

Exceptional precision using non-linear optical sensors at square root singularity

Reference: <https://journals.aps.org/prl/pdf/10.1103/PhysRevLett.129.013901>

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Agenda

- Introduction
- Setup and preliminary results
- Advantages
- Conclusion

Introduction to exceptional points

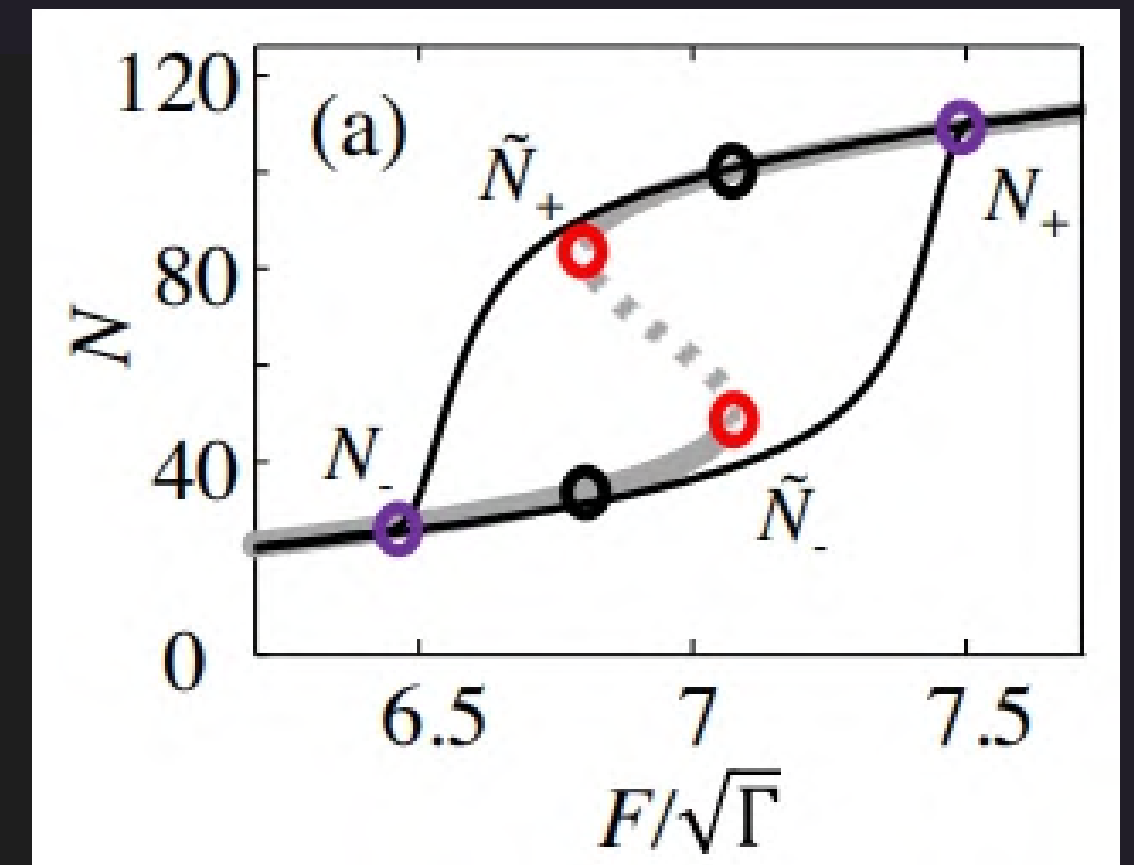
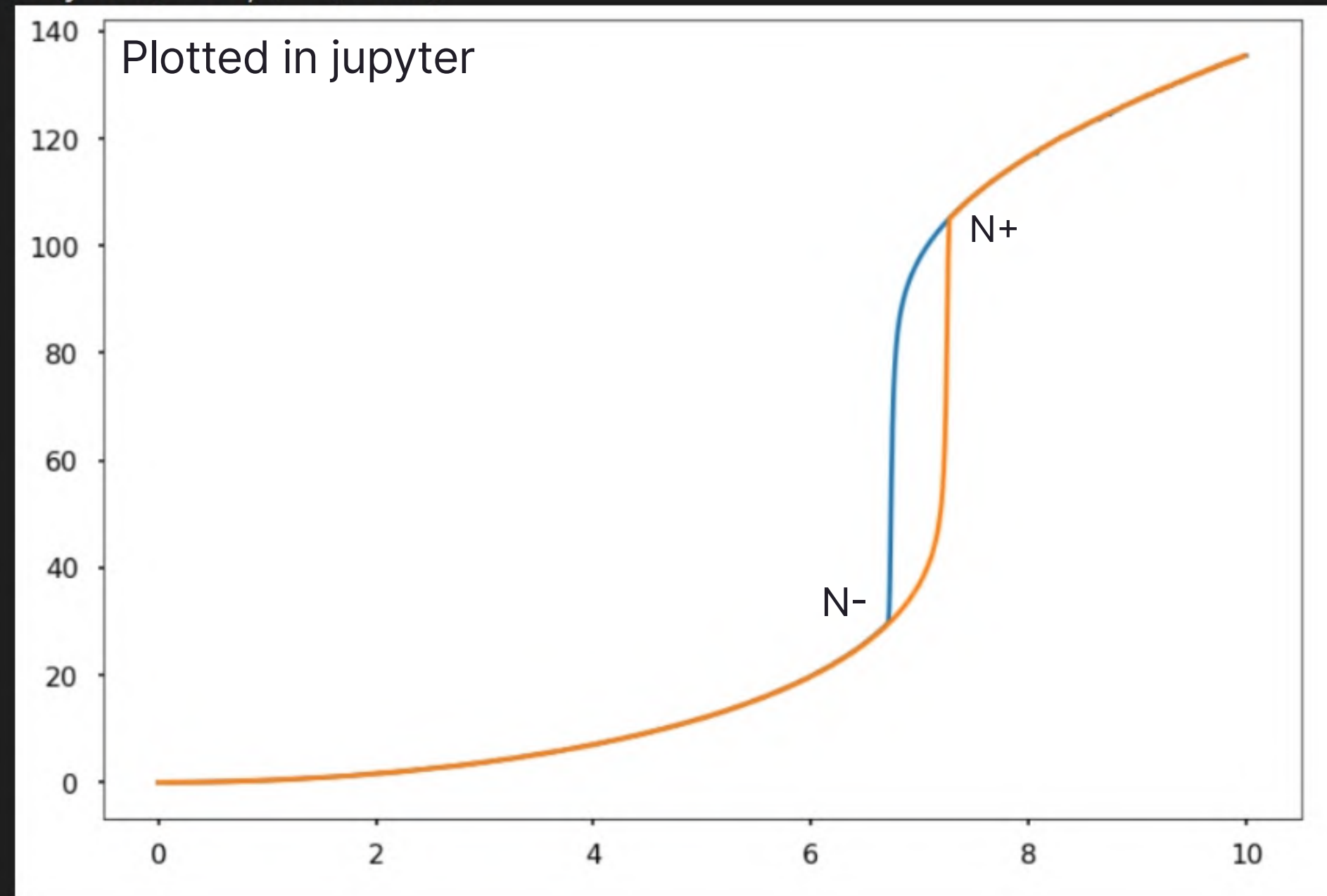
- Proposed by Wiersig in 2014
- Degeneracy in non-hermitian Hamiltonian is called an exceptional point (EP)
- Typical systems like 2 coupled non-linear oscillators show EP's
- Hamiltonian (assume $\hbar = 1$)

