

# Interpolation over Nonlinear Arithmetic

## Towards Program Reasoning and Verification

Mingshuai Chen

—Joint work with J. Wang, B. Zhan, N. Zhan, D. Kapur, J. An, T. Gan, L. Dai, and B. Xia—



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# What Is Interpolation?

## Interpolation /ɪntə:pə'leɪʃ(ə)n/

MATHEMATICS

*"the insertion of an intermediate value or term into a series by estimating or calculating it from surrounding known values."*

[OXFORD Dictionary]

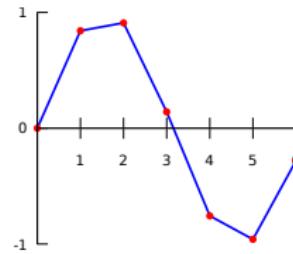
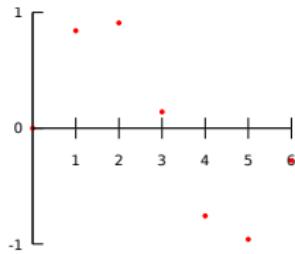
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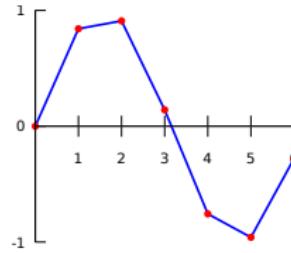
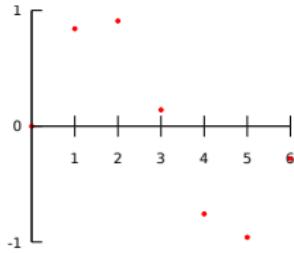
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LOGICAL REASONING

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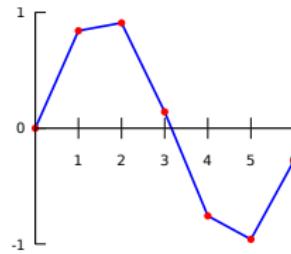
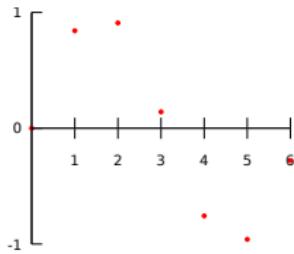
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$$P \models Q$$

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$$P \wedge Q \models \perp$$

