

Lecture 12: Bayesian Inference - I

Bayes' Theorem:

Consider two events A and B , defined on the sample space S . Then

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{P(A)P(B|A)}{P(B)}$$

$$= \frac{P(A)P(B|A)}{P(A \cap B) + P(A' \cap B)}$$

$$= \frac{P(A)P(B|A)}{P(A)P(B|A) + P(A')P(B|A')}$$

Here $P(A)$ = prior probability of A

$P(A|B)$ = posterior probability of A

$P(B|A)$ = likelihood

Now consider a r.v. X that has a probability distribution that depends on θ , where θ is an element of a well-defined set Ω . For example, if the symbol θ is the mean of a normal distribution, then Ω may be the real line (\mathbb{R}).

Let Θ be a r.v. that is distributed over the set Ω . Let $h(\theta)$ be the pdf of Θ . Then $h(\theta)$ is the prior pdf of Θ .

Thus, $f(x|\theta)$, is the conditional pdf of X .

We have $X|\theta \sim f(x|\theta)$, $\Theta \sim h(\theta)$.

Suppose X_1, X_2, \dots, X_n is a random sample from $f(x|\theta)$. Then the likelihood function

$$L(x|\theta) = f(x_1|\theta) f(x_2|\theta) \dots f(x_n|\theta)$$

defines the joint conditional pdf of \underline{X} , given $(H) = \theta$.

The joint pdf of \underline{X} and (H) is

$$g(\underline{x}, \theta) = L(\underline{x}|\theta)h(\theta)$$

So $g_1(\underline{x}) = \int_{-\infty}^{\infty} g(\underline{x}, \theta) d\theta$ if (H) is continuous

The conditional pdf (H) given \underline{X} , is

$$k(\theta|\underline{x}) = \frac{g(\underline{x}, \theta)}{g_1(\underline{x})} = \frac{L(\underline{x}|\theta)h(\theta)}{g_1(\underline{x})}$$

Here, $k(\theta|\underline{x})$ is called the posterior pdf of (H) .

Example 1:

Consider the model

$$X_i|\theta \sim \text{iid Poisson}(\theta)$$

$$(H) \sim \Gamma(\alpha, \beta), \text{ where } \alpha, \beta \text{ are known}$$

let $\underline{X}' = (X_1, X_2, \dots, X_n)$.

$$L(\underline{x}|\theta) = \prod_{i=1}^n \theta^{x_i} e^{-\theta} / x_i!, \quad x_i = 0, 1, 2, \dots, \\ i = 1, 2, \dots, n.$$

and the prior pdf is

$$h(\theta) = \frac{\theta^{\alpha-1} e^{-\theta/\beta}}{\Gamma(\alpha) \beta^\alpha}, \quad \theta < \infty$$

The joint pdf

$$g(\underline{x}, \theta) = L(\underline{x}|\theta) h(\theta)$$

$$= \left[\frac{\theta^{x_1} e^{-\theta}}{x_1!} \dots \frac{\theta^{x_n} e^{-\theta}}{x_n!} \right] \left[\frac{\theta^{\alpha-1} e^{-\theta/\beta}}{\Gamma(\alpha) \beta^\alpha} \right],$$

provided that $x_i = 0, 1, 2, 3, \dots$, $i = 1, 2, \dots, n$ and $0 < \theta < \infty$.

The marginal distribution of the sample

$$g_i(\underline{x}) = \int_0^\infty \frac{\theta^{\sum x_i + \alpha - 1} e^{-(n+1/\beta)\theta}}{x_1! x_2! \dots x_n! \Gamma(\alpha) \beta^\alpha} d\theta$$

$$= \frac{\Gamma(\sum_{i=1}^n x_i + \alpha)}{x_1! \dots x_n! \Gamma(\alpha) \beta^\alpha (n+1/\beta)^{\sum x_i + \alpha}}$$

