

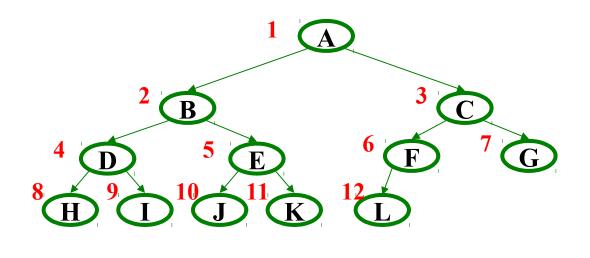
Algorithms & Data Structures I

Lesson 9: Binary Heaps

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Array Representation of Binary Trees



From node i:

left child: i*2

right child: i*2+1

parent: i/2

(wasting index 0 is convenient for the index arithmetic)

implicit (array) implementation:

	A	В	C	D	E	F	G	Н	I	J	K	L	
0	1	2	3	4	5	6	7	8	9	10	11	12	13

Judging the array implementation

Plusses:

- Non-data space: just index 0 and unused space on right
 - In conventional tree representation, one edge per node (except for root), so n-1 wasted space (like linked lists)
 - Array would waste more space if tree were not complete
- Multiplying and dividing by 2 is very fast (shift operations in hardware)
- Last used position is just index size

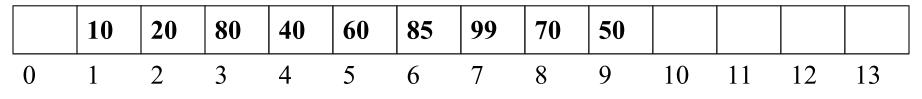
Minuses:

 Same might-be-empty or might-get-full problems we saw with stacks and queues (resize by doubling as necessary)

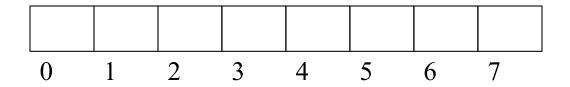
Plusses outweigh minuses: "this is how people do it"

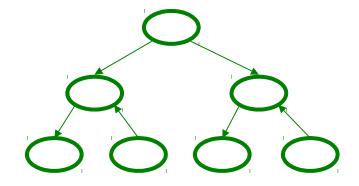
Pseudocode: insert into binary heap

```
void insert(int val) {
  if (size==arr.length-1)
    resize();
  size++;
  i=percolateUp(size,val);
  arr[i] = val;
             10
                   80
         20
           60
                (85)
        50
```



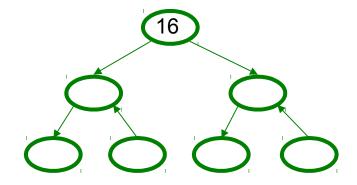
insert: 16, 32, 4, 67, 105, 43, 2





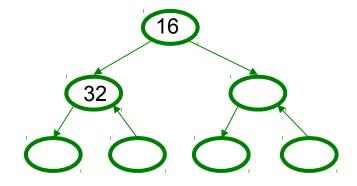
insert: **16**, 32, 4, 67, 105, 43, 2

	16							
0	1	2	3	4	5	6	7	



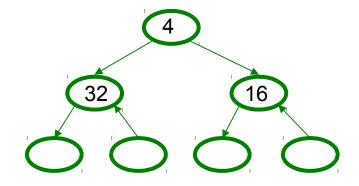
insert: <u>16</u>, <u>32</u>, 4, 67, 105, 43, 2

	16	32					
0	1	2	3	4	5	6	7



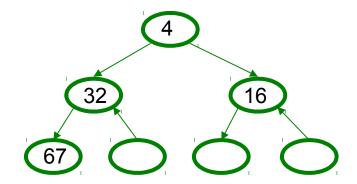
insert: <u>16</u>, <u>32</u>, <u>4</u>, 67, 105, 43, 2

	4	32	16				
0	1	2	3	4	5	6	7



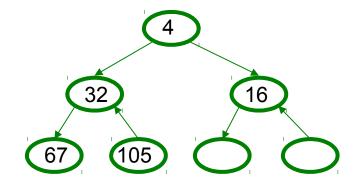
insert: <u>16</u>, <u>32</u>, <u>4</u>, <u>67</u>, 105, 43, 2

