

Lab: Control-Dependence and Reachability

(Week 3)

Yulei Sui

School of Computer Science and Engineering
University of New South Wales, Australia

Quiz-1 + Lab-Exercise-1 + Assignment-1

- A set of quizzes on WebCMS (5 points)
 - LLVM compiler and its intermediate representation
 - Code graphs (including ICFG and PAG)
- Lab-Exercise-1 (5 points)
 - Implement a graph traversal on a general graph
- Assignment-1 (20 points)
 - **Control-flow**: Implement a context-sensitive graph traversal on a CodeGraph (i.e., ICFG) and print **feasible** paths from a source node to a sink node on the graph
 - **Data-flow**: Implement Andersen's inclusion-based constraint solving for points-to analysis
 - Implement a taint checker using control-flow analysis and data-flow analysis.

Quiz-1 + Lab-Exercise-1 + Assignment-1

- A set of quizzes on WebCMS (5 points)
 - LLVM compiler and its intermediate representation
 - Code graphs (including ICFG and PAG)
- Lab-Exercise-1 (5 points)
 - Implement a graph traversal on a general graph
- Assignment-1 (20 points)
 - **Control-flow**: Implement a context-sensitive graph traversal on a CodeGraph (i.e., ICFG) and print **feasible** paths from a source node to a sink node on the graph
 - **Data-flow**: Implement Andersen's inclusion-based constraint solving for points-to analysis
 - Implement a taint checker using control-flow analysis and data-flow analysis.
 - **Specification and code template**: <https://github.com/SVF-tools/Software-Security-Analysis/wiki/Assignment-1>
 - **SVF APIs for control- and data-flow analysis** <https://github.com/SVF-tools/Software-Security-Analysis/wiki/SVF-CPP-API>

Context-Sensitive Control-Dependence

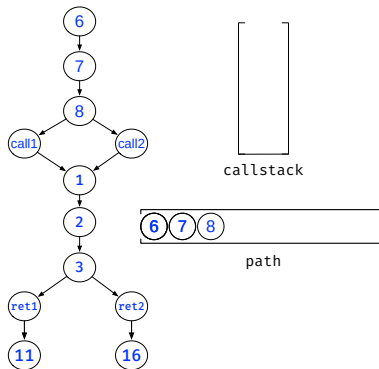
Algorithm 1: 1 Context sensitive control-flow reachability

```
Input : curNode : ICFGNode   snk : ICFGNode   path : vector<ICFGNode>
        callstack : vector<SVFInstruction>   visited : set<ICFGNode, callstack>;

1  dfs(curNode, dst)
2  pair = <curNode, callstack>;
3  if pair  $\in$  visited then
4  |   return;
5  visited.insert(pair);
6  path.push_back(curNode);
7  if src == snk then
8  |   printICFGPath(path);
9  foreach edge  $\in$  curNode.getOutEdges() do
10 | if edge.isIntraCFGEde() then
11 | |   dfs(edge.dst, snk);
12 | else if edge.isCallCFGEde() then
13 | |   callstack.push_back(edge.getCallSite());
14 | |   dfs(edge.dst, snk);
15 | |   callstack.pop_back();
16 | else if edge.isRetCFGEde() then
17 | |   if callstack  $\neq \emptyset$  && callstack.back() == edge.getCallSite() then
18 | | |   callstack.pop_back();
19 | | |   dfs(edge.dst, snk);
20 | | |   callstack.push_back(edge.getCallSite());
21 | |   else if callstack ==  $\emptyset$  then
22 | | |   dfs(edge.dst, snk);
23 visited.erase(pair);
24 path.pop_back();
```

