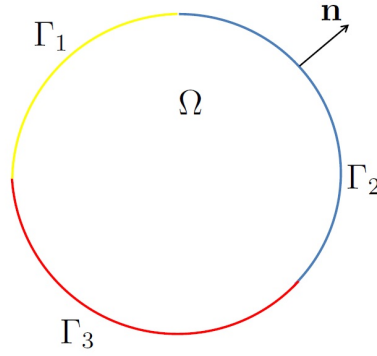


Nonlinear initial-boundary value problem:

$$u_t - \nabla \cdot (a \nabla u) = u^2 + 1, \quad x \in \Omega \quad (1)$$

$$u|_{\Gamma_1} = g, \quad \frac{\partial u}{\partial n} \Big|_{\Gamma_2} = 0, \quad a \frac{\partial u}{\partial n} + b(u - u_b) \Big|_{\Gamma_3} = 0. \quad (2)$$

$$u(x, 0) = u_0. \quad (3)$$



Time discretisation: $t_k = k\tau$, $k = 0, 1, \dots, N$; $u_k = u(k\tau)$.

$$u_k \in H^1(\Omega), \quad v \in H_0^1(\Omega) := \{v \in H^1(\Omega), \quad v|_{\Gamma_1} = 0\},$$

For each time moment ($k = 1, 2, \dots, N$), we use the following iterative procedure:

Step 1.

Initialize the counter: $m = 1$;
 $\tilde{u}_k = 0$.

Step 2.

Solve the problem:

$$(u_k, v) - (u_{k-1}, v) + \tau(a \nabla u_k, \nabla v) + \tau \int_{\Gamma_3} b(u_k - u_b) v d\Gamma = \tau(\tilde{u}_k^2 + 1, v), \quad u|_{\Gamma_1} = g,$$

or

$$(u_k, v) - (u_{k-1}, v) + \tau(a \nabla u_k, \nabla v) + \tau \int_{\Gamma_3} b(u_k - u_b) v d\Gamma = \tau(u_k \tilde{u}_k + 1, v), \quad u|_{\Gamma_1} = g,$$

where \tilde{u}_k is an approximation of the solution at last iteration.

Step 3.

$m = m + 1$;
 if ($m < M$) { $\tilde{u}_k = u_k$; goto step 2 } else {procedure finish}