	4	32	16	67			
0	1	2	3	4	5	6	7



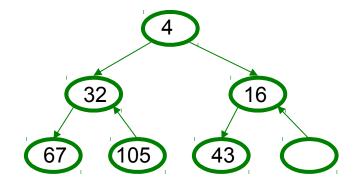
insert: <u>16</u>, <u>32</u>, <u>4</u>, <u>67</u>, <u>105</u>, 43, 2

	4	32	16	67	105		
0	1	2	3	4	5	6	7



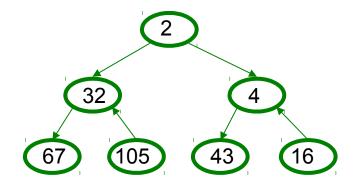
insert: <u>16</u>, <u>32</u>, <u>4</u>, <u>67</u>, <u>105</u>, <u>43</u>, 2

	4	32	16	67	105	43	
0	1	2	3	4	5	6	7



insert: <u>16</u>, <u>32</u>, <u>4</u>, <u>67</u>, <u>105</u>, <u>43</u>, <u>2</u>

	2	32	4	67	105	43	16
0	1	2	3	4	5	6	7



Other operations

- **decreaseKey**: given pointer to object in priority queue (e.g., its array index), lower its priority value by *p*
 - Change priority and percolate up
- increaseKey: given pointer to object in priority queue (e.g., its array index), raise its priority value by p
 - Change priority and percolate down
- remove: given pointer to object in priority queue (e.g., its array index), remove it from the queue
 - decreaseKey with $p = \infty$, then deleteMin

Running time for all these operations?

Build Heap

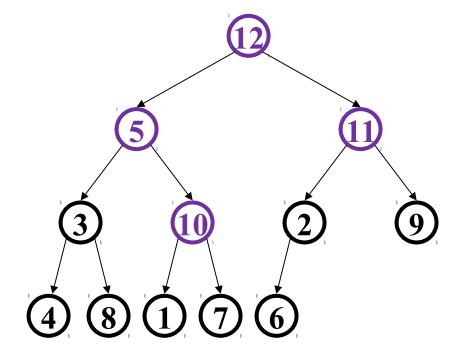
- Suppose you have n items to put in a new (empty) priority queue
 - Call this operation buildHeap
- n inserts works
 - Only choice if ADT doesn't provide buildHeap explicitly
 - $-O(n \log n)$
- Why would an ADT provide this unnecessary operation?
 - Convenience
 - Efficiency: an O(n) algorithm called Floyd's Method
 - Common issue in ADT design: how many specialized operations

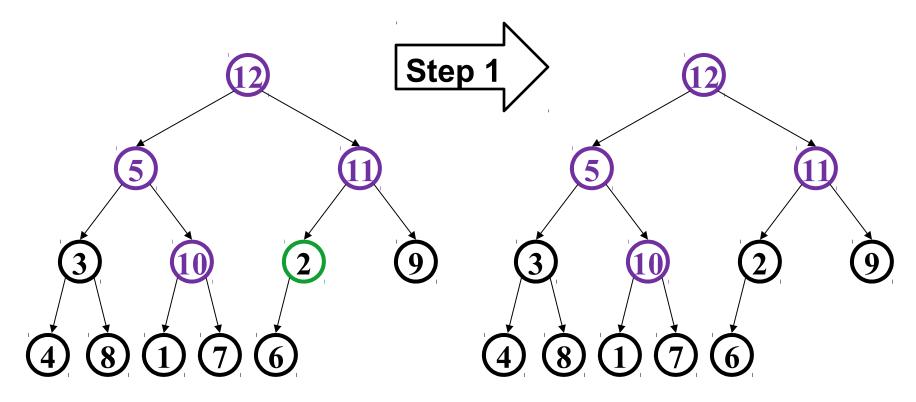
Floyd's Method

- 1. Use *n* items to make any complete tree you want
 - That is, put them in array indices 1,...,n
- 2. Treat it as a heap and fix the heap-order property
 - Bottom-up: leaves are already in heap order, work up toward the root one level at a time