Context-Sensitive Control-Dependence

Obtaining a path from node 6 to node 11 on ICFG



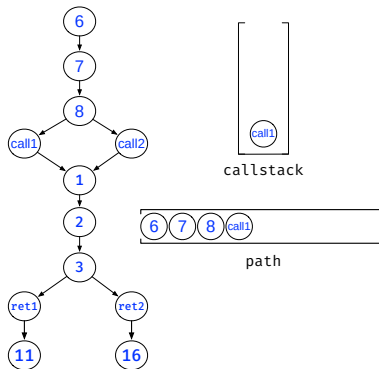
Algorithm 2: 1 Context sensitive control-flow reachability

```
Input : curNode : ICFGNode  snk : ICFGNode  path : vector<ICFGNode>
        callstack : vector<SVFInstruction>  visited : set<ICFGNode, callstack>;

1  dfs(curNode, dst)
2  pair = <curNode, callstack>;
3  if pair ∈ visited then
4  | return;
5  visited.insert(pair);
6  path.push_back(curNode);
7  if src == snk then
8  | printICFGPath(path);
9  foreach edge ∈ curNode.getOutEdges() do
10 | if edge.isIntraCFGEde() then
11 | | dfs(edge.dst, snk);
12 | else if edge.isCallCFGEde() then
13 | | callstack.push_back(edge.getCallSite());
14 | | dfs(edge.dst, snk);
15 | | callstack.pop_back();
16 | else if edge.isRetCFGEde() then
17 | | if callstack ≠ ∅ && callstack.back() == edge.getCallSite() then
18 | | | callstack.pop_back();
19 | | | dfs(edge.dst, snk);
20 | | | callstack.push_back(edge.getCallSite());
21 | | else if callstack == ∅ then
22 | | | dfs(edge.dst, snk);
23  visited.erase(pair);
24  path.pop_back();
```

Context-Sensitive Control-Dependence

Obtaining a path from node 6 to node 11 on ICFG

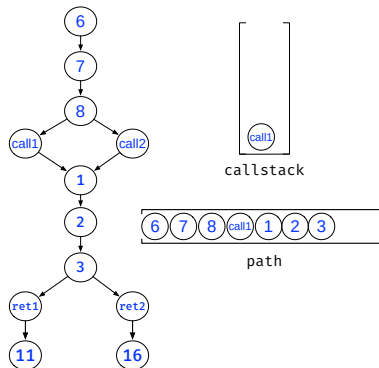


Algorithm 3: 1 Context sensitive control-flow reachability

```
Input : curNode : ICFGNode  snk : ICFGNode  path : vector<ICFGNode>
        callstack : vector<SVFInstruction>  visited : set<ICFGNode, callstack>;
1  dfs(curNode, dst)
2  pair = <curNode, callstack>;
3  if pair ∈ visited then
4  | return;
5  visited.insert(pair);
6  path.push_back(curNode);
7  if src == snk then
8  | printICFGPath(path);
9  foreach edge ∈ curNode.getOutEdges() do
10 | if edge.isIntraCFGEde() then
11 | | dfs(edge.dst, snk);
12 | else if edge.isCallCFGEde() then
13 | | callstack.push_back(edge.getCallSite());
14 | | dfs(edge.dst, snk);
15 | | callstack.pop_back();
16 | else if edge.isRetCFGEde() then
17 | | if callstack ≠ ∅ && callstack.back() == edge.getCallSite() then
18 | | | callstack.pop_back();
19 | | | dfs(edge.dst, snk);
20 | | | callstack.push_back(edge.getCallSite());
21 | | else if callstack == ∅ then
22 | | | dfs(edge.dst, snk);
23 visited.erase(pair);
24 path.pop_back();
```

