Lambda Algorithm

For f

$$f = \bigvee_{n=1}^{s} \bigwedge_{m}^{t_{n}} \ell_{m}^{n} = \bigvee_{n=1}^{s} T_{n}$$

$$f(x+a_{k}) = \bigvee_{n=1}^{s} ((\bigwedge_{\substack{x_{i} \in P\ell^{n} \\ a_{k}[i]=0}} x_{i}) \wedge (\bigwedge_{\substack{x_{i} \in P\ell^{n} \\ a_{k}[i]=1}} \neg x_{i}) \wedge (\bigwedge_{\substack{x_{j} \in N\ell^{n} \\ a_{k}[j]=0}} \neg x_{j}) \wedge (\bigwedge_{\substack{x_{j} \in N\ell^{n} \\ a_{k}[j]=1}} x_{j})$$

$$= \bigvee_{n=1}^{s} T_{n}^{a_{k}}$$

$$\mathcal{M}(f(x+a_{k})) = \bigvee_{n=1}^{s} ((\bigwedge_{\substack{x_{i} \in P\ell^{n} \\ a_{k}[i]=0}} x_{i}) \wedge (\bigwedge_{\substack{x_{j} \in N\ell^{n} \\ a_{k}[j]=1}} x_{j})$$

$$= \bigvee_{n=1}^{s} \{\bigwedge_{\substack{x_{i} \in P\ell^{n} \\ a_{k}[i]=1}} x_{i} \mid x \in \ell^{n}\}$$

$$= \bigvee_{n=1}^{s} \mathcal{T}_{k} = \bigvee_{n=1}^{s} \mathcal{M}(T_{n}^{a_{k}})$$

$$\mathcal{M}_{a_{k}}(f) = \mathcal{M}(f(x+a_{k}))(x+a_{k}) = (\bigvee_{n=1}^{s} \mathcal{T}_{k})(x+a_{k})$$

For $S_i = \{\widehat{v_n} + a_i \mid n\}$

$$\mathbf{M}_{\mathrm{DNF}}(S_{i}) = \{\mathbf{M}_{\mathrm{TERM}}(\widehat{v_{n}} + a_{i})) \mid (\widehat{v_{n}} + a_{i}) \in S_{i}\}$$

$$= \{ \bigwedge_{(\widehat{v_{n}} + a_{i})[j]=1} x_{j} \mid (\widehat{v_{n}} + a_{i}) \in S_{i}\}$$

$$\bigvee_{(\widehat{v_{n}} + a_{i}) \in S_{i}} \mathbf{M}_{\mathrm{DNF}}(S_{i}) = \bigvee_{(\widehat{v_{n}} + a_{i}) \in S_{i}} \bigwedge_{(\widehat{v_{n}} + a_{i})[j]=1} x_{j}$$

$$H_{i} = (\bigvee_{(\widehat{v_{n}} + a_{i}) \in S_{i}} \mathbf{M}_{\mathrm{DNF}}(S_{i}))(x + a_{i})$$

$$= \bigvee_{(\widehat{v_{n}} + a_{i}) \in S_{i}} ((\bigwedge_{\widehat{v_{n}}[j]=1} x_{j}) \wedge (\bigwedge_{\widehat{v_{n}}[j]=0} \neg x_{j}))$$

$$= \bigvee_{(\widehat{v_{n}} + a_{i}) \in S_{i}} ((\bigwedge_{\widehat{v_{n}}[j]=0} a_{i}) \wedge (\bigwedge_{\widehat{v_{n}}[j]=0} \neg x_{j}))$$

The idea is to fit $M_{DNF}(S_i)$ to \mathscr{T}_i in each a_i dimension s.t. H_i fits to $\mathscr{M}_{a_k}(f)$.

Proposition A

Let f be a boolean function. If a is an assignment such that f(a) = 1 and for all i where a[i] = 1 we have $f(a + \neg x_i) = 0$, then for any DNF $\bigvee_{i=1}^{s} T_i$ of f there is a term T_a such that $\mathcal{M}(T_a) = M_{\text{TERM}}(a)$.

Proof Assume

- 1. v^{δ} is a positive counterexample.
- 2. I^{δ} is non-empty.
- 3. $M_{\text{TERM}}(\widehat{v}^{\delta} + a_i) \in \mathscr{T}_i M_{\text{DNF}}(S_i^{\delta-1}) \text{ for } i \in I^{\delta}.$
- 4. $M_{DNF}(S_i^{\delta}) \subseteq \mathscr{T}_i$ for i = 1..t.
- 5. $H_i^{\delta} \to \mathcal{M}_{a_i}(f)$ for i = 1..t.

Then induction is as follows.

a. By hypothesis 5,

Therefore $v^{\delta+1}$ is a positive counterexample.

b. Since (a), $v^{\delta+1}$ is a positive counterexample, $(\bigwedge_{i=1}^t H_i^{\delta})(v^{\delta+1}) = 0$ and so

$$I^{\delta+1} = \{i \mid H_i^{\delta}(v^{\delta+1}) = 0\}$$

is non-empty.

c. Let $i \in I^{\delta+1}$. Since (b), $H_i^{\delta}(v^{\delta+1}) = 0$. By definition,

$$H_i^{\delta}(v^{\delta+1}) = (\bigvee_{(\widehat{v_n} + a_i) \in S_i^{\delta}} \mathcal{M}_{DNF}(S_i^{\delta}))(v^{\delta+1} + a_i) = 0$$

After walking, $v^{\delta+1}$ becomes $\widehat{v}^{\delta+1}$ and $\widehat{v}^{\delta+1} \leq_{a_i} v^{\delta+1}$ and

$$\widehat{v}^{\delta+1} + a_i \le v^{\delta+1} + a_i$$

Since $(\bigvee_{(\widehat{v_n}+a_i)\in S_i^{\delta}} M_{DNF}(S_i^{\delta}))$ is monotone,

$$\left(\bigvee_{(\widehat{v_n}+a_i)\in S_i^{\delta}} \mathcal{M}_{\mathrm{DNF}}(S_i^{\delta})\right) (\widehat{v}^{\delta+1}+a_i) = 0$$

$$M_{TERM}(\widehat{v}^{\delta+1} + a_i) \notin M_{DNF}(S_i^{\delta})$$

Since $\widehat{v}^{\delta+1}$ is walked towards a_i ,

$$f(\widehat{v}^{\delta+1}) = f((\widehat{v}^{\delta+1} + a_i) + a_i) = 1$$

and for all $(\widehat{v}^{\delta+1} + a_i)[j] = 1$

$$f(\widehat{v}^{\delta+1} + \neg x_i) = f(\widehat{v}^{\delta+1} + \neg x_i + a_i + a_i) = f((\widehat{v}^{\delta+1} + a_i) + \neg x_i + a_i) = 0$$

So by Proposition A, there is a term T in any DNF of $f(x+a_i)$ such that $\mathcal{M}(T) = \mathrm{M}_{\mathrm{TERM}}(\widehat{v}^{\delta+1} + a_i)$. Therefore

$$M_{TERM}(\widehat{v}^{\delta+1} + a_i) \in \mathscr{T}_i = \{\mathscr{M}(T) \mid T \in f(x + a_i)\}$$

This is the crux of the proof.

d. If $i \notin I^{\delta+1}$, then $S_i^{\delta+1} = S_i^{\delta}$. If $i \in I^{\delta+1}$, then

$$S_i^{\delta+1} = S_i^{\delta} \cup \{\widehat{v}^{\delta+1} + a_i\}.$$

Either way, by hypothesis 4 and (c), we have $M_{DNF}(S_i^{\delta+1}) \subseteq \mathscr{T}_i$.

e. By definition,

$$H_i^{\delta+1}(x) = (\bigvee_{(\widehat{v_n} + a_i) \in S_i^{\delta+1}} \mathcal{M}_{DNF}(S_i^{\delta+1}))(x + a_i)$$

and

$$\mathcal{M}_{a_k}(f) = (\bigvee_{s=1}^s \mathscr{T}_k)(x + a_k)$$

By (d), $M_{DNF}(S_i^{\delta+1}) \subseteq \mathscr{T}_i$, so

$$\bigvee_{(\widehat{v_n} + a_i) \in S_i^{\delta + 1}} \mathcal{M}_{\text{DNF}}(S_i^{\delta + 1}) \to \bigvee_{n=1}^s \mathscr{T}_k$$

Therefore

$$H_i^{\delta+1}(x) \to \mathscr{M}_{a_k}(f)$$