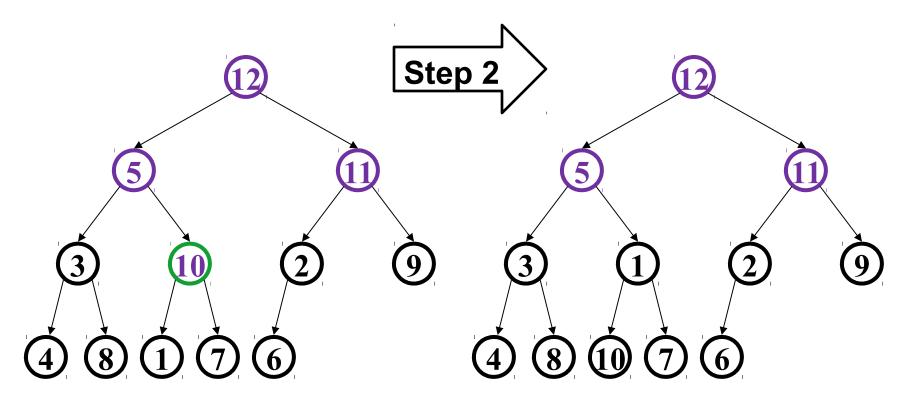
```
void buildHeap() {
  for(i = size/2; i>0; i--) {
    val = arr[i];
    hole = percolateDown(i,val);
    arr[hole] = val;
}
```

- In tree form for readability
 - Purple for node not less than descendants
 - heap-order problem
 - Notice no leaves are purple
 - Check/fix each non-leaf bottom-up (6 steps here)

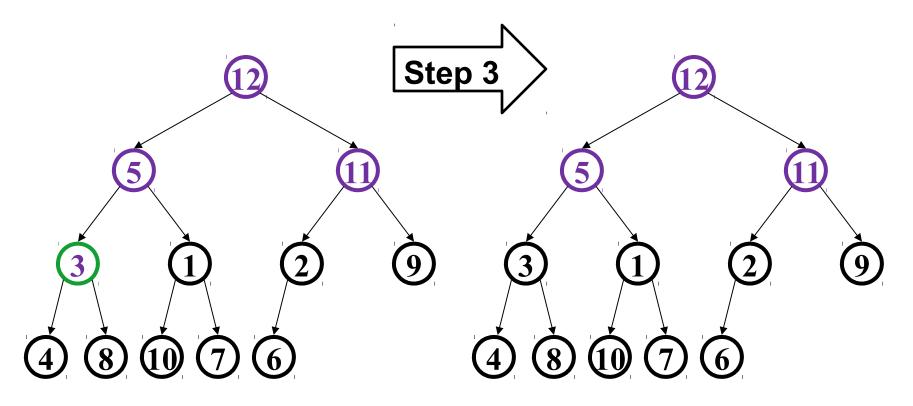




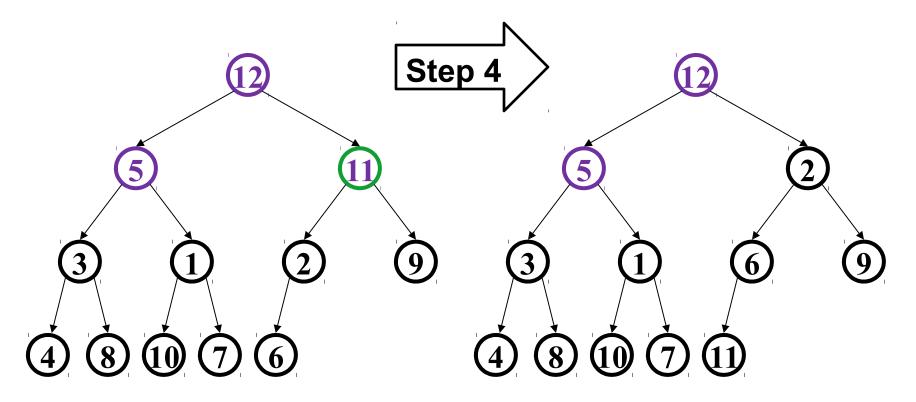
Happens to already be less than children (er, child)



