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frontier — Stochastic frontier models

Syntax Menu Description Options
Remarks and examples Stored results Methods and formulas References

Also see

Syntax 3 4 1

```
frontier depvar [indepvars][if][in][weight][, options]
 options
                                 Description
Model
                                 suppress constant term
 noconstant
 distribution(hnormal)
                                 half-normal distribution for the inefficiency term
 distribution(exponential) exponential distribution for the inefficiency term
                                 truncated-normal distribution for the inefficiency term
 distribution(tnormal)
 ufrom(matrix)
                                 specify untransformed log likelihood; only with d(tnormal)
 cm(varlist |, noconstant |)
                                 fit conditional mean model; only with d(tnormal); use
                                   noconstant to suppress constant term
Model 2
                                 apply specified linear constraints
 constraints (constraints)
 collinear
                                 keep collinear variables
 <u>uhet(varlist|, noconstant|)</u> explanatory variables for technical inefficiency variance
                                   function; use no constant to suppress constant term
 vhet (varlist | , no constant | ) explanatory variables for idiosyncratic error variance
                                    function; use noconstant to suppress constant term
                                 fit cost frontier model; default is production frontier model
 cost
SE
 vce(vcetype)
                                 vcetype may be oim, opg, bootstrap, or jackknife
Reporting
 level(#)
                                 set confidence level; default is level(95)
                                 do not display constraints
 nocnsreport
 display_options
                                 control column formats, row spacing, line width, display of omitted
                                    variables and base and empty cells, and factor-variable labeling
Maximization
                                 control the maximization process; seldom used
 maximize_options
                                 display legend instead of statistics
 coeflegend
```

indepvars and varlist may contain factor variables; see [U] 11.4.3 Factor variables. bootstrap, by, fp, jackknife, rolling, and statsby are allowed; see [U] 11.1.10 Prefix commands. Weights are not allowed with the bootstrap prefix; see [R] bootstrap. fweights, iweights, and pweights are allowed; see [U] 11.1.6 weight. coeflegend does not appear in the dialog box.

See [U] 20 Estimation and postestimation commands for more capabilities of estimation commands.

Menu

Statistics > Linear models and related > Frontier models

Description

frontier fits stochastic production or cost frontier models; the default is a production frontier model. It provides estimators for the parameters of a linear model with a disturbance that is assumed to be a mixture of two components, which have a strictly nonnegative and symmetric distribution, respectively. frontier can fit models in which the nonnegative distribution component (a measurement of inefficiency) is assumed to be from a half-normal, exponential, or truncated-normal distribution. See Kumbhakar and Lovell (2000) for a detailed introduction to frontier analysis.

Options

____ Model

noconstant; see [R] estimation options.

distribution (distname) specifies the distribution for the inefficiency term as half-normal (hnormal), exponential, or truncated-normal (tnormal). The default is hnormal.

ufrom(matrix) specifies a $1 \times K$ matrix of untransformed starting values when the distribution is truncated-normal (tnormal). frontier can estimate the parameters of the model by maximizing either the log likelihood or a transformed log likelihood (see Methods and formulas). frontier automatically transforms the starting values before passing them on to the transformed log likelihood. The matrix must have the same number of columns as there are parameters to estimate.

cm(varlist [, noconstant]) may be used only with distribution(tnormal). Here frontier will fit a conditional mean model in which the mean of the truncated-normal distribution is modeled as a linear function of the set of covariates specified in varlist. Specifying noconstant suppresses the constant in the mean function.

Model 2

constraints(constraints), collinear; see [R] estimation options.

By default, when fitting the truncated-normal model or the conditional mean model, frontier maximizes a transformed log likelihood. When constraints are applied, frontier will maximize the untransformed log likelihood with constraints defined in the untransformed metric.

uhet(varlist[, noconstant]) specifies that the technical inefficiency component is heteroskedastic, with the variance function depending on a linear combination of varlistu. Specifying noconstant suppresses the constant term from the variance function. This option may not be specified with distribution(tnormal).

vhet(varlist[, noconstant]) specifies that the idiosyncratic error component is heteroskedastic, with the variance function depending on a linear combination of varlistv. Specifying noconstant suppresses the constant term from the variance function. This option may not be specified with distribution(tnormal).

cost specifies that frontier fit a cost frontier model.

SF

vce(vcetype) specifies the type of standard error reported, which includes types that are derived from asymptotic theory (oim, opg) and that use bootstrap or jackknife methods (bootstrap, jackknife); see [R] vce_option.

Reporting

level(#); see [R] estimation options.

nocnsreport; see [R] estimation options.

display_options: noomitted, vsquish, noemptycells, baselevels, allbaselevels, nofvlabel, fvwrap(#), fvwrapon(style), cformat(%fmt), pformat(%fmt), sformat(%fmt), and nolstretch; see [R] estimation options.

Maximization

maximize_options: difficult, technique(algorithm_spec), iterate(#), [no]log, trace, gradient, showstep, hessian, showtolerance, tolerance(#), ltolerance(#), nrtolerance(#), nonrtolerance, and from(init_specs); see [R] maximize. These options are seldom used.

Setting the optimization type to technique(bhhh) resets the default vcetype to vce(opg).

The following option is available with frontier but is not shown in the dialog box: coeflegend; see [R] estimation options.

Remarks and examples

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Stochastic production frontier models were introduced by Aigner, Lovell, and Schmidt (1977) and Meeusen and van den Broeck (1977). Since then, stochastic frontier models have become a popular subfield in econometrics. Kumbhakar and Lovell (2000) provide a good introduction.

frontier fits three stochastic frontier models with distinct parameterizations of the inefficiency term and can fit stochastic production or cost frontier models.

Let's review the nature of the stochastic frontier problem. Suppose that a producer has a production function $f(\mathbf{z}_i, \boldsymbol{\beta})$. In a world without error or inefficiency, the *i*th firm would produce

$$q_i = f(\mathbf{z}_i, \boldsymbol{\beta})$$

Stochastic frontier analysis assumes that each firm potentially produces less than it might due to a degree of inefficiency. Specifically,

$$q_i = f(\mathbf{z}_i, \boldsymbol{\beta})\xi_i$$

where ξ_i is the level of efficiency for firm i; ξ_i must be in the interval (0,1]. If $\xi_i=1$, the firm is achieving the optimal output with the technology embodied in the production function $f(\mathbf{z}_i, \boldsymbol{\beta})$. When $\xi_i < 1$, the firm is not making the most of the inputs \mathbf{z}_i given the technology embodied in the production function $f(\mathbf{z}_i, \boldsymbol{\beta})$. Because the output is assumed to be strictly positive (that is, $q_i > 0$), the degree of technical efficiency is assumed to be strictly positive (that is, $\xi_i > 0$).

Output is also assumed to be subject to random shocks, implying that

$$q_i = f(\mathbf{z}_i, \boldsymbol{\beta}) \xi_i \exp(v_i)$$

Taking the natural log of both sides yields

$$\ln(q_i) = \ln\{f(\mathbf{z}_i, \boldsymbol{\beta})\} + \ln(\xi_i) + v_i$$

Assuming that there are k inputs and that the production function is linear in logs, defining $u_i = -\ln(\xi_i)$ yields

$$\ln(q_i) = \beta_0 + \sum_{j=1}^k \beta_j \ln(z_{ji}) + v_i - u_i$$
 (1)

Because u_i is subtracted from $\ln(q_i)$, restricting $u_i \geq 0$ implies that $0 < \xi_i \leq 1$, as specified above.

Kumbhakar and Lovell (2000) provide a detailed version of the above derivation, and they show that performing an analogous derivation in the dual cost function problem allows us to specify the problem as

$$\ln(c_i) = \beta_0 + \beta_q \ln(q_i) + \sum_{i=1}^k \beta_j \ln(p_{ji}) + v_i + u_i$$
 (2)

where q_i is output, z_{ii} are input quantities, c_i is cost, and the p_{ii} are input prices.

Intuitively, the inefficiency effect is required to lower output or raise expenditure, depending on the specification.

□ Technical note

The model that frontier actually fits is of the form

$$y_i = \beta_0 + \sum_{j=1}^{k} \beta_j x_{ji} + v_i - su_i$$

where

$$s = \left\{ \begin{array}{ll} 1, & \text{for production functions} \\ -1, & \text{for cost functions} \end{array} \right.$$

so, in the context of the discussion above, $y_i = \ln(q_i)$, and $x_{ji} = \ln(z_{ji})$ for a production function; and for a cost function, $y_i = \ln(c_i)$, and the x_{ji} are the $\ln(p_{ji})$ and $\ln(q_i)$. You must take the natural logarithm of the data before fitting a stochastic frontier production or cost model. frontier performs no transformations on the data.

