

Lab: Data-Dependence and Pointer Aliasing

(Week 3)

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School of Computer Science and Engineering
University of New South Wales, Australia

Quiz-1 + Lab-Exercise-1 + Assignment-1

- A set of quizzes on WebCMS (5 points)
 - LLVM compiler and its intermediate representation
 - Code graphs (including ICFG and PAG)
- Lab-Exercise-1 (5 points)
 - Implement a graph traversal on a general graph
- Assignment-1 (20 points)
 - **Control-flow**: Implement a context-sensitive graph traversal on a CodeGraph (i.e., ICFG) and print **feasible** paths from a source node to a sink node on the graph
 - **Data-flow**: Implement Andersen's inclusion-based constraint solving for points-to analysis
 - Implement a taint checker using control-flow analysis and data-flow analysis.

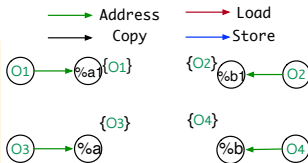
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 - **Specification and code template**: <https://github.com/SVF-tools/Software-Security-Analysis/wiki/Assignment-1>
 - **SVF APIs for control- and data-flow analysis** <https://github.com/SVF-tools/Software-Security-Analysis/wiki/SVF-CPP-API>

Andersen's Pointer Analysis

Algorithm

```
define i32 @main() #0 {  
entry:  
  %a1 = alloca i8, align 1      // O1  
  %a = alloca ptr, align 8      // O2  
  %b1 = alloca i8, align 1      // O3  
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  store ptr %a1, ptr %a, align 8  
  store ptr %b1, ptr %b, align 8  
  call void @swap(ptr %a, ptr %b)  
  ret i32 0  
}  
  
define void @swap(ptr %p, ptr %q) #0 {  
entry:  
  %0 = load ptr, ptr %p, align 8  
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  store ptr %0, ptr %q, align 8  
  ret void  
}
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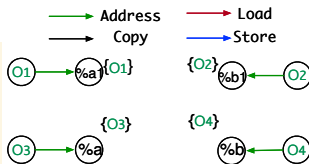
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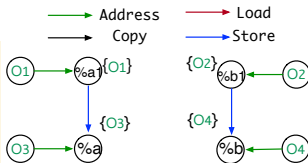
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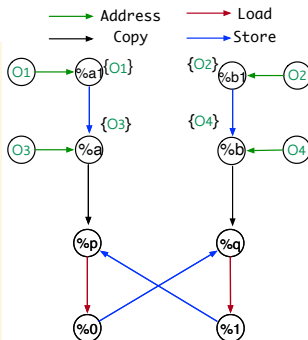


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V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes

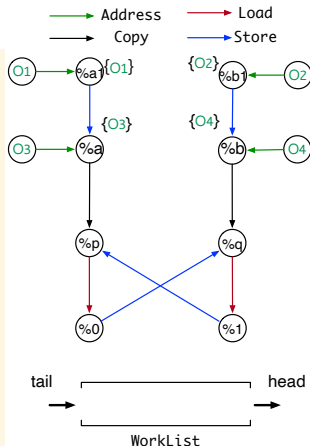
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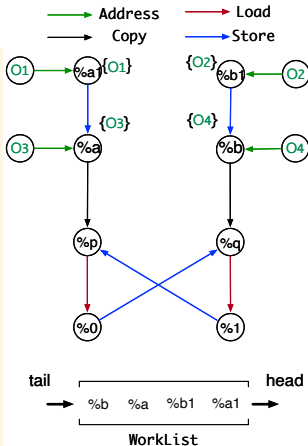
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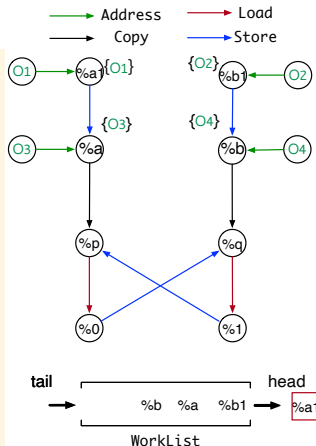
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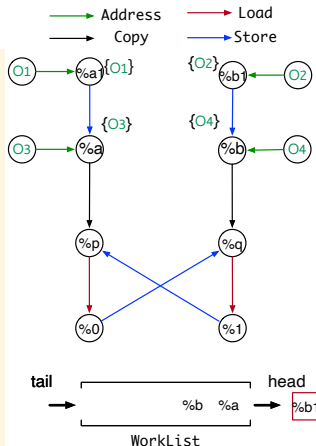
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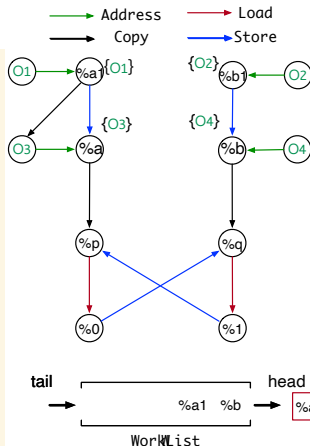
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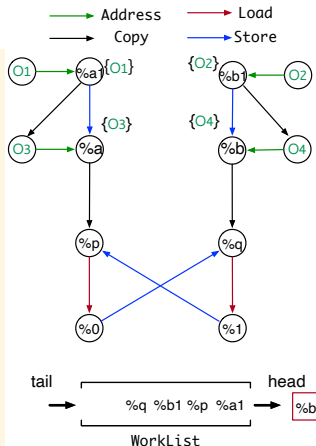
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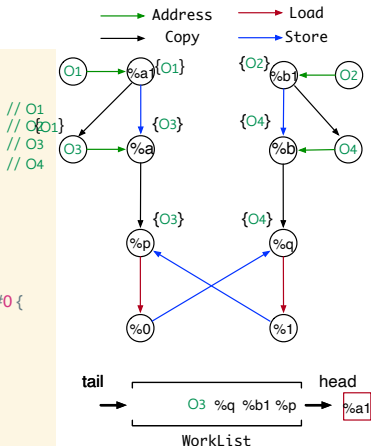
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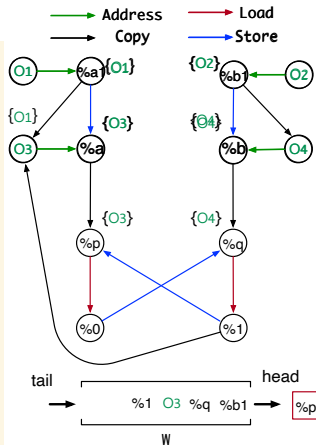
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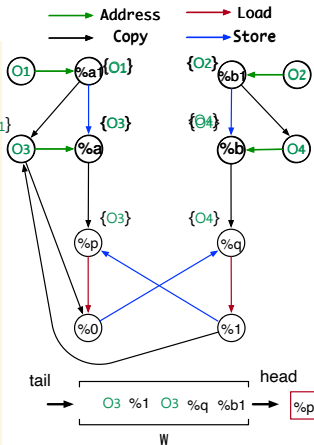
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G = <V,E> // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes

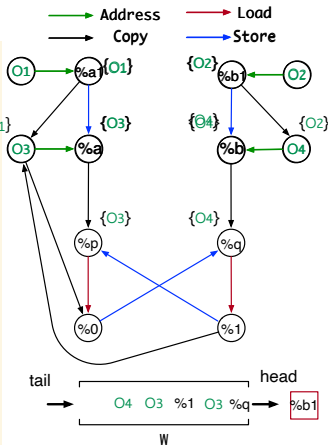
1 foreach o  $\xrightarrow{\text{Address}}$  p do // Address rule
2     pts(p) = {o}
3     pushIntoWorklist(p)
4 while WorkList  $\neq \emptyset$  do
5     p <- popFromWorklist()
6     foreach o  $\in$  pts(p) do
7         foreach q  $\xrightarrow{\text{Store}}$  p do // Store rule
8             if q  $\xrightarrow{\text{Copy}}$  o  $\notin E$  then
9                 E <- E  $\cup$  { q  $\xrightarrow{\text{Copy}}$  o } // Add copy edge
10                pushIntoWorklist(q)
11            foreach r  $\xrightarrow{\text{Load}}$  p do // Load rule
12                if o  $\xrightarrow{\text{Copy}}$  r  $\notin E$  then
13                    E <- E  $\cup$  { o  $\xrightarrow{\text{Copy}}$  r } // Add copy edge
14                pushIntoWorklist(o)
15        foreach p  $\xrightarrow{\text{Copy}}$  x  $\in E$  do // Copy rule
16            pts(x) <- pts(x)  $\cup$  pts(p)
17            if pts(x) changed then
18                pushIntoWorklist(x)
```


