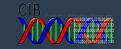


Semaphores



Synchronization Primitives

xCounting Semaphores

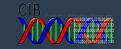
*Permit a limited number of threads to execute a section of the code

*BINARY SEMAPHORES - MUTEXES

*Permit only one thread to execute a section of the code

xCONDITION VARIABLES

*Communicate information about the state of shared data



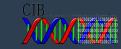
POSIX Semaphores

- *Named Semaphores (Implemented as "files")
 - *Provides synchronization between unrelated process and related process as well as between threads
 - *Kernel persistence
 - *System-wide and limited in number
 - *Uses sem_open

XUNNAMED SEMAPHORES



- *Provides synchronization between threads and between related processes
- *Thread-shared or process-shared
- xUses sem_init

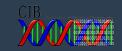


POSIX Semaphores

```
*DATA TYPE

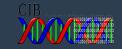
*Semaphore is a variable of type sem_t
#include < semaphore.h>

*ATOMIC OPERATIONS
int sem_init(sem_t *sem, int pshared, unsigned value);
int sem_destroy(sem_t *sem);
int sem_post(sem_t *sem);
int sem_trywait(sem_t *sem);
int sem_wait(sem_t *sem);
```



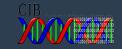
Unnamed Semaphores

```
#include < semaphore.h>
int sem_init(sem_t *sem, int pshared, unsigned value);
X NITIALIZE AN UNNAMED SEMAPHORE
XRETURNS
                                         You cannot make a copy of a
    x0 on success
                                             semaphore variable!!!
    x-1 on failure, sets errno
*PARAMETERS
    xsem:
       *Target semaphore
    *pshared:
       *0: only threads of the creating process can use the semaphore
       *Non-0: other processes can use the semaphore
    xvalue:
       *Initial value of the semaphore
```



Sharing Semaphores

- *Sharing semaphores between threads within a process is easy, use pshared=0
- *A NON-ZERO PSHARED ALLOWS ANY PROCESS THAT CAN ACCESS THE SEMAPHORE TO USE IT
 - *Places the semaphore in the global (OS) environment
 - *Forking a process creates copies of any semaphore it has
 - *Note: unnamed semaphores are not shared across unrelated processes



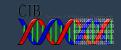
sem_init can fail

XON FAILURE

*sem_init returns -1 and sets errno

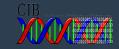
errno	cause
EINVAL	Value > sem_value_max
ENOSPC	Resources exhausted
EPERM	Insufficient privileges

```
sem_t semA; if (sem_init(\&semA, 0, 1) == -1) perror("Failed to initialize semaphore semA");
```



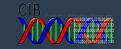
Semaphore Operations

```
#include < semaphore.h>
int sem_destroy(sem_t *sem);
XDESTROY A SEMAPHORE
XRETURNS
    x0 on success
    x-1 on failure, sets errno
XPARAMETERS
    xsem:
       xTarget semaphore
    ×Notes
       *Can destroy a sem_t only once
       *Destroying a destroyed semaphore gives undefined results
       *Destroying a semaphore on which a thread is blocked gives undefined
       results
```



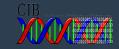
Semaphore Operations: signal

```
#include < semaphore.h>
int sem_post(sem_t *sem);
XUNLOCK A SEMAPHORE - SAME AS SIGNAL
XRETURNS
    x0 on success
   x-1 on failure, sets errno (== EINVAL if semaphore doesn't exist)
XPARAMETERS
    xsem:
       xTarget semaphore
       *sem > 0: no threads were blocked on this semaphore, the
       semaphore value is incremented
       *sem = 0: one blocked thread will be allowed to run
```



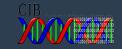
Semaphore Operations (wait)

```
#include < semaphore.h>
int sem_wait(sem_t *sem);
XLOCK A SEMAPHORE
   *Blocks if semaphore value is zero
XRETURNS
   x0 on success
   x-1 on failure, sets errno (== EINTR if interrupted by a signal)
XPARAMETERS
    xsem:
       *Target semaphore
       *sem > 0: thread acquires lock
       *sem = 0: thread blocks
```



