

$$x = 21$$

$$x = x_1 + x_p$$

$$x = c_1 \cdot e^{-\frac{1}{2}t} + 21, \quad \text{if } c_1 \in \mathbb{R}$$

$$x(0) = c_1 + 21 = m = c_1 - m - 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

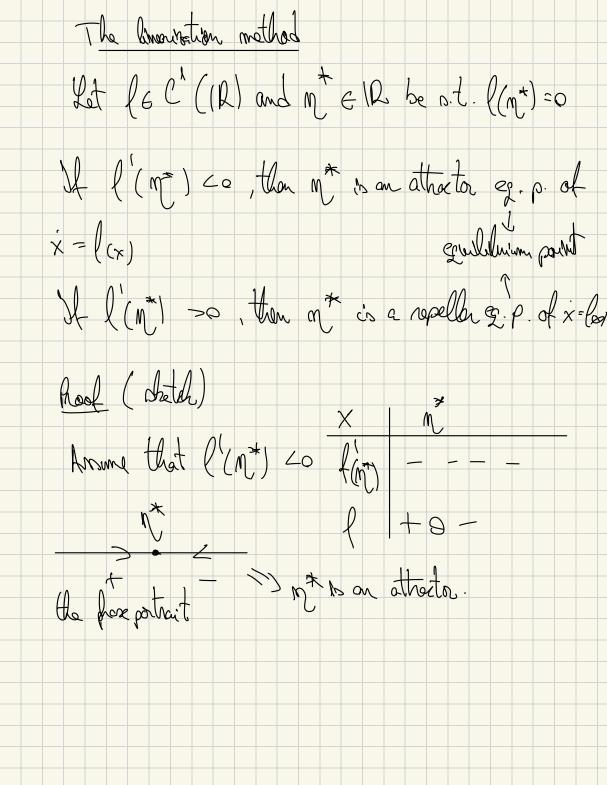
$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

$$x(0) = (m - 21) \cdot e^{-\frac{1}{2}t} + 21$$

m = 70



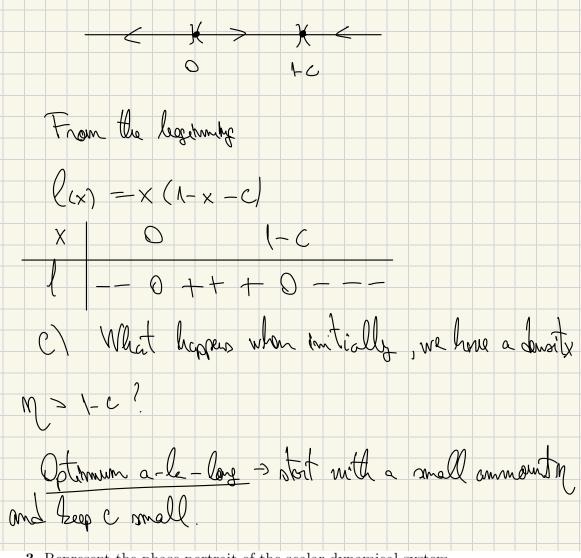
2. Let 
$$0 < c < 1$$
 be a parameter and consider the scalar dynamical system  $\dot{x} = x(1-x) - cx$ .

As Find its equilibria and study their stability using the linearization method.

Frepresent its phase portrait.

Colline a mobile.

Colline a



3. Represent the phase portrait of the scalar dynamical system

 $\dot{x} = x - x^3$ . Find  $\varphi(t, -1)$  and  $\varphi(t, 0)$  and justify. Specify the properties of the functions  $\varphi(t, -2)$ ,  $\varphi(t, 3)$  and, respectively,  $\varphi(t, -0.5)$ .

$$\hat{x} = x - x^{3}$$

$$l_{(x)} = x \left( 1 - x^{2} \right) = 0$$

$$x_{1} = 0 ; x_{2} = -1; x_{3} = 1 \quad (3 \text{ eg. points})$$

$$\begin{cases} (x) = -3x^2 + 1 \\ (\log x) = 1 & 20 \end{cases}$$

$$\begin{cases} (\log x) = -2 \end{cases}$$

$$(\log x)$$