Andersen's Pointer Analysis

Algorithm

```
define i32 @main() #0 {
entry:
  %a1 = alloca i8, align 1           // O1
  %a = alloca ptr, align 8           // O2
  %b1 = alloca i8, align 1           // O3
  %b = alloca ptr, align 8           // O4
  store ptr %a1, ptr %a, align 8
  store ptr %b1, ptr %b, align 8
  call void @swap(ptr %a, ptr %b)
  ret i32 0
}
```

```
define void @swap(ptr %p, ptr %q) #0 {
entry:
  %0 = load ptr, ptr %p, align 8
  %1 = load ptr, ptr %q, align 8
  store ptr %1, ptr %p, align 8
  store ptr %0, ptr %q, align 8
  ret void
}
```



```
G = <V, E> // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes

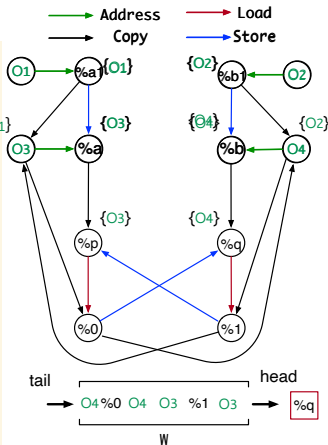
1 foreach o  $\xrightarrow{\text{Address}}$  p do // Address rule
2   pts(p) = {o}
3   pushIntoWorklist(p)
4 while WorkList  $\neq \emptyset$  do
5   p <- popFromWorklist()
6   foreach o  $\in$  pts(p) do
7     foreach q  $\xrightarrow{\text{Store}}$  p do // Store rule
8       if q  $\xrightarrow{\text{Copy}}$  o  $\notin E$  then
9         E <- E  $\cup$  { q  $\xrightarrow{\text{Copy}}$  o } // Add copy edge
10        pushIntoWorklist(q)
11      foreach p  $\xrightarrow{\text{Load}}$  r do // Load rule
12        if o  $\xrightarrow{\text{Copy}}$  r  $\notin E$  then
13          E <- E  $\cup$  { o  $\xrightarrow{\text{Copy}}$  r } // Add copy edge
14        pushIntoWorklist(o)
15      foreach p  $\xrightarrow{\text{Copy}}$  x  $\in E$  do // Copy rule
16        pts(x) <- pts(x)  $\cup$  pts(p)
17        if pts(x) changed then
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```

Andersen's Pointer Analysis

Algorithm

```
define i32 @main() #0 {
entry:
    %a1 = alloca i8, align 1           // O1
    %a = alloca ptr, align 8           // O2
    %b1 = alloca i8, align 1           // O3
    %b = alloca ptr, align 8           // O4
    store ptr %a1, ptr %a, align 8
    store ptr %b1, ptr %b, align 8
    call void @swap(ptr %a, ptr %b)
    ret i32 0
}

define void @swap(ptr %p, ptr %q) #0 {
entry:
    %0 = load ptr, ptr %p, align 8
    %1 = load ptr, ptr %q, align 8
    store ptr %1, ptr %p, align 8
    store ptr %0, ptr %q, align 8
    ret void
}
```



