

Rhithik Raj K

Y Kannur - India



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ABOUT ME

Career-minded CSE student with a record of good marks in different subjects. Works hard on assignments and consistently meets objectives. Looking to experience the field outside the classroom and build foundational knowledge and skills. Having a CGPA of 8.16 in the 6th semester. Consistently working to update myself to meet the industry's needs. Hardworking, Self-Motivated student having good experience in Robotics, web development, Internet-of-Things, and Machine Learning.

EDUCATION

√ Vellore Institute of Technology

Bachelor of Technology - BTech, Computer Science with specialization in Artificial Intelligence and Robotics 2020 - 2024

✓ Peralassery Government Higher Secondary School Kannur Kerala

Computer Science 2018 - 2020

12th Grade: 93 Percentage

✓ Rani Jai Higher Secondary School

2017 - 2018

10th Grade: 98 Percentage

SKILLS

- ✓ Python
- ✓ C++
- ✓ C
- ✓ Java
- ✓ Django
- Arduino
- SQL
- HTML
- CSS

- ✓ Android Application Development
- Java Servlet
- ✓ Java FX
- ✓ Hardware
- ✓ Internet-of-Things
- ✓ Machine Learning
- ✓ UiPath Studio

CERTIFICATIONS

- ✓ Pandas Kaggle
- ✓ Python Kaggle
- Robotics Virtual Internship Kodacy
- ✓ Cybersecurity Roles, Processes & Operating System **Security** - Coursera

LANGUAGES

- ✓ English
- Malayalam
- Tamil
- Hindi

PROJECTS

Arduino Based Movable Robotic Arm

It is a Arduino based robot which can controlled using an Bluetooth enabled app, app is created using MIT App Inventor. It can also be able to detect the obstacle and pick if it is needed by autonomously.

Arduino Based Automated Safety Rover

It was completely done in online application called TinkerCad. It was Arduino based robot which will avoid the obstacle autonomously by detecting using ultrasonic sensors.

Automatic number plate detection

It was done using python pytesseract module. We have used car images that collected from real life to run the model.

✓ Agri Bot

Agri Bot is a rover which is used to monitor the agriculture field such as moisture content, temperature and the smoke content in the field. According to their readings needed changes are done in the field by users. The monitoring of the field can be done using a mobile application which can also control the movement of the rover by connecting them using Bluetooth. Also ESP32 cam module is also incorporated inorder to control them in long range