$$\begin{pmatrix} \omega_1 & g \\ g & \omega_2 \end{pmatrix}$$

- Eigenvalues: $\omega_{\pm} = \tilde{\omega}_{av} \pm \tilde{\Delta}/2 \sqrt{1 + (\frac{2g}{\tilde{\Delta}})^2}$ where $\tilde{\omega}_{av} = (\tilde{\omega}_1 + \tilde{\omega}_2)/2$ and $\tilde{\Delta} = \tilde{\omega}_1 - \tilde{\omega}_2$
- Here, exceptional point occurs at $\frac{2g}{\tilde{\Delta}} = i$ (square root singularity)
- Around exceptional point perturbation of the form $\text{Re}(\tilde{\omega}_i) + \epsilon$ results in a splitting $\text{Re}(\omega_+ - \omega_-) \propto \sqrt{\epsilon}$ for small ϵ
- Tradeoff: Highly sensitive to noise due to enhanced sensitivity

Alternative: Non-linear optical sensor

- Single mode coherently driven non-linear Kerr oscillator
- Measured signal: Splitting in transmitted intensities at 2 endpoints of hysteresis cycle
- N (y axis) vs $F/\sqrt{\Gamma}$ (x axis)



(reference plot)

For different initial values and parameters

N is the intracavity photon number: will see equation in further slides

Non-Linear Optical sensor cont...

- Realised using a Fabry-Perot setup or any other architecture (whispering gallery, ring, photonic crystal etc.) having one mode spectrally distant from other modes and probes an intensity dependent refractive index
- In a frame rotating at driving frequency ω intracavity field α obeys following equation $i\dot{\alpha}(t) = -\Delta - \frac{i\Gamma}{2} + U(|\alpha(t)|^2 - 1)\alpha(t) + i\sqrt{\kappa_L}F + D\xi(t)$
 - α : Intracavity Field
 - Δ : Detuning ($\omega - \omega_0$) where ω_0 is the resonance frequency
 - Γ : Total Loss= $\gamma + \kappa_L + \kappa_R$ where γ is intrinsic loss, κ_L, κ_R is loss through left and right ports respectively
 - U : Kerr non-linearity strength
 - F : Amplitude of input laser
 - $D\xi(t)$: Gaussian white noise with variance D^2

