

Microeconomics 2 : Game Theory

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Session 1 : Pure strategies

1.1 Definitions and theorems

- Strategy profile : collection of strategies (one for each player) that specifies how each player will act in every situation (s_1, s_2, \dots, s_N) , with N the nb of players
- Strategy space : set that contains all strategies available to the player (regardless of whether they are rational or not)
- Rationalizability : set of rationalizable strategies is $\bigcap_{i=1}^{\infty} S_i^k$
 - strategy is rationalizable if it is a best response to beliefs that are themselves consistent with the rationality of others
 - This concept is weaker than Nash Equilibrium because it does not require beliefs to be correct, only consistent with rationality. It captures strategic reasoning without assuming perfect foresight.
- Best response set $(BR_i(s_{-i}))$ of player i to strat $s_{-i} = \operatorname{argmax}_{s_i \in S_i} u_i(s_i, s_{-i})$
- Correctness of a players belief : A player's belief is correct if he plays by that belief (strategies match beliefs)
- Nash Equilibrium : a strategy profile is a NE of G if $\forall i$ and $\forall s'_i \in S_i$ we have $u_i(s_i^{NE}, S_{-i}^{NE}) \geq u_i(s'_i, S_{-i}^{NE})$
 - formal definition : best response to my opponents best response ! (look for reciprocity of best responses)
 - situation that neither player would wish to deviate from unilaterally (either you both deviate or you don't)

1.2 Methods and Tricks

1.2.1 n°1 : Identifying the strict dominance of a strategy for a given player

- visual method : for player 2 : compare right-hand terms from the column of interest to those in all other columns, if they are strictly superior to all of them (pairwise comparisons) then this strategy is dominant
 - For player 1 : similar approach but reasons in rows and consider the left-hand terms

1.2.2 n°2 : Iterated strict dominance method

- $\forall k \in 1, \dots, N$, define $S_i^{k+1} =$
- $s_i \in S_i^k \mid \nexists s'_i \in S_i^k \text{ with } u_i(s'_i, s_{-i}) > u_i(s_i, s_{-i}) \text{ for all } s_{-i} \in S_{-i}^k$
- a dominant strategy exists if $\bigcap_{i=1}^{\infty} S_i^k$ is a singleton

- in practice :
 - Look at columns : if a column dominates another, eliminate the dominated column
 - Now look at remaining rows (the other player) : if a row dominates another then remove the dominated row
 - go back to square one and repeat the cycle as long as necessary until you can't find a dominated row/column

1.2.3 n°3 : Finding the rationalizable set

- just use the iterated strict dominance method, the set obtained will be the same as the rationalizable set

1.2.4 n°4 : Finding the Nash Equilibrias(classic)

- determine the rationalizable set
- Look at each player separately and write down their best responses to each possible action of the opposite player
- Now find the best responses to the best responses you determined previously → if it is a subset of the rationalizable set then this subset is the set of Nash Equilibrias (IMPORTANT : iterated dominant strategy → Nash equilibria but not reverse)
- non existence of NEs :
 - in pure strategies you conclude there are no Nash equilibria when: For every profile of pure strategies, at least one player can unilaterally switch his or her strategy to improve the payoff. OR There is no pair (or set, in games with more players) of actions such that each player's action is the best response to the other players' actions.

1.2.5 n°5 : Finding Nash Equilibrias with N players in a simultaneous game with cooperation

- Find situations that NO players would wish to deviate from (calculate cost/benefit of deviating individually for each player starting from a given situation → if it results in a loss for both then this is a NE)
- alt : circle Best responses for each line / column → if a strategy is the best response for both players it is a NE

1.2.6 n°6 : Solving Cournot Competition problems

- Define the formula for profits for each player (π_i)

$$ex : \pi_i = P(Q)q_i - cq_i \text{ with } P(Q) \text{ the inverse demand function for aggregate quantities } (1)$$

- Find the best response of player i to p_j (q_j) : Derive the FOC for player i wrt to p_i (or q_i depending on the set up) to maximize π_i as a function of p_j (respectively q_j)

- Do the same with for player j to find $BR(q_i)$ (respectively $BR(p_i)$)
- solving methods :
 - graphically (if 1x1) : by representing the set of best responses for each player \rightarrow the nash equilibrium is the pair (q_i, q_j) where the curves cross each others
 - iterated strict dominance : same as described earlier

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Session 2 : Mixed strategies

2.1 Definitions

- Mixed strategy : present in games in which players randomize over actions. A strategy is then defined by the probability you place on each action, it is a distribution on S_i for player i.

Mathematical definition of a mixed strategy σ_i :

$$u_i(\sigma_i, \sigma_{-i}) = \sum_{s_i, s_{-i}} u_i(s_i, s_{-i}) \sigma_i(s_i) \sigma_{-i}(s_{-i}) \quad (2)$$

s_i is a pure strategy playable by player i ($\in S_i$ the set of pure strategies playable by player 1)

- MSNE : a mixed strategy profile is a MSNE of G if :

$$\forall i, \forall \sigma_i \in \Sigma_i, \quad u_i(\sigma_i^{NE}, \sigma_{-i}^{NE}) \geq u_i(\sigma_i, \sigma_{-i}^{NE}) \quad (3)$$

- A MSNE exists when :
 1. a player cannot unilaterally deviate to increase his expected utility (for instance, can't assigne positive probabilities to another pure strategy, or cannot change the probabilities assigned to the strategies considered)
 2. player i must be indifferent between every pure strategy s_i played with strictly positive probabilities in σ_i (otherwise he would go for a degenerate lottery in favor of the most favorable strategies)

$$u_i(s_i, \sigma_{-i}^{NE}) = u_i(s'_i, \sigma_{-i}^{NE}) \quad (4)$$

2.2 Properties

- existence of a NE : in a game with a finite nb of players and actions there will always exist a NE

2.3 Methods

2.3.1 Solving for mixed NEs

- step 1 : assign probabilities to each option for each player (be mindful of which option you ascribe positive probabilities to)
- step 2 : compute expected payoffs for each options with a positive probability for each player
- step 3 : use the indifference condition to find equilibrium probabilities
- **WARNING** : when a question asks you to find all the mixed strategy NE, you should include the pure strategy NE in your answer as a pure strategy is nothing but a special case of mixed strategy.

