangeability (i.i.d.) of $(X_i, Y_i)_{i=1}^{n+1}$.

Split conformal prediction achieves this by partitioning the data into two parts: a training subset for fitting an arbitrary base model \hat{f} , and a calibration subset for quantifying the model's residual uncertainty. The calibration samples provide an empirical distribution of nonconformity scores, whose appropriate quantile is then used to expand the model's raw prediction into a prediction set with controlled miscoverage. In this way, split CP (Conformal Prediction) converts any point predictor into a distribution-free, finite-sample valid prediction region.

Algorithm 1 Split Conformal Prediction

Require: Dataset $\{(X_i, Y_i)\}_{i=1}^n$; base learner \mathcal{A} ; nonconformity function V_f ; miscoverage level $\alpha \in (0, 1)$

Ensure: Mapping $x \mapsto C_\alpha(x)$

- 1: Randomly split the index set $\{1, \dots, n\}$ into disjoint subsets: training indices I_{train} and calibration indices I_{cal}
- 2: Fit the prediction model on the training set:

$$f \leftarrow \mathcal{A}(\{(X_i, Y_i) : i \in I_{\text{train}}\})$$

- 3: For each $i \in I_{\text{cal}}$, compute the nonconformity score:

$$V_i \leftarrow V_f(X_i, Y_i), \quad i \in I_{\text{cal}}$$

- 4: Let $m \leftarrow |I_{\text{cal}}|$ and $k \leftarrow \lceil (1 - \alpha)(m + 1) \rceil$. Define $\hat{Q}_{1-\alpha}$ as the k -th smallest value in $\{V_i : i \in I_{\text{cal}}\}$
- 5: For any new input $x \in \mathcal{X}$, define the prediction set:

$$C_\alpha(x) \leftarrow \{y \in \mathcal{Y} : V_f(x, y) \leq \hat{Q}_{1-\alpha}\}$$

Moreover, the split conformal prediction algorithm comes with a rigorous theoretical coverage guarantee.

Theorem 1 (Conformal coverage guarantee for Split CP[10]). *Suppose the observations $(X_i, Y_i)_{i=1, \dots, n}$ and the test pair $(X_{\text{test}}, Y_{\text{test}})$ are i.i.d. and let $\hat{Q}_{1-\alpha}$ and $C_\alpha(X_{\text{test}})$ be defined as in Algorithm 1. Then the following coverage guarantee holds:*

$$\mathbb{P}(Y_{\text{test}} \in C_\alpha(X_{\text{test}})) \geq 1 - \alpha.$$

Notice that this theorem shows that the coverage guarantee of split CP is not asymptotic but holds non-asymptotically for any sample size.

3.2.2 Variances and Their Shared Framework

In recent years, conformal prediction has attracted considerable attention and has advanced rapidly. In the following, we provide several representative variants and explain how the components that vary, as well as those that remain invariant, help reveal the essential structure of the conformal prediction framework.

Method	Objective	Core Idea
CV+ / Jackknife+ [11]	Improve statistical efficiency and avoid overly wide intervals from data splitting	Use cross-validation or leave-one-out residuals to obtain more stable error estimates and produce tighter prediction sets.
Weighted CP [12]	Achieve valid coverage under covariate shift or population heterogeneity	Rank scores using importance weights that reflect differences between the target and calibration distributions.
Distributional CP [13]	Handle complex, multimodal, or asymmetric conditional distributions	Construct scores based on estimated CDF values (e.g., $ F(x, y) - 0.5 $) to form high-density prediction regions.
CP for hierarchical structure data [14]	Handle data with group-level heterogeneity and hierarchical sampling structures	Replace standard exchangeability with hierarchical exchangeability and construct prediction sets using pooled CDF, double conformal, or subsampling-based aggregation across groups.
Adaptive Prediction Sets [15, 16]	Improve fairness of coverage across classes and sample difficulty	Use cumulative softmax probability to define an ordered score and adjust prediction set size according to sample difficulty.
Conformalized Quantile Regression [17]	Construct more adaptive regression intervals	Measure deviation from upper and lower quantiles and calibrate these to form intervals adaptive to conditional distribution shape.

From the table, we can see that although recent developments in conformal prediction have produced many variants, their innovations mainly focus on how the score is designed, what is calibrated, or how the exchangeability assumption is extended. These represent the variant component of the CP framework. Different methods modify the source of the scores, the geometric form of the scores, or model the underlying data structure and distribution shift to better adapt to new tasks, data structures, or distributional settings. These changes improve the applicability of CP in complex, high-dimensional, heteroscedastic, multimodal, and non-i.i.d. scenarios, allowing the framework to remain flexible across different use cases.

In contrast, all methods preserve the invariant component of conformal prediction. No matter how the method varies, the validity mechanism follows the same basic design: construct a score that measures the discrepancy between the prediction and the ground truth, compute its empirical distribution on the calibration set, and rely on exchangeability to obtain validity guarantees.