$$P \models R \text{ and } R \wedge Q \models \perp$$

# Interpolants as Loop Invariants

Example ([Lin et al., ASE '17])

```
while (x ≠ n){  
    x := x + 1; y := y + 1;  
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assume( $x = 0 \wedge y = 0 \wedge n \geq 0$ );  
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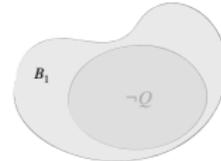
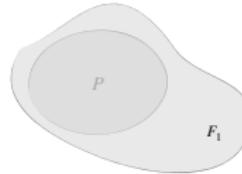
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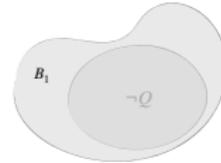
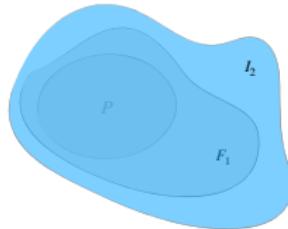
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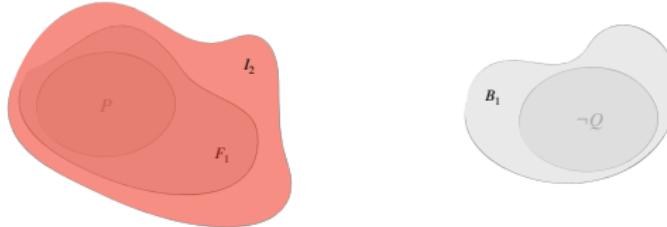
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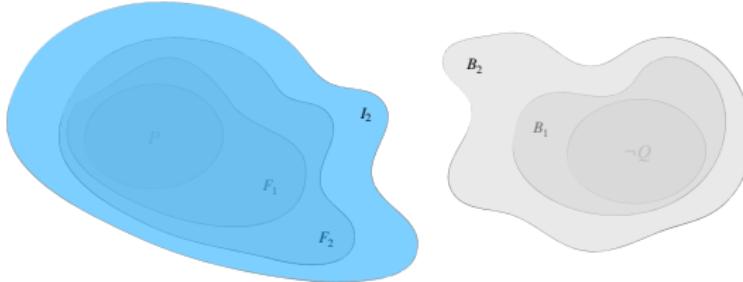
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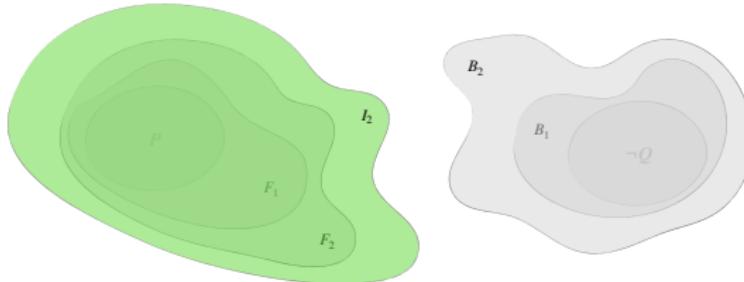
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Given  $\phi$  and  $\psi$  in a theory  $\mathcal{T}$  s.t.  $\phi \wedge \psi \models_{\mathcal{T}} \perp$ ,  $I$  is a (reverse) interpolant of  $\phi$  and  $\psi$  if

$$\phi \models_{\mathcal{T}} I \quad \text{and} \quad I \wedge \psi \models_{\mathcal{T}} \perp \quad \text{and} \quad \text{var}(I) \subseteq \text{var}(\phi) \cap \text{var}(\psi).$$

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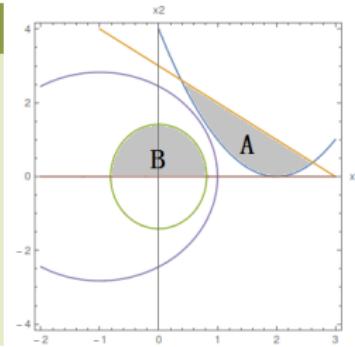
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## Example (Nonlinear $\mathcal{T}$ )

$$A \triangleq -x_1^2 + 4x_1 + x_2 - 4 \geq 0 \wedge -x_1 - x_2 + 3 - y^2 > 0$$

$$B \triangleq -3x_1^2 - x_2^2 + 1 \geq 0 \wedge x_2 - z^2 \geq 0$$

$$I \triangleq -3 + 2x_1 + x_1^2 + \frac{1}{2}x_2^2 > 0$$



# Binary Classification

## Binary Classifier

Given a dataset  $X = X^+ \uplus X^-$  of sample points,  $C: X \rightarrow \{\top, \perp\}$  is a *classifier* if

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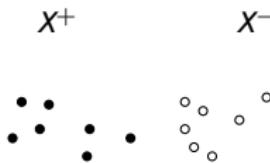


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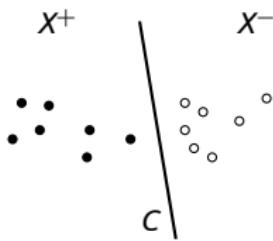


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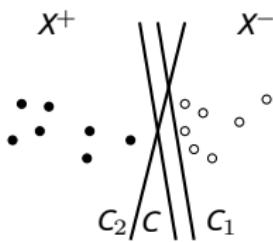


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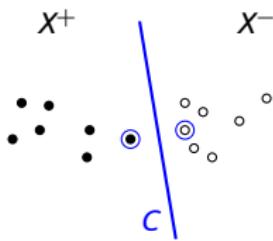
There could be (infinitely) many valid classifiers.