2.3.2 Lotteries and payoffs

- if you know the payoff for a strategy is equivalent to the expected payoff of a given lottery, you can compute this expected payoff and assume it is the payoff of the strategy in question

2.3.3 Reducing the number of strategies with positive probabilities

- SEE WITH JUAN

3

Session 3 : sequential games

3.1 Definitions

- pure strategy (for a given player i) : $s_i : H_i \rightarrow A_i | s_i(x) \in A(x)$ for each $x \in H_i$
 - H_i : set of nodes at which player i moves
 - $A(x)$: set of playable strategies for player i when faced with decision node x
 - $s_i(x)$: strategy played by player i at node x
- non credible threats: a threat that can be considered as not rationally enforceable as it would result in a loss of utility for the one carrying out the punishment
- subgame : for G an extensive form games with nodes in set X , a subgame G' of G is a subset $Y \subset X$ with a single **non-terminal** node $x \in X$ and all its successors. It includes :
 1. A single non-terminal node x in X . This is a node where decisions are still made, not a final outcome.
 2. A subset Y that includes this node x and all its successors. "Successors" here means every node that can be reached from x following the paths of the game (including subsequent decision nodes, chance nodes, and terminal nodes).
- subgame perfect Nash equilibrium :

- goal : eliminate non-credible threats
- A strategy profile is subgame perfect if it induces a Nash equilibrium in every subgame
- one-stage deviation principle : s_i is SP if $\forall i, t, a_i U(s_i) \geq U(s_{-i}, a'_i)$ with $a_i \in A_i(t)$ any alternative action that can be taken at any period t by player i
 - * check for potential deviations at every single stage

3.2 Methods and tricks

3.2.1 Finding the subgame perfect equilibria using backwards induction

- start from the end (nodes right before the terminal nodes)
- determine the optimal choice of the player playing last
- based on this optimal choice, find the optimal of the player playing at the previous node \rightarrow keep doing that until you find the only viable pure strategies that are left

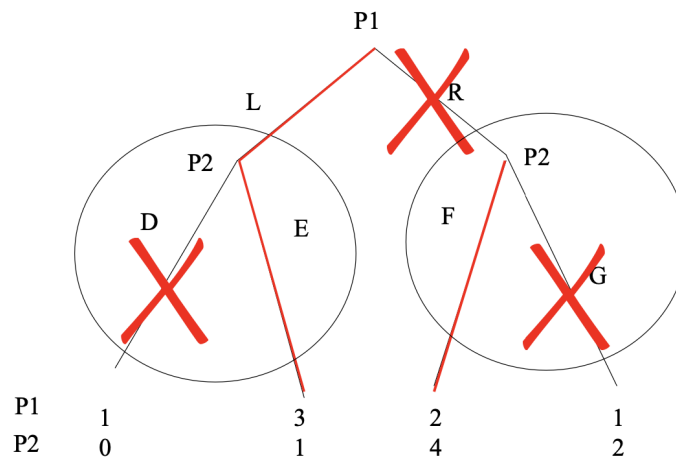


Figure 1: Example of a subgame perfect NE

3.2.2 Stackelberg Quantity competition

- Set-up : firm 1 chooses q_1 to optimize its profits. Then firm 2 chooses q_2 based on the chosen q_1 to optimize its profits.
- Characteristics :
 - non-credible threat from player 2 of playing q_2 such that neither player get any profit

- multiple equilibriums possible
- how to solve ?
 1. compute best response quantity $BR(q_1) = q_2^*$ assuming q_1 known
 2. compute optimal quantity for player 1 as a function of $BR(q_1)$

3.2.3 Preemptive action - entry deterrence game

- Introduce a new choice ahead of the existing choice to change the the subgame perfect NE (and thus the terminal outcome)
- Solving the entry deterrence game :
 1. Follow the same steps as with the classic Stackelberg quantity competition game
 2. Express q_1^* as a function of f (entry tax) and replace it in the profit function
 3. Maximize π_1 with respect to f to find optimal entry tax that player 1 should implement

3.2.4 Rubinstein bargaining model

- use the one stage deviation principle to find the unique SPNE
- only need to check existence of a profitable deviation when :
 1. player 1 makes an offer (consider deviation when player 2 refuses the offer) \rightarrow shows payoff is at most as good as the one she would have accepted without deviating
 2. player 2 makes an offer (same principle but with player 1)

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Session 4 : repeated games

4.1 Definitions

- stage game : game that is repeated
- correlated equilibrium :
- set of feasible payoff vectors (**blue line**) : a payoff vector v is feasible if there exist action profiles (a_1, \dots) and non negative weights λ_1, \dots with $\sum \lambda_k = 1$ such $\forall i, v_i = \sum \lambda_k u_i(a_k)$
 - in other words : Feasible payoff vectors represent outcomes that are possible or can be "realized" by appropriately randomizing over the available action profiles (set of outcomes players might be able to enforce or agree upon)
- set of strictly individually rational payoff vectors (**red line**) : a payoff vector v is S.I.R if $\forall i, v_i > \min_{\sigma_{-i} \in \Sigma_{-i}} [\max_{\sigma_i \in \Sigma_i} u_i(\sigma_i, \sigma_{-i})] = \underline{v}_i$

- in other words : A payoff vector v is strictly individually rational if each player's payoff is strictly greater than their min-max payoff.
- min-max payoff : The min-max payoff for a player is the minimum payoff they can guarantee themselves regardless of what other players do. (worst punishment player i 's opponents can coordinate on imposing)

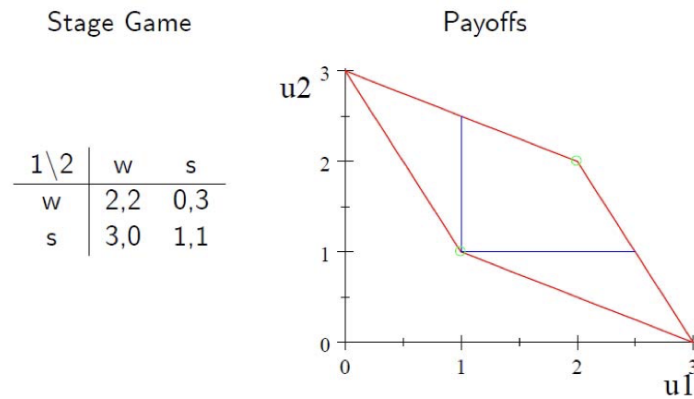


Figure 2: Example of game with payoff sets

- critical discount factor: The critical discount factor for player i is the lowest value of δ_i such that when $\delta_i \geq \underline{\delta}_i$, the strategy profile that yields payoff v_i for player i is NE. In other words, if players value future payoffs at least as much as this threshold value, the threat of future punishment (or loss of cooperative gains) is sufficient to deter unilateral deviation, making the equilibrium sustainable.

4.2 Repeated Finite game

4.2.1 Properties

- Proposition : if a stage game has a unique NE, then players will play the NE strategy of the stage game in every period !

4.2.2 Solving method

- solving method : use backwards induction
- n°1 : if a stage game has a unique NE, then unique SPNE in a finite repetition is such that players play the NE strategy of the stage game in every period
 1. Knowing that every player will play the stage game's NE in the last period, the same logic applies in the second-to-last period because any deviation is not rewarded in the final period. This logic is applied period by period backward to the first period.

4.3 Repeated Infinite game

4.3.1 Properties

- For a single Strategy, there are many possible SPNE (play C:C at every period, D:D etc..)
- Whenever we find a condition under which a set of strategies forms a SPNE of an infinitely repeated game it is always going to be of the type : $\delta \geq \bar{\delta}$
 - Why ? : player care about the future and fear punishments following a deviation
 - implication : anything can be an equilibrium if δ high enough
 - limit : Folk's theorem
- Folk theorem : G a simultaneous move game, A_1, A_2, \dots, A_I the action sets, u_1, u_2, \dots the payoff functions
 - Version 1 : for any feasible S.I.R payoff vector v , $\exists \delta < 1 | \forall \delta \geq \underline{\delta}, \exists \sigma^*$ a NE of $G(\delta)$ with payoff v

Proof

1. take a game where each player i adopts the following strategy : keep cooperating (play a_i) if 1) everyone cooperated so far, 2) more than one player deviated before (in other words, if a player deviates alone he will be punished)
2. normalize payoff by $(1 - \delta_i)$ to get rid of infinite sums
3. the payoff resulting from deviation is :

$$NPV(deviation) = \underbrace{(1 - \delta_i) \max_{a_i} g_i(a'_i, a_{-i})}_{\text{payoff from deviation}} + \underbrace{\delta_i v_i}_{NPV(post-punishment)} \quad (5)$$

4. find the critical discount factor δ_i by solving : $NPV(deviation) = v_i$

- version 2 : Let α^* be a static equilibrium of stage game with payoff e , then $\forall v \in V$ with $v_i > e_i$, for all players i , $\exists \underline{\delta} < 1 | \forall \delta \geq \underline{\delta}, \exists$ a SPNE of $G(\delta)$ with payoff v .

1.

4.3.2 Check if a strategy is SPNE in a repeated infinite game

- decide on the equilibrium you are considering
- define the overall strategy that both players will be following throughout the whole game (grim trigger, tit for tat..)
- consider all possible subgames/configurations (for instance : one player played C before, no player ever played C before...)

- for each of these configuration compare the expected payoff of deviating at this round (and this round only : one stage deviation) to that of not deviating.
- check if there exists conditions on delta such that the strategy you adopted is NE every subgame (never profitable to deviate from that strategy)

4.3.3 Grim-trigger strategy

- if someone deviates from the agreement, it triggers a common punishment forever (classic perception of the prisoner's game in infinite time)
- limit : works only if players care enough for the future (δ high enough)

4.3.4 Price Collusion game

- set up :
 1. $N \geq 2$ firms, with the same constant marginal cost c , choose prices at each stage
 2. profits of a firm : $\pi(p) = (p - c)Q(p)$
 3. customer buy only from least expensive firm (split equally if ties)
- result : unique NE is to price at marginal cost, however there is a SPNE in which firms all price at the monopoly price (depends on value of δ)

Proof

Nash equilibrium strategies (similar to GTS here):

1. choose $p = p_m$ if everyone chose p_m before
2. choose $p = c$ if anyone deviated before

if $\delta \geq \frac{n-1}{n}$ firms won't wish to deviate from cooperation if they cooperated before

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Session 5 : Incomplete information - Introduction

5.1 Concepts & Definitions

- Characteristic of an incomplete information game G with I players :
 1. set of possible player types (Θ): the type of a player is drawn randomly at the beginning of the game and the distribution of types is known to both players but not the realized type (except their own).
 2. set of possible strategies (S_1, \dots, S_I)
 - a Strategy is the association of a type and an action (see below : Bayesian pure strategy)

3. Prior distribution : Joint probability distribution over types $p(\theta_1, \dots, \theta_I)$ reflecting uncertainty about private information before signal is received
 Posterior distribution : players update their beliefs on other player's types given their own types (which they know about) : $p(\theta_{-i}|\theta_i)$
 4. payoff function u_i : gives the payoff for a given player i on a given type, $S \times \Theta \rightarrow \mathbb{R}$ ¹
- Bayesian pure strategy set (S^{Θ_i}) : for a player i , a Bayesian pure strategy is a function that associates a strategy to each type $f_i : \Theta_i \mapsto S_i$.
 - Bayesian strategy profile (bsp) contains the Bayesian pure strategies played by each player (f_1, \dots, f_I)
 - Bayesian NE : A Bayesian strategy profile is BNE if it is the best response bsp to the bsp of the other players (see mathematical expression below)
- $$\forall i, \theta_i, s_i, \sum_{\theta_{-i} \in \Theta_{-i}} u_i(f_i(\theta_i), f_{-i}(\theta_{-i}), \theta_i, \theta_{-i})p(\theta_{-i}|\theta_i) \geq \sum_{\theta_{-i} \in \Theta_{-i}} u_i(s_i, f_{-i}(\theta_{-i}), \theta_i, \theta_{-i})p(\theta_{-i}|\theta_i) \quad (6)$$
- game with private values : the realization of your type is the only one influencing your payoffs (the type of the other players does not impact your payoffs)

5.2 Methods

5.2.1 Classic public good game

- set up :
 1. Cost faced by each player depends on their realized type. Both players face the same set of types.
 2. type for each player is drawn from the same uniform distribution on \underline{c}, \bar{c} , known by both players.
- solving method : Show a strategy profile is a BNE
 1. step 1 : describe the strategy profile that you wish to test
 - example (call/don't call game): P1 plays don't, P2 plays don't if cost is high and call if cost is low
 2. step 2 : write down the payoff matrix with the cost of one player being probabilistically determined (for instance $c \sim Ber(p)$)
 3. step 3 (perspective of P2) : we fix the strategy of P1 (assume he plays his NE strategy regardless of P2) and show P2 will want to play his NE strategy as well (easily verified)
 4. step 4 (perspective of P1) : Now we fix the strategy of P2 and look at P1's best response depending on his belief about the information of P2. To do this, we compute the expected payoff of P1 for each of his possible actions depending on the type distribution for P_2 (can take type θ_1 or θ_2) :

$$E_{P_1}(call) = p(\theta_1)u_{1,\theta_1}(call) + p(\theta_2)u_{1,\theta_2}(call) \quad (7)$$

¹note that the type of the other player may also influence payoffs !

5. step 5 : if the strategy of player 1 we fixed before is indeed $BR(S_{P_2})$ (highest expected payoff) then this strategy is NE !
- NOTE : there might be several BNE for the same game (for the example game, P_1 call and P_2 never call works too)
 - identifying the uniqueness of a BNE (if it is valid) : similar mechanism
 1. let's take the same game as before but lower the cost for P_1
 2. you can then show that the second BNE mentioned above wins everytime by looking at : payoff of P_2 under each type \rightarrow expected payoffs of $P_1 \rightarrow$ payoffs of P_2 given P_1 plays optimally

5.2.2 Public good game with private information

- similar as the classic public good game except the cost for each player is determined probabilistically (uniform distribution on $[0,2]$), not just for player 2.
- example of BNE strategy $f_i(c_i)$ for player i (given all players play a similar strat) : don't call if $c_i > c_i^*$ | call if $c_i \leq c_i^*$ with starred values being cutoff costs for each player
- Determining cutoff values :
 1. step 1 : assume P_1 faces exactly his cutoff cost, c_1^* , and that he is indifferent between either action
 2. step 2 : compute the expected payoffs for both actions (call/don't) for P_1 depending on the probability of P_2 playing call/don't (which depends on his own cutoff cost c_2^*)
 3. step 3 : equate expected payoffs to get an equation linking c_1^* to c_2^* then follow the exact same steps for P_2 and get the other equation to form a system and solve for each player's cutoff cost.
- NOTE : this is not a MSE !

6

Session 6 : Incomplete information - Auction games

Why do we use auctions :

- alternative to fixed prices and bargaining
- used to sell or buy items with uncertain demand (supply) : companies, electricity transmission rights, art...

6.1 Types of auction

- Ascending price auction : bids starts low and increase as participants call out higher bids until no one is willing to bid further. Highest bid wins and constitutes the price paid by the winner.
- Dutch Auction : bids starts high and goes down as participants call out lower bids. Winner is the one proposing the lowest price and ays that price.
- Sealed Bid first price auction : All bidders submit their bids privately without knowing each others' bids. Highest bidder wins and pays the amount he bid.
- Sealed second price auction : all bidders submit their bids privately. Highest bidder wins byt pays the amount of the second highest bid.

6.2 Types of bidders valuation

- Private values : value of object differs across bidders and valuation does not depend on others' valuation
- Common value : value of object is the same to all bidders. Each bidder has his/her own estimate of the true value.

6.3 Useful theorems

- revenue equivalence theorem : all four auction lead to same revenue for **designer** (the one selling the object here) if bidders are risk neutral and valuations are i.i.d.

6.4 Classic frameworks & Methods

6.4.1 Sealed Bid first price

- class : simultaneous, incomplete info game
- information : each knows his own valuation v_i and knows all bidders follow a uniform distribution on support $[0, 1]$ for their own valuation.
- payoff :

$$u_i(b_i, b_{-i}) = \begin{cases} v_i - b_i & \text{if wins} \\ \frac{1}{2}(v_i - b_i) & \text{if } b_i = b_{-i} \\ 0 & \text{if loses} \end{cases} \quad (8)$$

- BNE : $f_i(v_i) = v_i/2$

Proof

1. problem solved by P_1

$$\max_{b_1} (v_1 - b_1) P(f_2(v_2) < b_1) = \max_{b_1} (v_1 - b_1) P(v_2 < f_2^{-1}(b_1)) \quad (9)$$

2. step 1 : compute the expected payoff for player 1 depending on the valuation of player v_2 and its strategy profile f_2 (with $f_2 \sim U[0, \frac{1}{2}]$) which determines the bid P_2 will place.

$$\underbrace{E[u_1(b_1, f_2, v_1, v_2)]}_{\text{expected payoff } P_1} = \underbrace{(v_1 - b_1)}_{\text{payoff if win}} P(f_2(v_2) < b_1) = (v_1 - b_1) 2b_1 \quad (10)$$

3. step 2 : maximize with respect to b_1 to get the optimal bid for P_1 . We get the optimal value we hypothethized before.

Symmetric case equilibrium : $f_1 = f_2$, even easier to solve, you just take the objective function, derive it wrt f_1 , then replace $b_1 = f_1(v_1)$ in the FOC.

6.4.2 Sealed Bid second price

- class : simultaneous, incomplete info game
- information : each knows his own valuation v_i and knows all bidders follow a common distribution F on support $[0, \bar{v}]$ for their own valuation.
- payoff : with j the second highest bidder

$$u_i = \begin{cases} v_i - b_i & \text{if wins} \\ 0 & \text{if loses} \end{cases} \quad (11)$$

- optimal strategy : bid exactly your valuation v_i

Proof

1. Case 1 : bid more than v_i

- would have won by playing v_i : no change
- would not have won \implies win : you win but your payoff is $v_i - b_i$ with $b_i > v_i$ so you get a negative payoff !
- would not have won \implies lose : no difference

2. Case 2 : bid less than v_i

- would have won \implies lose : worse off as you lose a potential positive payoff
- would have lost : no change

Session 7 : Incomplete information - Bayesian Games

7.1 Concepts

- information sets (at which player i moves) : $h(x)$ the set of nodes that are possible given what player i knows, X set of all possible nodes, $i(x)$ the player who moves at x (maps a node to the player supposed to make a decision at that node). We denote A_i the set of actions available to i at any of his info sets.
 - collection of nodes that the player cannot distinguish between based on his or her info when making the decision
 - when making the decision, player i knows he is somewhere in set $h(x)$ and needs to make a decision.
 - H_i represents the set of all information sets for player i

$$H_i = \left\{ S \subset X : S = h(x), x \in X, \underbrace{i(x) = i}_{\text{sets where player } i \text{ moves}} \right\} \quad (12)$$

- Pure strategy : function $s_i : H_i \mapsto A_i$ such that $s_i(h) \in A_i(h)$ for each $h \in H_i$
 - $s_i(h)$ mapping that assigns to each info set h in H_i an action $s_i(h)$ in A_i
 - the pure strategy s_i tell players i what to do in every situation where they may have to make a decision (no randomness involved here) \implies player i commits to a decision rule !
- Assessment (σ_i, μ_i) : comprises a strategy σ_i and belief function μ_i (about which node they are at), which, for each info set h_i , assigns a probability distribution over the nodes with h_i
- Profile of assessments (σ, μ) is a perfect bayesian equilibrium if :
 - $\forall i, \forall h \in H_i, \sigma_i$ maximizes i 's expected payoff conditional on having reached h and given μ_i, σ_{-i}
 - Beliefs μ_i are updated using Bayes' rule whenever it applies
- Bayes formula : $P(\theta_1|A) = \frac{P(A|\theta_1)P(\theta_1)}{P(A|\theta_1)P(\theta_1) + P(A|\theta_2)P(\theta_2)}$

7.2 Main frameworks

7.2.1 Cournot game with incomplete information

Set-up :

- Inverse demand function given by $P(Q)$
- Firm A has deterministic marginal cost C , while the other firm can have C_L or C_H with probability $1 - \theta$

- Both players choose a nonnegative quantity to produce (Player 2 won't produce the same depending on the MC it is facing)
- Strategy profile : q_1, q_L, q_H

Method : Solving for the BNE To solve this game, we compute the best responses functions and find their intersection accounting for the fact that the best response of player 1 faces uncertainty (expected value)

$$\begin{aligned} q_1^* &= \operatorname{argmax}_{q_1 \geq 0} [\theta(P(q_1 + q_L^*) - C)q_1 + (1 - \theta)(P(q_1 + q_H^*) - C)q_1] \\ q_L^* &= \operatorname{argmax}_{q_L \geq 0} [(P(q_1^* + q_L) - C_L)q_L]^2 \end{aligned} \quad (13)$$

3

7.2.2 A Reputation model : barriers to entry

Set-up

- Long run player (P1) plays against a series of short run players (P2) which observe what happened in the past
- under complete info P2 enters and P1 accommodates.
- P1 has a non null probability q of being crazy and fighting in every period
- The uninformed party (P2) plays first !

Checking for Perfect Bayesian Nash Equilibria We start by determining a condition on q under which P2 is better not entering (OUT) \Rightarrow cutoff : if q is high enough then P2 won't want to risk a fight **case 1** : $q > 1/2$

- Step 1 (game played twice) : describe the strategy followed by each player (P1 normal, P1 crazy, P2) in each period (1 and 2) in the case where $q > 1/2$
 - in the case where q is low enough for P2 to consider entering in period 1 : P1 picks its probability to fight in period 1 so as to make P2 indifferent between entering and staying out in period 2 if entry occurs in period 1.
- Step 2 : Check for potential profitable deviations off the equilibrium path (does either of the player have an incentive to deviate from the proposed strategy) \Rightarrow compute expected profit of deviation and see if there is a possible improvement

case 1 : $q < 1/2$ More complex as player 1 will want to mix in the first period to influence the belief of Player 2 about his type. Player 2 will also mix in response.

- Step 1 : as before, determine the strategy that will be played by each player and that you want to check for. This includes describing the probability that P1 will choose to fight in period 1.

³same structure for q_H

- Step 2 (first period) : show that a strategy that does not involve mixing in the first round (either always fight or always accomodate) always has a positive profitable deviation (meaning it cannot be a PBE)
- Step 3 (second period) :
 - show P1 and P2 won't want to deviate from their equilibrium strategies for period 2 if P1 accomodated in period 1.
 - show P2 will fight with a certain probability if he saw fight in period 1. To do this, use bayes rule to find $P(Crazy|a_1 = F)$ knowing the equilibrium probability of P1 to fight in period 1. \Rightarrow find P2 is indifferent between IN and OUT
- Step 4 (first period) : show the P1 indeed mixes as well in the first period by writing down the expected utility of P1 given P2 mixing.
- step 5 : determine the expected payoff of entering in the first period for P2 and find the cutoff value for its mixing strategy. (need to consider mixing in both periods when computing it)

7.2.3 Poker game

- P1 draws a card that is known to him only and decides whether to raise or not. Then P2 chooses to fold or call. We note β the probability P1 has to bluff ($P(raise|king)$), and γ the probability P2 calls when sees raise
- step 1 (P1) : compute the expected payoff from raising/folding for P1 when he has a king and equate them to find γ .
- step 2 (P2) : determine the conditional probability that P1 raised conditional on having an ace as a function of β
- step 2 (P2) : now that we have the conditional probability, we equate the expected payoffs of P2 folding vs raising to find β .

8

Session 8 : Incomplete information - Signaling Games

8.1 Definition

- PBE in a signalling game : strategy profile $s_1(\theta), s_2(a_1)$ with beliefs $\mu(\theta|a_1)$ such that :

1. P1's strategy is optimal given P2's strategy : $s_1(\theta)$ solves :

$$\max_{a_1 \in A_1} u_1(a_1, a_2, \theta), \forall \theta \in \Theta \quad (14)$$

2. P2's beliefs are compatible with Baye's rule i.e if some type of P1 plays a_1 with positive probability then : (otherwise $\mu(\theta|a_1)$ is arbitrary

$$\mu(\theta|a_1) = \frac{P(s_1(\theta) = a_1)P(\theta)}{\sum_{\theta \in \Theta} P(s_1(\theta') = a_1)P(\theta')} \quad (15)$$

3. P2's strategy is optimal given his beliefs and given player one's action : $s_2(a_1)$ solves

$$\max_{a_2 \in A_2} \sum u_2(a_1, a_2, \theta) \mu(\theta|a_1), \forall a_1 \in A_1 \quad (16)$$

- types of equilibria:

1. Separating : each type of player uses an action that is different from the one taken by other types. P2 perfectly learns the type in equilibrium, $\forall \theta \in \Theta, \exists! \theta' c, \mu(\theta'|a_1) = 1$ all others are equal to 0 for a_1 .
2. Pooling equilibria : all types choose the same, no information on types is revealed
3. Semi-separating : some actions are chosen by several types, others are taken by a single type

8.2 The job-market signalling game : Spence's Game

8.2.1 Set-Up

- Nature draws a type θ for the informed player, based on a given probability distribution that is known by both players.
- P1 is a worker, P2 an employer. P1's type is his ability and his level of education is the signal. P2 chooses the wage.
- each worker's ability is given by $\theta = (\theta_L, \theta_H)$
- the worker is informed about his type and the labor market assigns probability λ to him having type θ_H . We note $\mu(e) = P(\theta_H|e)$
- course of play :
 1. nature picks types of worker
 2. worker picks education level (with cost $c(e, \theta)$ increasing in e , submodular in e, θ)

$$\text{solves : } \max_e w(e) - c(e, \theta) \quad (17)$$

3. firm chooses wage offered

$$w(e) = \mu(e)\theta_H + (1 - \mu(e))\theta_L \quad (18)$$

- due to submodularity of the cost function, we have a single crossing property for worker's indifference curves (depending on type) : we have a flatter utility curve for high productivity workers and $u(e, w) = U$
- $w(e)$ and $\mu(e)$ come from the worker's choice on the equilibrium path (otherwise, for levels of education that are not chosen in eq, the beliefs can be anywhere between θ_L, θ_H)

8.2.2 Solving for PBE : Separating Equilibria

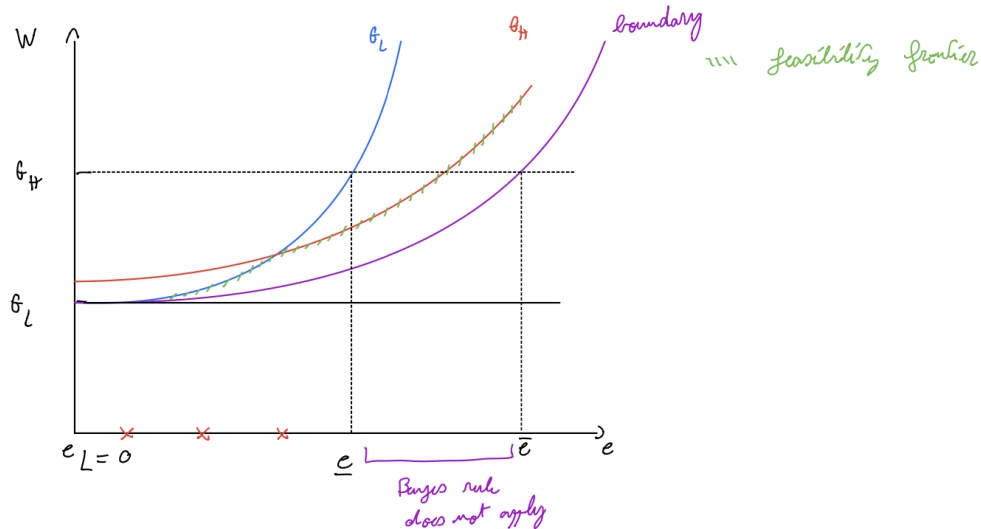


Figure 3: Representation of the separating Equilibrium Case

Assume $e(\theta_H) \neq e(\theta_L)$

- Step 1 - prove $e(\theta_L) = 0$: imagine $e(\theta_L) > 0$, then if low worker picks $e(\theta_L) = 0$ the firm will now assign a non negative probability of him being high types so the proposed wage will be at least as high as θ_L while reducing the cost (pure improvement).

$$\theta_L - c(0, \theta_L) \geq \underbrace{\theta_H - c(e(\theta_H), \theta_L)}_{\text{utility if choose the same } e \text{ as } \theta_H} \quad (19)$$

- Step 2 - finding $e(\theta_H)$: we can easily establish the $e(\theta_H)$ will be above 0 (otherwise they would get θ_L).

$$\theta_H - c(e(\theta_H), \theta_H) > \theta_L - c(0, \theta_H) \quad (20)$$

- Step 3 : we now need to consider the case where a worker might wish to pick $e \notin [e(\theta_L), e(\theta_H)]$. To do this we must pick $\mu(e)$ low enough to have : (we could fix $\mu(e) = 0$ arbitrarily for instance)

$$\begin{aligned} \theta_H - c(e(\theta_H), \theta_H) &\geq w(e) - c(e, \theta_H) \\ \theta_L - c(0, \theta_L) &\geq w(e) - c(e, \theta_L) \end{aligned} \quad (21)$$

- Step 4 - additional conditions on $(e(\theta_H))$:

1. notice that if θ_L workers are indifferent between "no education | low wage" and (High education | high wage" then θ_H ones will strictly prefer having "High education | High wage" since they have a lesser cost of education due to the single crossing property.

$$\theta_L - c(0, \theta_L) = \theta_H - c(\underline{e}, \theta_L) \quad (22)$$

2. Similarly, if θ_H workers are indifferent between the two options, the inequality for θ_L workers will hold strictly (will always prefer not paying for education and getting θ_L)⁴

$$\theta_H - c(\bar{e}, \theta_H) = \theta_L - c(0, \theta_H) \quad (23)$$

Why Bayes rule does not apply when $e \in [\underline{e}; \bar{e}]$

These are off-path actions—actions that have zero probability of occurring in equilibrium. Since no worker is expected to choose an education level in between these two in a separating equilibrium, Bayes' rule cannot be applied to update beliefs based on such observations.

Without any equilibrium probability mass, the updating process is not well-defined, and the assignment of beliefs is indeterminate or arbitrary according to equilibrium refinements (like the Intuitive Criterion or the Divinity Criterion).

8.2.3 Solving for PBE : Pooling Equilibria

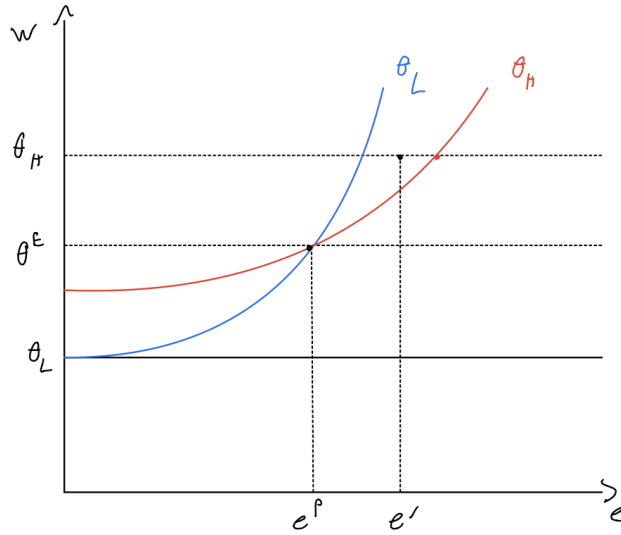


Figure 4: Representation of the Pooling Equilibria

⁴if $e(\theta_H)$ is already judged too expensive for high type, then it will be even more so for low types

Assume every worker chooses the same education level e^P with probability 1. We define : with θ_E the expected productivity of a worker (similar to pooling wage)

$$\begin{aligned} \text{Pooling wage : } w(e^P) &= \lambda\theta_H + (1 - \lambda)\theta_L \\ \text{Critical Education level : } \theta^E - c(\hat{e}, \theta_L) &= \theta_L - c(0, \theta_L) \end{aligned} \tag{24}$$

the critical education level identifies the max education level a low-ability worker would be willing to acquire in a pooling equilibrium. Low worker will be indifferent between :

- Choosing \hat{e} and receiving pooling wage θ_E (worker will never choose $e^P > \hat{e}$, otw would deviate to $e=0$)
- choosing $e=0$ and receiving θ_L

Solving method :

- Step 1 ($e^P \leq \hat{e}$)- prove that for any $e^P \in [0, \hat{e}]$ there is a pooling eq in which all workers choose e^P for certain:
 1. suppose $\forall e \neq e^P, \mu(e) = 0$ so that $w(e) = \theta_L < w(e^P) \Rightarrow$ if employer witness any education level $\neq \theta_P$ they will assume by default this is a θ_L worker !
 2. no one will want to choose $e > e^P$, besides θ_L workers will prefer e^P by definition of \hat{e} ⁵
 3. by the single crossing property, it will be the same for types θ_H (since education is relatively less costly for them)
- Step 2 (intuitive criterion check) : prove that in the job market signalling model, any pooling equilibrium fails the intuitive criterion. Here we can easily find an example graphically (we called it e' on the graph) where the high type is made better off (places above his utility curve) by picking $e > e^P$

⁵Proof: $c(e^P, \theta_L) \leq c(\hat{e}, \theta_L)$ since education is costly and $e^P \leq \hat{e}$. Then $\theta_E - c(e^P, \theta_L) \geq \theta_E - c(e^b, \theta_L) = \theta_L - c(0, \theta_L)$ so it is not profitable to deviate to $e = 0$ or to any $e \neq e^P$ (since deviation to 0 would have been the most profitable)

The Intuitive Criterion

Goal : restricting beliefs to only include types that might reasonably deviate, the Intuitive Criterion often eliminates pooling equilibria in favor of separating equilibria in signaling games.

Let $BR_2(T, a_1)$ denote the set of player 2's best responses if player 1 chose a_1 and player 2's beliefs have support in $T \subset \Theta$:

$$BR_2(T, a_1) = \bigcup_{\mu \in \Delta(T)} \arg \max_{a_2 \in A_2} \sum_{\theta \in \Theta} u_2(a_1, a_2, \theta) \mu(\theta) \quad (25)$$

Definition 8.1 (Intuitive Criterion) *A Perfect Bayesian Equilibrium s^* fails the intuitive criterion if there exists $a_1 \in A_1$, $\theta' \in \Theta$ and $J \subset \Theta$ such that:*

$$1. u_1(s^*, \theta) > \max_{a_2 \in BR_2(\Theta, a_1)} u_1(a_1, a_2, \theta) \quad \forall \theta \in J \quad (26)$$

$$2. u_1(s^*, \theta') < \min_{a_2 \in BR_2(\Theta \setminus J, a_1)} u_1(a_1, a_2, \theta') \quad (27)$$

where $BR_2(T, a_1)$ denotes the set of player 2's best responses if player 1 chose a_1 (an off equilibrium action) and player 2's beliefs have support in $T \subset \Theta$.

- The first inequality corresponds to the group J of types that will never want to deviate as their equilibrium payoff $u_1(s^*, \theta) \Rightarrow$ **Types in J would never have played a_1 since even if they could convince player 2 they were of a particular type they would do worse**
- The second inequality corresponds to the group of types, not included in J, that would benefit from deviating to an off equilibrium action (equilibrium payoff is strictly less than the worse payoff they could get from deviating) \Rightarrow **Type θ' definitely does better playing a_1 rather than the equilibrium if she can convince player 2 that her type is not in J**

The Intuitive Criterion thus distinguishes between types that could potentially benefit from a deviation and those that definitely would not, eliminating equilibria that rely on implausible beliefs about which types might deviate.

A concrete example :

- High types might benefit from deviating to high education if employers believed only high types would make this deviation
- Low types would never benefit from this deviation regardless of employer beliefs
- Therefore, the pooling equilibrium fails the Intuitive Criterion

8.3 General Solving method for PBE

8.3.1 Set-up

Here we consider a two player signaling game where the first player can pick either 3 or 5 and player 2 can accept or decline the proposal made by player 1. The first player is either honest or dishonest (types)

8.3.2 Finding Separating Equilibria

- Step 1 : decide on the equilibrium strategy played by each type of player 1 knowing both types can't play the same strategy. Note μ_3, μ_5 the belief function of player 2 knowing player 1 played 5 (3 respectively) before. Since we are considering a separating equilibria μ_5, μ_3 are either 0 or 1 (no intermediate probability), for instance :

$$\mu_5 = P(\theta_H|5) = 1, \mu_3 = P(\theta_H|3) = 0 \quad (28)$$

- Step 2 : based on these strategies and probabilities, see how the game will unfold (check player 2's decisions at the end of each path taken by P1 at equilibrium)
- Step 3 : check whether the equilibrium path is optimal
- Step 4 : check if there are rational off-equilibrium deviations (look at outcomes if Player 1 player differently, for instance if the honest type player 3 in our above example)

8.3.3 Finding Pooling Equilibria

- Step 1 : we decide on the equilibrium strategy that is played by both types, knowing both types will play the same strategy. Denote the μ_X for the strategy played as p and consider the other one to be determined arbitrarily (off the equilibrium path). For instance, if both the honest and dishonest type play 5, we note :

$$\begin{aligned} \mu_5 &= p \\ \mu_3 &= \text{arbitrary} \end{aligned} \quad (29)$$

- Step 2 : look at expected conditional payoffs for player 2 as a function of p and μ_3 (in our example).
- Step 3 (indifference) : equate expected conditional payoffs that are on the same subgame (for instance $E(Accept|5) = E(Refuse|5)$) and find a cutoff value for $\mu_3 \Rightarrow$ enables us to determine how many potential values we must consider for μ_3 to fully explore the problem
- Step 4 : For μ_3 on either side of the cutoff value, check if there exists profitable deviations for each of the player 1 types. This gives us our first PBE.
- we note the PBE this way : if we consider the case $\mu_3 < 2/5$ with $2/5$ our cutoff value

$$PBE : \{(\text{path chosen by honest P1}, \text{path chosen by dishonest P1}), (\text{response of P2 to 5}, \text{response of P2 to 3}), \mu_5\} \quad (30)$$

Vary the equilibrium strategy and the side of the cutoff value considered to capture all possible PBEs.

Session 9 : Incomplete information - Dynamic games

Two classes of models

- non verifiable information (cheap talk games) : actors can tell actual lies
- verifiable information : actors can only lie by omission

9.1 Definitions

- Symmetric equilibrium : all player follow the same strategy in equilibrium

9.2 The Cheap Talk Game

9.2.1 Set-Up

- 3 stage games :
 1. nature choose type of P_1 (sender) from distribution p
 2. P_1 observes θ and chooses $m \in M$ (message he wishes to send)
 3. P_2 (receiver) observes m and chooses $a \in A$

9.2.2 The non separating equilibriums problem

Communication difficulty : credible communication⁶ is complicated if : 1) all types of senders have perfectly aligned preferences (all receiver will play the same way so no additional info) , 2) all types of senders have perfectly opposed preferences (too much variation, so the receiver just won't listen to the messages) \Rightarrow separating equilibria in cheap talk games do not always exist in these settings (depends on receiver payoffs⁷) !

Proof

- Aligned preferences case : types are fully revealed by the message. So all types can get more by sending the same message as the type who gets the most out of his message (profitable deviation from separating strategy exists)
- Opposed preferences case : same intuition except both type will wish to switch messages with each other (instead of all turning to the same most profitable message)

⁶communication that actually conveys information about the state of world

⁷see slide 8 vs slide 10

9.2.3 General model set-up

- types : $\theta \sim U[0, 1]$
- P_2 has actions denoted $a \in \mathcal{R}$ and payoff $u_2(a, \theta) = -(a - \theta)^2$
- P_1 has payoff $u_1(a, \theta) = -(a - \theta - c)^2$
- optimal choice differs across players ($a = \theta$ vs $a = \theta + c$)

Babbling equilibrium

- P_1 send m no matter θ (no info conveyed so no bayesian updating) so P_2 assigns equal probability to all values of θ regardless of m (since θ follows uniform distribution). Then P_2 sets action $a = E[\theta] = 1/2$

Two message equilibrium

- P_1 sends m_1 or m_2 and we impose $a(m_1) < a(m_2)$ (message conveys information)
- step 1 - show P_1 adopts a threshold strategy with θ^* : just show the incremental gain for player 1 $payoff(m_2) - payoff(m_1)$ is increasing in θ (if pick m_2 for a θ^* then you will wish to pick the same message for any $\theta > \theta^*$)
- step 2 - find the equilibrium values of $a(m_1), a(m_2)$:

1. P_2 set : $a(m) = E[\theta|m]$
2. when P_2 receives m_1 he knows $\theta \sim [0, \theta^*]$ so $a(m_1) = E[\theta|m_1] = \frac{\theta^*}{2}$
3. same reasoning for m_2 gives us : $a(m_2) = E[\theta|m_2] = \frac{1+\theta^*}{2}$
4. indifference condition : we find the P_1 cutoff value θ^* using the fact that at θ^* we must have⁸

$$u_2(a(m_1), \theta^*) = u_2(a(m_2), \theta^*) \quad (31)$$

5. we know $\theta^* > 0$ which gives us a condition on c

Three message equilibrium

- now : $[0, \theta_1)$ choose m_1 , (θ_1, θ_2) choose m_2 and the rest choose m_3
- we use exactly the same reasoning except we now have two indifference conditions
- look at the condition on c and notice that the threshold for the three message equilibrium is lower than for the two message one, so can have both in this situation. (threshold fgives us the maximum number we can communicate given a certain value of c)

⁸be careful since when taking the square root we have absolute values so it's better to directly multiply the left hand side by $(-1)^2$ to ensure we have directly a positive term when taking the root

9.3 The War of attrition game

9.3.1 Set-Up :

- 2 firms fight to be the only one in a market and get a prize of $v > 1$
- As long as they are both in the market, they make a loss of 1 per period (cost of fighting)
- payoff of one of the firms leaving at t : 1) for the loss equality notice we have a finite geometric series with $a=1$ and $r=\delta$ ⁹ 2) for total utility notice we have a one time benefit of 1 (not a perpetuity)

$$\text{Loss until period } t : L(t) = -1 - \delta - \delta^2 \dots - \delta^{t-1} = - \sum_{k=0}^{t-1} \delta^k = \frac{1 - \delta^t}{1 - \delta} \quad (32)$$

$$\text{Total utility for firm which stays : } F(t) = L(t) + \delta^t v$$

9.3.2 solving for equilibrium

Equilibrias in discrete time :

- asymmetric equilibria : P_1 never stops and P_2 always stops (so stops immediately basically)
- mixed strategy equilibria : both players play the same strategy "if other has not stopped before t , I stop at t with probability p "

1. We wish to find p such that each firm i is indifferent between stopping at t or $t+1$
2. to get it just solve for p using this indifference equality :

$$\underbrace{L(t)}_{\text{cost of exiting at } t} = \underbrace{pF(t)}_{\substack{\text{firm } j \text{ stops} \\ \text{with proba } p}} + \underbrace{(1-p)L(t+1)}_{\text{utility of staying in period } t+1} \quad (33)$$

Equilibrias in continuous time

- modeling continuous time: consider period of length δ and make them tend towards 0. We denote : $n = t/\Delta$ the number of periods between 0 and t .
- Step 1 : we find the equilibrium probability of stopping p^* through :

$$\underbrace{p^* v}_{\text{MB of continuing}} = \underbrace{(1-p^*)\Delta}_{\text{MC of continuing}} \quad (34)$$

- Step 2 - find the probability that a player does not stop before t : 1) Write down probability of not stopping for n periods, 2) Substitute n by its expression, 3) Rewrite it with an exponential and use a Taylor approximation for the \ln function (possible given Δ small)

$$1 - G(t) = (1 - p^*)^n \approx e^{-t/v} \quad (35)$$

with $G(t)$ the probability of stopping before t (it is a distribution)

⁹To see more about this formula : About geometric series

- Step 3 : rewrite the discount factor as a function of the interest rate r

$$\delta^t = (e^{-r})^t \quad (36)$$

- Step 4 : rewrite the loss function $L(t)$ as an integral of the discount factor between 0,t

$$L(t) = \int_0^t e^{-rs} ds = \frac{1}{r} [1 - e^{-rt}] \quad (37)$$

- Step 5 : we write $F(t)$ using the same formula that we used for discrete time

$$F(t) = [L(t) + e^{-rt}v] \quad (38)$$

- Step 6 - write the expected profits of stopping at time T : we integrate over t given a density $g(t)$ ¹⁰ for stopping at a time t ¹¹

$$E(\text{profits of stopping at } T) = \underbrace{\int_0^T F(t)g(t)dt}_{E(\text{payoff}) \text{ if opponent stop at } t \leq T} + \underbrace{\int_T^{+\infty} L(T)g(t)dt}_{E(\text{payoff}) \text{ if opponents stop at } t > T} \quad (39)$$

- to visualize it more easily, you may view this as a weighted sum of all possible outcomes with a given weight $g(t)dt$ for each outcome. (we sum over the full distribution of $g(t)$)
- Step 7 - derive expected profits with respect to T (use Leibniz rule) and set it to 0 (players are indifferent between when to stop) to get the hazard rate $\frac{g(T)}{1-G(T)}$
- The hazard rate measures the instantaneous probability of the opponent stopping at time T , given they have survived up to T

¹⁰PDF of the opponent's stopping time

¹¹we account for the fact that at each period, the other firm has a non null probability of exiting