#### Lecture 2

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#### Administrative

No lecture on the 1st of June!

Homework from 2019-05-11 due now!

# Questions?

## Probability theory

Richard von Mises (1883-1953): The term probability is meaningful for us only with regard to a clearly defined collective (or population).



Sir Harold Jeffreys (1891-1989): [T]here is a valid primitive idea expressing the degree of confidence that we may reasonably have in a proposition.

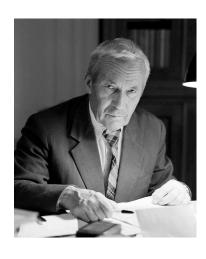


#### Mathematical model

#### A. N. Kolmogorov (1903-1987):

- $\bullet$   $\Omega$ , the set of all possible outcomes
- Event, the set of all events Event  $\subseteq \mathbb{P}(\Omega)$
- p: Event → [0, 1], the probability measure, satisfying

  - for all events X<sub>1</sub>, ..., X<sub>n</sub>, ... pairwise disjoint,
    - $\Sigma p(X_i) = p(\bigcup X_i)$



#### Examples

Drawing a card from a standard deck.

```
• \Omega = \{2 \clubsuit, 2 \spadesuit, 2 \heartsuit, 2 \spadesuit, \ldots\}
• Event = \mathbb{P}(\Omega)
```

2 Choosing a point of the unit disc.

```
 Ω = {(x, y) | x, y ∈ ℝ, x<sup>2</sup> + y<sup>2</sup> ≤ 1}
```

- We would like to have Event =  $\mathbb{P}(\Omega)$  ... but we can't
- We can take Event =  $\{X : \Omega \rightarrow \{0, 1\} \mid X \text{ computable}\}$

# The classical model of probability

```
Ω finite, Event = \mathbb{P}(Ω), and p defined by p(X) = card(X) / card(Ω) Interpretations:
```

#### \_

- Frequentist: every elementary outcome  $\omega \in \Omega$  turns up with approximately the same frequency as any other.
- Bayesian: we have no reason to prefer one elementary outcome over any other.

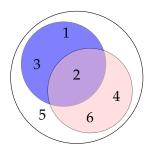
## Example

#### Rolling a die:

- $\Omega = \{1, 2, 3, 4, 5, 6\}, \operatorname{card}(\Omega) = 6$
- rolling an even number: even = {2, 4, 6}, card(even) = 3
- probability of rolling an even number:
   p(even) = card(even)/card(Ω) = 3/6 = 0.5

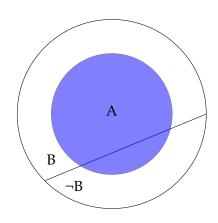
## Operations with events

- union: A ∪ B
- intersection: A n B
- complement:  $\neg A = \Omega A$
- result is even and ≤ 3
- result is even or  $\leq 3$
- result is  $not \le 3$



#### **Exercises**

- Derive the formula for p(A n B).
- Derive the formula for p(A U B)
- Assume that B<sub>1</sub>, ..., B<sub>n</sub> are pairwise disjoint. Show that
- $p(A) = p(A \cap B_1) + \ldots + p(A \cap B_n)$



## Conditional probability

```
Definition: Let (\Omega, \text{ Event}, p) as above, X \in \text{ Event } s.t p(X) \neq 0. Let Y \in \text{ Event}. The conditional probability of Y given X is defined by p(Y \mid X) = p(Y \cap X) / p(X)
```

### Notational problems

- is | a set-theoretical operation?
- is | commutative?
- Kolmogorov's original notation:  $p_X(Y)$

# The law of total probability

```
B_1, ..., B_n pairwise disjoint, p(B_1) \neq 0 for all i. Show that p(A) = p(A \mid B_1) * p(B_1) + ... + p(A \mid B_n) * p(B_n)
```

### Bayesian learning

- Set of hypotheses, H
- Data, d ∈ D
- Find the "best" hypothesis that fits the data
  - e.g., Find-S, "best" = the most specific hypothesis consistent with the data.
- Bayesian learning: "best" = the most probable hypothesis, given the data.