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**Support Vector Machine (SVM)** finds a “middle” one – separating hyperplane that yields the largest distance (functional margin) to the nearest samples (support vectors) – via *convex optimization*.

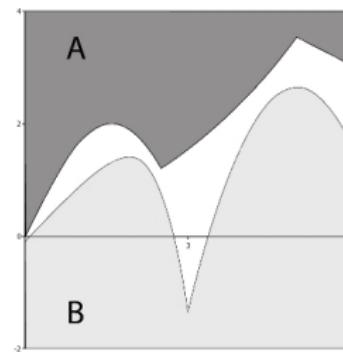
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- ☺  $X^+$  and  $X^-$  are often not linearly separable for nonlinear  $\phi$  and  $\psi$  :

$$\begin{aligned}
 A &\triangleq (x < 2.5 \Rightarrow y \geq 2 \sin(x)) \\
 &\wedge (x \geq 2.5 \wedge x < 5 \Rightarrow y \geq 0.125x^2 + 0.41) \\
 &\wedge (x \geq 5 \wedge x \leq 6 \Rightarrow y \geq 6.04 - 0.5x) \\
 B &\triangleq (x < 3 \Rightarrow y \leq x \cos(0.1e^x) - 0.083) \\
 &\wedge (x \geq 3 \wedge x \leq 6 \Rightarrow y \leq -x^2 + 10x - 22.35)
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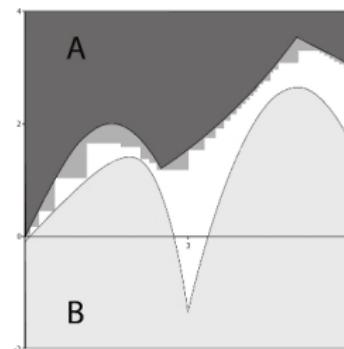


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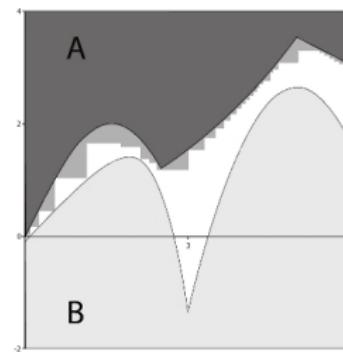
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- ☺ Encoding interpolants as logical combinations of linear constraints.

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 & \wedge (x \geq 3 \wedge x \leq 6 \Rightarrow y \leq -x^2 + 10x - 22.35)
 \end{aligned}$$



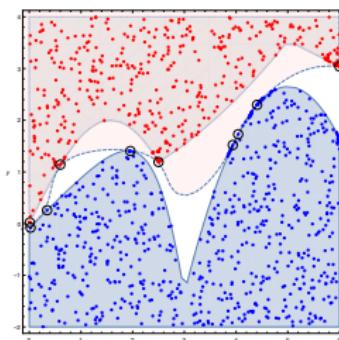
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- ☺ Encoding interpolants as logical combinations of linear constraints.
- ☺ Yielding rather complex interpolants (even of an infinite length in the worst case).

# Interpolation vs. Classification

- ☺ Linear interpolants can be viewed as hyperplane classifiers [Sharma et al., CAV'12] : sampling from  $\llbracket \phi \rrbracket$  and  $\llbracket \psi \rrbracket \rightarrow$  building a hyperplane classifier  $\rightarrow$  refining by CEs.
- ☺  $X^+$  and  $X^-$  are often not linearly separable for nonlinear  $\phi$  and  $\psi$  :

$$\begin{aligned}
 A \quad \hat{=} \quad & (x < 2.5 \Rightarrow y \geq 2 \sin(x)) \\
 & \wedge (x \geq 2.5 \wedge x < 5 \Rightarrow y \geq 0.125x^2 + 0.41) \\
 & \wedge (x \geq 5 \wedge x \leq 6 \Rightarrow y \geq 6.04 - 0.5x) \\
 \\ 
 B \quad \hat{=} \quad & (x < 3 \Rightarrow y \leq x \cos(0.1e^x) - 0.083) \\
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©Chen et al., CADE'19

- ☺ Encoding interpolants as logical combinations of linear constraints.
- ☺ Yielding rather complex interpolants (even of an infinite length in the worst case).
- ☺ NIL : learning nonlinear interpolants.

# Space Transformation & Kernel Trick

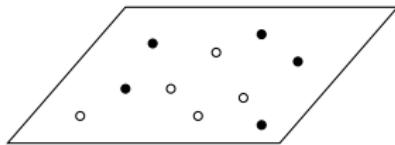


Figure – 2-dimensional input space

# Space Transformation & Kernel Trick

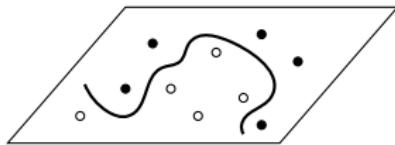


Figure – 2-dimensional input space

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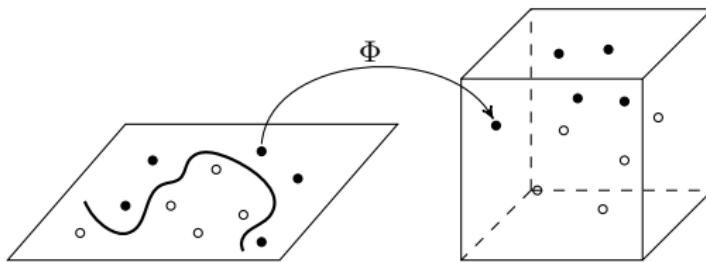


Figure – 2-dimensional input space  $\mapsto$  3-dimensional feature (monomial) space with linear separation.

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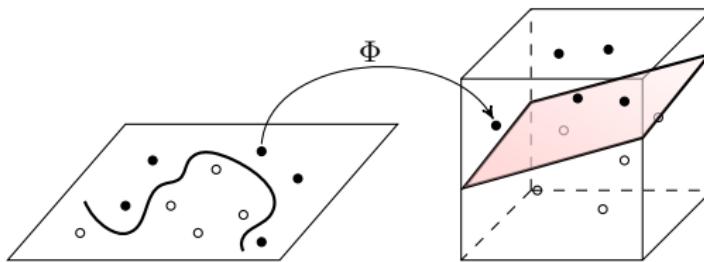


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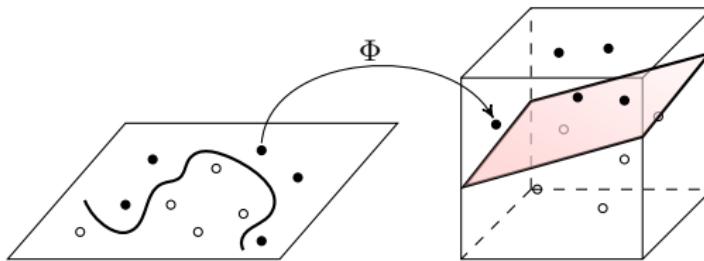


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Optimal-margin classifier /:

$$\sum_{i=1}^n \alpha_i \kappa(\vec{x}_i, \mathbf{x}) = 0$$

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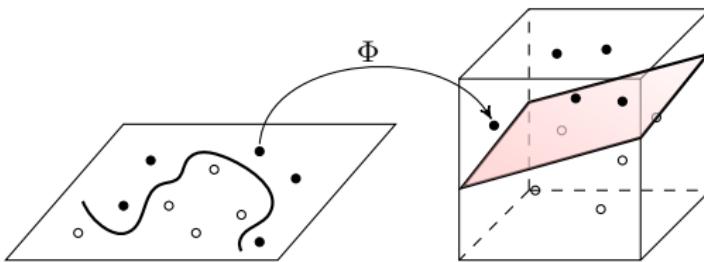


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kernel function  
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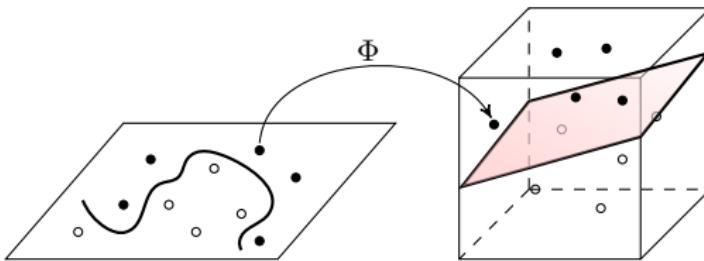


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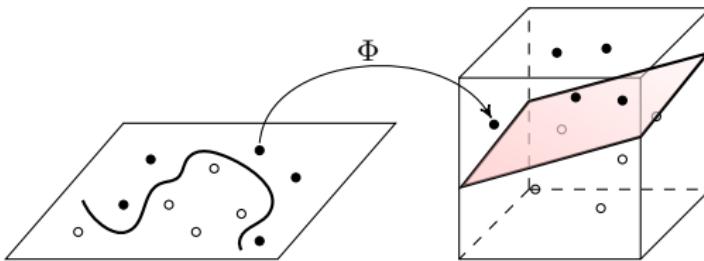


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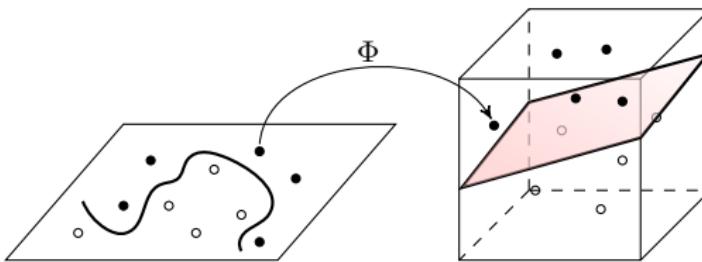


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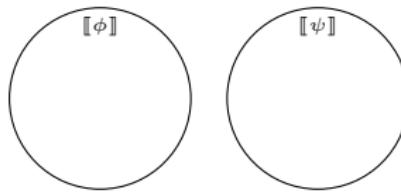
kernel function

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polynomial degree describing complexity of the monomial space

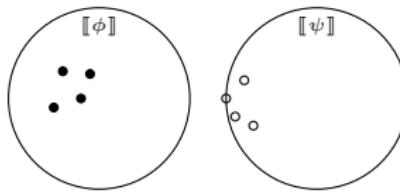
# The NIL Algorithm

- 1 Given mutually contradictory nonlinear  $\phi$  and  $\psi$  over common variables  $x$ .
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- 3 Find a classifier by SVMs (with kernel-degree  $m$ ) as a candidate interpolant.
- 4 Refine the candidate by CEs till it being verified as a true interpolant.



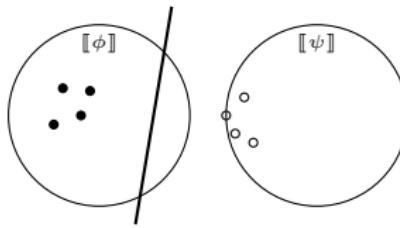
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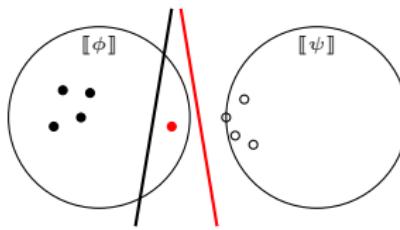
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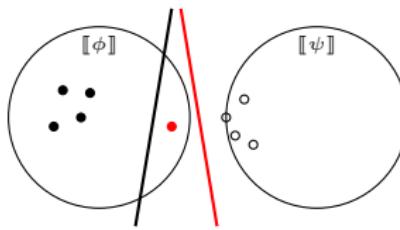
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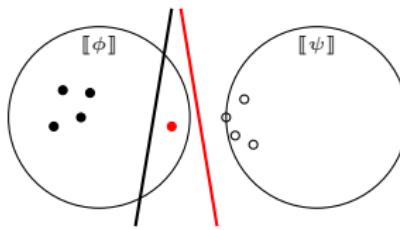
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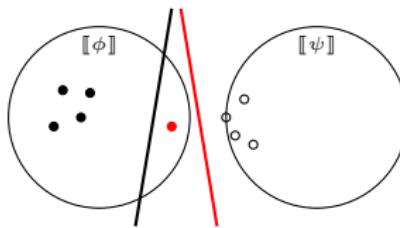


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# Comparison with Naïve QE-Based Method

	<b>QE-based method</b>	<b>NIL</b>
Logical strength	strongest : $\exists y. \phi(x, y)$ weakest : $\forall z. \neg\psi(x, z)$	medium $\Rightarrow$ robust
Complexity of /	direct projection $\Rightarrow$ complex	single polynomial $\Rightarrow$ simple
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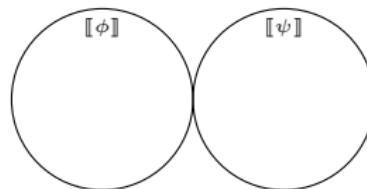
QE + template?

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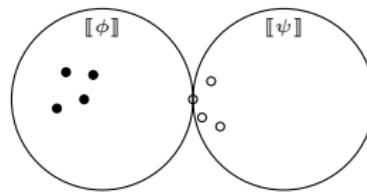
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QE + template?  $\Rightarrow$  Too many unknown parameters.

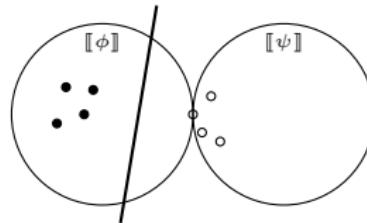
# NIL $_{\delta}$ : For Cases with Zero Functional Margin



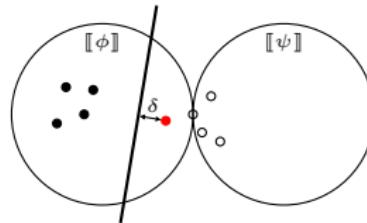
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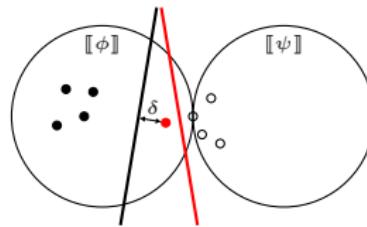
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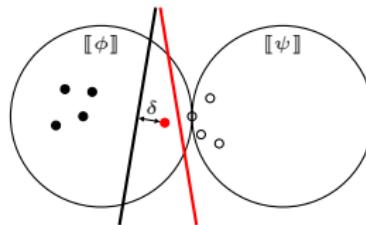
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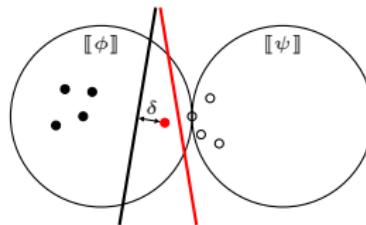


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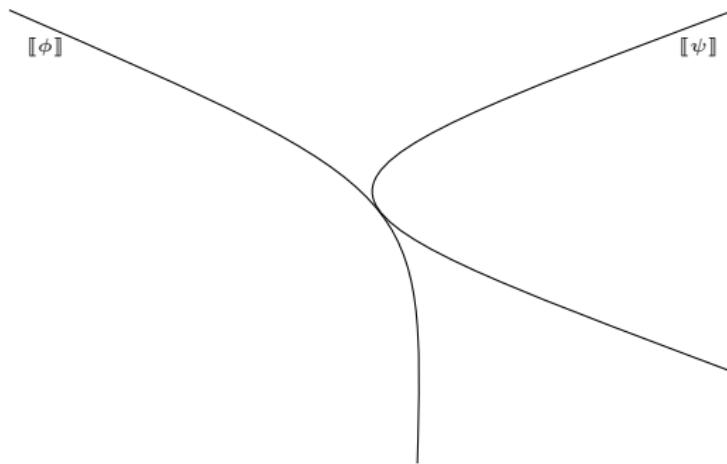
⌚  $\delta$ -sound, and  $\delta$ -complete if  $[[\phi]]$  and  $[[\psi]]$  are bounded sets even with zero functional margin.

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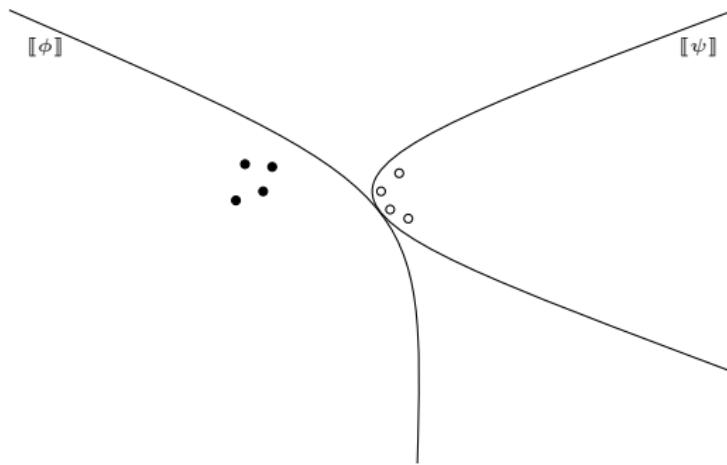


- ⌚  $\delta$ -sound, and  $\delta$ -complete if  $[\phi]$  and  $[\psi]$  are bounded sets even with zero functional margin.
- ⌚ May not converge to an actual interpolant when  $[\phi]$  or  $[\psi]$  is unbounded.

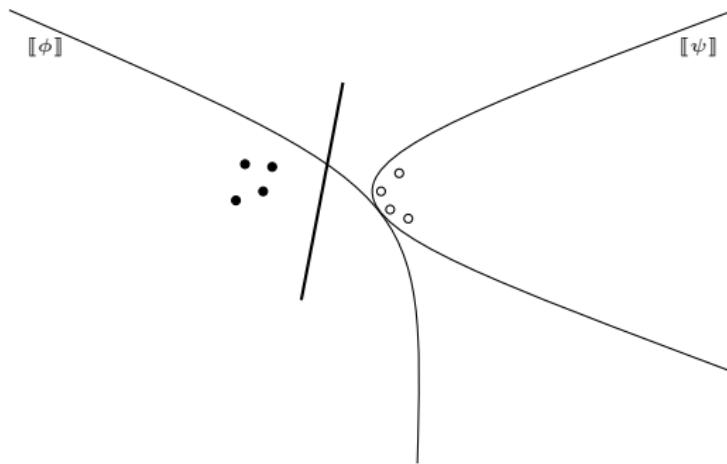
# NIL $_{\delta,B}^*$ : For Unbounded Cases with Varying Tolerance



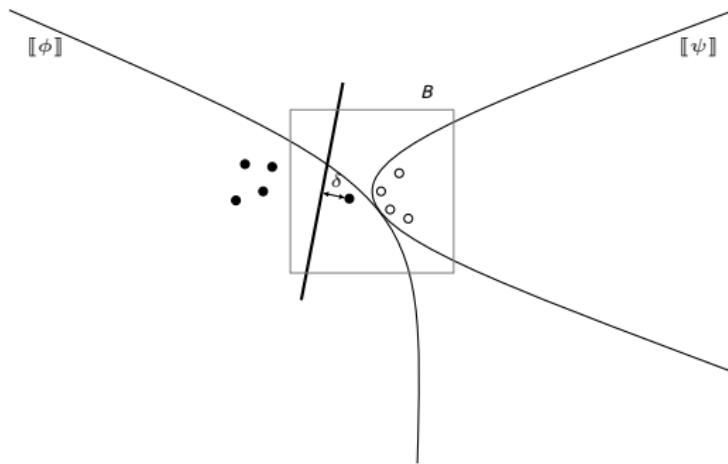
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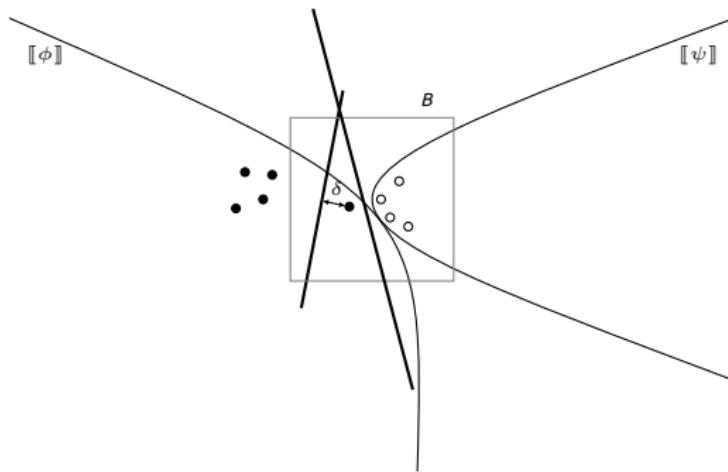
