Predictor-Corrector Method

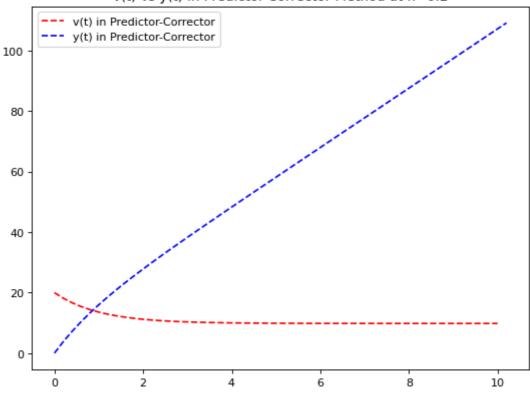
When step size, h=0.2

```
In [1]:
         import numpy as np
         import matplotlib.pyplot as plt
         from matplotlib.pyplot import figure
In [2]:
         figure(num=None, figsize=(8, 6), dpi=80, facecolor='w', edgecolor='k')
         # Solving for the Predictor-Corrector method at step-size h=0.2
         g = 9.81
         m = 1
         c = 1
         def f(t,v):
              return g-(c/m)*v
         a = 0
         b = 10
         va = 20
         N = 50
         h = (b-a)/N
         t = np.arange(a, b+h, h)
         v = np.zeros((N+1,))
         v[0] = va
          #using fourth oreder Runge-Kutta to obtain the first 3 points
         for i in range(0,N):
             if i in range(0,3):
                 k1 = h * f(t[i],v[i])
                 k2 = h * f(t[i] + (h/2.0), v[i] + (k1/2.0))
                 k3 = h * f(t[i] + (h/2.0), v[i] + (k2/2.0))
                 k4 = h * f(t[i] + h, v[i] + k3)
                 v[i + 1] = v[i] + (k1 + 2.0*k2 + 2.0*k3 + k4)/6.0
             else:
                 v[i + 1] = v[i] + h*(55.0 * f(t[i], v[i]) - 59.0 * f(t[i-1], v[i-1]) +
                 v[i + 1] = v[i] + h*(9.0 * f(t[i+1], v[i + 1]) + 19.0 * f(t[i], v[i])
         h1 = 0.2
         def g1(v):
             g = 9.8
             return g-v
         v0 = [20]
         t0 = [0]
         y0 = [0]
         # solving the v(t) used for y(t)
         for i in range(N+1):
             v1 = v0[i] + h1*g1(v0[i])
             v0.append(v1)
             t0.append(t0[i]+h1)
         # solving for y(t)
         for j in range(N+1):
             y1 = y0[j] + (h1/2)*(v0[j] + v0[j+1])
             y0.append(y1)
         y0 = list(np.around(np.array(y0),3))
         v = list(np.around(np.array(v),3))
         print("y(t) = ", y0)
         print("v(t) = ", v)
```

```
print("t =", t)
legends = []
plt.plot(t,v,"--",label="v(t) in Predictor-Corrector", color="r")
plt.plot(t0,y0,"--", label="y(t) in Predictor-Corrector", color="b")
plt.legend(loc="best")
plt.title("v(t) vs y(t) in Predictor-Corrector Method at h=0.2")
plt.show()
```