“

N which was plotted 2 slides ago is related to intracavity field by the equation

$$N = |\alpha|^2$$

– Shadab Anjum, student @ IITB

Hence, it is plotted by solving for α using the equation in previous slide

Solving for α

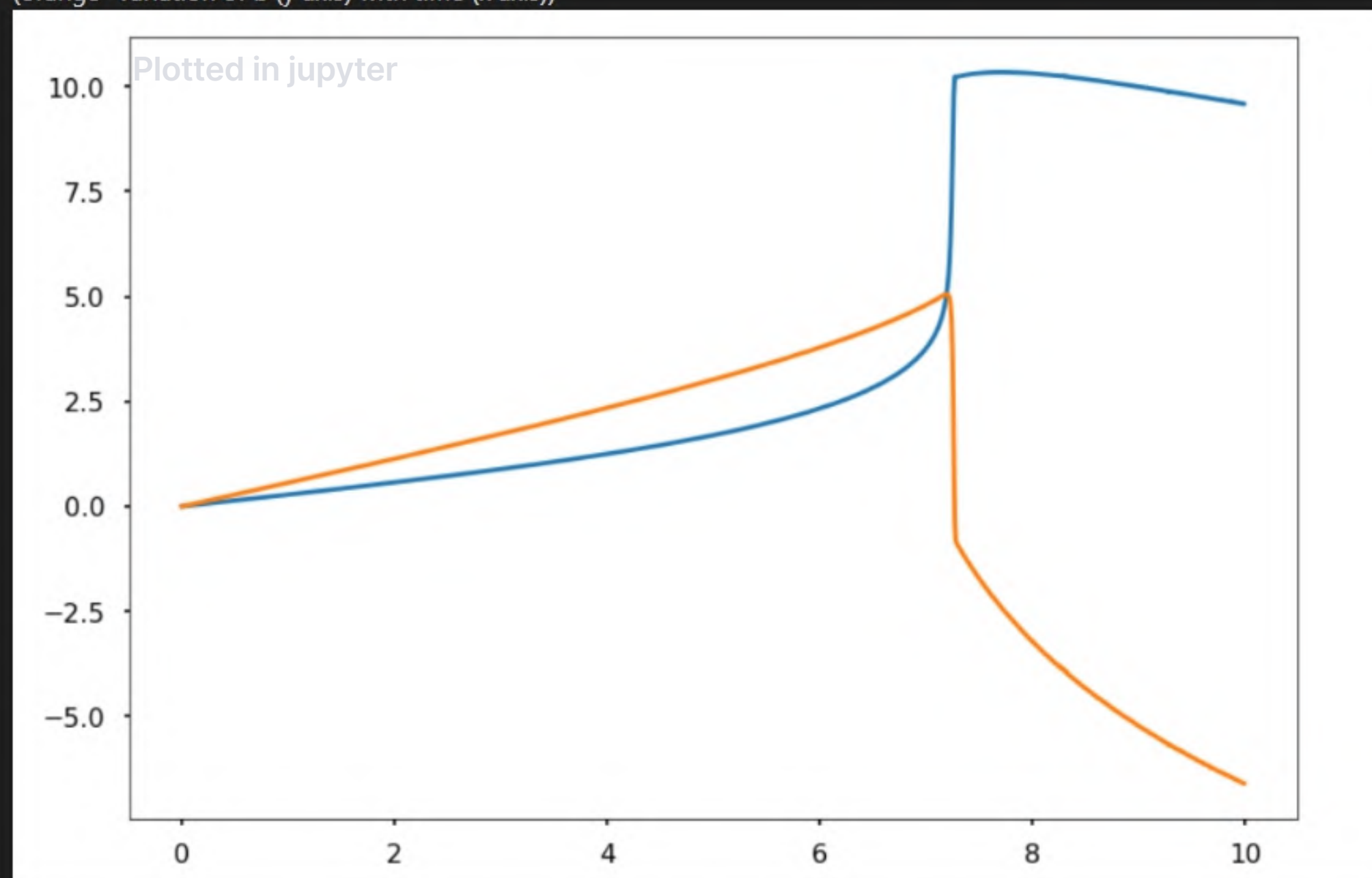
Setting α as $a+ib$ where a and b are real, we transform the equation for $\dot{\alpha}$ to the following coupled non-linear differential equations.

$$\begin{aligned}\dot{a} &= (-\Delta + U(a^2 + b^2 - 1))b - \frac{a\Gamma}{2} + \sqrt{\kappa_L}F \\ \dot{b} &= \frac{-b\Gamma}{2} - a(-\Delta + U(a^2 + b^2 - 1))\end{aligned}$$