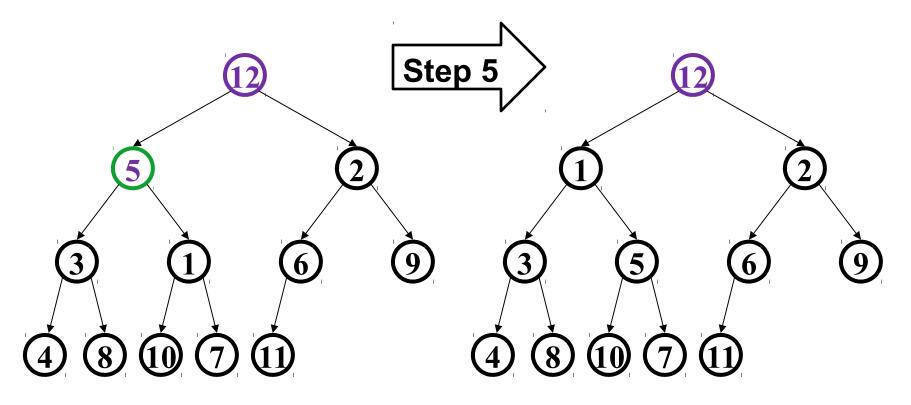
Percolate down (notice that moves 1 up)

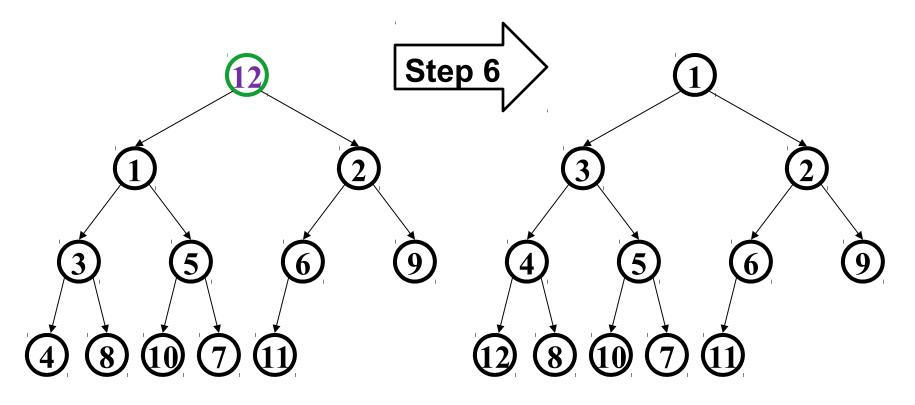


Another nothing-to-do step



Percolate down as necessary (steps 4a and 4b)





But is it right?

- "Seems to work"
 - Let's prove it restores the heap property (correctness)
 - Then let's prove its running time (efficiency)

```
void buildHeap() {
  for(i = size/2; i>0; i--) {
    val = arr[i];
    hole = percolateDown(i,val);
    arr[hole] = val;
}
```

Correctness

```
void buildHeap() {
  for(i = size/2; i>0; i--) {
    val = arr[i];
    hole = percolateDown(i,val);
    arr[hole] = val;
}
```

Loop Invariant: For all j>i, arr[j] is less than its children

- True initially: If j > size/2, then j is a leaf
 - Otherwise its left child would be at position > size
- True after one more iteration: loop body and percolateDown make arr[i] less than children without breaking the property for any descendants

So after the loop finishes, all nodes are less than their children

Efficiency

```
void buildHeap() {
  for(i = size/2; i>0; i--) {
    val = arr[i];
    hole = percolateDown(i,val);
    arr[hole] = val;
  }
}
```

Easy argument: buildHeap is $O(n \log n)$ where n is size

- size/2 loop iterations
- Each iteration does one percolateDown, each is O(log n)

This is correct, but there is a more precise ("tighter") analysis of the algorithm...

Efficiency

```
void buildHeap() {
  for(i = size/2; i>0; i--) {
    val = arr[i];
    hole = percolateDown(i,val);
    arr[hole] = val;
}
```

Better argument: buildHeap is O(n) where n is size

- size/2 total loop iterations: O(n)
- 1/2 the loop iterations percolate at most 1 step
- 1/4 the loop iterations percolate at most 2 steps
- 1/8 the loop iterations percolate at most 3 steps
- ...
- ((1/2) + (2/4) + (3/8) + (4/16) + (5/32) + ...) < 2 (page 4 of Weiss)
 - So at most 2 (size/2) total percolate steps: O(n)

Lessons from buildHeap

- Without buildHeap, our ADT already let clients implement their own in O(n log n) worst case
- By providing a specialized operation internal to the data structure (with access to the internal data), we can do O(n) worst case
 - Intuition: Most data is near a leaf, so better to percolate down
- Can analyze this algorithm for:
 - Correctness:
 - Non-trivial inductive proof using loop invariant
 - Efficiency:
 - First analysis easily proved it was O(n log n)
 - Tighter analysis shows same algorithm is O(n)