4 Key Insights and Benefit of Conformal Prediction

Therefore, the true insight of conformal prediction is that it offers a meta-methodology:

1. Decoupling: It separates model performance (implicitly reflected through the score function A) from output guarantees (derived from rank-based calibration and exchangeability).
2. Guarantee-first design: It reverses the traditional approach. Instead of trying to make model outputs “look like” probabilities and then hoping for guarantees, CP first builds a framework that inherently provides guarantees (via calibration and set-valued prediction), and then embeds any model inside it.

5 Alternative Methods

A wide range of uncertainty quantification techniques have been developed across statistics and machine learning. These approaches differ in their underlying assumptions, the form of guarantees they provide, and their suitability for various application settings. Table summarizes the main methodological families commonly used as competitors to conformal prediction.

Method Family	Key Idea	Representative Competitors
Classical parametric prediction intervals	Assume a fully specified parametric model, typically linear with Gaussian noise	Gaussian linear model (t-interval)
Semi- / Non-parametric prediction bands	Assume a functional form for estimation, such as conditional means or quantiles, without making distributional assumptions	Quantile regression bands
Bayesian framework	Characterize uncertainty through the posterior predictive distribution	Bayesian neural networks; Bayesian model averaging
PAC-learning	Provide worst-case upper bounds on prediction error over the hypothesis class	Vapnik–Chervonenkis bounds; Littlestone–Warmuth bounds
Hold-out and resampling-based methods	Estimate uncertainty empirically via data splitting or repeated resampling	Train–test hold-out; cross-validation; bootstrap

None of these approaches simultaneously achieve the combination of distribution-free operation, finite-sample validity, and instance-wise guarantees that conformal prediction provides. Nevertheless, each method family has its own advantages and suitable application contexts. The remainder of this section outlines the core ideas behind several representative competitors and contrasts them with conformal prediction to highlight its distinct value.

5.1 Bayesian Framework

Bayesian methods can yield efficient and well-calibrated intervals when the likelihood and prior are correctly specified, and they naturally account for parameter uncertainty through the posterior. However, their guarantees depends on the prior. Under misspecification, Bayesian credible intervals often suffer from severe undercoverage despite appearing narrow, and the Bayesian framework provides no coverage guarantee.

In contrast, conformal prediction is agnostic to the data-generating mechanism and avoids reliance on priors or likelihood models. Its intervals remain finite-sample valid under the sole assumption of exchangeability, maintaining stable coverage even when the predictive model is misspecified. The trade-off is efficiency: conformal intervals are typically wider, particularly at high confidence levels or with limited calibration data, because they must guard against worst-case residual behavior.

In this section, the comparisons are organized across three settings. First, full Bayesian and empirical Bayesian approaches are examined in the context of ridge regression, contrasting full posterior integration with the empirical Bayes approximation that estimates prior hyperparameters from data. Second, the analysis is extended to a Bayesian neural network on the UCI ENB2012 Energy dataset[18], using an MLP backbone to isolate the effect of the Bayesian treatment itself. Together, these experiments provide a unified view of how Bayesian uncertainty behaves in both linear and nonlinear models, and how it compares with distribution-free conformal prediction.

5.1.1 Full Bayesian and Empirical Bayesian

This experiment based on the general setup of [19] and compare the interval performance of Full Bayesian Ridge Regression and Split Conformal Prediction using generated data. The input features $x \in [-10, 10]^5$ are independently sampled from a uniform distribution, and the weight vector w is drawn from a standard normal prior $\mathcal{N}(0, I)$. Labels are generated according to

$$y = x^\top w + \varepsilon, \quad \varepsilon \sim \mathcal{N}(0, 1).$$

A single training–test split (100 training points and 100 test points) is fixed using a predetermined random seed, and we evaluate 20 significance levels $\alpha \in [0.01, 0.99]$ on this fixed dataset. Each