Semaphore Operations

```
#include < semaphore.h>
int sem_trywait(sem_t *sem);
*Test a semaphore's current condition
   *Does not block
XRETURNS
   x0 on success
   x-1 on failure, sets errno (== AGAIN if semaphore already locked)
XPARAMETERS
   xsem:
       *Target semaphore
       *sem > 0: thread acquires lock
       *sem = 0: thread returns
```



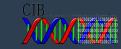
*PROTECT SHARED VARIABLE BALANCE WITH A SEMAPHORE WHEN USED IN:

*x*decshared

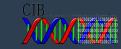
*Decrements current value of balance

*x*incshared

*Increments the balance



```
int decshared() {
  while (sem_wait(\&balance_sem) == -1)
    if (errno != EINTR)
      return -1;
  balance--;
  return sem_post(&balance_sem);
int incshared() {
  while (sem_wait(\&balance_sem) == -1)
    if (errno != EINTR)
      return -1;
  balance++;
  return sem_post(&balance_sem);
```

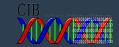


```
#include <errno.h>
#include <semaphore.h>

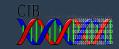
static int balance = 0;
static sem_t bal_sem;

int initshared(int val) {

if (sem_init(&bal_sem, 0, 1) == -1)
    return -1;
    balance = val;
    return 0;
}
```



Which one is going first?



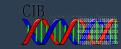
Unix/Linux Advanced Semaphores

```
int semget(key_t key, int nsems, int semflg);
```

xGet set of semaphores

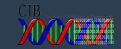
int semop (int semid, struct sembuf *sops, unsigned int nsops);

*Atomically perform a user-defined array of semaphore operations on the set of semaphores



Pthread Synchronization

- **X**TWO PRIMITIVES
 - xMutex (binary semaphore)
 - xSemaphore with maximum value 1
 - **x**Condition variable
 - *Provides a shared signal
 - *Combined with a mutex for synchronization



Pthread Mutex

XSTATES

xLocked

*Some thread holds the mutex

*x*Unlocked

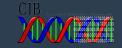
*No thread holds the mutex

*When several threads compete

XOne wins

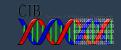
*The rest block

*Queue of blocked threads



Mutex Variables

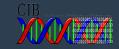
- *A TYPICAL SEQUENCE IN THE USE OF A MUTEX
 - 1)Create and initialize mutex
 - 2)Several threads attempt to lock mutex
 - 3)Only one succeeds and now owns mutex
 - 4)The owner performs some set of actions
 - 5)The owner unlocks mutex
 - 6)Another thread acquires mutex and repeats the process
 - 7) Finally mutex is destroyed



Creating a mutex

```
#include <pthread.h>
int pthread_mutex_init(pthread_mutex_t *mutex, const pthread_mutexattr_t *attr);
NITIALIZE A PTHREAD MUTEX: THE MUTEX IS INITIALLY UNLOCKED
XRETURNS
    x0 on success
    xError number on failure
       *EAGAIN: The system lacked the necessary resources; ENOMEM: Insufficient
       memory; EPERM: Caller does not have privileges; EBUSY: An attempt to re-
       initialise a mutex; EINVAL: The value specified by attr is invalid
XPARAMETERS
    xmutex: Target mutex
    xattr:
       XNULL: the default mutex attributes are used
```

*Non-NULL: initializes with specified attributes

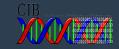


Creating a mutex

- *DFFAULT ATTRIBUTES
 - *****Use PTHREAD_MUTEX_INITIALIZER

pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;

- xStatically allocated
- *Equivalent to dynamic initialization by a call to pthread_mutex_init() with parameter attr specified as NULL
- *No error checks are performed



Destroying a mutex

```
#include <pthread.h>
int pthread_mutex_destroy(pthread_mutex_t *mutex);
*Destroy a pthread mutex
XRETURNS
   x0 on success
    *Error number on failure
       *EBUSY: An attempt to re-initialise a mutex; EINVAL: The value
       specified by attr is invalid
XPARAMETERS
   *mutex: Target mutex
```