Hence we can see U represents the strength of non-linearity in this equation

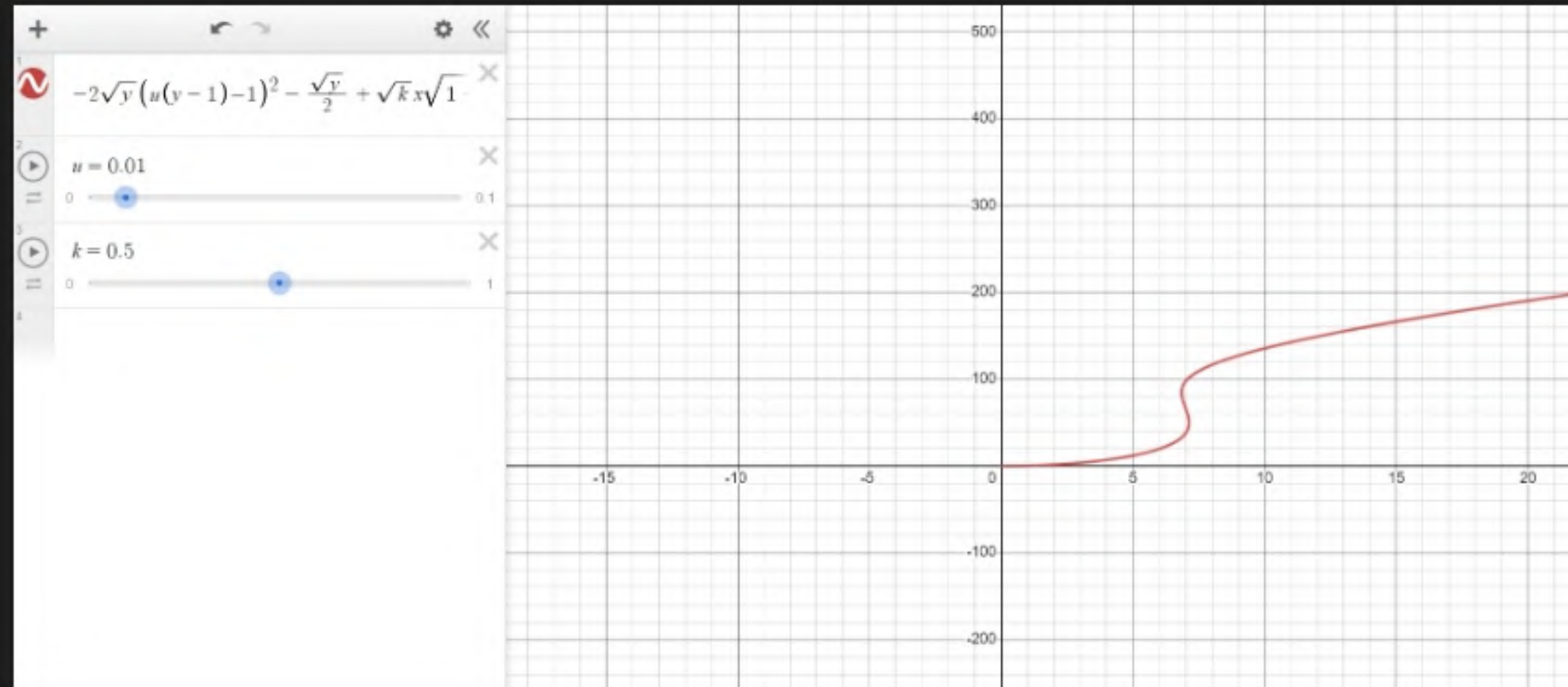
(blue- variation of a (y axis) with time (x axis))

(orange- variation of b (y axis) with time (x axis))