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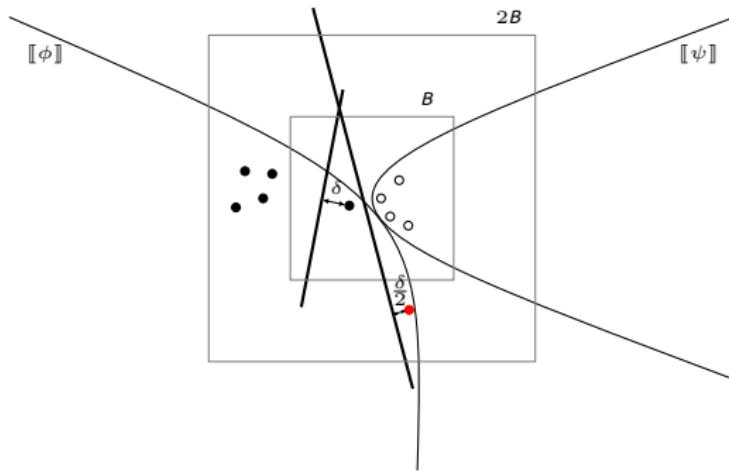
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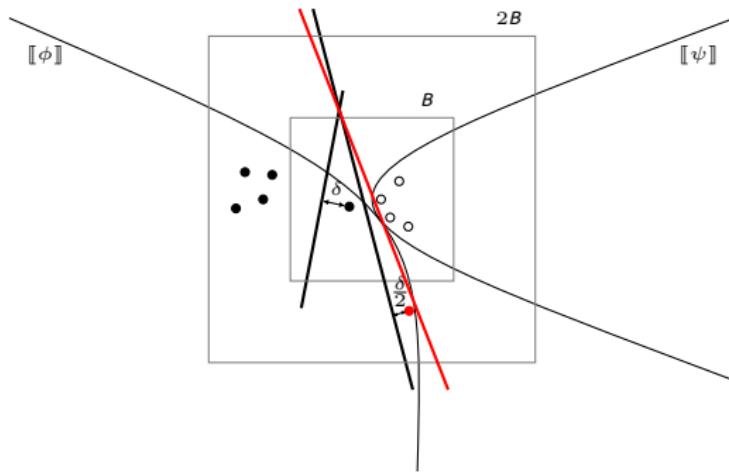
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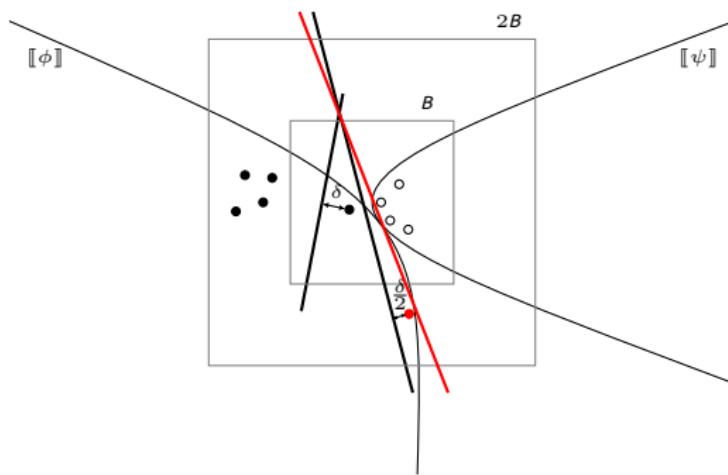
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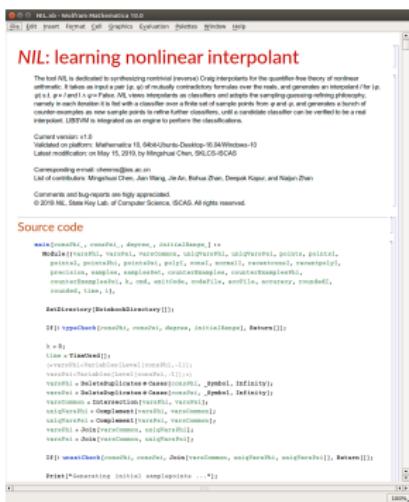
# $\text{NIL}_{\delta,B}^*$ : For Unbounded Cases with Varying Tolerance



- ⌚ The sequence of candidate interpolants converges to an actual interpolant.

## Tool Support

- LIBSVM : SVM classifications;
  - Reduce : verification of candidate interpolants;
  - FindInstance : generation of counterexamples;
  - Rational recovery : rounding off floating-point computations [Lang, Springer NY '12].

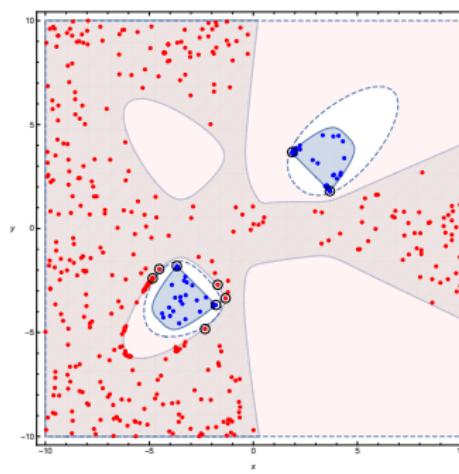
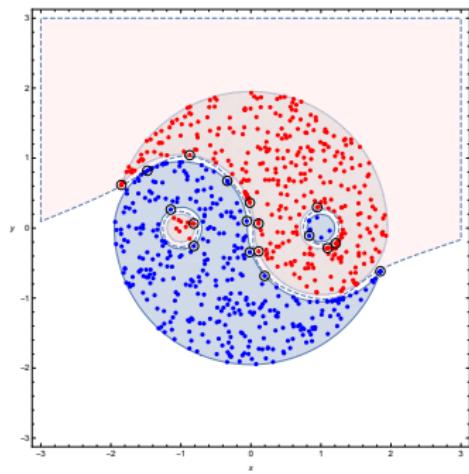


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2.  <https://notebookarchive.org/nil-learning-nonlinear-interpolants--2021-08-5lcseyb7/>

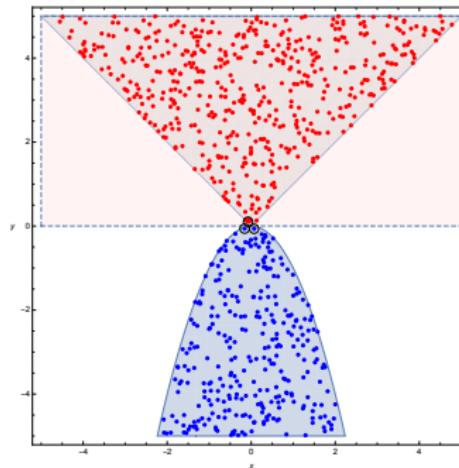
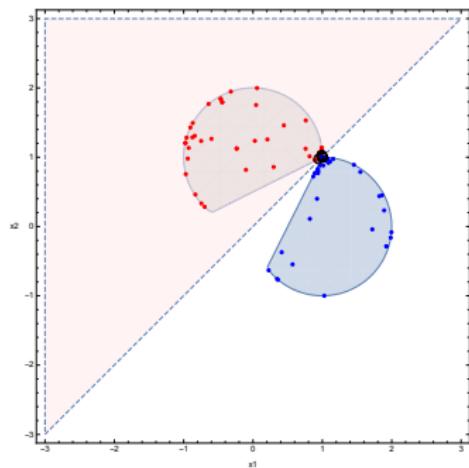
# Examples

Beyond the scope of concave quadratic formulas as required in [Gan et al., IJCAR '16] :



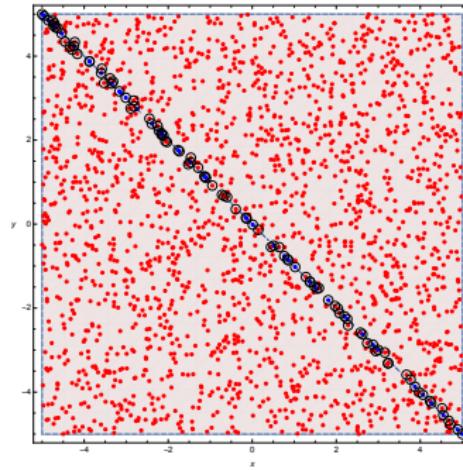
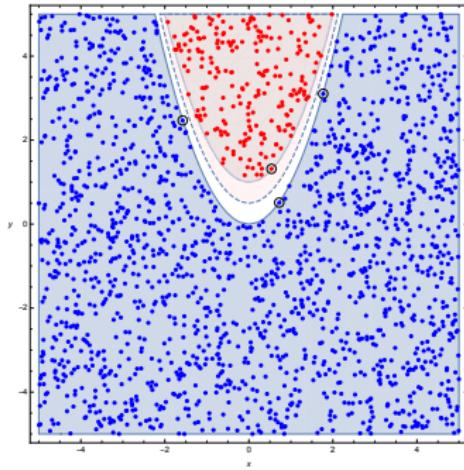
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Adjacent and sharper cases as in [Okudono et al., APLAS '17] :



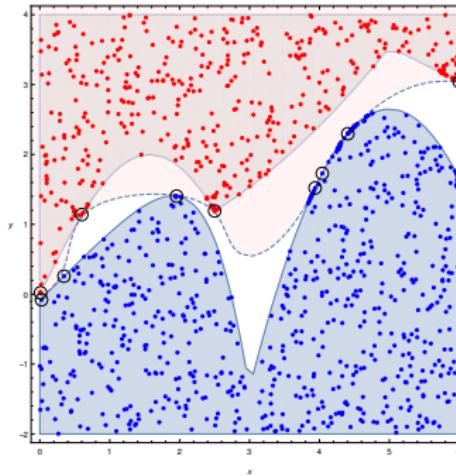
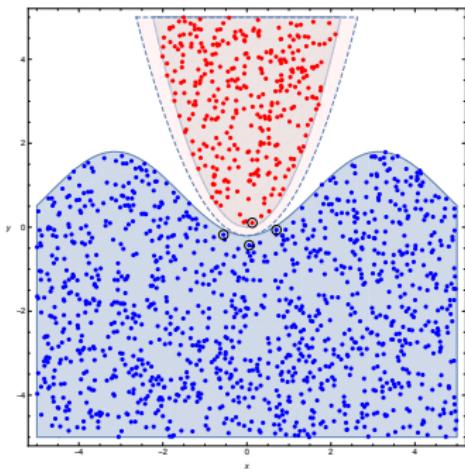
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Formulas sharing parallel or coincident boundaries :



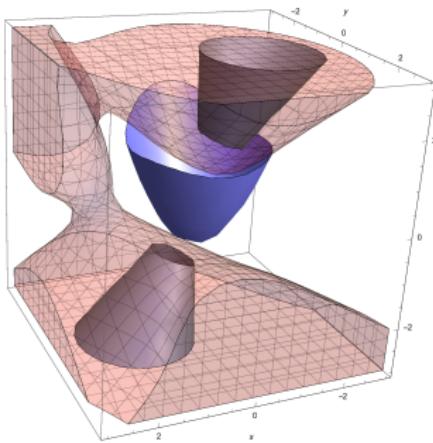
# Examples

Transcendental cases from [Gao & Zufferey, TACAS '16] and [Kupferschmid & Becker, FORMATS '11], yet with simpler interpolants :

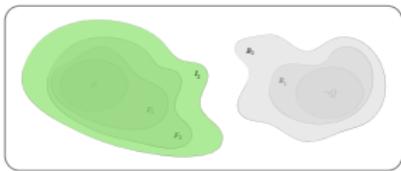


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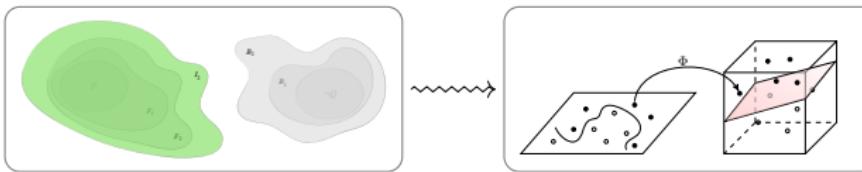
Three-dimensional case from [Dai et al., CAV'13], yet with simpler interpolants :



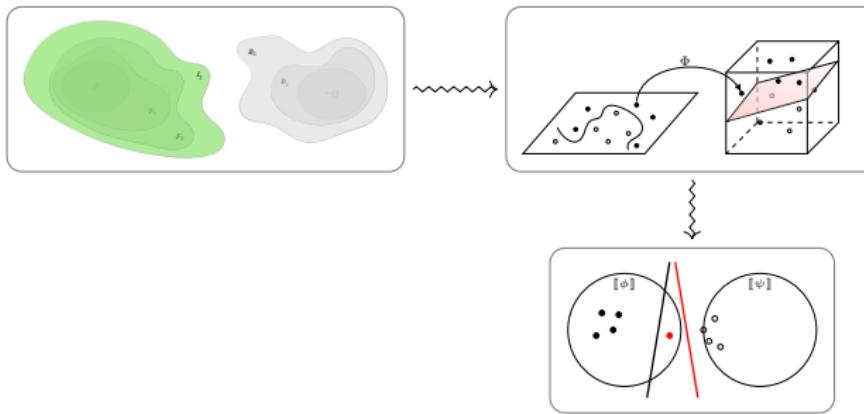
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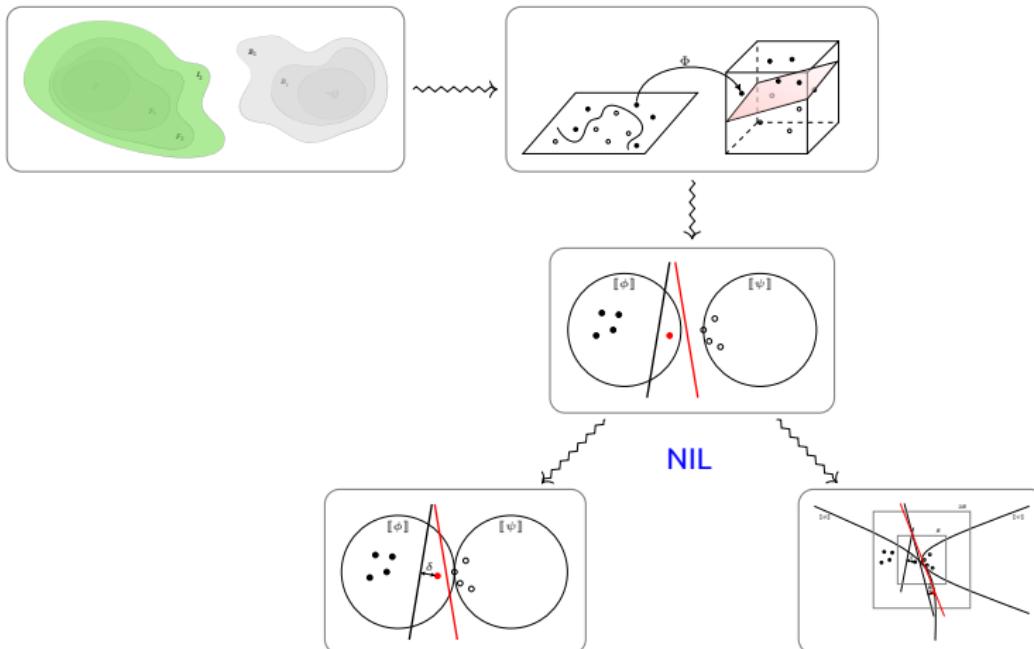


# Summary



NIL

# Summary



# Interpolants as Loop Invariants

Example ([Sharma et al., CAV'12])