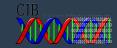


Locking/unlocking a mutex

```
#include <pthread.h>
int pthread_mutex_lock(pthread_mutex_t *mutex);
int pthread_mutex_trylock(pthread_mutex_t *mutex);
int pthread_mutex_unlock(pthread_mutex_t *mutex);
XRETURNS
```

- x0 on success
- *Error number on failure

*EBUSY: already locked; EINVAL: Not an initialised mutex; EDEADLK: The current thread already owns the mutex; EPERM: The current thread does not own the mutex



Simple Example

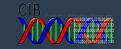
```
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
static pthread_mutex_t my_lock =
    PTHREAD_MUTEX_INITIALIZER;
void *mythread(void *ptr) {
  long int i,j;
  while (1) {
   pthread_mutex_lock (&my_lock);
   for (i=0; i<10; i++) {
     printf ("Thread %d\n", int) ptr);
     for (j=0; j<5000000; j++);
   pthread_mutex_unlock (&my_lock);
   for (j=0; j<5000000; j++);
```

```
int main (int argc, char *argv[]) {
   pthread_t thread[2];

pthread_create(&thread[0], NULL, mythread, (void
     *)0);

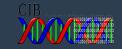
pthread_create(&thread[1], NULL, mythread, (void
     *)1);

getchar();
}
```



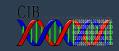
Condition Variables

- *Used to communicate information about the state of shared data
 - *Execution of code depends on the state of
 - **x**A data structure or
 - *Another running thread
- *ALLOWS THREADS TO SYNCHRONIZE BASED UPON THE ACTUAL VALUE OF DATA
- *WITHOUT CONDITION VARIABLES
 - *Threads continually poll to check if the condition is met



Condition Variables

- *****SIGNALING, NOT MUTUAL EXCLUSION
 - *A mutex is needed to synchronize access to the shared data
- *EACH CONDITION VARIABLE IS ASSOCIATED WITH A SINGLE MUTEX
 - *Wait atomically unlocks the mutex and blocks the thread
 - *Signal awakens a blocked thread



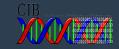
Creating a Condition Variable

XSIMILAR TO PTHREAD MUTEXES

```
int pthread_cond_init(pthread_cond_t *cond, const pthread_condattr_t
*attr);
```

```
int pthread_cond_destroy(pthread_cond_t *cond);
```

```
pthread_cond_t cond = PTHREAD_COND_INITIALIZER;
```

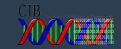


Using a Condition Variable

*WAITING

- *Block on a condition variable.
- *Called with mutex locked by the calling thread
- *Atomically release mutex and cause the calling thread to block on the condition variable
- **x**On return, mutex is locked again

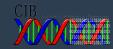
```
int pthread_cond_wait(pthread_cond_t *cond, pthread_mutex_t *mutex);
int pthread_cond_timedwait(pthread_cond_t *cond, pthread_mutex_t
*mutex, const struct timespec *abstime);
```



Using a Condition Variable

*****SIGNALS ARE NOT SAVED

*Must have a thread waiting for the signal or it will be lost



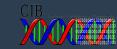
Condition Variable: Why do we need the mutex?

```
/* lock mutex */
pthread_mutex_lock(&mutex);
while (!predicate) {
                                            /* check predicate */
 pthread_cond_wait(&condvar, &mutex);
                                            /* go to sleep - recheck
                                              pred on awakening */
                                            /* unlock mutex */
pthread_mutex_unlock(&mutex);
                                                       /* lock the mutex
pthread_mutex_lock(&mutex);
                                            /* set the predicate
predicate=1;
pthread_cond_broadcast(&condvar);
                                                       /* wake everyone up
                                                       /* unlock the mutex
pthread_mutex_unlock(&mutex);
```



Condition Variable: No mutex!

```
/* lock mutex */
pthread_mutex_lock(&mutex);
while (!predicate) { /* check predicate
 pthread_mutex_unlock(&mutex); /* unlock mutex
 pthread_cond_wait(&condvar);
                                       /* go to sleep - recheck
                                                    pred on awakening
                                       /* lock mutex
 pthread_mutex_lock(&mutex);
                                     /* unlock mutex
pthread_mutex_unlock(&mutex);
                       What can happen here? -
                                                  /* lock the mutex
pthread_mutex_lock(&mutex);
                                        /* set the predicate */
predicate=1;
pthread_cond_broadcast(&condvar);
                                                 /* wake everyone up
                                                  /* unlock the mutex
pthread_mutex_unlock(&mutex);
```

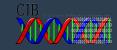


Condition Variable: No mutex!