Context-Sensitive Control-Dependence

Obtaining a path from node 6 to node 11 on ICFG

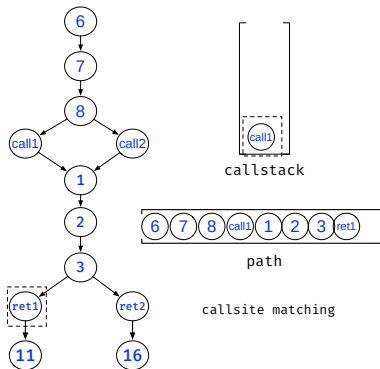


Algorithm 4: 1 Context sensitive control-flow reachability

```
Input : curNode : ICFGNode  snk : ICFGNode  path : vector<ICFGNode>  
        callstack : vector<SVFInstruction>  visited : set<ICFGNode, callstack>;  
1  dfs(curNode, dst)  
2  pair = <curNode, callstack>;  
3  if pair ∈ visited then  
4  |   return;  
5  visited.insert(pair);  
6  path.push_back(curNode);  
7  if src == snk then  
8  |   printICFGPath(path);  
9  foreach edge ∈ curNode.getOutEdges() do  
10 if edge.isIntraCFGEde() then  
11 |   dfs(edge.dst, snk);  
12 else if edge.isCallCFGEde() then  
13 |   callstack.push_back(edge.getCallSite());  
14 |   dfs(edge.dst, snk);  
15 |   callstack.pop_back();  
16 else if edge.isRetCFGEde() then  
17 |   if callstack ≠ ∅ && callstack.back() == edge.getCallSite() then  
18 |   |   callstack.pop_back();  
19 |   |   dfs(edge.dst, snk);  
20 |   |   callstack.push_back(edge.getCallSite());  
21 |   else if callstack == ∅ then  
22 |   |   dfs(edge.dst, snk);  
23 visited.erase(pair);  
24 path.pop_back();
```

Context-Sensitive Control-Dependence

Obtaining a path from node 6 to node 11 on ICFG

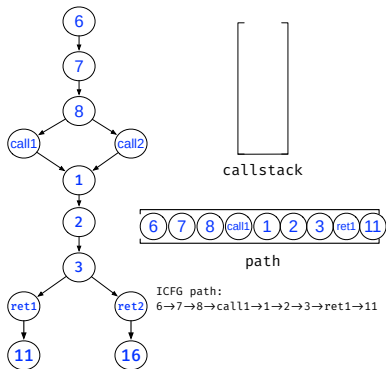


Algorithm 5: 1 Context sensitive control-flow reachability

```
Input : curNode : ICFGNode  snk : ICFGNode  path : vector<ICFGNode>  
        callstack : vector<SVFInstruction>  visited : set<ICFGNode, callstack>;  
1  dfs(curNode, dst)  
2  pair = <curNode, callstack>;  
3  if pair ∈ visited then  
4  | return;  
5  visited.insert(pair);  
6  path.push_back(curNode);  
7  if src == snk then  
8  | printICFGPath(path);  
9  foreach edge ∈ curNode.getOutEdges() do  
10 if edge.isIntraCFGEde() then  
11 | dfs(edge.dst, snk);  
12 else if edge.isCallCFGEde() then  
13 | callstack.push_back(edge.getCallSite());  
14 | dfs(edge.dst, snk);  
15 | callstack.pop_back();  
16 else if edge.isRetCFGEde() then  
17 | if callstack ≠ ∅ && callstack.back() == edge.getCallSite() then  
18 | | callstack.pop_back();  
19 | | dfs(edge.dst, snk);  
20 | | callstack.push_back(edge.getCallSite());  
21 | else if callstack == ∅ then  
22 | | dfs(edge.dst, snk);  
23 visited.erase(pair);  
24 path.pop_back();
```


Context-Sensitive Control-Dependence

Obtaining a path from node 6 to node 11 on ICFG

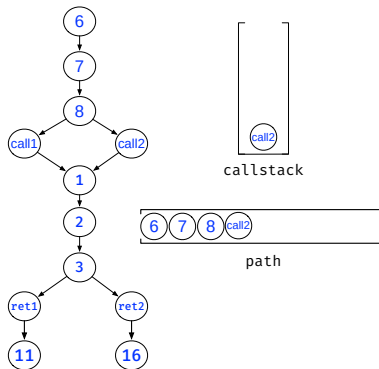


Algorithm 6: 1 Context sensitive control-flow reachability

```
Input : curNode : ICFGNode  snk : ICFGNode  path : vector<ICFGNode>  
        callstack : vector<SVFInstruction>  visited : set<ICFGNode, callstack>;  
1  dfs(curNode, dst)  
2  pair = <curNode, callstack>;  
3  if pair ∈ visited then  
4  | return;  
5  visited.insert(pair);  
6  path.push_back(curNode);  
7  if src == snk then  
8  | printICFGPath(path);  
9  foreach edge ∈ curNode.getOutEdges() do  
10 | if edge.isIntraCFGEde() then  
11 | | dfs(edge.dst, snk);  
12 | else if edge.isCallCFGEde() then  
13 | | callstack.push_back(edge.getCallSite());  
14 | | dfs(edge.dst, snk);  
15 | | callstack.pop_back();  
16 | else if edge.isRetCFGEde() then  
17 | | if callstack ≠ ∅ && callstack.back() == edge.getCallSite() then  
18 | | | callstack.pop_back();  
19 | | | dfs(edge.dst, snk);  
20 | | | callstack.push_back(edge.getCallSite());  
21 | | else if callstack == ∅ then  
22 | | | dfs(edge.dst, snk);  
23  visited.erase(pair);  
24  path.pop_back();
```