The posterior pdf of (H) , given $\underline{X} = \underline{x}$ is

$$\begin{aligned} k(\theta | \underline{x}) &= \frac{L(\underline{x} | \theta) h(\theta)}{g_1(\underline{x})} \\ &= \frac{\theta^{\sum x_i + \alpha - 1} e^{-\theta / (\beta / (n\beta + 1))}}{\Gamma(\sum x_i + \alpha) [\beta / (n\beta + 1)]^{\sum x_i + \alpha}} \end{aligned}$$

provided that $0 < \theta < \infty$. This

conditional pdf is of the gamma type, with parameters

$$\alpha^* = \sum_{i=1}^n x_i + \alpha$$

$$\beta^* = \beta / (n\beta + 1)$$

Note that it is not really necessary to determine the marginal pdf $g_1(\underline{x})$ to find the posterior pdf $K(\theta|\underline{x})$.

Dividing $L(\underline{x}|\theta)h(\theta)$ by $g_1(\underline{x})$ yields $c(\underline{x}) \theta^{\sum x_i + \alpha - 1} e^{-\theta/\beta/(n\beta + 1)}$,

where $c(\underline{x})$ does not depend on θ .

Therefore

$$K(\theta|\underline{x}) = c(\underline{x}) \theta^{\sum x_i + \alpha - 1} e^{-\theta/\beta/(n\beta + 1)},$$

provided that $0 < \theta < \infty$, and $x_i = 0, 1, 2, \dots$,

$i = 1, 2, \dots, n$. However, $c(\underline{x})$ must be

a constant needed to make $K(\theta|\underline{x})$

a pdf i.e. $c(\underline{x}) = \frac{1}{\Gamma(\sum x_i + \alpha) [\beta/(n\beta + 1)]^{\sum x_i + \alpha}}$

So, $K(\theta|\underline{x}) \propto L(\underline{x}|\theta)h(\theta)$

Here, we write

$$K(\theta | \underline{x}) \propto \theta^{\sum_{i=1}^n x_i + \alpha - 1} e^{-\theta / [\beta / (n\beta + 1)]},$$

$0 < \theta < \infty$. Clearly, $K(\theta | \underline{x})$ is a gamma pdf with parameters

$$\alpha^* = \sum_{i=1}^n x_i + \alpha, \quad \beta^* = \beta / (n\beta + 1)$$

Now suppose that there exists a sufficient statistic $Y = u(\underline{x})$ for θ

so that $L(\underline{x} | \theta) = g[u(\underline{x}) | \theta] H(\underline{x})$,

where $g(y | \theta)$ is the pdf of Y , given

$\Theta = \theta$. Then $K(\theta | \underline{x}) \propto g[u(\underline{x}) | \theta] h(\theta)$,

since $H(\underline{x})$ does not depend on θ and

hence can be dropped. We can then

write $K(\theta | y) \propto g(y | \theta) h(\theta)$. In the continuous

case, $g_i(y) = \int_{-\infty}^{\infty} g(y | \theta) h(\theta) d\theta$.

Bayesian Point Estimation

Suppose we wish to find a point estimator of θ . Then we must select a decision function $\delta(x)$, so that $\delta(x)$ is a predicted value of θ when both the computed value x and conditional pdf $K(\theta|x)$ are known. The choice of this decision function depends on a loss function $L(\theta, \delta(x))$ in such a way that the conditional expectation of the loss is a minimum. So a Bayes estimate is a decision function $\delta(x)$ that minimizes

$$E\{L(\Theta, \delta(\underline{x})) | \underline{X} = \underline{x}\} = \int_{-\infty}^{\infty} L(\theta, \delta(\underline{x})) K(\theta | \underline{x}) d\theta$$

i.e. $\delta(\underline{x}) = \operatorname{argmin}_{\delta} \int_{-\infty}^{\infty} L(\theta, \delta(\underline{x})) K(\theta | \underline{x}) d\theta.$

Note:

a) If $L(\theta, \delta(\underline{x})) = (\theta - \delta(\underline{x}))^2$, then

$\delta(\underline{x}) = E(\Theta | \underline{x})$, the mean of the conditional distribution of Θ , given $\underline{X} = \underline{x}$.