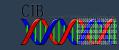
Condition Variable: No mutex!

```
pthread_mutex_lock(&mutex); /* lock mutex */
while (!predicate) { /* check predicate */
pthread_mutex_unlock(&mutex); /* unlock mutex */
pthread_cond_wait(&condvar); /* go to sleep - recheck
pred on awakening */
pthread_mutex_lock(&mutex); /* lock mutex */

pthread_mutex_unlock(&mutex); /* unlock mutex */
```

```
Another thread might acquire the mutex, set the predicate, and issue the broadcast before <a href="mailto:pthread_cond_wait">pthread_cond_wait</a>() gets called
```

```
/* lock the mutex */
the predicate */
/* wake everyone up */
/* unlock the mutex */
```



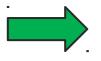
Condition Variable: We need the mutex!

```
pthread_mutex_lock(&mutex); /* lock mutex */
while (!predicate) { /* check predicate */
pthread_cond_wait(&condvar, &mutex);

/* go to sleep - recheck
pred on awakening */

}
pthread_mutex_unlock(&mutex); /* unlock mutex */
```





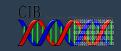
```
pthread_mutex_lock(&mutex);
predicate=1;
pthread_cond_broadcast(&condvar);
pthread_mutex_unlock(&mutex);
```

```
/* lock the mutex */
/* set the predicate */
/* wake everyone up */
/* unlock the mutex */
```



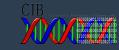
Condition Variable: Why do we need the mutex?

- *SEPARATING THE CONDITION VARIABLE FROM THE MUTEX
 - *Thread goes to sleep when it shouldn't
 - **x**Problem
 - *pthread_mutex_unlock() and pthread_cond_wait() are not guaranteed to be atomic
- *)OINING CONDITION VARIABLE AND MUTEX
 - *Call to pthread_cond_wait() unlocks the mutex
 - *****UNIX kernel can guarantee that the calling thread will not miss the broadcast



Using a Condition Variable: Challenges

- *Call pthread_cond_signal() before calling pthread_cond_wait()
 - *Logical error waiting thread will not catch the signal
- *FAIL TO LOCK THE MUTEX BEFORE CALLING PTHREAD_COND_WAIT()
 - *May cause it NOT to block
- *FAIL TO UNLOCK THE MUTEX AFTER CALLING PTHREAD_COND_SIGNAL()
 - *May not allow a matching pthread_cond_wait() routine to complete (it will remain blocked).



Example without Condition Variables

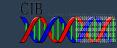
```
int data_avail = 0;
pthread_mutex_t data_mutex = PTHREAD_MUTEX_INITIALIZER;
void *producer(void *) {
    pthread_mutex_lock(&data_mutex);
    <Produce data>
    <Insert data into queue;>
    data_avail=1;
    pthread_mutex_unlock(&data_mutex);
```



Example without Condition Variables

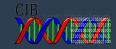
```
void *consumer(void *) {
    while (!data_avail ); /* do nothing */
    pthread_mutex_lock(&data_mutex);
    <Extract data from queue;>
    if (queue is empty)
    data_avail = 0;
    pthread_mutex_unlock(&data_mutex);
    <Consume Data>
```

Busy Waiting!