```
x := 0; y := 0;  
while (*)  
  {x := x + 1; y := y + 1; }  
  while (x ≠ 0)  
    {x := x - 1; y := y - 1; }  
  if (y ≠ 0)  
    error();
```

# Interpolants as Loop Invariants

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# Interpolants as Loop Invariants

Example ([Sharma et al., CAV'12])

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 $x := 0; y := 0;$                                  $A \triangleq x_1 = 0 \wedge y_1 = 0 \wedge$ 
while (*)
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  -----
while ( $x \neq 0$ )
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```

$$\begin{aligned} & ite(b, \\ & \quad x = x_1 \wedge y = y_1, \\ & \quad x = x_1 + 1 \wedge y = y_1 + 1) \end{aligned}$$

# Interpolants as Loop Invariants

Example ([Sharma et al., CAV'12])

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<b>while</b> ( $x \neq 0$ )	$B \triangleq ite(x = 0,$
$\{x := x - 1; y := y - 1;\}$	$x_2 = x \wedge y_2 = y,$
<b>if</b> ( $y \neq 0$ )	$x_2 = x - 1 \wedge y_2 = y - 1) \wedge$
<b>error</b> ();	$x_2 = 0 \wedge \neg(y_2 = 0)$

# Interpolants as Loop Invariants

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$x := 0; y := 0;$	$A \hat{=} x_1 = 0 \wedge y_1 = 0 \wedge$
<b>while</b> (* )	$ite(b,$
$\{x := x + 1; y := y + 1;\}$	$x = x_1 \wedge y = y_1,$
-----	$x = x_1 + 1 \wedge y = y_1 + 1)$
<b>while</b> ( $x \neq 0$ )	$B \hat{=} ite(x = 0,$
$\{x := x - 1; y := y - 1;\}$	$x_2 = x \wedge y_2 = y,$
<b>if</b> ( $y \neq 0$ )	$x_2 = x - 1 \wedge y_2 = y - 1) \wedge$
<b>error</b> ();	$x_2 = 0 \wedge \neg(y_2 = 0)$

$$A \wedge B \models \perp. \quad I(x, y) \hat{=} x = y \text{ s.t. } A \models I \text{ and } I \wedge B \models \perp.$$

# Interpolants as Loop Invariants

Example ([Sharma et al., CAV'12])

