Receive other Send other robots' best node. robots' best Interface node through module network Send it to robot

Send current best node Fire holed STRONG OF THE ST

if $\Delta t < \alpha_1$

if $\Delta t < \alpha_2$

Control

module

node **Deployment** Send it to interface module Receive other robots' best node

Compute next best

• Move the robot • Obstacle avoidance

module

- Request new best node