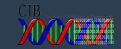
Example with Condition Variables

```
int data_a vail = 0;
pthread_mutex_t data_mutex = PTHREAD_MUTEX_INITIALIZER;
pthread_cont_t data_cond = PTHREAD_COND_INITIALIZER;
void *producer(void *) {
    pthread_mutex_lock(&data_mutex);
    <Produce data>
    <Insert data into queue;>
    data_avail = 1;
    pthread_cond_signal(&data_cond);
    pthread_mutex_unlock(&data_mutex);
```



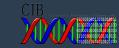
Example with Condition Variables

```
Mutex solution
                                                  while(!data_avail); /* do nothing */
void *consumer(void *) {
    pthread_mutex_lock(&data_mutex);
    while(!data_avail) {
         /* sleep on condition variable*/
         pthread_cond_wait(&data_cond, &data_mutex);
    /* woken up */
    <Extract data from queue;>
                                                          No Busy Waiting!
    if (queue is empty)
    data_avail = 0;
    pthread_mutex_unlock(&data_mutex);
    <Consume Data>
```



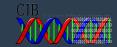
More Complex Example

- *MASTER THREAD
 - *Spawns a number of concurrent slaves
 - *Waits until all of the slaves have finished to exit
 - *Tracks current number of slaves executing
- *A MUTEX IS ASSOCIATED WITH COUNT AND A CONDITION VARIABLE WITH THE MUTEX



Example

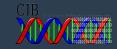
```
#include <stdio.h>
#include <pthread.h>
#define NO_OF_PROCS 4
typedef struct _SharedType {
                                     /* number of active slaves */
 int count;
 pthread_mutex_t lock; /* mutex for count */
 pthread_cond_t done;
                        /* sig. by finished slave */
} SharedType, *SharedType_ptr;
SharedType_ptr shared_data;
```



Example: main

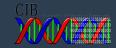
```
main(int argc, char **argv) {
 int res;
 /* allocate shared data */
 if ((sh\_data = (SharedType *)
    malloc(sizeof(SharedType))) == NULL) {
    exit(1);
 sh_data->count=0;
 /* allocate mutex */
 if ((res = pthread_mutex_init(&sh_data->lock,
    NULL)) != 0) {
  exit(1);
```

```
/* allocate condition var */
 if ((res = pthread\_cond\_init(\&sh\_data->done,
     NULL)) != 0) {
  exit(1);
 /* generate number of slaves to create */
 srandom(O);
 /* create up to 15 slaves */
 master((int) random()%16);
```



Example: main

```
main(int argc, char **argv) {
 int res;
 /* allocate shared data */
                                                       pthread_cont_t data_cond =
 if ((sh_data = (SharedType *)
                                                       PTHREAD_COND_INITIALIZER;
     malloc(sizeof(SharedType))) == NULL) {
    exit(1);
 sh_data->count=0;
                                                        srandom(O);
                                                        /* create up to 15 slaves */
 /* allocate mutex */
                                                        master((int) random()%16);
 pthread_mutex_t data_mutex =
 PTHREAD_MUTEX_INITIALIZER;
```



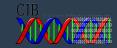
Example: Master

```
pthread_mutex_lock(&sh_data->lock);

while (sh_data->count != 0)
    pthread_cond_wait(&sh_data->done, &sh_data->lock);

pthread_mutex_unlock(&sh_data->lock);

printf("All %d slaves have finished.\n", nslaves);
    pthread_exit(0);
}
```



Example: Slave

```
void slave(void *shared) {
  int i, n;
  sh_data = shared;
  printf("Slave.\n", n);
  n = random() % 1000;

for (i = 0; i < n; i+= 1)
  Sleep(10);</pre>
```

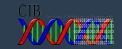
```
/* mutex for shared data */
pthread_mutex_lock(&sh_data->lock);

/* dec number of slaves */
sh_data->count -= 1;
```

```
/* done running */
printf("Slave finished %d cycles.\n", n);

/* signal that you are done working */
pthread_cond_signal(&sh_data->done);

/* release mutex for shared data */
pthread_mutex_unlock(&sh_data->lock);
}
```



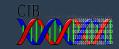
Semaphores vs. CVs

XSEMAPHORE

- xInteger value (>=0)
- *Wait does not always block
- *Signal either releases thread or inc's counter
- *If signal releases thread, both threads continue afterwards

*****CONDITION VARIABLES

- xNo integer value
- *Wait always blocks
- *Signal either releases thread or is lost
- *If signal releases thread, only one of them continue



Dining Philosophers

- N PHILOSOPHERS AND N FORKS
 - PHILOSOPHERS EAT/THINK
 - EATING NEEDS 2 FORKS
 - PICK ONE FORK AT A TIME

