

## MEC 232

Name: Roban Kimas Social

Roll No: RM2041A01

Reg No: 12011878

1. Define the variable t as t=3.2; then evaluate:

a) 1. e2t - 3.81t3

2

b) 
$$6t^2+6t-2$$

= t = 3.2i

$$\alpha = (e^{(2*t)})/2 - 3.81*t^3$$

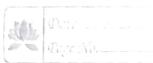
$$a = 176.08$$

b=8.5108

Create the following matrix by typing one command. Do not use elements explicitly.

G=

3.



	1247 C. W.							
	C =							
	4							
	0 0 0 1 1							
	0 0 0 1 1							
5.	A 70 th-bas of vice is being willed by a person by and in a large Fat							
<u> </u>	A 70 lb-bag of sice is being pulled by a person by applying a force Fat							
	On angle 8 as shown. The force required to drag the bag is given by:							
$F(\theta) = \frac{70 \mu}{2.00  \text{cm}}$								
	where $\mu = 0.35$ is the friction coefficient.							
(L)								
	actermine the angle of where F is minimum.							
Sd"=	mu = 0.35;							
~	theta = [5 10 15 20 25 30 35]							
	Fi = (70 * p mu) / (mu * sind (Heta (: 1)) + cord (Heta (: 1));							
	F2 = (70* mu)/(mu* sind (theta(:, 2)) + cosd (theta(; 2)));							
	F3 = (70 * mu)/( mu * Amd (Heta(: 3)) + cord (Heta(: 3));							
	Fy = (70* mu) / (mu* sind (theta(: 4)) + cosd (theta(: 4)));							
	F5 = (70* mu)/(mu* sind (thetal: ,5)) + coyd (thetal: 5)));							
F6=(70* mu)/(mu * sind (theta(:,6)) + cord (theta(:,6)));								
Fr = (70* mu) / (mu* sind (Hetal: 7) + coxd (Hetal: 7));								
	F= [F, F2 F3 F4 F5 F6 F7]							
	plot (theta, F)							
	Min F = min (F)							
	Proceedings of the control of the co							
	Bela =							
	5 io 15 20 25 30 35							
	J 10 13 AU A3 JU 7 J							



	F =							
		23-432	23-190	23-126	23-240	23-534	24.022	
	202		.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,			<i>y</i> = <b>,</b> -	•	
	MinF = 23,1	26						
				7				
-								
		×						

```
Octave
                                                                                                                                                                                                                         Х
                                                                                                                                                                                                            File Edit Debug Window Help News
                                         Current Directory: and Stastical Method Laboratory\CA1\CA1 \times 
                                                                                                                                                                                                                       ₽×
Editor
File Edit View Debug Run Help
       □ - ≥ ≥ ≥ | ♦ ∂ | ⊗ | ⊗ | | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 0 | 0
  CA1.m 🖾
      1 %Name: Rohan Kumar Saini
      2 %Roll Number:RM2041A01
      3 %Registration Number: 12011878
      4 %Ouestion1
      5 t=3.2;
         a=(e^{(2*t)})/2-3.81*t^3
           b = (6*t^2+6*t-2) / (t^2-1)
      8
         %Question3
           G=[ones(3,5); zeros(2,3) ones(2,2)]
    11
    12
         %Ouestion5
    13 mu=0.35;
         theta=[5 10 15 20 25 30 35]
    14
         F1=(70*mu)/(mu*sind(theta(:,1))+cosd(theta(:,1)));
    16 F2=(70*mu)/(mu*sind(theta(:,2))+cosd(theta(:,2)));
    17 F3=(70*mu)/(mu*sind(theta(:,3))+cosd(theta(:,3)));
   18 F4 = (70 * mu) / (mu * sind(theta(:, 4)) + cosd(theta(:, 4)));
    19 F5=(70*mu)/(mu*sind(theta(:,5))+cosd(theta(:,5)));
    20 F6 = (70 \pm mu) / (mu \pm sind (theta(:, 6)) + cosd (theta(:, 6)));
    21 F7 = (70 \pm mu) / (mu \pm sind(theta(:,7)) + cosd(theta(:,7)));
    22 F=[F1 F2 F3 F4 F5 F6 F7]
    23
           plot(theta, F)
    24 MinF=min(F)
line: 1
            col: 1
                        encoding: SYSTEM (CP1252) eol: CRLF
  Command Window
                                Documentation
                                                         Variable Editor
                                                                                  Editor
```