```
G = <V,E> // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes

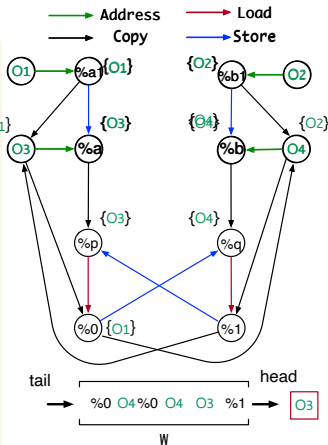
1 foreach o  $\xrightarrow{\text{Address}}$  p do // Address rule
2   pts(p) = {o}
3   pushIntoWorklist(p)
4 while WorkList  $\neq \emptyset$  do
5   p <- popFromWorklist()
6   foreach o  $\in$  pts(p) do
7     foreach q  $\xrightarrow{\text{Store}}$  p do // Store rule
8       if q  $\xrightarrow{\text{Copy}}$  o  $\notin$  E then
9         E <- E  $\cup$  { q  $\xrightarrow{\text{Copy}}$  o } // Add copy edge
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13          E <- E  $\cup$  { o  $\xrightarrow{\text{Copy}}$  r } // Add copy edge
14        pushIntoWorklist(o)
15      foreach p  $\xrightarrow{\text{Copy}}$  x  $\in$  E do // Copy rule
16        pts(x) <- pts(x)  $\cup$  pts(p)
17        if pts(x) changed then
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```

Andersen's Pointer Analysis

Algorithm

```
define i32 @main() #0 {
entry:
    %a1 = alloca i8, align 1           // O1
    %a = alloca ptr, align 8           // O2
    %b1 = alloca i8, align 1           // O3
    %b = alloca ptr, align 8           // O4
    store ptr %a1, ptr %a, align 8
    store ptr %b1, ptr %b, align 8
    call void @swap(ptr %a, ptr %b)
    ret i32 0
}

define void @swap(ptr %p, ptr %q) #0 {
entry:
    %0 = load ptr, ptr %p, align 8
    %1 = load ptr, ptr %q, align 8
    store ptr %1, ptr %p, align 8
    store ptr %0, ptr %q, align 8
    ret void
}
```



```
G = <V,E> // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes

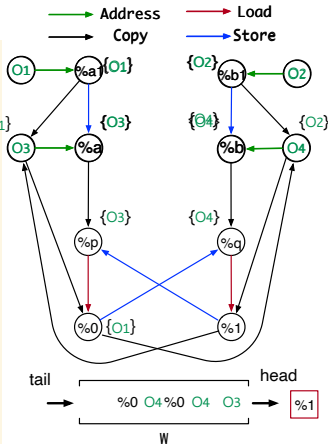
1 foreach o  $\xrightarrow{\text{Address}}$  p do // Address rule
2     pts(p) = {o}
3     pushIntoWorklist(p)
4 while WorkList  $\neq \emptyset$  do
5     p <- popFromWorklist()
6     foreach o  $\in$  pts(p) do
7         foreach q  $\xrightarrow{\text{Store}}$  p do // Store rule
8             if q  $\xrightarrow{\text{Copy}}$  o  $\notin E$  then
9                 E <- E  $\cup$  { q  $\xrightarrow{\text{Copy}}$  o } // Add copy edge
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12                if o  $\xrightarrow{\text{Copy}}$  r  $\notin E$  then
13                    E <- E  $\cup$  { o  $\xrightarrow{\text{Copy}}$  r } // Add copy edge
14                pushIntoWorklist(o)
15            foreach p  $\xrightarrow{\text{Copy}}$  x  $\in E$  do // Copy rule
16                pts(x) <- pts(x)  $\cup$  pts(p)
17                if pts(x) changed then
18                    pushIntoWorklist(x)
```