Steady state solutions

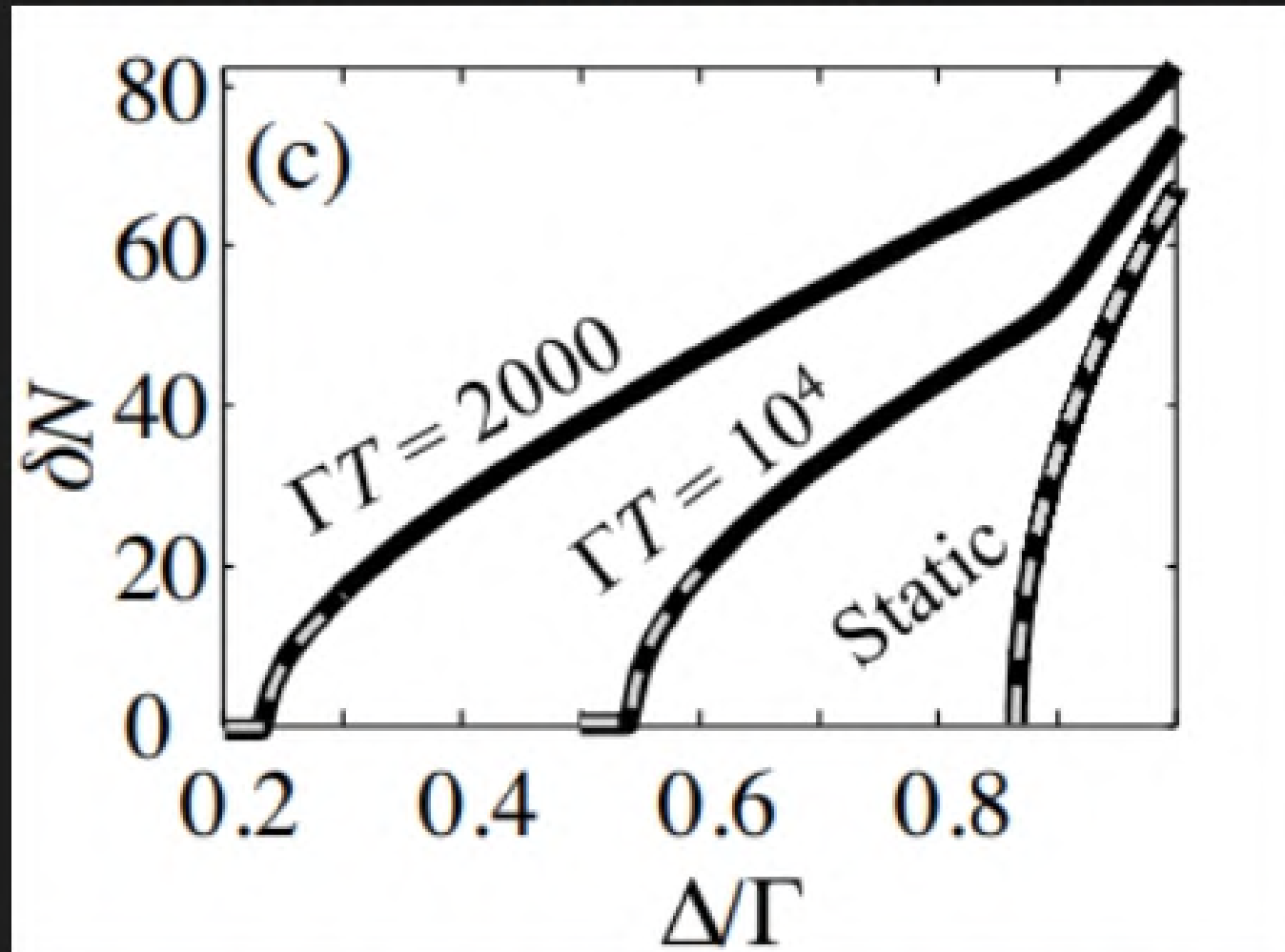
- Set $\dot{\alpha} = 0$ (steady state approximation)
- Also set $\frac{d|F|^2}{dN} = 0$ (turning points)
- Solutions are $\tilde{N}_{\pm} = \frac{2\Delta}{3U} \pm \frac{2\Delta}{6U} \sqrt{1 - \left(\frac{\sqrt{3}\Gamma}{2\Delta}\right)^2}$ (notice similarity with EP sensors)
- <https://www.desmos.com/calculator/zhxszbxbxrs>



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Properties

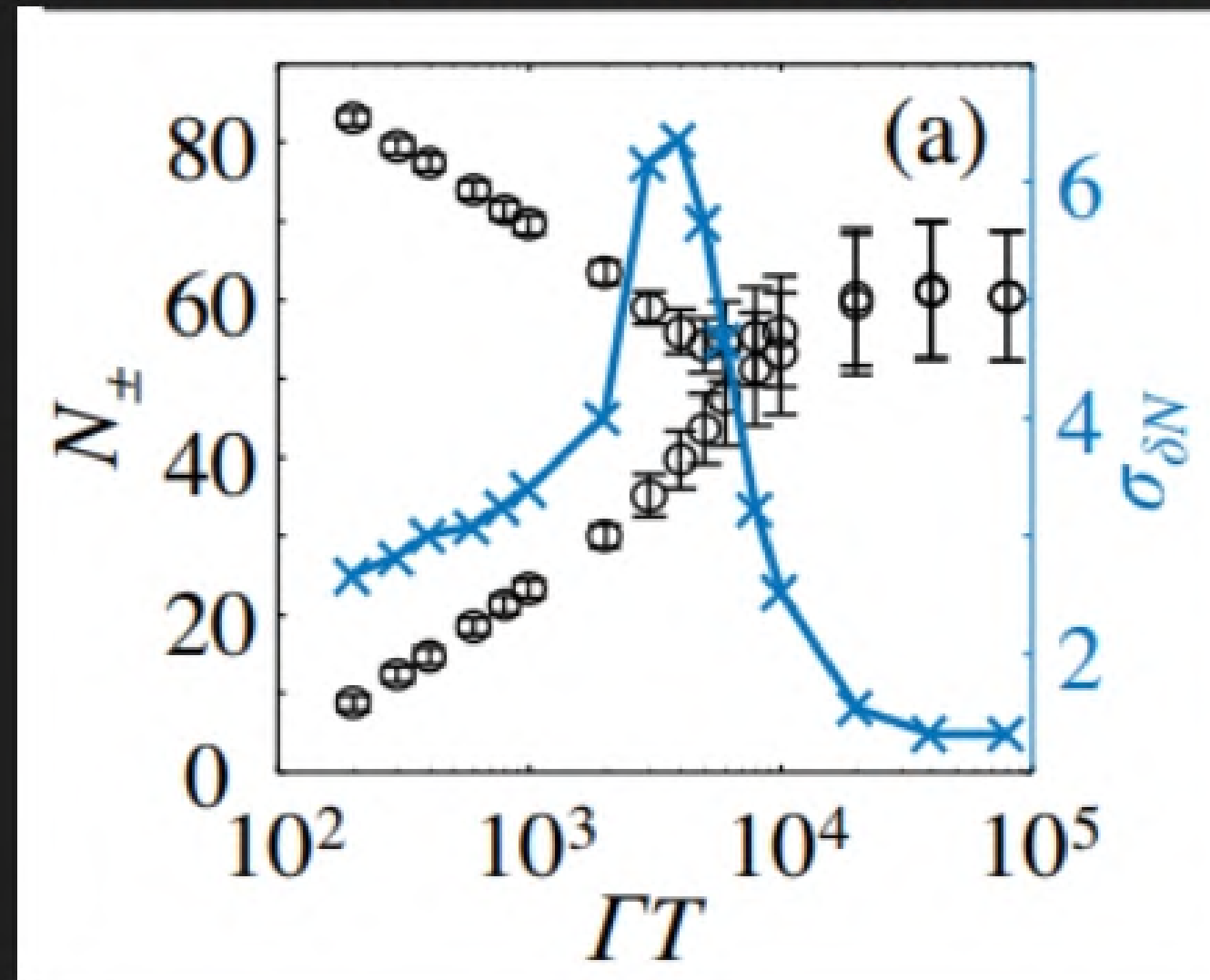
- Notice that the transmitted signal ($\delta N = N_+ - N_-$) depends on Δ and measurement time.
- The dependence (as plotted by the authors) has been shown below