Context-Sensitive Control-Dependence

Obtaining a path from node 6 to node 11 on ICFG

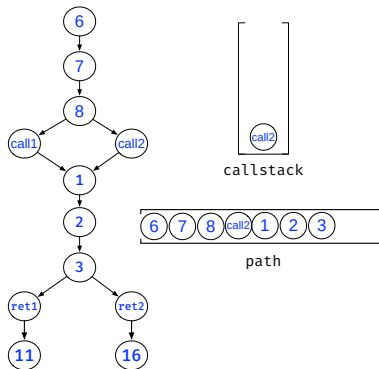


Algorithm 7: 1 Context sensitive control-flow reachability

```
Input : curNode : ICFGNode  snk : ICFGNode  path : vector<ICFGNode>
        callstack : vector<SVFInstruction>  visited : set<ICFGNode, callstack>;
1  dfs(curNode, dst)
2  pair = <curNode, callstack>;
3  if pair ∈ visited then
4  | return;
5  visited.insert(pair);
6  path.push_back(curNode);
7  if src == snk then
8  | printICFGPath(path);
9  foreach edge ∈ curNode.getOutEdges() do
10 | if edge.isIntraCFGEde() then
11 | | dfs(edge.dst, snk);
12 | else if edge.isCallCFGEde() then
13 | | callstack.push_back(edge.getCallSite());
14 | | dfs(edge.dst, snk);
15 | | callstack.pop_back();
16 | else if edge.isRetCFGEde() then
17 | | if callstack ≠ ∅ && callstack.back() == edge.getCallSite() then
18 | | | callstack.pop_back();
19 | | | dfs(edge.dst, snk);
20 | | | callstack.push_back(edge.getCallSite());
21 | | else if callstack == ∅ then
22 | | | dfs(edge.dst, snk);
23 visited.erase(pair);
24 path.pop_back();
```

Context-Sensitive Control-Dependence

Obtaining a path from node 6 to node 11 on ICFG

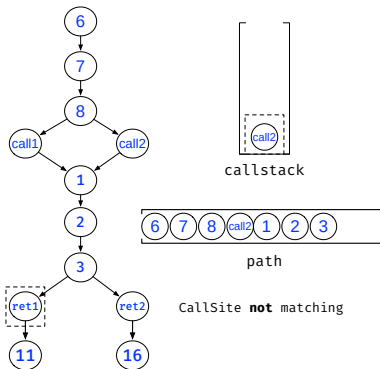


Algorithm 8: 1 Context sensitive control-flow reachability

```
Input : curNode : ICFGNode  snk : ICFGNode  path : vector<ICFGNode>  
        callstack : vector<SVFInstruction>  visited : set<ICFGNode, callstack>;  
1  dfs(curNode, dst)  
2  pair = <curNode, callstack>;  
3  if pair ∈ visited then  
4  |   return;  
5  visited.insert(pair);  
6  path.push_back(curNode);  
7  if src == snk then  
8  |   printICFGPath(path);  
9  foreach edge ∈ curNode.getOutEdges() do  
10 |   if edge.isIntraCFGEde() then  
11 |       dfs(edge.dst, snk);  
12 |   else if edge.isCallCFGEde() then  
13 |       callstack.push_back(edge.getCallSite());  
14 |       dfs(edge.dst, snk);  
15 |       callstack.pop_back();  
16 |   else if edge.isRetCFGEde() then  
17 |       if callstack ≠ ∅ && callstack.back() == edge.getCallSite() then  
18 |           callstack.pop_back();  
19 |           dfs(edge.dst, snk);  
20 |           callstack.push_back(edge.getCallSite());  
21 |       else if callstack == ∅ then  
22 |           dfs(edge.dst, snk);  
23  visited.erase(pair);  
24  path.pop_back();
```