Andersen's Pointer Analysis

Algorithm

```
define i32 @main() #0 {
entry:
    %a1 = alloca i8, align 1           // O1
    %a = alloca ptr, align 8           // O2
    %b1 = alloca i8, align 1           // O3
    %b = alloca ptr, align 8           // O4
    store ptr %a1, ptr %a, align 8
    store ptr %b1, ptr %b, align 8
    call void @swap(ptr %a, ptr %b)
    ret i32 0
}

define void @swap(ptr %p, ptr %q) #0 {
entry:
    %0 = load ptr, ptr %p, align 8
    %1 = load ptr, ptr %q, align 8
    store ptr %1, ptr %p, align 8
    store ptr %0, ptr %q, align 8
    ret void
}
```



```
G = <V,E> // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes

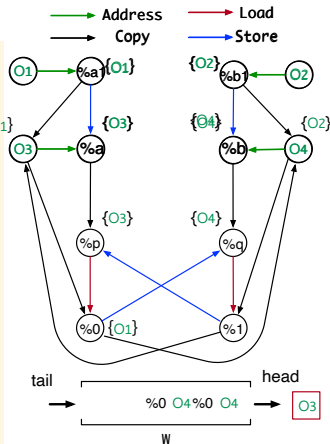
1 foreach o  $\xrightarrow{\text{Address}}$  p do // Address rule
2     pts(p) = {o}
3     pushIntoWorklist(p)
4 while WorkList  $\neq \emptyset$  do
5     p <- popFromWorklist()
6     foreach o  $\in$  pts(p) do
7         foreach q  $\xrightarrow{\text{Store}}$  p do // Store rule
8             if q  $\xrightarrow{\text{Copy}}$  o  $\notin E$  then
9                 E <- E  $\cup$  { q  $\xrightarrow{\text{Copy}}$  o } // Add copy edge
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13                    E <- E  $\cup$  { o  $\xrightarrow{\text{Copy}}$  r } // Add copy edge
14                pushIntoWorklist(o)
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16                pts(x) <- pts(x)  $\cup$  pts(p)
17                if pts(x) changed then
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```

Andersen's Pointer Analysis

Algorithm

```
define i32 @main() #0 {
entry:
    %a1 = alloca i8, align 1           // O1
    %a = alloca ptr, align 8           // O2
    %b1 = alloca i8, align 1           // O3
    %b = alloca ptr, align 8           // O4
    store ptr %a1, ptr %a, align 8
    store ptr %b1, ptr %b, align 8
    call void @swap(ptr %a, ptr %b)
    ret i32 0
}

define void @swap(ptr %p, ptr %q) #0 {
entry:
    %0 = load ptr, ptr %p, align 8
    %1 = load ptr, ptr %q, align 8
    store ptr %1, ptr %p, align 8
    store ptr %0, ptr %q, align 8
    ret void
}
```



```
G = <V,E> // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes

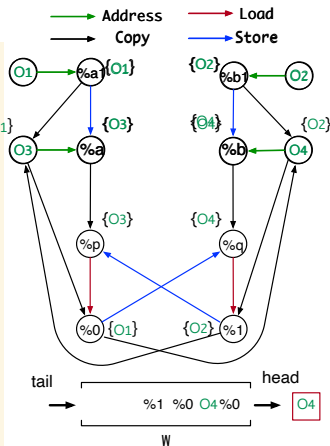
1 foreach o  $\xrightarrow{\text{Address}}$  p do // Address rule
2     pts(p) = {o}
3     pushIntoWorklist(p)
4 while WorkList  $\neq \emptyset$  do
5     p <- popFromWorklist()
6     foreach o  $\in$  pts(p) do
7         foreach q  $\xrightarrow{\text{Store}}$  p do // Store rule
8             if q  $\xrightarrow{\text{Copy}}$  o  $\notin E$  then
9                 E <- E  $\cup$  { q  $\xrightarrow{\text{Copy}}$  o } // Add copy edge
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```