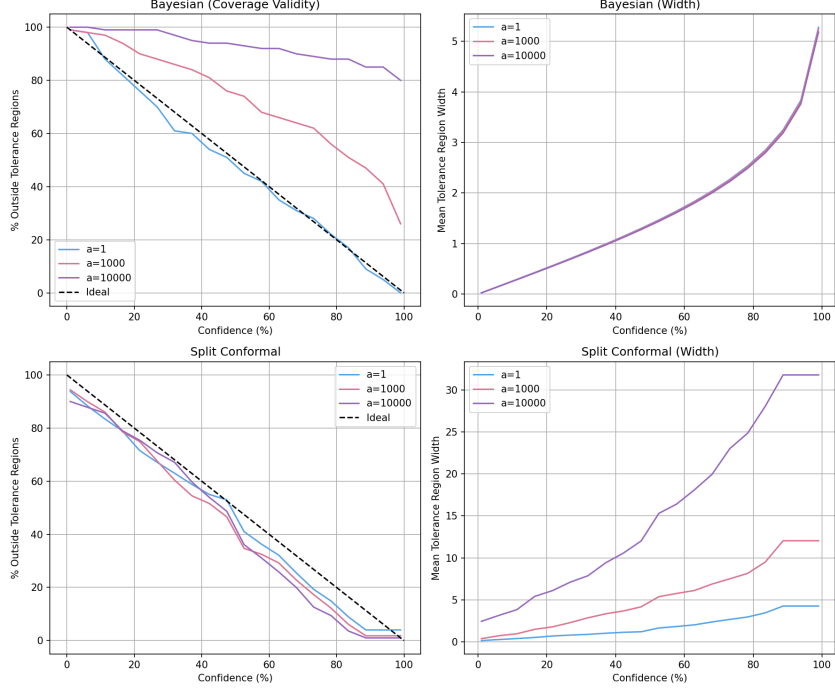


Figure 1: Full Bayesian RR and Split Conformal prediction for RR.

(a, α) configuration is repeated 10 times: Bayesian Ridge uses the same dataset in all repetitions, whereas Split Conformal varies only the internal random seed that determines the calibration split.

Bayesian Ridge Regression applies

$$\Sigma = (X^\top X + aI)^{-1}, \quad \mu = \Sigma X^\top y,$$

and constructs Gaussian predictive intervals via

$$y \mid \mathcal{D} \sim \mathcal{N}(x\mu, 1 + x\Sigma x),$$

evaluating the effect of prior misspecification with $a \in \{1, 1000, 10000\}$.

Split Conformal Prediction uses the same Ridge predictor but randomly partitions the training data into 80% proper training and 20% calibration subsets, forming distribution-free intervals from the finite-sample quantile of the calibration residuals.

Across all confidence $(1 - \alpha)$, this experiment evaluate both the empirical coverage and the mean interval width, thereby comparing the sensitivity of Bayesian intervals to prior misspecification against the distribution-free robustness of Split Conformal Prediction.

In addition, since Full Bayesian methods are no longer the preferred choice after the introduction of Empirical Bayes, the experiment also incorporates an Empirical Bayesian variant to provide a more modern and practically relevant comparison.

As shown in figure 1, when the prior is correctly specified ($a = 1$), Bayesian Ridge Regression produces valid prediction intervals. As a increases and the prior becomes misspecified, the Bayesian intervals deteriorate sharply: their coverage collapses while the interval width remains almost unchanged. In contrast, the width of the Split Conformal intervals increases with the confidence level and maintains valid coverage across all settings.

A similar pattern appears in the empirical Bayesian variant in 2. With the correct prior, it achieves good coverage with intervals narrower than those of the full Bayesian method. Under severe prior misspecification, the empirical Bayesian intervals widen and display some degree of robustness, yet their coverage still remains below that of Split Conformal Prediction, can not reach the desired level.

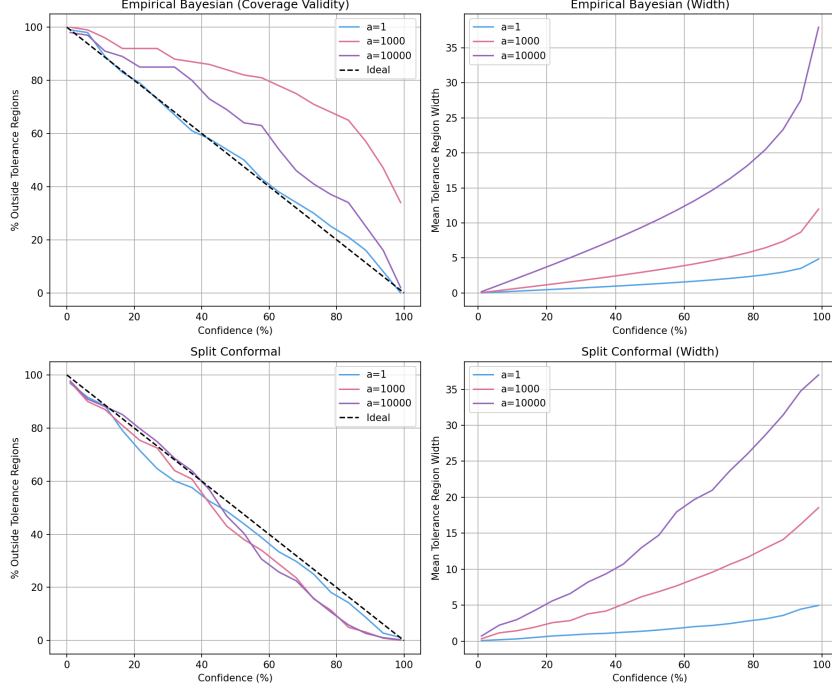


Figure 2: Empirical Bayesian RR and Split Conformal prediction for RR.