- Observe: For faster measurement time, less detuning needed for signal \Rightarrow better sensitivity for faster measurement times.
- Dashed Lines: Square root fit near each singularity

Effects of Noise

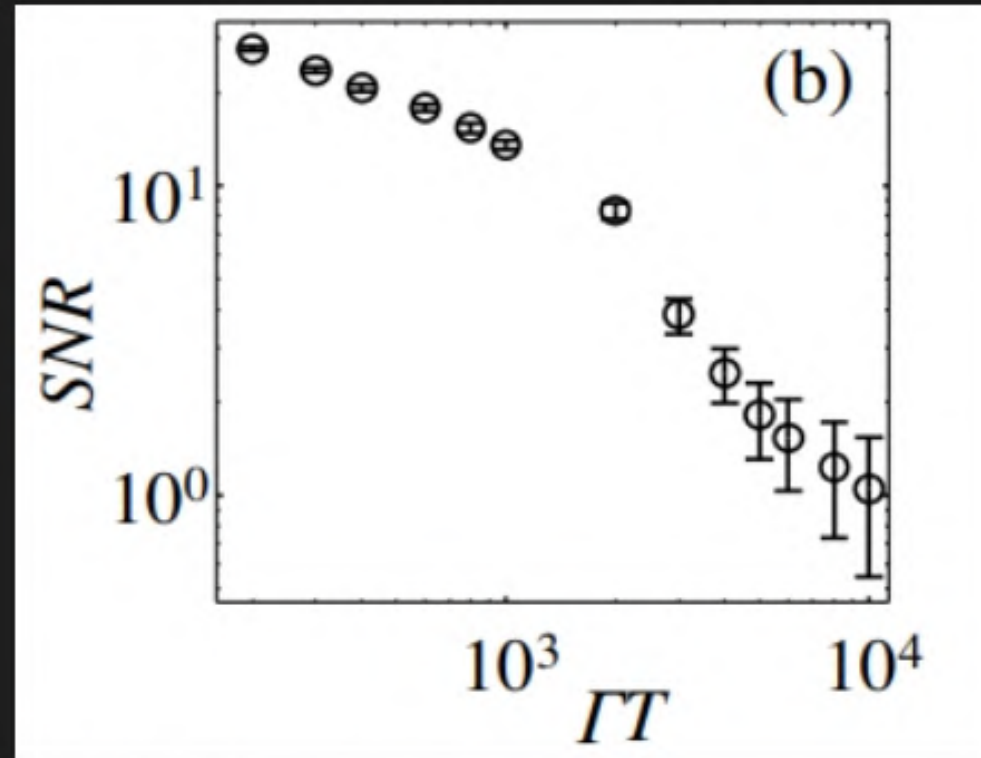
- Till now analysis was based on assumption $D=0$
- With noise, solve numerically with different random seeds



(reference plot)