Andersen's Pointer Analysis

Algorithm

```
define i32 @main() #0 {
entry:
    %a1 = alloca i8, align 1           // O1
    %a = alloca ptr, align 8           // O2
    %b1 = alloca i8, align 1           // O3
    %b = alloca ptr, align 8           // O4
    store ptr %a1, ptr %a, align 8
    store ptr %b1, ptr %b, align 8
    call void @swap(ptr %a, ptr %b)
    ret i32 0
}

define void @swap(ptr %p, ptr %q) #0 {
entry:
    %0 = load ptr, ptr %p, align 8
    %1 = load ptr, ptr %q, align 8
    store ptr %1, ptr %p, align 8
    store ptr %0, ptr %q, align 8
    ret void
}
```



```
G = <V,E> // Constraint Graph
V: a set of nodes in graph
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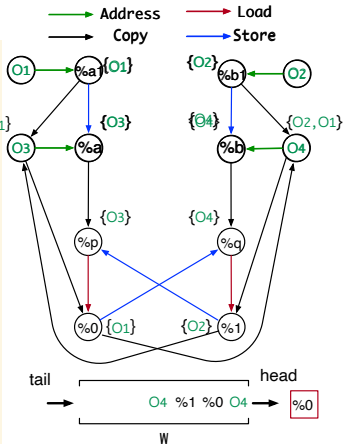
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2   pts(p) = {o}
3   pushIntoWorklist(p)
4 while WorkList  $\neq \emptyset$  do
5   p <- popFromWorklist()
6   foreach o  $\in$  pts(p) do
7     foreach q  $\xrightarrow{\text{Store}}$  p do // Store rule
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9         E <- E  $\cup$  { q  $\xrightarrow{\text{Copy}}$  o } // Add copy edge
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16        pts(x) <- pts(x)  $\cup$  pts(p)
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```

Andersen's Pointer Analysis

Algorithm

```
define i32 @main() #0 {
entry:
    %a1 = alloca i8, align 1           // O1
    %a = alloca ptr, align 8           // O2
    %b1 = alloca i8, align 1           // O3
    %b = alloca ptr, align 8           // O4
    store ptr %a1, ptr %a, align 8
    store ptr %b1, ptr %b, align 8
    call void @swap(ptr %a, ptr %b)
    ret i32 0
}

define void @swap(ptr %p, ptr %q) #0 {
entry:
    %0 = load ptr, ptr %p, align 8
    %1 = load ptr, ptr %q, align 8
    store ptr %1, ptr %p, align 8
    store ptr %0, ptr %q, align 8
    ret void
}
```



```
G = <V,E> // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes

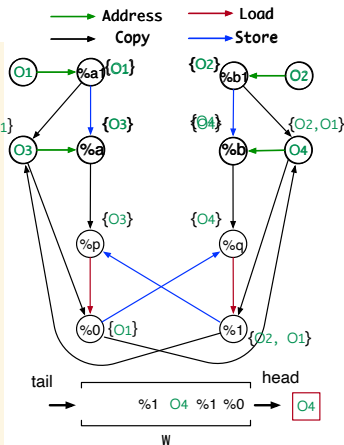
1 foreach o  $\xrightarrow{\text{Address}}$  p do // Address rule
2   pts(p) = {o}
3   pushIntoWorklist(p)
4 while WorkList  $\neq \emptyset$  do
5   p <- popFromWorklist()
6   foreach o  $\in$  pts(p) do
7     foreach q  $\xrightarrow{\text{Store}}$  p do // Store rule
8       if q  $\xrightarrow{\text{Copy}}$  o  $\notin E$  then
9         E <- E  $\cup$  { q  $\xrightarrow{\text{Copy}}$  o } // Add copy edge
10        pushIntoWorklist(q)
11      foreach p  $\xrightarrow{\text{Load}}$  r do // Load rule
12        if o  $\xrightarrow{\text{Copy}}$  r  $\notin E$  then
13          E <- E  $\cup$  { o  $\xrightarrow{\text{Copy}}$  r } // Add copy edge
14        pushIntoWorklist(o)
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16        pts(x) <- pts(x)  $\cup$  pts(p)
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```