y(t) = [0.0, 3.796, 7.225, 10.36, 13.26, 15.972, 18.534, 20.975, 23.32, 25.58]8, 27.794, 29.951, 32.069, 34.155, 36.216, 38.257, 40.282, 42.293, 44.295, 4 6.288, 48.274, 50.255, 52.232, 54.206, 56.177, 58.145, 60.112, 62.078, 64.04 2, 66.006, 67.969, 69.931, 71.893, 73.854, 75.815, 77.776, 79.737, 81.698, 8 3.658, 85.618, 87.579, 89.539, 91.499, 93.459, 95.42, 97.38, 99.34, 101.3, 10 3.26, 105.22, 107.18, 109.14] v(t) = [20.0, 18.153, 16.641, 15.402, 14.389, 13.559, 12.879, 12.323, 11.867,11.494, 11.189, 10.939, 10.734, 10.567, 10.43, 10.317, 10.225, 10.15, 10.088, 10.038, 9.997, 9.963, 9.935, 9.912, 9.894, 9.879, 9.866, 9.856, 9.848, 9.841, 9.835, 9.831, 9.827, 9.824, 9.821, 9.819, 9.818, 9.816, 9.815, 9.814, 9.813, 9.813, 9.812, 9.812, 9.812, 9.811, 9.811, 9.811, 9.811, 9.811, 9.81] 0.2 1.2 1.4 1.6 1.8 2. t = [0.0.4 0.6 0.8 1. 2.2 2.4 2.6 4.2 4.4 4.6 4.8 5. 5.2 5.4 2.8 3.2 3.4 3.8 4. 3.6 7.2 7.4 7.6 7.8 8. 7. 5.6 5.8 6. 6.8 6.2 6.4 6.6 8.6 9.6 9.8 10.] 9. 9.2 8.8 9.4

v(t) vs y(t) in Predictor-Corrector Method at h=0.2



When step size, h=0.5

```
In [3]: figure(num=None, figsize=(8, 6), dpi=80, facecolor='w', edgecolor='k')
# Solving for the Predictor-Corrector method at step-size h=0.5

N = 20
h = (b-a)/N
t = np.arange(a, b+h, h)
v = np.zeros((N+1,))
v[0] = va

#using fourth oreder Runge-Kutta to obtain the first 3 points
for i in range(0,N):
```

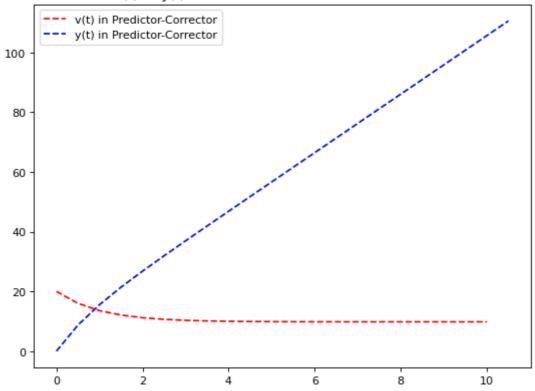
```
k3 = h * f(t[i] + (h/2.0), v[i] + (k2/2.0))
        k4 = h * f(t[i] + h, v[i] + k3)
        v[i + 1] = v[i] + (k1 + 2.0*k2 + 2.0*k3 + k4)/6.0
    else:
        v[i + 1] = v[i] + h*(55.0 * f(t[i], v[i]) - 59.0 * f(t[i-1], v[i-1]) +
        v[i + 1] = v[i] + h*(9.0 * f(t[i+1], v[i + 1]) + 19.0 * f(t[i], v[i])
h1 = 0.5
def g1(v):
    q = 9.8
    return g-v
v0 = [20]
t0 = [0]
v0 = [0]
# solving the v(t) used for y(t)
for i in range(N+1):
    v1 = v0[i] + h1*g1(v0[i])
    v0.append(v1)
    t0.append(t0[i]+h1)
# solving for y(t)
for j in range(N+1):
    y1 = y0[i] + (h1/2)*(v0[i] + v0[i+1])
    y0.append(y1)
y0 = list(np.around(np.array(y0),3))
v = list(np.around(np.array(v),3))
print("y(t) = ", y0)
print("v(t) = ", v)
print("t =", t)
legends = []
plt.plot(t,v,"--",label="v(t) in Predictor-Corrector", color="r")
plt.plot(t0,y0,"--", label="y(t) in Predictor-Corrector", color="b")
plt.legend(loc="best")
plt.title("v(t) vs y(t) in Predictor-Corrector Method at h=0.5")
plt.show()
y(t) = [0.0, 8.725, 15.538, 21.394, 26.772, 31.911, 36.93, 41.89, 46.82, 51.7]
35, 56.643, 61.546, 66.448, 71.349, 76.25, 81.15, 86.05, 90.95, 95.85, 100.7
5, 105.65, 110.55]
v(t) = [20.0, 15.993, 13.562, 12.086, 11.18, 10.635, 10.307, 10.109, 9.99, 9.
918, 9.875, 9.849, 9.834, 9.824, 9.819, 9.815, 9.813, 9.812, 9.811, 9.811, 9.
81]
t = [0. 0.5 1. 1.5 2. 2.5 3. 3.5 4.
                                                   4.5 5.
                                                             5.5 6.
                                                                       6.5
 7. 7.5 8. 8.5 9. 9.5 10.
```