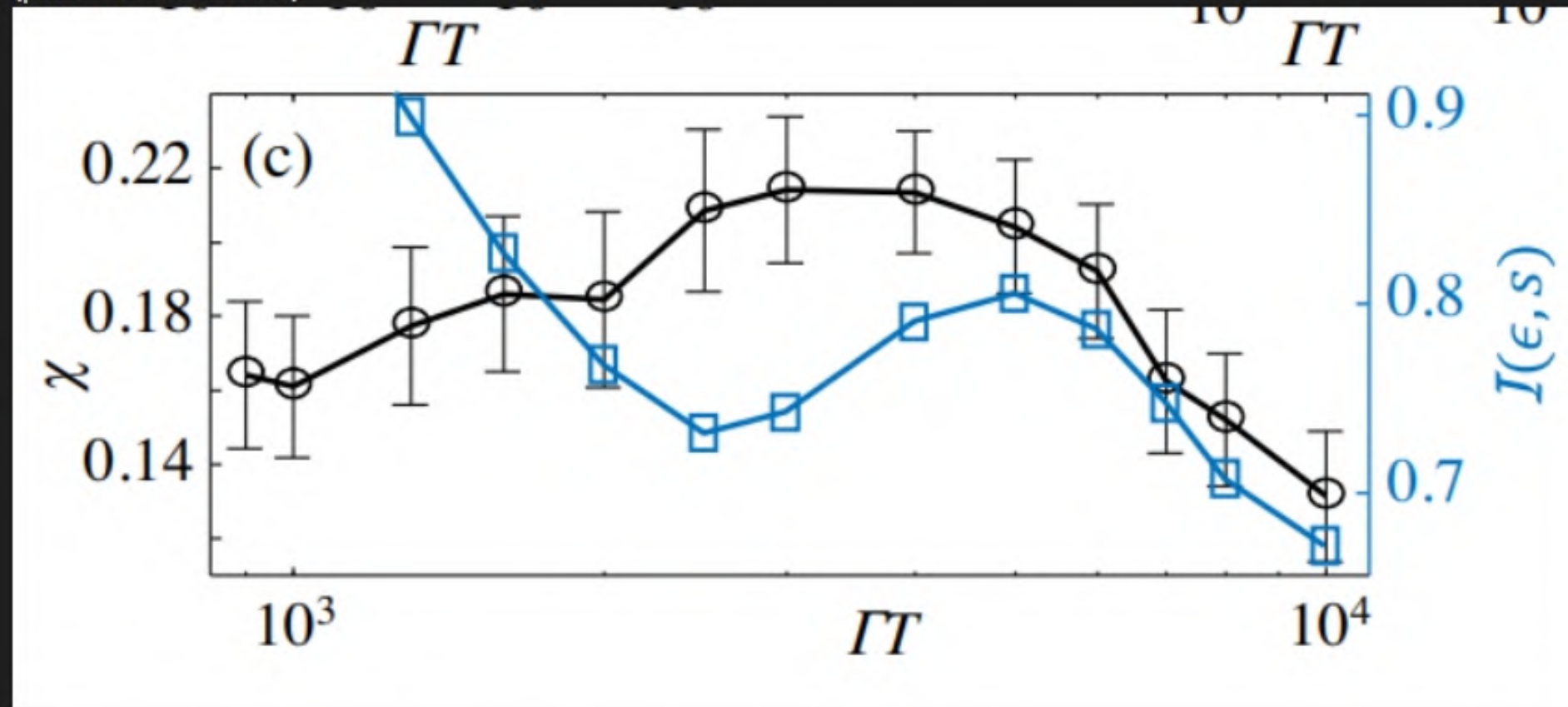
Parameters: $\Delta = 0.7\Gamma$

Advantages cont...



SNR increases with decrease in measurement time

(plots from reference)



Tradeoff between measurement time and precision

Peak occurs near T_{ss} : demonstrates precision enhancement by square root singularity

SNR: Signal to noise ratio defined as $\frac{\delta N}{\sigma_{\delta N}}$

χ : Precision figure of merit: $\frac{\delta \bar{N}_\epsilon - \delta \bar{N}_0}{\sigma_0 + \sigma_\epsilon}$; Quantifies the mean change in signal relative to measurement uncertainty