## Maximum a posteriori hypothesis

The aim of Bayesian learning is to determine the **maximum a posteriori (MAP) hypothesis**:

```
h_{map} = argmax_h p(h \mid d)
What does p(h \mid d) mean?
```

## Bayes' theorem

```
X, Y ∈ Event, p(X) * p(Y) \neq 0.

p(X \mid Y) = p (X \cap Y) / p (Y)
    therefore p(X \cap Y) = p(X \mid Y) * p(Y)

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```

## Example

Mitchell, pages 157-158:

- H = {healthy, ill}
- test results: ⊖, ⊕
- 0.008 of the population have the disease.
- patient ill ⇒ test positive in 98% of the cases
- patient healthy ⇒ test positive in 3% of the cases
- A patient's test has come back positive.

What is the MAP hypothesis?

## Translation to probability-speak

- $\Omega$  = the set of people in the population
- Event =  $\mathbb{P}(\Omega)$
- classical model for p:  $p(X) = card(X)/card(\Omega)$
- the events of interest: Healthy, Ill, Pos, Neg
- p(healthy) = 0.992, p(ill) = 0.008, p(⊕ | ill) ) = 0.98, p(⊕ | healthy) = 0.03

Compute p(ill | ⊕).

## Applying Bayes' theorem

```
p(ill \mid \oplus)
= p(\oplus \mid ill) * p(ill) / p(\oplus)
= 0.98 * 0.008 / p(\oplus)
= 0.00784 / p(\oplus)

p(healthy \mid \oplus)
= p(\oplus \mid healthy) * p(healthy) / p(\oplus)
= 0.03 * 0.992 / p(\oplus)
= 0.02976 / p(\oplus)
```

Therefore, the MAP hypothesis is healthy.

## A general argument

```
h_{map} = argmax_h p(h \mid d)
= argmax_h (p(d \mid h) * p(h) / p(d))
= argmax_h (p(d \mid h) * p(h)) -- p(d) is constant w.r.t. h
```

#### Likelihood

If all hypotheses are equally likely:

A hypothesis that maximises the likelihood is a *maximum likelihood hypothesis* (*ML*). Therefore

```
h_{ml} = argmax_h p(d | h)
In general, h_{map} \neq h_{ml}!
```

#### Exercise

What is  $h_m \iota$  in the example above?

#### Homework

Apply Bayes' theorem to answer the following question (Elmer Mode 1966, page 53):

A class in advanced mathematics contains 10 juniors, 30 seniors, and 10 graduate students. Three of the juniors, 10 of the seniors, and 5 of the graduate students received an A in the course. If a student is chosen at random from this class and is found to have earned an A, what is the probability that he is a graduate student?

# Concept learning revisited

```
Concept: c : X \to \{0, 1\} h \in H \to h : X \to \{0, 1\}) We assume c \in H The data: d = \{(x_1, c(x_1)), \dots, (x_m, c(x_m))\}
```

## "Brute-force" Bayesian concept learning

```
given H, p(h)
for every h \in H:
 compute p(h \mid d) = p(d \mid h) * p(h) / p(d)
 return h_{map} = argmax_h p(h \mid d)
```

The problem is computing, for every h,  $p(d \mid h)$ . We also want to compute p(d).

# Computing the likelihood

Assumption: the data is completely correct, and hypotheses are not "noisy" functions.

# Computing p(d | h)

We can now compute p(d) by applying the law of total probability:

$$p(d) = \Sigma_h p(d | h) * p(h)$$

In a certain sense, the data and the hypothesis must have the same nature.

#### Consistent learners

Assume all hypotheses are equally likely. Then the brute-force Bayesian concept learning algorithm will return an ML hypothesis:

```
h_{map} = h_{ml} = argmax_h p(d | h)
```

Since  $p(d \mid h) = 1$  if h is consistent with the data, and  $p(d \mid h) = 0$  otherwise, the algorithm will return any one of the hypotheses in H consistent with d.

#### Bayesian concept learning and Find-S

Find-S returns a consistent hypothesis ⇒ it returns a MAP (and an ML) hypothesis!

Even if p is not constant w.r.t. hypotheses, Find-S can still return a MAP hypothesis, if there is a unique most specific hypothesis consistent with d in H and

```
h_i \subseteq h_j \Rightarrow p(h_i) \geq p(h_j)
```