if i **in** range(0,3):

k1 = h * f(t[i],v[i])

k2 = h * f(t[i] + (h/2.0), v[i] + (k1/2.0))

v(t) vs y(t) in Predictor-Corrector Method at h=0.5



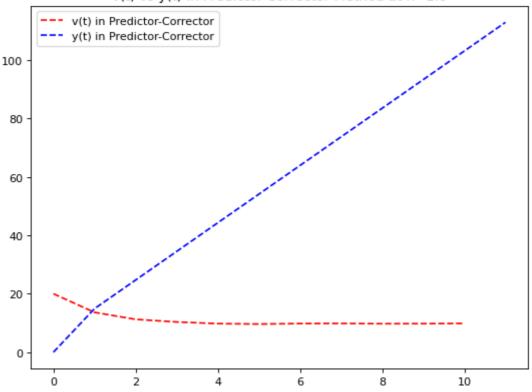
When step size, h=1

```
In [4]:
         figure(num=None, figsize=(8, 6), dpi=80, facecolor='w', edgecolor='k')
         # Solving for the Predictor-Corrector method at step-size h=1.0
         va = 20
         N = 10
         h = (b-a)/N
         t = np.arange(a, b+h, h)
         v = np.zeros((N+1,))
         v[0] = va
          #using fourth oreder Runge-Kutta to obtain the first 3 points
         for i in range(0,N):
             if i in range(0,3):
                 k1 = h * f(t[i],v[i])
                 k2 = h * f(t[i] + (h/2.0), v[i] + (k1/2.0))
                 k3 = h * f(t[i] + (h/2.0), v[i] + (k2/2.0))
                 k4 = h * f(t[i] + h, v[i] + k3)
                 v[i + 1] = v[i] + (k1 + 2.0*k2 + 2.0*k3 + k4)/6.0
             else:
                 v[i + 1] = v[i] + h*(55.0 * f(t[i], v[i]) - 59.0 * f(t[i-1], v[i-1]) +
                 v[i + 1] = v[i] + h*(9.0 * f(t[i+1], v[i + 1]) + 19.0 * f(t[i], v[i])
         h1 = 1.0
         def g1(v):
             g = 9.8
             return g-v
         v0 = [20]
         t0 = [0]
         y0 = [0]
         # solving the v(t) used for y(t)
         for i in range(N+1):
             v1 = v0[i] + h1*g1(v0[i])
```

```
v0.append(v1)
    t0.append(t0[i]+h1)
# solving for y(t)
for j in range(N+1):
    y1 = y0[j] + (h1/2)*(v0[j] + v0[j+1])
    y0.append(y1)
y0 = list(np.around(np.array(y0),3))
v = list(np.around(np.array(v),3))
print("y(t) =", y0)
print("v(t) =", v)
print("t =", t)
legends = []
plt.plot(t,v,"--",label="v(t) in Predictor-Corrector", color="r")
plt.plot(t0,y0,"--", label="y(t) in Predictor-Corrector", color="b")
plt.legend(loc="best")
plt.title("v(t) vs y(t) in Predictor-Corrector Method at h=1.0")
plt.show()
```

```
 y(t) = [0.0, 14.9, 24.7, 34.5, 44.3, 54.1, 63.9, 73.7, 83.5, 93.3, 103.1, 11 \\ 2.9] \\ v(t) = [20.0, 13.631, 11.243, 10.347, 9.777, 9.635, 9.799, 9.834, 9.745, 9.76 \\ 7, 9.841] \\ t = [0. 1. 2. 3. 4. 5. 6. 7. 8. 9. 10.]
```

v(t) vs y(t) in Predictor-Corrector Method at h=1.0



In []: