Project 1 Readme

Overview

This README serves as a comprehensive guide to my implementation of a multithreaded file transfer system using the GetFile protocol. The project consists of four progressive components: **Echo** (basic socket communication), **Transfer** (file transfer fundamentals), **GFLib** (GetFile protocol implementation), and **MTGF** (multithreaded server). Each component builds upon the previous, demonstrating mastery of socket programming, protocol design, and concurrent programming with proper synchronization.

Warmup 1: Echo Client-Server Implementation

Design Approach and Rationale

What I implemented: A basic client-server pair where the server echoes back any message received from the client (up to 15 bytes).

Key Design Decisions:

- IPv4/IPv6 Dual-Stack Support: I chose to implement the server using AF_INET6 with dual-stack capability rather than separate IPv4/IPv6 implementations.
 - Why: This approach handles both protocol families with a single socket, reducing complexity
 - Alternative Considered: Separate sockets for IPv4 and IPv6, but rejected due to increased resource usage and complexity
- Client Address Resolution: Used AF_UNSPEC in the client to connect to any available address family.
 - Why: Allows the client to connect regardless of server's address family configuration
 - Implementation: Iterates through all resolved addresses until successful connection
- Enabling port reuse: setsockopt(SO_REUSEADDR)

Flow of Control - Echo Implementation

ECHO SERVER:

- 1. getaddrinfo(NULL, port, AF_INET6, AI_PASSIVE) → Get server address
- socket() → Create listening socket with dual-stack support
- 3. setsockopt(SO_REUSEADDR) → Enable port reuse for development
- 4. bind() → Bind to address
- 5. listen() → Enter passive listening mode
- 6. while (1):
 - accept() → Accept incoming connection
 - recv(fd, buffer, 16) → Read client message
 - send(fd, buffer, received_bytes) → Echo message back
 - □ close(fd) → Close connection and continue

```
ECHO CLIENT:

1. getaddrinfo(hostname, port, AF_UNSPEC) → Resolve server address

2. socket() → Create client socket

3. connect() → Attempt connection to server

4. send(socket, message, length) → Send message to server

5. recv(socket, buffer, 16) → Receive echoed response

6. fwrite(buffer, received_bytes, stdout) → Output response

7. close() → Clean up and exit
```

Testing Strategy - Echo

Tests I Developed:

- Message Integrity Test: Verified exact byte-for-byte echo with various message lengths (1-15 bytes)
- IPv4/IPv6 Compatibility: Tested server with both IPv4 and IPv6 clients
- Edge Case Testing: Empty messages, maximum 15-byte messages, and connection drops

Debugging Process: Used CLion with Docker toolchain for development environment consistency

Warmup 2: Transfer Client-Server Implementation

Design Approach and Rationale

What I implemented: A file transfer system where the server sends a complete file to any connecting client, and the client saves the received data to disk.

Critical Design Decision - Partial I/O Handling:

- Problem: Network operations don't guarantee complete data transfer in single calls
- My Solution: Implemented comprehensive loops for both send and receive operations

```
// Example from my transfer client - handling partial writes
while (written < received) {
   ssize_t currWritten = write(fd, buffer + written, received - written);
   if (currWritten == -1) handle_error();
   written += currWritten;
}</pre>
```

Why This Approach: TCP provides a stream abstraction, not message boundaries. The OS may only accept/deliver partial data based on buffer availability.

Memory Management Strategy: Used fixed-size buffers (512 bytes) with streaming I/O rather than loading entire files into memory.

• Why: Supports large file transfers without memory constraints

• Alternative Rejected: Full file buffering - would fail with large files or limited memory

Flow of Control - Transfer Implementation

TRANSFER SERVER:
1. Initialize socket and bind to port (Same flow as echo)
2. open(filename, O_RDONLY) → Open file for reading
3. while (1):
— accept() → Accept client connection
— Iseek(fd, 0, SEEK_SET) → Reset file pointer to beginning
├─ while (not EOF):
\mid read(fd, buffer, BUFSIZE) \rightarrow Read file chunk
├─ while (sent < bytes_read):
$ \sqsubseteq$ send(socket, buffer + sent, remaining) \rightarrow Send with partial handling
☐ Continue until file complete
└─ close(connection) → Signal EOF to client
TRANSFER CLIENT:
1. Connect to server
2. open(output_file, O_WRONLY O_CREAT O_TRUNC) → Create output file
3. while ((received = recv(socket, buffer, BUFSIZE)) > 0):
while (written < received):
4. close(socket) → Server closes connection to signal completion
5. close(output_file) → File transfer complete

Testing Strategy - Transfer

Tests I Developed:

- **File Integrity Verification**: Used Docker containers to transfer files and verify MD5 checksums match
- Large File Testing: Tested with files up to 100MB to verify partial I/O handling
- Connection Robustness: Simulated network interruptions during transfer

Development Environment: Used CLion with Docker toolchain for development environment consistency

Part 1: GetFile Protocol Library (GFLib) Implementation

Design Approach and Rationale

What I Implemented: A complete HTTP-like protocol implementation with client library (gfclient) and server library (gfserver) supporting the GetFile protocol.

Core Design Philosophy - Opaque Pointer Pattern:

```
struct gfcrequest_t {
    char *server;
    unsigned short portno;
    char *path;
    int sfd;
    void (*writefunc)(void *data, size_t data_len, void *arg);
    void *writearg;
    gfstatus_t status;
    size_t fileLength;
    size_t bytesReceived;
};
```

Why Opaque Pointers: Provides clean separation between interface and implementation, preventing client code from accessing internal structures while maintaining flexibility for future modifications.

Protocol State Management Strategy:

- Challenge: Parse variable-length headers followed by binary content without excessive buffering
- My Solution: Two-phase parsing approach
 - 1. First phase: Keep receiving header until VINIVIN delimiter to extract status and content-length
 - 2. Second phase: Stream body content through registered callbacks

Callback-Based Architecture:

- Why: Allows users to handle data streaming without library making assumptions about storage
- Benefit: Memory-efficient for large files no need to buffer complete file in memory

Flow of Control - GetFile Protocol

```
GFCLIENT LIBRARY EXECUTION:

APPLICATION CODE:

— gfc_create() → Returns opaque gfcrequest_t*

— gfc_set_server/port/path() → Configure request parameters

— gfc_set_writefunc/writearg() → Register data callback

— gfc_perform(request) → Execute request:

| — socket() and connect() → Establish connection

| — send("GETFILE GET /path\r\n\r\n") → Send protocol request

| — Parse response header:

| — recv() until "\r\n\r\n" found → Extract header

| — Parse status (OK/FILE_NOT_FOUND/ERROR/INVALID)

| — Extract content-length if status is OK

| — while (bytes_received < content_length):

| — recv(socket, buffer, chunk_size) → Receive data chunk

| — writefunc(buffer, received, writearg) → Callback to application
```

Return final status to application
☐ gfc_cleanup() → Free all allocated resources
GFSERVER LIBRARY EXECUTION: MAIN THREAD: — gfs_create() → Initialize server structure — gfs_set_handler() → Register request handler callback — gfs_serve() → Start server: — socket(), bind(), listen() → Setup listening socket — while (1): — accept() → Accept incoming connection — Parse request header → Extract method and path
Context cleanup and connection close
HANDLER CALLBACK (Provided):
— Validate request path and check file existence
 — if (file not found): gfs_sendheader(ctx, GF_FILE_NOT_FOUND, 0) — else:
 — gfs_sendheader(ctx, GF_OK, file_size) → Send success header — while (file data remaining):
├─ read(fd, buffer, chunk_size) → Read file chunk
gfs_send(ctx, buffer, bytes_read) \rightarrow Send to client
return gfh_success

Testing Strategy - GetFile Protocol

Tests I Developed:

- **Protocol Compliance Validator**: Custom test scripts sending malformed requests and verifying proper error responses
- Edge Case Testing: Invalid schemes, missing headers, incomplete requests
- Status Code Verification: Tested all status codes (OK, FILE_NOT_FOUND, ERROR, INVALID) with appropriate scenarios

Development Tools: CLion with Docker toolchain provided consistent development environment for protocol testing across different network configurations.

Part 2: Multithreaded GetFile (MTGF) Implementation

Design Approach and Rationale

What I Implemented: A complete multithreaded file server and client using the boss-worker pattern with proper synchronization.

Critical Design Decision - Boss-Worker Pattern

Synchronization Strategy:

```
typedef struct {
  int active_workers;
  int shutdown;
  steque_t *queue;
  pthread_mutex_t* mutex;
  pthread_cond_t* worker_cond;
  pthread_cond_t* finish_cond;
} worker_fn_args_t;
```

Why This Design:

- Mutex: Protects shared queue state from race conditions
- Condition Variables: Prevent CPU waste when workers are idle more efficient than busy-waiting
- Separate Condition Variables: Different signals for worker wake-up vs. completion notification

Context Ownership Transfer Challenge:

- Problem: Safely passing gfcontext_t ownership from main thread to worker threads
- My Solution: Ownership transfer pattern with explicit pointer nullification

```
// In handler - transfer ownership to worker
task→ctx = *ctx;
*ctx = NULL; // Prevent double-free by nullifying main thread's pointer
```

Flow of Control - Multithreaded Server

```
MAIN THREAD (Boss):

pthread_create() × N → Create worker thread pool

steque_init() → Initialize shared work queue

pthread_mutex/cond_init() → Initialize synchronization primitives

while (server running):

| — accept() → Wait for client connection (blocking)

| — Create task_item_t:

| — task→ctx = gfcontext (transfer ownership)

| — task→path = requested_path

| — task→arg = application_argument

| — pthread_mutex_lock(mutex)

| — steque_push(queue, task) → Add work to queue

| — pthread_cond_signal(worker_cond) → Wake up waiting worker

| — pthread_mutex_unlock(mutex)

| — Continue to next accept() (connection now owned by worker)
```

WORKER THREADS (N workers running worker_fn):
— while (1): // Infinite worker loop
— pthread_mutex_lock(mutex)
while (steque_isempty(queue)):
— task = steque_pop(queue) → Get work item
— pthread_mutex_unlock(mutex)
├─ content_get(task → path) → Open requested file (fd or -1)
— if (fd == -1):
gfs_sendheader(task→ctx, GF_FILE_NOT_FOUND, 0)
— else:
— while (offset < file_size):
$ \ \ $ pread(fd, buffer, chunk_size, offset) \rightarrow Read file chunk
— gfs_cleanup(task→ctx) → Clean up connection resources
CRITICAL SYNCHRONIZATION POINTS:
- Queue access: All steque operations protected by mutex
- Worker coordination: Condition variables prevent busy-waiting
- Context handoff: Ownership transfer prevents double-free errors
- Resource cleanup: Each worker responsible for complete cleanup

Multithreaded Client Implementation

```
CLIENT MAIN THREAD (Boss):

— Parse workload file → Generate list of download requests

— steque_push(queue, request) → Push all download requests to queue

— pthread_create() × N → Create worker thread pool

— pthread_mutex_lock(mutex)

— pthread_cond_broadcast(worker_cond) → Wake all workers

— while (steque_isempty(queue) || active_workers > 0):

— pthread_cond_wait(finish_cond, mutex) → Wait for completion

— pthread_join() → Clean up worker threads

— clean up mutex/cond/queue/tids
```

```
CLIENT WORKER THREADS:
├─ while (1):
  — pthread_mutex_lock(mutex)
  — while (steque_isempty(queue) && !shutdown):
     pthread_cond_wait(worker_cond, mutex)
  if (steque_isempty(queue) && shutdown):

    break → Exit worker loop

  request = steque_pop(queue)

— active_workers++ → Increment active count

  — pthread_mutex_unlock(mutex)

— gfc_perform(request) → Execute download using gfclient library.

  pthread_mutex_lock(mutex)
  — active_workers-- → Decrement active count
  if (stegue_isempty(queue) && active_workers == 0):
     ☐ pthread_cond_signal(finish_cond) → Signal potential completion
  pthread_mutex_unlock(mutex)
```

Testing Strategy - Multithreaded Implementation

Tests I Developed:

- **Concurrency Stress Testing:** Created custom workloads with 100+ simultaneous requests to identify race conditions
- Thread Pool Scaling: Tested with 1, 4, 8, 16, 32 worker threads to find optimal configuration
- Resource Leak Detection: Extended operation tests to verify no memory leaks or file descriptor leaks
- Deadlock Prevention: Systematic testing of different request orderings and timing scenarios

References - Code and Materials Used

Code I Used But Did Not Write

- **Steque Library (steque.c/steque.h)**: Used the provided thread-safe queue implementation for work distribution between boss and worker threads
- Content Library (content.c/content.h): Used provided file access abstraction for server-side file operations
- Workload Library (workload.c/workload.h): Used provided workload parsing for client request generation

Code I Copied Within My Own Project

• **Socket Setup Pattern**: Replicated the getaddrinfo()/socket()/bind() sequence from echo server in transfer server and gfserver implementations

- Error Handling Patterns: Consistent error checking and cleanup patterns copied across all components
- Partial I/O Loops: Similar send/receive loop patterns used in transfer, gfclient, and gfserver implementations

Technical References I Consulted

- **POSIX Threads Programming Tutorial** (LLNL): For understanding condition variable usage patterns and avoiding common deadlock scenarios
- Beej's Guide to Network Programming: Referenced for socket programming best practices and IPv4/IPv6 dual-stack implementation
- **CS6200 Lecture Slides on Multithreading:** Boss-worker pattern design and synchronization primitive selection
- Stack Overflow Thread #23207312: "pthread condition variable example" helped understand proper condition variable signaling patterns
- **GNU C Library Manual**: File I/O operations documentation, specifically for pread() usage and file descriptor management
- Course Piazza Posts: Specific clarifications about GetFile protocol format and threading requirements

Development Tools I Used

- CLion IDE with Docker Toolchain: Primary development environment with integrated debugging support
- Docker: Containerized development environment for consistent testing across platforms

Note: All external materials were used for concept understanding and best practice guidance. No code was directly copied from external sources - implementations represent my own understanding and application of these concepts.

Project Improvement Suggestions

1. Enhanced Local Testing Framework

Problem I Observed: Students lack comprehensive testing tools and rely heavily on Gradescope for validation, limiting learning opportunities.

Actionable Solution: Create a local testing framework that provides immediate feedback

2. Improved Project Instructions

Problem I Encountered: The GFLib implementation instructions are unclear about responsibility boundaries between student code and provided callbacks.

Current Instructions Say: "The handler callback should not contain any of the socket-level code. Instead, it should use the gfs_sendheader, gfs_send, and potentially the gfs_abort functions

provided by the gfserver library."

What's Confusing: I don't know whether invalid and wrong headers should be handled by my logic or the provided handler callback.

Actionable Solution: Include a decision flowchart showing exactly when student protocol code vs. application handler should handle different error conditions.