Different specifications of the u_i and the v_i terms give rise to distinct models. frontier provides estimators for the parameters of three basic models in which the idiosyncratic component, v_i , is assumed to be independently $N(0, \sigma_v)$ distributed over the observations. The basic models differ in their specification of the inefficiency term, u_i , as follows:

exponential: the u_i are independently exponentially distributed with variance σ_u^2

hnormal: the u_i are independently half-normally $N^+(0,\sigma_u^2)$ distributed

tnormal: the u_i are independently $N^+(\mu, \sigma_u^2)$ distributed with truncation point at 0

For half-normal or exponential distributions, frontier can fit models with heteroskedastic error components, conditional on a set of covariates. For a truncated-normal distribution, frontier can also fit a conditional mean model in which the mean is modeled as a linear function of a set of covariates.

Example 1: The half-normal and the exponential models

For our first example, we demonstrate the half-normal and exponential models by reproducing a study found in Greene (2003, 505), which uses data originally published in Zellner and Revankar (1969). In this study of the transportation-equipment manufacturing industry, observations on value added, capital, and labor are used to estimate a Cobb-Douglas production function. The variable lnv is the log-transformed value added, lnk is the log-transformed capital, and lnl is the log-transformed labor. OLS estimates are compared with those from stochastic frontier models using both the half-normal and exponential distribution for the inefficiency term.

- . use http://www.stata-press.com/data/r13/greene9
- . regress lnv lnk lnl

Source	SS	df		MS		Number of obs	s = 25 s = 397.54
Model Residual	44.1727741 1.22225984	2 22		086387 557265		Prob > F R-squared Adj R-squared	= 0.0000 = 0.9731
Total	45.3950339	24	1.89	145975		Root MSE	= .23571
lnv	Coef.	Std.	Err.	t	P> t	[95% Conf	Interval]
lnk	. 2454281	.1068	3574	2.30	0.032	.0238193	.4670368
lnl	.805183	.1263	3336	6.37	0.000	.5431831	1.067183
_cons	1.844416	. 2335	928	7.90	0.000	1.359974	2.328858
. frontier lnv	v lnk lnl						
Iteration 0:	log likeliho	od =	2.335	7572			
Iteration 1:	log likeliho	od =	2.467	3009			
Iteration 2:	log likeliho	od =	2.469	5125			
Iteration 3:	log likeliho	od =	2.469	5222			
Iteration 4:	log likeliho	od =	2.469	5222			
Stoc. fronties	r normal/half-	normal	mode	1	Numb	er of obs =	25
					Wald	chi2(2) =	743.71
Log likelihood	i = 2.4695222				Prob	> chi2 =	0.0000
	r						

lnv	Coef.	Std. Err.	z	P> z	[95% Conf.	Interval]
lnk lnl _cons	.2585478 .7802451 2.081135	.098764 .1199399 .281641	2.62 6.51 7.39	0.009 0.000 0.000	.0649738 .5451672 1.529128	.4521218 1.015323 2.633141
/lnsig2v /lnsig2u	-3.48401 -3.014599	.6195353 1.11694	-5.62 -2.70	0.000 0.007	-4.698277 -5.203761	-2.269743 8254368
sigma_v sigma_u sigma2	.1751688 .2215073 .0797496	.0542616 .1237052 .0426989			.0954514 .074134 0039388	.3214633 .6618486 .163438

Likelihood-ratio test of sigma_u=0: chibar2(01) = 0.43 Prob>=chibar2 = 0.256

.9355204

1.593552

.1678684

1.264536

lambda

[.] predict double u_h, u

. frontier lnv lnk lnl, distribution(exponential)

Iteration 0: $log\ likelihood = 2.7270659$ $log\ likelihood = 2.8551532$ Iteration 1: log likelihood = 2.8604815 log likelihood = 2.8604897 Iteration 2: Iteration 3: Iteration 4: log likelihood = 2.8604897

