

# Huaiyuan Rao

☎ 470-257-9071 ✉ [hrao43@gatech.edu](mailto:hrao43@gatech.edu) 🌐 [github.com/huaiyuan-rao](https://github.com/huaiyuan-rao)

## Education

<b>Georgia Institute of Technology</b> <i>Master of Science in Electrical and Computer Engineering, GPA: 4.00 / 4.00</i>	2022-Present Atlanta, Georgia
<b>East China Jiaotong University</b> <i>Bachelor of Science in Automation, GPA: 3.96 / 5.00 (89.6 / 100)</i>	2018-2022 Nanchang, Jiangxi

## Experience

<b>Georgia Institute of Technology, CORE Lab (Buzzblimp team)</b> <i>Research Intern, Advisor: Prof. Matthew Hale</i> <ul style="list-style-type: none"><li>Deploy custom yolov5 model on rk3588 series NPU using multithreading, which run a yolov5 model in 120 fps.</li><li>Using ROS2 to rossify entire detecting framework and integrate with blimp's position and rotation control part.</li></ul>	June 2024 – Present Atlanta, Georgia
<b>Georgia Institute of Technology</b> <i>Research Intern, Advisor: Prof. Kyriakos G. Vamvoudakis</i> <ul style="list-style-type: none"><li>Leverage RRT<sup>X</sup> for global path planning and replanning to produce waypoints for agent.</li><li>Develop RL-CBF-RRT<sup>X</sup>, using a critic-only value network to online learn a reasonably larger portion of the actual safe set with user predefined rewards and generate safe controller for navigating in an unknown environment.</li></ul>	Jan 2024 – May 2023 Atlanta, Georgia
<b>Chinese University of Hong Kong (Shenzhen), Robotics &amp; AI Lab</b> <i>Research Intern, Advisor: Prof. Zhenglong Sun</i> <ul style="list-style-type: none"><li>Using Sparse Identification of nonlinear dynamical systems (SINDy) to approximate continuum robot's model.</li><li>Develop model reference reinforcement learning framework. Using MPC to tracking desired model output and using RL to compensate the disturbance between real world model and reference model.</li></ul>	May 2023 – Dec 2023 Shenzhen, Guangdong
<b>East China Jiaotong University, Intelligent Driving Team</b> <i>Captain &amp; Founder, Advisor: Yun Yang</i> <ul style="list-style-type: none"><li>Develop the Fuzzy Adaptive IMM (FAIMM) target tracking algorithm for vehicle detection on the AWR1843-BOOST (Texas Instruments) platform, designed to operate in harsh environments. This system will provide drivers with real-time updates on the distance and angle to the car ahead.</li></ul>	May 2020 – June 2022 Nanchang, Jiangxi

## Publications

- **Huaiyuan Rao**, Yichen Zhao, Qiang Lai. Predicting Chaotic System Behavior using Machine Learning Techniques. *Preprint*

## Selected Projects

<b>Predicting Chaotic System Behavior using Machine Learning Techniques.</b>   Georgia Tech	March 2024 - August 2024
<ul style="list-style-type: none"><li>Comparing prediction capability of reservoir computing, next-generation reservoir computing and LSTM on chaotic system behavior.</li></ul>	
<b>Chaotic image encryption algorithm</b>   Graduation Design, ECJTU	Dec 2021 - June 2022
<ul style="list-style-type: none"><li>Develop <b>CMT-ICSM</b>, an image encryption algorithm that integrates a novel Sine-Henon high dimensional map (ICSM) with the chaotic magic transform (CMT).</li></ul>	

## Selected Awards and Honors

<b>China National Scholarship</b>	2021
<b>Finalist Prize</b> , COMAP's Mathematical Contest in Modeling (Top 1%)	2022
<b>1st class Academic Scholarship</b> (3 years)	2021
<b>Second Prize</b> , National Undergraduate Electronics Design Contest	2020

## Technical Skills

**Program:** C, C++, Python, MATLAB

**Tools:** ROS2 and Gazebo, Linux, Git, OpenCV, STM32, LATEX