#### Lecture 4

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DEPARTMENT FOR CONTINUING 08/06 EDUCATION



#### Administrative

- Homework from 25/05/2019 due now!
- Please complete and hand in the declarations of authorship.

# Questions?

### Unsupervised learning

- we have a sequence of data points that fall into k classes
- example:
  - images of cats and dogs
  - images of possibly malfunctioning engines
  - images of handwritten digits
- we want the learning program to determine the k classes by itself

```
• Task = Image -> \{1, 2, ..., k\}
```

• Experience = List(Image)

```
Task = Image -> {1, 2, ..., k}
Experience = List(Image)
perf : (Task, List(Image)) → R
```

```
• Task = Image -> {1, 2, ..., k}
• Experience = List(Image)
• perf : (Task, List(Image)) → ℝ
•

perf(t, [img1, ..., imgn]) = sum [correct(t, img1), ..., corr
• correct : (Task, List(Image)) → {1, 2, ..., k} is
"hypothetical"
```

### Exemplars

The data usually comes in the form of tuples of fixed length (the **features**):

$$X = (X_1, \ldots, X_m) \in (\Omega_1, \ldots, \Omega_m), \Omega_i \subseteq \mathbb{R}$$

We usually assume the classification is based on "ideal" elements:

$$\xi = (\xi_1, \ldots, \xi_m) \in (\Omega_1, \ldots, \Omega_m), \Omega_i \subseteq \mathbb{R}$$

The data is a distortion of the ideal exemplars, e.g.

$$x = (x_1, ..., x_m) = (\xi_1 + \epsilon_1, ..., \xi_m + \epsilon_m)$$

where  $\varepsilon_1$  is a random variable with mean 0.

Thus, if we only had one exemplar, we could reconstruct it by estimating the mean value of the data.

### Expectations

Consider a coin toss experiment:

```
\Omega = \{H, T\}
p: Event \rightarrow [0, 1]
p(H) = \alpha
```

What is the expected value of the result?

### Expectations

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$$h * \alpha + t * (1 - \alpha)$$

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```

• Even if we consider  $\Omega'$ , it is still the case that the expected value is *not* a possible result of the experiment.

#### Random variable

**Definition**: Given  $\Omega$ , Event, p. A random variable is a function  $X : \Omega \to \mathbb{R}$ .

Probability theory and statistics are largely the study of random variables.

### Expected value

```
Definition: Given \Omega, Event, p and a random variable X. Assume that \Omega is finite: \Omega = \{\omega_1, \omega_2, \ldots, \omega_n\}. The mean or expected value of X is E(X) = X(\omega_1) * p(\omega_1) + X(\omega_2) * p(\omega_2) + \ldots + X(\omega_n) * p(\omega_n)
```

Intuition: center of mass.

### Classical statistics versus machine learning

The expected value minimises the guessing error.

This is not always what we want: cf., penalty shots.

#### Exercise

Consider a card game played with a full deck, in which aces have a value of 11, jacks 12, queens 13, kings 14, and all other cards a value of 0. We draw a card at random from the deck. What is its expected value? Define  $\Omega$ , Event, p and the random variable whose expected value you are computing.

#### Standard deviation

```
Definition: Consider \Omega = \{\omega_1, \omega_2, \ldots, \omega_n\}, Event, p, X : \Omega \to \mathbb{R}.
 Let E(X) = \mu The standard deviation of X is 
 std_dev(X) = \sqrt{((X(\omega_1) - \mu)^2 * p(\omega_1) + \ldots (X(\omega_n) - \mu)^2 * p(\omega_n))}
 The variance of X is std_dev(X)^2
```

#### Exercise

Compute the standard deviation of the random variable defined for the card game exercise.

#### Notation

In the following, when no ambiguities arise, we use  $\mu$  to denote E(X) and  $\sigma$  for std\_dev(X)

### Chebyshev's theorem

```
Let \Omega, Event, p and X as above. Let  Far_k = \{ \omega \in \Omega \mid ||X(\omega) - \mu|| > k * \sigma \}  Then p(Far_k) \le 1/k^2.
```

### Interpretation of Chebyshev's theorem

- $\Omega$ , Event, p and X as above. If we draw a random element from  $\Omega$ , then
  - it will fall in the interval [ $\mu$  2 \*  $\sigma$ ,  $\mu$  + 2 \*  $\sigma$ ] with probability at least 0.75
  - it will fall in the interval [ $\mu$  3 \*  $\sigma$ ,  $\mu$  + 3 \*  $\sigma$ ] with probability at least 0.889
  - it will fall in the interval [ $\mu$  4 \*  $\sigma$ ,  $\mu$  + 4 \*  $\sigma$ ] with probability at least 0.938

### Example

The mean price of houses in a certain neighbourhood is 400000 \$, and the standard deviation is 80000 \$. Find the price range in which 75% of the houses will sell. (Bluman, Chapter 3)

*Solution*: From Chebyshev's theorem, we know that at least 75% of the houses are within the interval [ $\mu$  - 2 \*  $\sigma$ ,  $\mu$  + 2 \*  $\sigma$ ]. Therefore, the interval is [240000, 560000].

#### The normal distribution

$$pdf(x) = (1/\sqrt{(2 * \pi * \sigma^2)}) * exp(-(x - \mu)^2/(2 * \sigma^2))$$

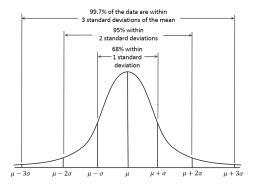


Figure 1: Normal distribution<sup>1</sup>

<sup>&</sup>lt;sup>1</sup>Figure by Dan Kernler - Own work, CC BY-SA 4.0, https://commons.wikimedia.org/w/index.php?curid=36506025

### Example

Consider the neighbourhood from the previous example, where the mean price of houses is 400000 \$, and the standard deviation is 80000 \$. Find the price range in which 75% of the houses will sell, but now assuming that *the prices are normally distributed*.

Solution: We use the Python function scipy.stats.normal.interval:

```
import scipy.stats
scipy.stats.norm.interval(0.75, 400000, 80000)
```

We obtain [307972, 492028]. From Chebyshev's theorem, we had the much larger interval [240000, 560000].

#### The central limit theorem

 $\Omega$ , Event, p and X as above. Consider the following experiment: n elements  $e_1$ , ...,  $e_n$  are drawn independently from  $\Omega$  and we compute the mean value of X for this sample  $\mu_s = (X(e_1) + \ldots + X(e_n))/n$ . Then  $\mu_s$  is a random variable whose probability distribution approaches with increasing n the normal distribution with mean  $\mu$  and standard deviation  $\sigma/\sqrt{n}$ .

#### Homework

The theorem states that  $\mu_s$  is a random variable. But a random variable is a function defined in the context of a probability space. What is that probability space here? You will need to specify

```
\Omega', Event', p' : Event' \rightarrow [0, 1] and define \mu_s : \Omega' \rightarrow \mathbb{R} as a function in terms of in terms of the given Omega, Event, p, and X.
```

### Quality of approximation

- If the random variable X is itself normally distributed, then the approximation in the central limit theorem is good even for small sample sizes n.
- If the random variable X is not normally distributed, the approximation requires larger n. In many practical applications, a value n ≥ 30 will be adequate.

### Example

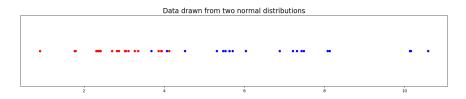
The Nielsen agency reported that children between 2 and 5 watch an average of 25 hours of TV per week. Assuming a normal distribution with  $\sigma=3$  hours. If 20 children are randomly selected, find the probability that the average TV watching time in a week will be  $\mu_{s}>26.3$  hours. (Bluman, Chapter 6)

Solution: The sample average  $\mu_s$  is a random variable that is approximately normally distributed, with mean 25 and standard deviation  $3/\sqrt{(20)}$ . We need to find the probability that the value of  $\mu_s$  is bigger than 26.3. We use the Python function scipy.stats.norm.cdf to find the probability that  $\mu_s$  is smaller or equal to 26.3, and subtract from unity:

```
import scipy.stats
1 - scipy.stats.norm.cdf(26.3, 25, 3/scipy.sqrt(20))
```

We obtain 0.026316151282870237, or approximately 2.6%.

**Example**: Data generated from normal(3, 0.8) (red) and normal(7, 2) (blue).



- 20 dots of each colour
- the **sample** means and standard deviations are 2.8, 0.8 red, 6.97, 2.0 for blue.

What if we do not know which points came from which distribution?



We are looking for  $\mu_1$ ,  $\sigma_1$ ,  $\mu_2$ ,  $\sigma_2$ .

- hypothesis space:  $H = (\mathbb{R}, \mathbb{R}, \mathbb{R}, \mathbb{R})$
- data:  $d = (x_1, ..., x_n)$  drawn from the two probability distributions.

```
We want h<sub>map</sub> ∈ H
```

```
h_{map} = argmax p(h | d)
```

If we have a uniform prior on H, then this is equivalent to  $h_m \iota$ :

```
h_{ml} = argmax p(d | h)
```

```
p(d | h) = p(x_1, ..., x_n | h) = p(x_1 | h) * ... * p(x_n | h)
```

If we know that  $x_1$  has been drawn from distribution j, we can compute

```
p(x_i \mid h) = pdf(x_i, \mu_i, \sigma_i) = (1/\sqrt{(2 * \pi * \sigma_i^2)}) * 
exp(-(x - \mu_i)^2/(2 * \sigma_i^2))
```

#### Introduce the "hidden data":

data: d = ((x<sub>1</sub>, z<sub>11</sub>, z<sub>12</sub>) ..., (x<sub>n</sub>, z<sub>n1</sub>, z<sub>n2</sub>)), where
 z<sub>ij</sub> ∈ {0, 1} is 1, if x<sub>i</sub> has been drawn from distribution j, and 0 otherwise.

The data has become a random variable, hence we cannot maximise  $ln\ p(d\ |\ h)$ . Instead, we maximise

```
E (ln p(d | h))
```

```
E (ln p(x_i, z_{i1}, z_{i2} | h)
=
    E (\ln ((1/\sqrt{(2 * \pi * \sigma_1^2)}) * \exp(-z_{i1} * (x_i - \mu_1)^2/(2 * \sigma_1^2))
                (1/\sqrt{(2 * \pi * \sigma_2^2)}) * \exp(-z_{i2} * (x_i - \mu_2)^2/(2 * \sigma_2^2)))
=
    E (\ln 1/\sqrt{(2 * \pi * \sigma_1^2)} - z_{i1} * (x_i - \mu_1)^2/(2 * \sigma_1^2)) +
         \ln 1/\sqrt{(2 * \pi * \sigma_2^2)} - Z_{i2} * (X_i - \mu_2)^2/(2 * \sigma_2^2))
=
     (\ln 1/\sqrt{(2 * \pi * \sigma_1^2)} + \ln 1/\sqrt{(2 * \pi * \sigma_2^2)} - E(z_{i1} * (x_i - \mu_1))
      \ln 1/\sqrt{(2 * \pi * \sigma_2^2)} - E(z_{i2} * (x_i - \mu_2)^2/(2 * \sigma_2^2))
=
     (\ln 1/\sqrt{(2 * \pi * \sigma_1^2)} + \ln 1/\sqrt{(2 * \pi * \sigma_2^2)} - E(z_{i1}) * (x_i - \mu_1)
      \ln 1/\sqrt{(2 * \pi * \sigma_2^2)} - E(z_{i2}) * (x_i - \mu_2)^2/(2 * \sigma_2^2)
```

Computing  $E(z_{ij})$  given h is easy:

```
E(z_{i1}) = p(x_i | \mu_1, \sigma_1) / (p(x_i | \mu_1, \sigma_1) + p(x_i | \mu_2, \sigma_2))
```

We now assume that  $z_{ij} = E(z_{i1})$ . Therefore, we now have "complete" data and can compute  $h_{m1}$ .

#### EM algorithm

- Pick arbitrary h ∈ H
- Iterate until convergence: 1.1 Compute E(z) 1.2 Use z := E(z) in order to calculate  $h_m \ 1$  1.3. replace h with new  $h_m \ 1$

algorithm is to maximise E (ln p(d | h)) iteratively. We consider an initial h, and then compute the corresponding value of E (ln p(d | h)). This will involve finding out  $E(z_{\perp j})$ . We then assume that the values of the hidden variables are equal to the expected values. This gives us "complete" data, for which we can maximise the log-likelihood (not just the expected log-likelihood). We thus obtain a new h, and we iterate.