Context-Sensitive Control-Dependence

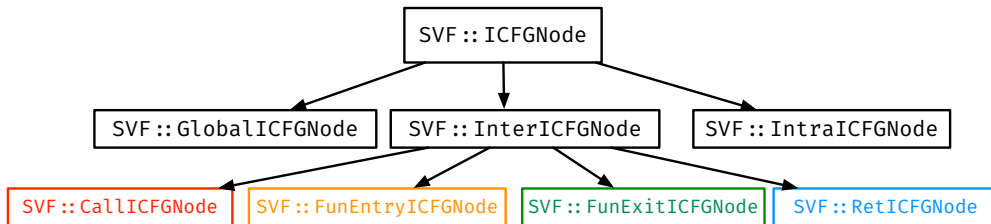
Obtaining a path from node 6 to node 11 on ICFG



Algorithm 9: 1 Context sensitive control-flow reachability

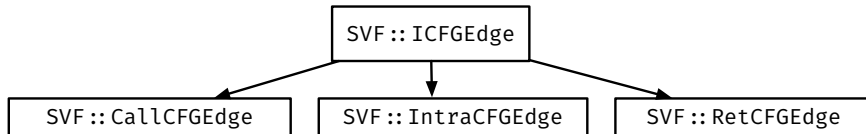
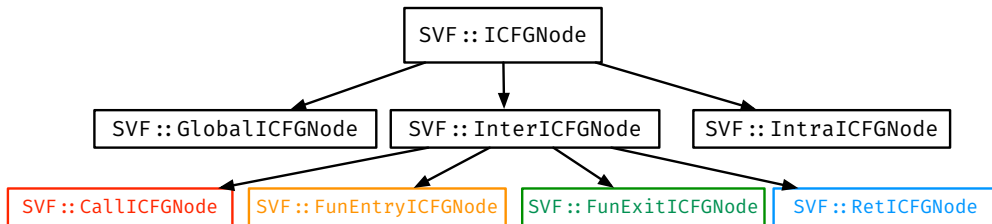
```
Input : curNode : ICFGNode  snk : ICFGNode  path : vector<ICFGNode>
        callstack : vector<SVFInstruction>  visited : set<ICFGNode, callstack>;
1  dfs(curNode, dst)
2  pair = <curNode, callstack>;
3  if pair ∈ visited then
4  | return;
5  visited.insert(pair);
6  path.push_back(curNode);
7  if src == snk then
8  | printICFGPath(path);
9  foreach edge ∈ curNode.getOutEdges() do
10 if edge.isIntraCFGEde() then
11 | dfs(edge.dst, snk);
12 else if edge.isCallCFGEde() then
13 | callstack.push_back(edge.getCallSite());
14 | dfs(edge.dst, snk);
15 | callstack.pop_back();
16 else if edge.isRetCFGEde() then
17 | if callstack ≠ ∅ && callstack.back() == edge.getCallSite() then
18 | | callstack.pop_back();
19 | | dfs(edge.dst, snk);
20 | | callstack.push_back(edge.getCallSite());
21 | else if callstack == ∅ then
22 | | dfs(edge.dst, snk);
23 visited.erase(pair);
24 path.pop_back();
```

ICFG Node and Edge Classes



<https://github.com/SVF-tools/SVF/blob/master/include/Graphs/ICFGNode.h>

ICFG Node and Edge Classes



<https://github.com/SVF-tools/SVF/blob/master/include/Graphs/ICFGEde.h>

cast and dyn_cast

- C++ Inheritance: see slides in Week 2.
- Casting a **parent** class pointer to pointer of a **Child** type:
 - `SVFUtil::cast`
 - Casts a pointer or reference to an instance of a specified class. This cast fails and aborts the program if the object or reference is not the specified class at runtime.
 - `SVFUtil::dyn_cast`
 - "Checked cast" operation. Checks to see if the operand is of the specified type, and if so, returns a pointer to it (this operator does not work with references). If the operand is not of the correct type, a null pointer is returned.
 - Works very much like the `dynamic_cast<>` operator in C++, and should be used in the same circumstances.
- Example: accessing the attributes of the child class via casting.
 - `RetBlockNode* retNode = SVFUtil::cast<RetBlockNode>(ICFGNode);`
 - `CallCFGEde* callEdge = SVFUtil::dyn_cast<CallCFGEde>(ICFGEde);`