Stoc. frontier normal/exponential model

Log likelihood = 2.8604897

Number of obs = 25 Wald chi2(2) = 845.68 Prob > chi2 = 0.0000

lnv	Coef.	Std. Err.	z	P> z	[95% Conf.	Interval]
lnk lnl _cons	.2624859 .7703795 2.069242	.0919988 .1109569 .2356159	2.85 6.94 8.78	0.004 0.000 0.000	.0821717 .5529079 1.607444	.4428002 .9878511 2.531041
/lnsig2v /lnsig2u	-3.527598 -4.002457	.4486176 .9274575	-7.86 -4.32	0.000	-4.406873 -5.820241	-2.648324 -2.184674
sigma_v sigma_u sigma2 lambda	.1713925 .1351691 .0476461 .7886525	.0384448 .0626818 .0157921 .087684			.1104231 .0544692 .016694 .616795	.2660258 .3354317 .0785981 .9605101

Likelihood-ratio test of sigma_u=0: chibar2(01) = 1.21 Prob>=chibar2 = 0.135

- . predict double u_e, u
- . list state u_h u_e

	state	u_h	u_e
1. 2.	Alabama California	.2011338	.14592865
3.	Connecticut	.1903485	.13478797
4.	Florida	.51753139	.5903303
5.	Georgia	.10397912	.07140994
6.	Illinois	.12126696	.0830415
7.	Indiana	.21128212	.15450664
8.	Iowa	.24933153	.20073081
9.	Kansas	.10099517	.06857629
10.	Kentucky	.05626919	.04152443
11.	Louisiana	.20332731	.15066405
12.	Maine	.22263164	.17245793
13.	Maryland	.13534062	.09245501
14.	Massachusetts	.15636999	.10932923
15.	Michigan	.15809566	.10756915
16.	Missouri	.10288047	.0704146
17.	NewJersey	.09584337	.06587986
18.	NewYork	.27787793	.22249416
19.	Ohio	.22914231	.16981857
20.	Pennsylvania	.1500667	.10302905
21.	Texas	.20297875	.14552218
22.	Virginia	.14000132	.09676078
23.	Washington	.11047581	.07533251
24.	WestVirginia	.15561392	.11236153
25.	Wisconsin	.14067066	.0970861

1

The parameter estimates and the estimates of the inefficiency terms closely match those published in Greene (2003, 505), but the standard errors of the parameter estimates are estimated differently (see the technical note below).

The output from frontier includes estimates of the standard deviations of the two error components, σ_v and σ_u , which are labeled sigma_v and sigma_u, respectively. In the log likelihood, they are parameterized as $\ln \sigma_v^2$ and $\ln \sigma_u^2$, and these estimates are labeled /lnsig2v and /lnsig2u in the output. frontier also reports two other useful parameterizations. The estimate of the total error variance, $\sigma_S^2 = \sigma_v^2 + \sigma_u^2$, is labeled sigma2, and the estimate of the ratio of the standard deviation of the inefficiency component to the standard deviation of the idiosyncratic component, $\lambda = \sigma_u/\sigma_v$, is labeled lambda.

At the bottom of the output, frontier reports the results of a test that there is no technical inefficiency component in the model. This is a test of the null hypothesis $H_0: \sigma_u^2 = 0$ against the alternative hypotheses $H_1: \sigma_u^2 > 0$. If the null hypothesis is true, the stochastic frontier model reduces to an OLS model with normal errors. However, because the test lies on the boundary of the parameter space of σ_u^2 , the standard likelihood-ratio test is not valid, and a one-sided generalized likelihood-ratio test must be constructed; see Gutierrez, Carter, and Drukker (2001). For this example, the output shows LR = 0.43 with a p-value of 0.256 for the half-normal model and LR = 1.21 with a p-value of 0.135 for the exponential model. There are several possible reasons for the failure to reject the null hypothesis, but the fact that the test is based on an asymptotic distribution and the sample size was 25 is certainly a leading candidate among those possibilities.

□ Technical note

frontier maximizes the log-likelihood function of a stochastic frontier model by using the Newton-Raphson method, and the estimated variance-covariance matrix is calculated as the inverse of the negative Hessian (matrix of second partial derivatives); see [R] ml. When comparing the results with those published using other software, be aware of the difference in the optimization methods, which may result in different, yet asymptotically equivalent, variance estimates.

Example 2: Models with heteroskedasticity

Often the error terms may not have constant variance. frontier allows you to model heteroskedasticity in either error term as a linear function of a set of covariates. The variance of either the technical inefficiency or the idiosyncratic component may be modeled as

$$\sigma_i^2 = \exp(\mathbf{w}_i \boldsymbol{\delta})$$

The default constant included in \mathbf{w}_i may be suppressed by appending a noconstant option to the list of covariates. Also, you can simultaneously specify covariates for both σ_{u_i} and σ_{v_i} .

In this example, we use a sample of 756 observations of fictional firms producing a manufactured good by using capital and labor. The firms are hypothesized to use a constant returns-to-scale technology, but the sizes of the firms differ. Believing that this size variation will introduce heteroskedasticity into the idiosyncratic error term, we estimate the parameters of a Cobb-Douglas production function. To do this, we use a conditional heteroskedastic half-normal model, with the size of the firm as an explanatory variable in the variance function for the idiosyncratic error. We also perform a test of the hypothesis that the firms use a constant returns-to-scale technology.

```
. use http://www.stata-press.com/data/r13/frontier1, clear
```

. frontier lnoutput lnlabor lncapital, vhet(size)

Iteration 0: log likelihood = -1508.3692
Iteration 1: log likelihood = -1501.583
Iteration 2: log likelihood = -1500.3942
Iteration 3: log likelihood = -1500.3794
Iteration 4: log likelihood = -1500.3794

Stoc. frontier normal/half-normal model Number of obs = Wald chi2(2) =

Prob > chi2

756

9.68

4

0.0079

Log likelihood = -1500.3794

lnoutput	Coef.	Std. Err.	z	P> z	[95% Conf	. Interval]
lnoutput						
lnlabor	.7090933	.2349374	3.02	0.003	.2486244	1.169562
lncapital	.3931345	.5422173	0.73	0.468	6695919	1.455861
_cons	1.252199	3.14656	0.40	0.691	-4.914946	7.419344
lnsig2v						
size	0016951	.0004748	-3.57	0.000	0026256	0007645
_cons	3.156091	.9265826	3.41	0.001	1.340023	4.97216
lnsig2u						
_cons	1.947487	.1017653	19.14	0.000	1.748031	2.146943
sigma_u	2.647838	.134729			2.396514	2.925518

```
. test _b[lnlabor] + _b[lncapital] = 1
```

(1) [lnoutput]lnlabor + [lnoutput]lncapital = 1

chi2(1) = 0.03Prob > chi2 = 0.8622

The output above indicates that the variance of the idiosyncratic error term is a function of firm size. Also, we failed to reject the hypothesis that the firms use a constant returns-to-scale technology.

□ Technical note

In small samples, the conditional heteroskedastic estimators will lack precision for the variance parameters and may fail to converge altogether.

Example 3: The truncated-normal model

Let's turn our attention to the truncated-normal model. Once again, we will use fictional data. For this example, we have 1,231 observations on the quantity of output, the total cost of production for each firm, the prices that each firm paid for labor and capital services, and a categorical variable measuring the quality of each firm's management. After taking the natural logarithm of the costs (lncost), prices (lnp_k and lnp_l), and output (lnout), we fit a stochastic cost frontier model and specify the distribution for the inefficiency term to be truncated normal.

```
. use http://www.stata-press.com/data/r13/frontier2
```

. frontier lncost lnp_k lnp_l lnout, distribution(tnormal) cost

Iteration 0: log likelihood = -2386.9523
Iteration 1: log likelihood = -2386.5146
Iteration 2: log likelihood = -2386.2704
Iteration 3: log likelihood = -2386.2504
Iteration 4: log likelihood = -2386.2493
Iteration 5: log likelihood = -2386.2493

Stoc. frontier normal/truncated-normal model

Number of obs = 1231 Wald chi2(3) = 8.82 Prob > chi2 = 0.0318

Ιοσ	likelihood	=	-2386	2493
LOK	TIVETIHOOG	_	-2300.	2433

т						
lncost	Coef.	Std. Err.	z	P> z	[95% Conf.	Interval]
lnp_k	.3410717	.2363861	1.44	0.149	1222366	.80438
lnp_l	.6608628	.4951499	1.33	0.182	3096131	1.631339
lnout	.7528653	.3468968	2.17	0.030	.0729601	1.432771
_cons	2.602609	1.083004	2.40	0.016	.4799595	4.725259
/mu	1.095705	.881517	1.24	0.214	632037	2.823446
/lnsigma2	1.5534	.1873464	8.29	0.000	1.186208	1.920592
/ilgtgamma	1.257862	.2589522	4.86	0.000	.7503255	1.765399
sigma2	4.727518	.8856833			3.274641	6.825001
gamma	.7786579	.0446303			.6792496	.8538846
sigma_u2	3.681119	.7503408			2.210478	5.15176
sigma_v2	1.046399	.2660035			.5250413	1.567756