This follows from the fact that

$$E[(W - b)^2] \text{ is a minimum}$$

when $b = E(W)$.

b) If $L(\theta, \delta(\underline{x})) = |\theta - \delta(\underline{x})|$, then

$\delta(\underline{x}) = \operatorname{med}(\Theta | \underline{x})$, the median of the conditional distribution.

This follows from the fact that

$E(|W-b|)$ is a minimum when

$b = \text{median of the distribution of } W.$

But the conditional expectation of the loss function, given $\underline{X} = \underline{x}$ is a r.v. that is a function of \underline{x} . Its

expected value is

$$\int_{-\infty}^{\infty} \left\{ \int_{-\infty}^{\infty} L(\theta, \delta(\underline{x})) K(\theta|\underline{x}) d\theta \right\} g_1(\underline{x}) d\underline{x}$$

$$= \int_{-\infty}^{\infty} \left\{ \int_{-\infty}^{\infty} L(\theta, \delta(\underline{x})) L(\underline{x}|\theta) d\underline{x} \right\} h(\theta) d\theta \quad \text{--- ①}$$

Here $\int_{-\infty}^{\infty} L(\theta, \delta(\underline{x})) L(\underline{x}|\theta) d\underline{x} = R(\theta, \delta)$, the

risk function.

So ① above defines the mean risk or expected risk

Thus, a Bayes estimate $\delta(x)$ minimizes

$$\int_{-\infty}^{\infty} L(\theta, \delta(x)) K(\theta|x) d\theta \quad \text{for every } x$$

for which $g(x) > 0$, also minimizes the mean value of the risk.

Example 2:

Consider $X_i|\theta \sim \text{iid } b(1, \theta)$

$\theta \sim \text{beta}(\alpha, \beta)$, α and β are known

$$\text{i.e. } h(\theta) = \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)} \theta^{\alpha-1} (1-\theta)^{\beta-1}, \quad 0 < \theta < 1$$

We are seeking for $\delta(x)$ that is a Bayes solution.

Now, $Y = \sum_{i=1}^n X_i$ is a sufficient statistic for θ , and $Y \sim b(n, \theta)$

$$g(y|\theta) = \binom{n}{y} \theta^y (1-\theta)^{n-y}, \quad y = 0, 1, 2, \dots$$

Therefore, $k(\theta|y) \propto \theta^y (1-\theta)^{n-y} \theta^{\alpha-1} (1-\theta)^{\beta-1}$,
 $0 < \theta < 1$.

i.e. $k(\theta|y) = \frac{\Gamma(n+\alpha+\beta)}{\Gamma(\alpha+y)\Gamma(n+\beta-y)} \theta^{y+\alpha-1} (1-\theta)^{n-y+\beta-1}$

$$\equiv \text{beta}(\alpha+y, \beta+n-y)$$

For $L(\theta, \delta(y)) = [\theta - \delta(y)]^2$, (square error loss),

$$\delta(y) = \frac{\alpha+y}{\alpha+\beta+n}.$$

$$= \left(\frac{n}{\alpha+\beta+n} \right) \frac{y}{n} + \left(\frac{\alpha+\beta}{\alpha+\beta+n} \right) \frac{\alpha}{\alpha+\beta},$$

a weighted average of the MLE of θ and the mean $\alpha/(\alpha+\beta)$ of the prior pdf of the parameter.

For large n , the Bayes estimate is close to the MLE of θ and $\delta(Y)$ is a consistent estimator of θ .

Exercise (fill in missing steps)

Consider $X_i | \theta \sim \text{iid } N(\theta, \sigma^2)$, σ^2 known

$(\theta) \sim N(\theta_0, \sigma_0^2)$, where θ_0 and σ_0^2 are known.

Then $Y = \bar{X}$ is a sufficient statistic.