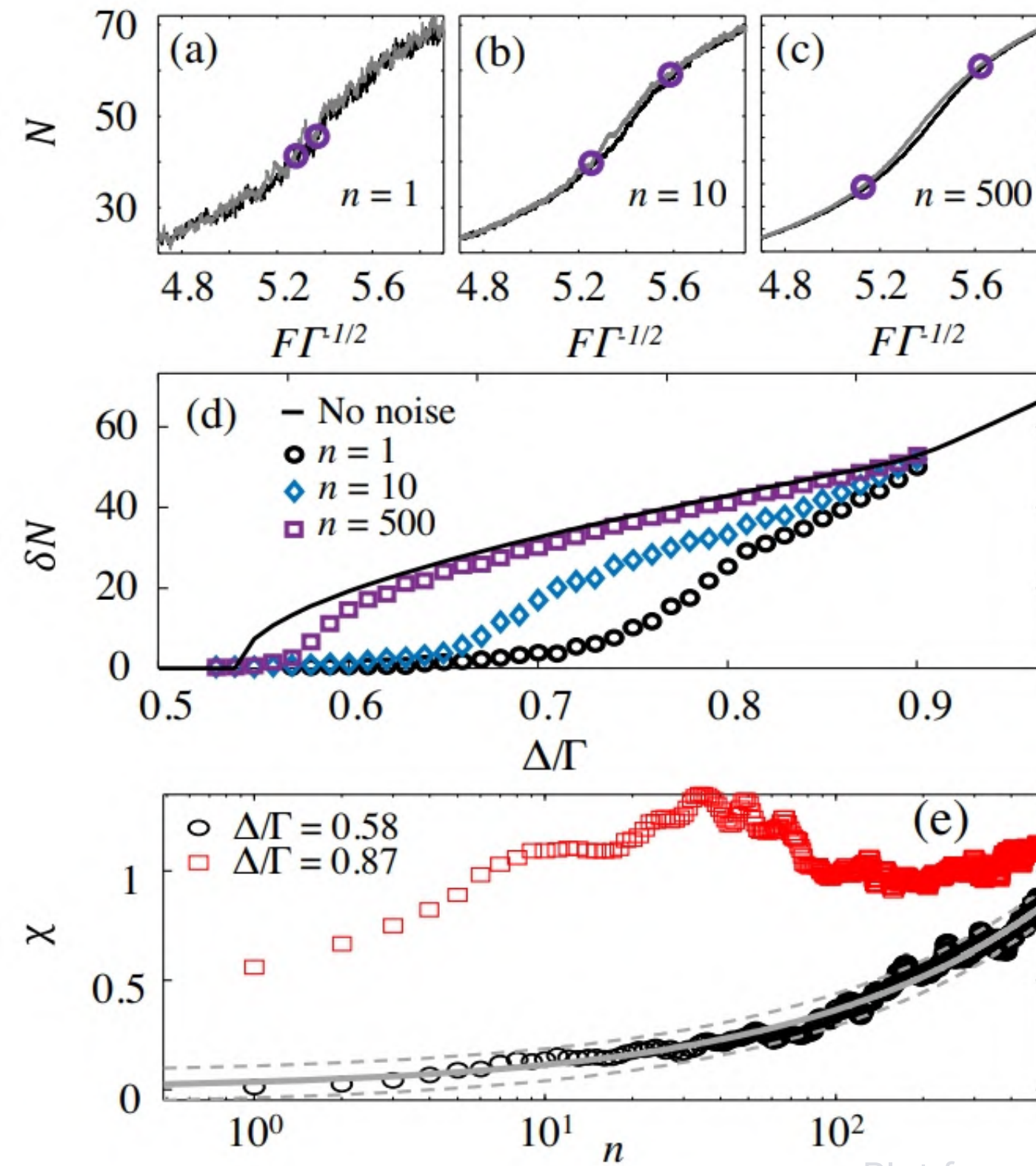
Alternative viewpoint: Information theory

- Mutual information between 2 random variables: Measure of certainty of a random variable given knowledge of the other variable
- $I(\epsilon; S) = \sum_{s \in S} \sum_{\epsilon \in E} p_{\epsilon, S}(\epsilon, s) \log \frac{p_{(\epsilon, S)}(\epsilon, s)}{p_{\epsilon}(\epsilon) p_S(s)}$ (from KL divergence between $p_{(\epsilon, S)}(\epsilon, s)$ and $p_{\epsilon} p_S(s)$)
- KL divergence: Measure of similarity between two probability distributions P and Q
- Set $p_{\epsilon}(\epsilon)$ gaussian with mean $\Gamma/100$ and $\sigma = \Gamma/1000$ and calculate $p_s(s)$ numerically using detuning $\Delta_0 = 0.7\Gamma$. Then based on value of s we get the joint probability distribution
- Observe the enhancement of information content near T_{ss}
- Correlation between square root singularity, mutual information and precision.
- Results are general for $\epsilon \ll \Gamma$

Effects of averaging

- Smoothens effects of noise thus improving precision
- For same protocol F , it enhances sensitivity
- Tradeoff: Measurement time vs precision: averaging detrimental to fast sensing
- Non-trivial dependence of χ on number of cycles n .
- Peak followed by fall (unexpected) followed by gradual rise (expected)

⇒ Possibility of model parameters having best of both worlds (speed and precision)



Plot from reference

Summary

**Square root singularity
improved precision,
information and
sensitivity**

**Simple monochromatic
intensity measurements as
sensing strategy, no error
prone spectral fittings as in EPs**

**Reduced
Measurement time
resulted in better
signal to noise ratio**

**Square root singularity
achieved easily using
commercially available
amplitude modulators**

A night photograph of a mountain range. The sky is dark blue with many stars. A bright shooting star streaks across the upper left. The mountains are rugged and rocky, with some snow on the peaks. A large, prominent rock formation is visible on the right side of the image.

Thank You !!