HO: No inefficiency component:

z = 5.595

Prob>=z = 0.000

In addition to the coefficients, the output reports estimates for several parameters. sigma_v2 is the estimate of σ_v^2 . sigma_u2 is the estimate of σ_v^2 . sigma_u2 is the estimate of σ_v^2 . sigma_u2 is the estimate of $\sigma_S^2 = \sigma_v^2 + \sigma_u^2$. Because γ must be between 0 and 1, the optimization is parameterized in terms of the inverse logit of γ , and this estimate is reported as ilgtgamma. Because σ_S^2 must be positive, the optimization is parameterized in terms of $\ln(\sigma_S^2)$, whose estimate is reported as lnsigma2. Finally, mu is the estimate of μ , the mean of the truncated-normal distribution.

In the output above, the generalized log-likelihood test for the presence of the inefficiency term has been replaced with a test based on the third moment of the OLS residuals. When $\mu=0$ and $\sigma_u=0$, the truncated-normal model reduces to a linear regression model with normally distributed errors. However, the distribution of the test statistic under the null hypothesis is not well established, because it becomes impossible to evaluate the log likelihood as σ_u approaches zero, prohibiting the use of the likelihood-ratio test.

However, Coelli (1995) noted that the presence of an inefficiency term would negatively skew the residuals from an OLS regression. By identifying negative skewness in the residuals with the presence of an inefficiency term, Coelli derived a one-sided test for the presence of the inefficiency term. The results of this test are given at the bottom of the output. For this example, the null hypothesis of no inefficiency component is rejected.

In the example below, we fit a truncated model and detect a statistically significant inefficiency term in the model. We might question whether the inefficiency term is identically distributed over all firms or whether there might be heterogeneity across firms. frontier provides an extension to the truncated normal model by allowing the mean of the inefficiency term to be modeled as a linear function of a set of covariates. In our dataset, we have a categorical variable that measures the quality of a firm's management. We refit the model, including the cm() option, specifying a set of

binary indicator variables representing the different categories of the quality-measurement variable as covariates.

. frontier lncost lnp_k lnp_l lnout, distribution(tnormal) cm(i.quality) cost $log\ likelihood = -2386.9523$ Iteration 0: Iteration 1: log likelihood = -2384.936Iteration 2: $log\ likelihood = -2382.3942$ $log\ likelihood = -2382.324$ Iteration 3: Iteration 4: $log\ likelihood = -2382.3233$ Iteration 5: $log\ likelihood = -2382.3233$ Stoc. frontier normal/truncated-normal model Number of obs 1231 Wald chi2(3) 9.31 Log likelihood = -2382.3233Prob > chi2 0.0254 lncost Coef. Std. Err. P>|z| [95% Conf. Interval] z lncost lnp_k .3611204 .2359749 1.53 0.126 -.1013819 .8236227 lnp_l .680446 .4934935 1.38 0.168 -.2867835 1.647675 lnout .7605533 .3466102 2.19 0.028 .0812098 1.439897 _cons 2.550769 1.078911 2.36 0.018 .4361417 4.665396 mıı quality 2 .5056067 .3382907 1.49 0.135 -.1574309 1.168644 3 .783223 .376807 2.08 0.038 .0446947 1.521751 4 .5577511 .3355061 1.66 0.096 -.0998288 1.215331 5 .6792882 .3428073 1.98 0.048 .0073981 1.351178 _cons .6014025 .990167 0.61 0.544 -1.339289 2.542094 0.000 /lnsigma2 1.541784 8.61 1.190769 1.892799 .1790926 /ilgtgamma 1.242302 .2588968 4.80 0.000 .734874 1.749731 6.637923 .8368852 3.289611 sigma2 4.67292 gamma .7759645 .0450075 .6758739 .8519189 sigma_u2 3.62602 .7139576 2.226689 5.025351 1.0469 .2583469 .5405491 1.553251 sigma_v2

The conditional mean model was developed in the context of panel-data estimators, and we can apply frontier's conditional mean model to panel data.