5.1.2 Bayesian Neural Network

Recent years have introduced improved Bayesian neural network (BNN) methods [20]. Their core idea is simple: instead of learning a single set of network weights, a BNN places a prior over the weights and learns a posterior distribution. Sampling from this posterior gives multiple plausible models, allowing the prediction uncertainty to reflect both model uncertainty (epistemic) and data noise (aleatoric).

This experiment applies such a BNN to the UCI ENB2012 Energy dataset[18], using the same MLP backbone as in the CP baseline.

The UCI ENB2012 Energy dataset contains 768 simulated building designs, each described by eight physical and geometric features such as wall area, roof area, glazing ratio, and overall height. These features are used to predict two real-valued heating and cooling load indicators. The dataset is low-dimensional, noise-modest, and exhibits smooth nonlinear structure, making it a standard benchmark for regression and uncertainty quantification.

In this experiment, both the BNN and Split CP use the same base learner: an MLP with input dimension 8, one hidden layer of width 64 with ReLU. The BNN adopts a mean-field variational formulation (Bayes-by-Backprop style)[21], placing independent Gaussian priors on all weights and learning Gaussian posterior parameters via an ELBO objective with reparameterized sampling.

and a 1-dimensional output. The BNN employs Gaussian priors $w, b \sim \mathcal{N}(0, 1)$ and is trained for 100 epochs using Adam (10^{-3} learning rate, batch size 64). Posterior prediction is approximated with $T = 200$ Monte Carlo samples, yielding predictive mean μ and standard deviation σ (after inverting the response scaling). The $(1 - \alpha)$ interval is $\mu \pm z_{1-\alpha/2} \sigma$.

For Split CP, the same MLP is trained on 70% of the data, with the remaining 30% used for calibration. Absolute residuals are sorted, and the conformal radius for level α is taken at index $\lceil (n_{\text{cal}} + 1)(1 - \alpha) \rceil$. CP intervals are obtained by adding/subtracting this radius to the MLP predictions on the raw scale.

Figure 3 shows that, under the same MLP base model, BNN intervals deviate sharply from the ideal diagonal: the fraction of points outside the intervals is far above nominal, reflecting severely

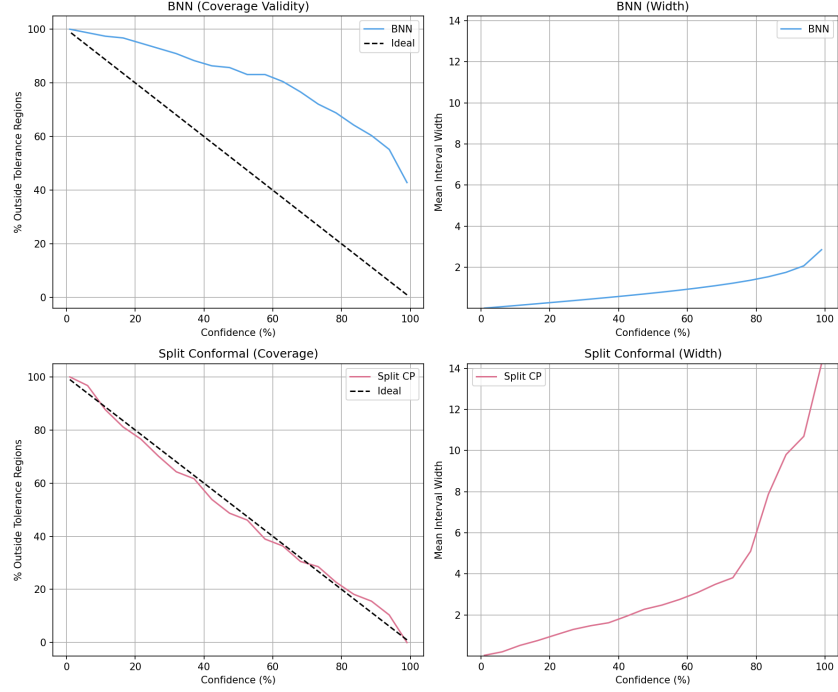


Figure 3: BNN and Split CP on UCI ENB2012.

underestimated posterior variance and strong overconfidence. The intervals remain narrow across confidence levels, consistent with the observed undercoverage.

By contrast, Split Conformal closely follows the ideal line, with interval width increasing predictably with confidence. Although wider, these intervals achieve near-nominal coverage.

Overall, BNN fails to provide valid frequentist coverage, while Split Conformal delivers stable, distribution-free, finite-sample guarantees.

5.2 Bootstrap resampling

5.3 quantile regression

5.4 Others

6 Implications of a World Without Conformal Prediction

TBC

7 Conclusion

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