```

 $x := 0; y := 0;$   $A \hat{=} x_1 = 0 \wedge y_1 = 0 \wedge$   

while (*)
 $\{x := x + 1; y := y + 1;\}$   $ite(b,$   



---


while ( $x \neq 0)$   $x = x_1 \wedge y = y_1,$   

 $\{x := x - 1; y := y - 1;\}$   $x = x_1 + 1 \wedge y = y_1 + 1)$   

if ( $y \neq 0)$   $B \hat{=} ite(x = 0,$   

error();  $x_2 = x \wedge y_2 = y,$   

 $x_2 = x - 1 \wedge y_2 = y - 1) \wedge$   

 $x_2 = 0 \wedge \neg(y_2 = 0)$ 
```

$$A \wedge B \models \perp. \quad I(x, y) \hat{=} x = y \text{ s.t. } A \models I \text{ and } I \wedge B \models \perp.$$

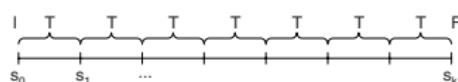


Figure – Bounded model checking.

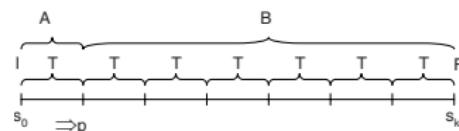


Figure – Computing image by interpolation.

# Interpolation-based Verification

⌚ The bottleneck of existing formal verification techniques lies in **scalability**.

# Interpolation-based Verification

- ⌚ The bottleneck of existing formal verification techniques lies in **scalability**.
- ⌚ Interpolation helps in scaling these verification techniques due to its inherent capability of **local and modular reasoning** :
  - **Nelson-Oppen method** : equivalently decomposing a formula of a composite theory into formulas of its component theories;
  - **SMT** : combining different decision procedures to verify programs with complicated data structures;
  - **Bounded model-checking** : generating invariants to verify infinite-state systems due to McMillan;
  - ...

# Benchmark Examples

Category	ID	Name	$\phi$	$\psi$	$\iota$	Time/s
	1	Dummy	$x < -1$	$x \geq 1$	$x < 0$	0.11
	2	Necklace	$y - x^2 - 1 = 0$	$y + x^2 + 1 = 0$	$\frac{x^4}{223} - \frac{y^2}{356} + x^2(\frac{x^2}{45} - \frac{y}{170} - \frac{2}{9}) +$	0.21
	3	Face	$(x+4)^2 + y^2 - 1 \leq 0 \vee$ $(x-4)^2 + y^2 - 1 \leq 0$	$x^2 + y^2 - 64 \leq 0 \wedge$ $(x+4)^2 + y^2 - 9 \geq 0 \wedge$ $(x-4)^2 + y^2 - 9 \geq 0$	$x(\frac{y^3}{89} + \frac{y^2}{68} - \frac{y}{74} - \frac{1}{55}) + \frac{y^4}{146} +$ $\frac{y^3}{95} + \frac{y^2}{37} + \frac{y}{366} + 1 < 0$	0.33
	4	Tinted	$x^2 - 2xy^2 + 3x^2 - y^2$ $-yx + x^2 - 1 \geq 0 \wedge$ $\frac{1}{120}(-x^2 - y^2) + x^2y^2 -$ $x^2 + \frac{1}{4}(x^4 + 2x^2y^2 + y^4) +$ $y^2x^2 - y^2 - 4 \leq 0$	$w^2 + 4(x-y)^4 + (x+y)^2 - 80 \leq 0 \wedge$ $-w^2(x-y)^4 + 100(x+y)^2 - 3000 \geq 0$	$-\frac{x^4}{160} + x^3\left(\frac{y}{170} - \frac{1}{113}\right) + x^2\left(\frac{-x^2}{225} + \frac{y}{76} + \frac{2}{27}\right) +$ $x\left(\frac{y^3}{259} + \frac{y^2}{63} + \frac{5y}{51} - \frac{1}{316}\right) - \frac{y^4}{183} - \frac{y^3}{94} + \frac{y^2}{14} + \frac{y}{255} - 1 < 0$	140.62
with/without rounding	5	Ultimate	$x^2 + y^2 - 3.8025 \leq 0 \wedge y \geq 0 \vee$ $(x-1)^2 + y^2 - 0.9025 \leq 0 \wedge$ $(x-1)^2 + y^2 - 0.09 > 0 \wedge$ $(x-1)^2 + y^2 - 1.1025 \geq 0 \vee$ $(x+1)^2 + y^2 - \frac{1}{25} \leq 0$	$(-3.8025 + x^2 + y^2 \leq 0 \wedge y \geq 0 \vee$ $-0.9025 + (-1 - x)^2 + y^2 \leq 0 \wedge)$ $-0.09 + (-1 - x)^2 + y^2 > 0 \wedge$ $-1.1025 + (1 - x)^2 + y^2 \geq 0 \vee$ $-\frac{1}{25} + (1 + x)^2 + y^2 \leq 0$	$\frac{x^2}{27} + y^2(-\frac{y}{5} - \frac{1}{96}) + x^2(\frac{2x^2}{9} - \frac{y}{32} - \frac{1}{2}) +$ $x^4(-\frac{2y^3}{9} + \frac{y}{3} + \frac{1}{31}) + x^3(\frac{x^4}{11} - \frac{y^3}{10} - \frac{10y^2}{13} + \frac{y}{18} + \frac{15}{16}) +$ $x^2(-\frac{y^5}{25} - \frac{y^4}{18} - \frac{y^3}{10} + \frac{y^2}{32}) +$ $x\left(\frac{y^6}{71} + \frac{2y^4}{11} - \frac{y^3}{25} - \frac{y^2}{45} - \frac{3}{8}\right) +$ $\frac{y^6}{48} - \frac{y^5}{6} - \frac{y^4}{2} - \frac{y^3}{6} - \frac{y^2}{59} + \frac{1}{85} < 0$	48.82
	6	UCAR16-1	$-x_1^2 + 4x_1 + x_2 - 4 \geq 0 \wedge$ $-x_1 - x_2 + 3 - y^2 \geq 0$	$-3x_1^2 - x_2^2 + 1 \geq 0 \wedge x_2 - x^2 \geq 0$	$1 - \frac{3x_1}{4} - \frac{x_2}{2} < 0$	0.16
	7	CAV13-1	$1 - x^2 - b^2 > 0 \wedge a^2 + b - 1 - x = 0 \wedge$ $b + bx + 1 - y = 0$	$x^2 - 2y^2 - 4 > 0$	$-1 + \frac{x^2}{2} - \frac{y}{3} + \frac{xy}{3} - \frac{y^2}{4} < 0$	3.25
	8	CAV13-2	$x^2 + y^2 + z^2 - 2 \geq 0 \wedge$ $1.2x^2 + y^2 + xz = 0$	$20 - 3x^2 - 4y^2 - 10z^2 \geq 0 \wedge$ $x^2 + y^2 - z - 1 = 0$	$105x^4 + y^2(140y^2 + 249(5z + 7) + 35z(3z + 8)) +$ $2(70y^2 + 1)(24y^2 + 21z + 26) - 14y(6z^3 + 5z^2 +$ $10) - 35(3z^4 + 8z^2 + 4z + 9) < 14x(20z^2(x + 1) +$ $10y^2(x + 2) - 3y(4z^2 - 5x + 4) - 20z(x^2 + 2))$	3857.89
	9	CAV13-3	$vc < 49.61 \wedge fa = 0.5418vc \wedge$ $fa = 1000 - fa \wedge vc = 0.0005fa \wedge$ $vc_1 = vc - vc$	$vc_1 \geq 49.61$	$-1 + \frac{2vc_1}{93} < 0$	40.63
with rounding	10	Parallel parabola	$y - x^2 = 0 \wedge$	$y - x^2 < 0$	$\frac{1}{2} + x^2 < y$	4.50
	11	Parallel halfplane	$y - x - 1 \geq 0$	$y - x + 1 < 0$	$\frac{1}{2} < y$	2.46
	12	Sharpen-1	$y + 1 < 0$	$y^2 + x^2 < 1 \leq 0$	$2 + y < y^2$	2.19
	13	Sharpen-2	$y - x > 0 \wedge x + y > 0$	$y + x^2 \leq 0$	$y > 0$	2.38
	14	Coincident	$x + y > 0 \vee x + y < 0$	$x + y = 0$	$(x + y)^2 > 0$	0.18
	15	Adjacent	$y - x^2 > 0$	$y - x^2 \leq 0$	$x^2 < y$	0.25
	16	UCAR16-2	$-x_1^2 - x_2^2 + 2x_1y_1 - 2y_1 + 2x_2 \geq 0 \wedge$ $-x_2^2 - x_3^2 - x_2^2 - 4y_2 + 2x_2 - 4 \geq 0$ $x_1 + 2x_2 \geq 0 \wedge x_1 + 2x_2 - x_1 = 0 \wedge$ $-2x_2 + yx_1 - y_1 = 0 \wedge x - x_1 - 1 = 0 \wedge$ $y = y_1 + x \wedge x = x - 2y \wedge yx_1 = 2x + y$	$-x_1^2 - x_2^2 + 4x_1x_2 + 3x_1 - 6x_2 - 2 \geq 0 \wedge$ $-x_2^2 - x_3^2 - x_2^2 + 2x_1 + x_2 - 2x_2 - 1 \geq 0$ $x_0 + 2y_0 < 0$ $2x_0 + 4y_0 > 5$	$x_1 < x_2$	12.33
beyond polynomials	18	TACAS16	$y - x^2 \geq 0$	$y + \cos x - 0.8 \leq 0$	$15x^2 < 4 + 20y$	12.71
	19	Transcendental	$\sin x \geq 0.6$	$\sin x \leq 0.4$	SVM failed	-
unbalanced	20	Unbalanced	$x > 0 \vee x < 0$	$x = 0$	$x^2 > 0$	

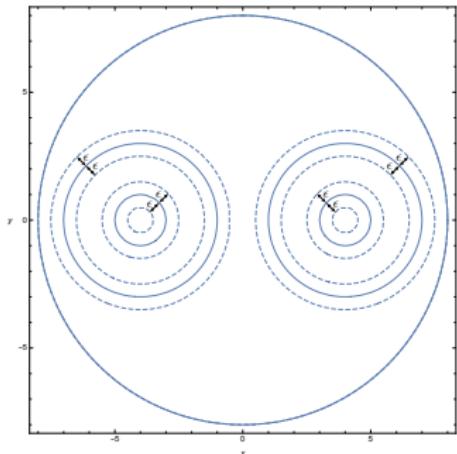
# Interpolants of Simpler Forms

Name	Interpolants by NIL	Interpolants from the sources
IJCAR16-1	$1 - \frac{3x_1}{4} - \frac{x_2}{2} < 0$	$-3 + 2x_1 + x_1^2 + \frac{1}{2}x_2^2 > 0$
CAV13-1	$-1 + \frac{x^2}{2} - \frac{y}{3} + \frac{xy}{3} - \frac{y^2}{4} < 0$	$436.45(x^2 - 2y^2 - 4) + \frac{1}{2} \leq 0$ $- 14629.26 + 2983.44x_3 + 10972.97x_3^2 +$ $297.62x_2 + 297.64x_2x_3 + 0.02x_2x_3^2 + 9625.61x_2^2 -$ $1161.80x_2^2x_3 + 0.01x_2^2x_3^2 + 811.93x_2^3 +$ $2745.14x_2^4 - 10648.11x_1 + 3101.42x_1x_3 +$
CAV13-2	$105x^4 + x^2(140y^2 + 24y(5z + 7) + 35z(3z + 8)) +$ $2(70y^3z + 5y^2(12z^2 + 21z + 28) - 14y(6z^3 + 5z^2 +$ $10) - 35(3z^4 + 8z^2 + 4z - 9)) < 14x(20x^2(z + 1) +$ $10y^2(z + 2) - 3y(4z^2 - 5z + 4) - 20z(z^2 + 2))$	$8646.17x_1x_3^2 + 511.84x_1x_2 - 1034x_1x_2x_3 +$ $0.02x_1x_2x_3^2 + 9233.66x_1x_2^2 + 1342.55x_1x_2^2x_3 -$ $138.70x_1x_2^3 + 11476.61x_1^2 - 3737.70x_1^2x_3 +$ $4071.65x_1^2x_3^2 - 2153.00x_1x_2x_2 + 373.14x_1^2x_2x_3 +$ $7616.18x_1^2x_2^2 + 8950.77x_1^3 + 1937.92x_1^3x_3 -$ $64.07x_1^3x_2 + 4827.25x_1^4 > 0$
CAV13-3	$-1 + \frac{2\kappa_1}{99} < 0$	$-1.3983\kappa_1 + 69.358 > 0$
Sharper-1	$2 + y < y^2$	$34y^2 - 68y - 102 \geq 0$
Sharper-2	$y > 0$	$8y + 4x^2 > 0$
IJCAR16-2	$x_1 < x_2$	$-x_1 + x_2 > 0$
CAV13-4	$2xa + 4ya > 5$	$716.77 + 1326.74(ya) + 1.33(ya)^2 + 433.90(ya)^3 +$ $668.16(ya) - 155.86(ya)(ya) + 317.29(ya)(ya)^2 +$ $222.00(ya)^2 + 592.39(ya)^2(ya) + 271.11(ya)^3 > 0$
TACAS16	$15x^2 < 4 + 20y$	$y > 1.8 \vee (0.59 \leq y \leq 1.8 \wedge -1.35 \leq x \leq 1.35) \vee$ $(0.09 \leq y < 0.59 \wedge -0.77 \leq x \leq 0.77) \vee$ $(y \geq 0 \wedge -0.3 \leq x \leq 0.3)$

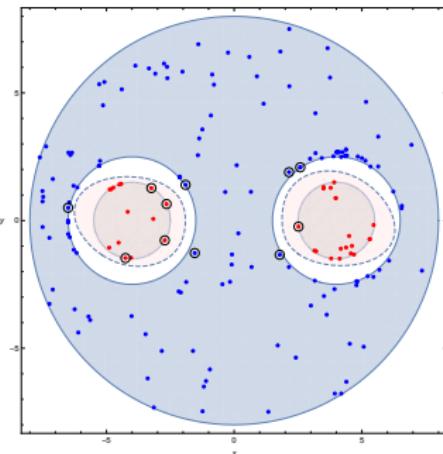
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# Perturbation-Resilient Interpolants



(a)  $\epsilon$ -perturbations in the radii



(b) Interpolant resilient to  $\epsilon$ -perturbations

**Figure –** Introducing  $\epsilon$ -perturbations (say with  $\epsilon$  up to 0.5) in  $\phi$  and  $\psi$ . The synthesized interpolant is hence resilient to any  $\epsilon$ -perturbation in the radii satisfying  $-0.5 \leq \epsilon \leq 0.5$ .

# Summary

**Problem:** We face that

- polynomial constraints have been shown useful to express invariant properties for programs and hybrid systems,
- little work on synthesizing nonlinear interpolants, which either restricts the input formulae or yields complex results.

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**Future Work :** We plan to

- improve the efficiency of NIL by substituting the general purpose QE procedure with alternative methods,
- combine nonlinear arithmetic with EUFs, by resorting to, e.g., predicate-abstraction techniques,
- investigate the performance of NIL over different classification techniques, e.g., the widespread regression-based methods.

# Probabilistic Craig Interpolants?

## Probabilistic Craig Interpolants?

- Generalized Craig Interpolation for stochastic-SAT : resolution-based BMC of MDPs.
  - ⇒ Teige, T., Fränzle, M. : *Generalized Craig Interpolation for Stochastic Boolean Satisf. Prob.*. TACAS '11.
- Generalized Craig Interpolation for stochastic-SMT : resolution-based UMC of PHA.
  - ⇒ Mahdi, A., Fränzle, M. : *Generalized Craig Interpolation for Stochastic Satisf. Modulo Theory Prob.*. RP '14.