Stored results

frontier stores the following in e():

```
Scalars
    e(N)
                                number of observations
                                model degrees of freedom
    e(df_m)
                                number of parameters
    e(k)
                                number of equations in e(b)
    e(k_eq)
                                number of equations in overall model test
    e(k_eq_model)
    e(k_dv)
                                number of dependent variables
                                \chi^2
    e(chi2)
                                log likelihood
    e(11)
    e(11_c)
                                log likelihood for H_0: \sigma_u = 0
    e(z)
                                test for negative skewness of OLS residuals
    e(sigma_u)
                                standard deviation of technical inefficiency
                                standard deviation of v_i
    e(sigma_v)
                                significance
    e(p)
    e(chi2_c)
                                LR test statistic
                                p-value for z
    e(p_z)
                                rank of e(V)
    e(rank)
                                number of iterations
    e(ic)
    e(rc)
                                return code
    e(converged)
                                1 if converged, 0 otherwise
Macros
    e(cmd)
                                frontier
    e(cmdline)
                                command as typed
    e(depvar)
                                name of dependent variable
    e(function)
                                production or cost
    e(wtype)
                                weight type
    e(wexp)
                                weight expression
    e(title)
                                title in estimation output
    e(chi2type)
                                Wald; type of model \chi^2 test
    e(dist)
                                distribution assumption for u_i
    e(het)
                                heteroskedastic components
    e(u_hetvar)
                                varlist in uhet()
    e(v_hetvar)
                                varlist in vhet()
                                vcetype specified in vce()
    e(vce)
    e(vcetype)
                                title used to label Std. Err.
    e(opt)
                                type of optimization
    e(which)
                                max or min; whether optimizer is to perform maximization or minimization
                                type of ml method
    e(ml_method)
    e(user)
                                name of likelihood-evaluator program
    e(technique)
                                maximization technique
    e(properties)
    e(predict)
                                program used to implement predict
                                factor variables fyset as asbalanced
    e(asbalanced)
    e(asobserved)
                                factor variables fvset as asobserved
```

Matrices

e(b) coefficient vector

e(Cns) constraints matrix

e(ilog) iteration log (up to 20 iterations)

e(gradient) gradient vector

e(V) variance—covariance matrix of the estimators

e(V_modelbased) model-based variance

Functions

e(sample) marks estimation sample

Methods and formulas

Consider an equation of the form

$$y_i = \mathbf{x}_i \boldsymbol{\beta} + v_i - s u_i$$

where y_i is the dependent variable, \mathbf{x}_i is a $1 \times k$ vector of observations on the independent variables included as indent covariates, $\boldsymbol{\beta}$ is a $k \times 1$ vector of coefficients, and

$$s = \left\{ \begin{array}{ll} 1, & \text{for production functions} \\ -1, & \text{for cost functions} \end{array} \right.$$

The log-likelihood functions are as follows.

Normal/half-normal model:

$$\ln L = \sum_{i=1}^{N} \left\{ \frac{1}{2} \ln \left(\frac{2}{\pi} \right) - \ln \sigma_S + \ln \Phi \left(-\frac{s\epsilon_i \lambda}{\sigma_S} \right) - \frac{\epsilon_i^2}{2\sigma_S^2} \right\}$$

Normal/exponential model:

$$\mathrm{ln}L = \sum_{i=1}^{N} \left\{ -\ln\!\sigma_u + \frac{\sigma_v^2}{2\sigma_u^2} + \ln\!\Phi\left(\frac{-s\epsilon_i - \frac{\sigma_v^2}{\sigma_u}}{\sigma_v}\right) + \frac{s\epsilon_i}{\sigma_u} \right\}$$

Normal/truncated-normal model:

$$\begin{split} \ln L &= \sum_{i=1}^{N} \left\{ -\frac{1}{2} \ln{(2\pi)} - \ln \sigma_{S} - \ln \Phi \left(\frac{\mu}{\sigma_{S} \sqrt{\gamma}} \right) \right. \\ &\left. + \ln \Phi \left[\frac{(1-\gamma) \, \mu - s \gamma \epsilon_{i}}{\left\{ \sigma_{S}^{2} \gamma \, (1-\gamma) \right\}^{1/2}} \right] - \frac{1}{2} \left(\frac{\epsilon_{i} + s \mu}{\sigma_{S}} \right)^{2} \right\} \end{split}$$

where $\sigma_S = (\sigma_u^2 + \sigma_v^2)^{1/2}$, $\lambda = \sigma_u/\sigma_v$, $\gamma = \sigma_u^2/\sigma_S^2$, $\epsilon_i = y_i - \mathbf{x}_i \boldsymbol{\beta}$, and $\Phi()$ is the cumulative distribution function of the standard normal distribution.

