view frames Result Recorded at time: 1738540247.1011586 map Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 odom Broadcaster: default authority Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 suspension back left 1 suspension back right 1 suspension front left 1 chasis 1 base footprint joint suspension front right 1 Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: 10.211 Average rate: 10.211 Average rate: 10000.0 Buffer length: 4.799 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.799 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 1738540247.078385 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 1738540247.078385 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 1738540242.279568 Oldest transform: 1738540242.279568 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 direction back left 1 direction back right 1 direction front left 1 Lidar direction front right 1 Camara Broadcaster: default authority Average rate: 10.211 Average rate: 10.211 Average rate: $1\overline{0.211}$ Average rate: 10.211 Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Buffer length: 4.799 Buffer length: 0.0 Buffer length: 4.799 Buffer length: 4.799 Buffer length: 4.799 Buffer length: 0.0 Most recent transform: 1738540247.078385 Most recent transform: 1738540247.078385 Most recent transform: 1738540247.078385 Most recent transform: 1738540247.078385 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 1738540242.279568 Oldest transform: 1738540242.279568 Oldest transform: 1738540242.279568 Oldest transform: 1738540242.279568 Oldest transform: 0.0 Oldest transform: 0.0 rim_back_left_1 rim back right 1 rim_front_left_1 $lidar_optical_frame$ camera_optical_frame rim_front_right_1 Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 tire_back_left_1 tire front left 1 tire_front_right_1 tire_back_right_1