Andersen's Pointer Analysis

Algorithm

```
define i32 @main() #0 {
entry:
    %a1 = alloca i8, align 1           // O1
    %a = alloca ptr, align 8           // O2
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    %b = alloca ptr, align 8           // O4
    store ptr %a1, ptr %a, align 8
    store ptr %b1, ptr %b, align 8
    call void @swap(ptr %a, ptr %b)
    ret i32 0
}

define void @swap(ptr %p, ptr %q) #0 {
entry:
    %0 = load ptr, ptr %p, align 8
    %1 = load ptr, ptr %q, align 8
    store ptr %1, ptr %p, align 8
    store ptr %0, ptr %q, align 8
    ret void
}
```



$G = \langle V, E \rangle$ // Constraint Graph
 V : a set of nodes in graph
 E : a set of edges in graph
 WorkList: a vector of nodes

```

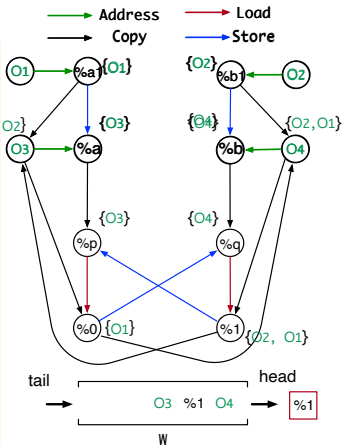
1  foreach  $o \xrightarrow{\text{Address}} p$  do // Address rule
2      pts(p) = {o}
3      pushIntoWorklist(p)
4  while WorkList  $\neq \emptyset$  do
5      p <- popFromWorklist()
6      foreach  $o \in \text{pts}(p)$  do
7          foreach  $q \xrightarrow{\text{Store}} p$  do // Store rule
8              if  $q \xrightarrow{\text{Copy}} o \notin E$  then
9                   $E \leftarrow E \cup \{ q \xrightarrow{\text{Copy}} o \}$  // Add copy edge
10                 pushIntoWorklist(q)
11             foreach  $p \xrightarrow{\text{Load}} r$  do // Load rule
12                 if  $o \xrightarrow{\text{Copy}} r \notin E$  then
13                      $E \leftarrow E \cup \{ o \xrightarrow{\text{Copy}} r \}$  // Add copy edge
14                 pushIntoWorklist(o)
15         foreach  $p \xrightarrow{\text{Copy}} x \in E$  do // Copy rule
16             pts(x) <- pts(x)  $\cup$  pts(p)
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```


Andersen's Pointer Analysis

Algorithm

```
define i32 @main() #0 {
entry:
    %a1 = alloca i8, align 1           // O1
    %a = alloca ptr, align 8           // O2
    %b1 = alloca i8, align 1           // O3
    %b = alloca ptr, align 8           // O4
    store ptr %a1, ptr %a, align 8
    store ptr %b1, ptr %b, align 8
    call void @swap(ptr %a, ptr %b)
    ret i32 0
}