To obtain estimation for u_i , you can use either the mean or the mode of the conditional distribution $f(u|\epsilon)$.

$$E(u_i \mid \epsilon_i) = \mu_{*i} + \sigma_* \left\{ \frac{\phi(-\mu_{*i}/\sigma_*)}{\Phi(\mu_{*i}/\sigma_*)} \right\}$$

$$M(u_i \mid \epsilon_i) = \left\{ \begin{matrix} \mu_{*i} & \text{if } \mu_{*i} \ge 0 \\ 0 & \text{otherwise} \end{matrix} \right.$$

Then the technical efficiency (s = 1) or cost efficiency (s = -1) will be estimated by

$$\begin{split} E_i &= E\left\{\exp(-su_i) \mid \epsilon_i\right\} \\ &= \left\{\frac{1 - \Phi\left(s\sigma_* - \mu_{*i}/\sigma_*\right)}{1 - \Phi\left(-\mu_{*i}/\sigma_*\right)}\right\} \exp\left(-s\mu_{*i} + \frac{1}{2}\sigma_*^2\right) \end{split}$$

where μ_{*i} and σ_{*} are defined for the normal/half-normal model as

$$\mu_{*i} = -s\epsilon_i \sigma_u^2 / \sigma_S^2$$
$$\sigma_* = \sigma_u \sigma_v / \sigma_S$$

for the normal/exponential model as

$$\mu_{*i} = -s\epsilon_i - \sigma_v^2 / \sigma_u$$
$$\sigma_* = \sigma_v$$

and for the normal/truncated-normal model as

$$\mu_{*i} = \frac{-s\epsilon_i \sigma_u^2 + \mu \sigma_v^2}{\sigma_S^2}$$
$$\sigma_* = \sigma_u \sigma_v / \sigma_S$$

In the half-normal and exponential models, when heteroskedasticity is assumed, the standard deviations, σ_u or σ_v , will be replaced in the above equations by

$$\sigma_i^2 = \exp(\mathbf{w}_i \boldsymbol{\delta})$$

where w is the vector of explanatory variables in the variance function.

In the conditional mean model, the mean parameter of the truncated normal distribution, μ , is modeled as a linear combination of the set of covariates, w.

$$\mu = \mathbf{w}_i \boldsymbol{\delta}$$

Therefore, the log-likelihood function can be rewritten as

$$\begin{split} \ln & L = \sum_{i=1}^{N} \left[-\frac{1}{2} \ln{(2\pi)} - \ln\!\sigma_S - \ln\!\Phi \left(\frac{\mathbf{w}_i \pmb{\delta}}{\sqrt{\sigma_S^2 \gamma}} \right) \right. \\ & \left. + \ln\!\Phi \left\{ \frac{(1-\gamma) \, \mathbf{w}_i \pmb{\delta} - s \gamma \epsilon_i}{\sqrt{\sigma_S^2 \gamma \, (1-\gamma)}} \right\} - \frac{1}{2} \left(\frac{\epsilon_i + s \mathbf{w}_i \pmb{\delta}}{\sigma_S} \right)^2 \right] \end{split}$$

The z test reported in the output of the truncated-normal model is a third-moment test developed by Coelli (1995) as an extension of a test previously developed by Pagan and Hall (1983). Coelli shows that under the null of normally distributed errors, the statistic

$$z = \frac{m_3}{\left(\frac{6m_2^3}{N}\right)^{1/2}}$$

has a standard normal distribution, where m_3 is the third moment from the OLS regression. Because the residuals are either negatively skewed (production function) or positively skewed (cost function), a one-sided p-value is used.

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Also see

- [R] frontier postestimation Postestimation tools for frontier
- [R] regress Linear regression
- [XT] **xtfrontier** Stochastic frontier models for panel data
- [U] 20 Estimation and postestimation commands