Equivalent formulation:

$$Y | \theta \sim N(\theta, \sigma^2/n)$$

$$(\theta) \sim N(\theta_0, \sigma_0^2)$$

Here $K(\theta | y) \propto \frac{1}{\sqrt{2\pi}\sigma/\sqrt{n}} \cdot \frac{1}{\sqrt{2\pi}\sigma_0} \exp \left[\frac{-(y-\theta)^2}{2(\sigma^2/n)} - \frac{(\theta-\theta_0)^2}{2\sigma_0^2} \right]$

After eliminating all constant factors, we have

$$K(\theta|y) \propto \exp \left[- \frac{[\sigma_0^2 + (\sigma^2/n)] \theta^2 - 2[y\sigma_0^2 + \theta_0(\sigma^2/n)] \theta}{2(\sigma^2/n) \sigma_0^2} \right]$$

This can be simplified by completing the square to become:

$$K(\theta|y) \propto \exp \left[- \frac{\left(\theta - \frac{y\sigma_0^2 + \theta_0(\sigma^2/n)}{\sigma_0^2 + (\sigma^2/n)} \right)^2}{\frac{2(\sigma^2/n) \sigma_0^2}{[\sigma_0^2 + (\sigma^2/n)]}} \right]$$

So, the posterior pdf of the parameter is normal with mean

$$\begin{aligned} \frac{y\sigma_0^2 + \theta_0(\sigma^2/n)}{\sigma_0^2 + (\sigma^2/n)} &= \left(\frac{\sigma_0^2}{\sigma_0^2 + (\sigma^2/n)} \right) y \\ &\quad + \left(\frac{\sigma^2/n}{\sigma_0^2 + (\sigma^2/n)} \right) \theta_0 \end{aligned}$$

and variance $(\sigma^2/n) \sigma_0^2 / [\sigma_0^2 + (\sigma^2/n)]$

If the squared-error loss function is used, then this posterior mean is the Bayes estimator, which is a weighted average of MLE $y = \bar{x}$ and the prior mean θ_0 .

For large n , the Bayes estimator is close to the MLE and $\delta(Y)$ is consistent θ .

If the absolute-error loss function was used, the Bayes solution, $\delta(Y)$, would be the median of the posterior distribution.

Bayesian Interval Estimation

To obtain an interval estimate of θ , we find two functions $u(\underline{x})$ and $v(\underline{x})$

so that $P(u(\underline{x}) < \Theta < v(\underline{x}) \mid X = \underline{x})$

$$= \int_{u(\underline{x})}^{v(\underline{x})} \kappa(\theta \mid \underline{x}) d\theta$$

is large, say 0.95. The interval $(u(\underline{x}), v(\underline{x}))$ is an interval estimate of θ in that the conditional probability of Θ being there is 0.95 (say). Such an interval is called credible or probability interval.

In the Exercise above, the posterior pdf of Θ given $Y = y$ had mean $\frac{y\sigma_0^2 + \theta_0(\sigma^2/n)}{\sigma_0^2 + (\sigma^2/n)}$ and variance $(\sigma^2/n)\sigma_0^2/(\sigma_0^2 + (\sigma^2/n))$.

Thus, a credible interval of probability 0.95

for θ is
$$\frac{y\sigma_0^2 + \theta_0(\sigma^2/n)}{\sigma_0^2 + (\sigma^2/n)} \pm 1.96 \sqrt{\frac{(\sigma^2/n)\sigma_0^2}{\sigma_0^2 + (\sigma^2/n)}}$$

In Example 1, the posterior pdf was

$\Gamma(y+\alpha, \beta/(n\beta+1))$, where $y = \sum x_i$ (the sufficient statistic for θ).

$$\delta(y) = \frac{\beta(y+\alpha)}{n\beta+1} = \left(\frac{n\beta}{n\beta+1}\right) \frac{y}{n} + \left(\frac{\alpha\beta}{n\beta+1}\right)$$

Note that $\frac{2(n\beta+1)}{\beta} (H) \sim \chi^2(df = 2(\sum x_i + \alpha))$

Therefore, the $100(1-\alpha)\%$ credible interval for θ is:

$$\left(\frac{\beta}{2(n\beta+1)} \chi^2_{1-\alpha/2} \left[2 \left(\sum_1^n x_i + \alpha \right) \right], \frac{\beta}{2(n\beta+1)} \chi^2_{\alpha/2} \left[2 \left(\sum_1^n x_i + \alpha \right) \right] \right)$$