define void @swap(ptr %p, ptr %q) #0 {
entry:
    %0 = load ptr, ptr %p, align 8
    %1 = load ptr, ptr %q, align 8
    store ptr %1, ptr %p, align 8
    store ptr %0, ptr %q, align 8
    ret void
}
```



$G = \langle V, E \rangle$ // Constraint Graph

V : a set of nodes in graph

E : a set of edges in graph

WorkList: a vector of nodes

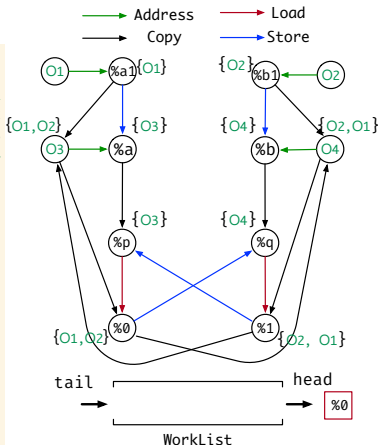
```
1 foreach o  $\xrightarrow{\text{Address}}$  p do // Address rule
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5   p <- popFromWorklist()
6   foreach o  $\in$  pts(p) do
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9         E <- E  $\cup$  { q  $\xrightarrow{\text{Copy}}$  o } // Add copy edge
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17        if pts(x) changed then
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```

Andersen's Pointer Analysis

Algorithm

```
define i32 @main() #0 {
entry:
%a1 = alloca i8, align 1      // O1
%b1 = alloca i8, align 1      // O2
%a = alloca i8*, align 8      // O3
%b = alloca i8*, align 8      // O4
store i8* %a1, i8** %a, align 8
store i8* %b1, i8** %b, align 8
call void @swap(i8** %a, i8** %b)
ret i32 0
}

define void @swap(i8** %p, i8** %q)
#0 {
entry:
%0 = load i8** %p, align 8
%1 = load i8** %q, align 8
store i8* %1, i8** %p, align 8
store i8* %0, i8** %q, align 8
ret void
}
```



```
G = < V, E > // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes

1 foreach o  $\xrightarrow{\text{Address}}$  p do // Address rule
2   pts(p) = {o}
3   pushIntoWorklist(p)
4 while WorkList  $\neq \emptyset$  do
5   p  $\leftarrow$  popFromWorklist()
6   foreach o  $\in$  pts(p) do
7     foreach q  $\xrightarrow{\text{Store}}$  p do // Store rule
8       if q  $\xrightarrow{\text{Copy}}$  o  $\notin$  E then
9         E  $\leftarrow$  E  $\cup$  {q  $\xrightarrow{\text{Copy}}$  o} // Add copy edge
10        pushIntoWorklist(q)
11      foreach p  $\xrightarrow{\text{Load}}$  r do // Load rule
12        if o  $\xrightarrow{\text{Copy}}$  r  $\notin$  E then
13          E  $\leftarrow$  E  $\cup$  {o  $\xrightarrow{\text{Copy}}$  r} // Add copy edge
14          pushIntoWorklist(o)
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16        pts(x)  $\leftarrow$  pts(x)  $\cup$  pts(p)
17        if pts(x) changed then
18          pushIntoWorklist(x)
```

Assignment Structure

BVDataPTAImpl



AndersenBase



AndersenPTA

- You will be working on AndersenPTA's `solveWorklist` method.

Assignment Structure

BVDataPTAImpl



AndersenBase



AndersenPTA

- You will be working on AndersenPTA's `solveWorklist` method.
- Constraint graph is the field `consCG`.

Assignment Structure

BVDataPTAImpl



AndersenBase



AndersenPTA

- You will be working on AndersenPTA's `solveWorklist` method.
- Constraint graph is the field `consCG`.
- Address edge processing is done for you.

Assignment Structure

BVDataPTAImpl



AndersenBase



AndersenPTA

- You will be working on AndersenPTA's `solveWorklist` method.
- Constraint graph is the field `consCG`.
- Address edge processing is done for you.
- Note in the API there is a `getDirectInEdges/getDirectOutEdges` but no `getCopyIn/OutEdges`. This is intentional, use the `Direct` variant.
- You will reuse this assignment for assignment 4, make sure it is clean. :)