

# Introduction to Deep Learning and Transfer Learning



# Global formalism

## Input/output

- **Goal:** infer a function from an input (often tensor) space to an output (often tensor) space,  $\mathbf{y} = f(\mathbf{x})$ ,
- **Example:** input can be an image, output a vector where the largest value indicate the category the image belongs to.

## Error/Loss

- **Loss:** nonnegative measure of the discrepancy between expected output  $\hat{\mathbf{y}}$  and obtained output  $\mathbf{y}$ .
- **Example:** output should be  $[0, 1]$  but is  $[0.2, 0.8]$ .

## Parameters

- $f = f_\theta$  contains **parameters**  $\theta$  to be trained,
- In most cases, an ideal  $f_\theta$  exists but is **hard to find in practice**,
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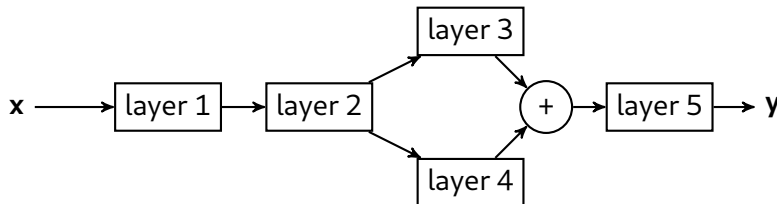
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# Deep learning

## Main idea

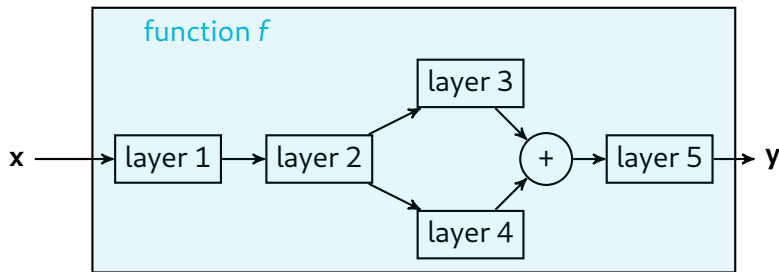
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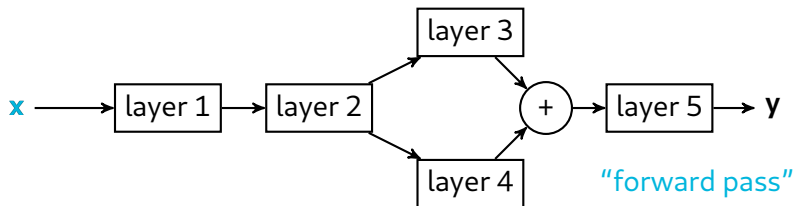
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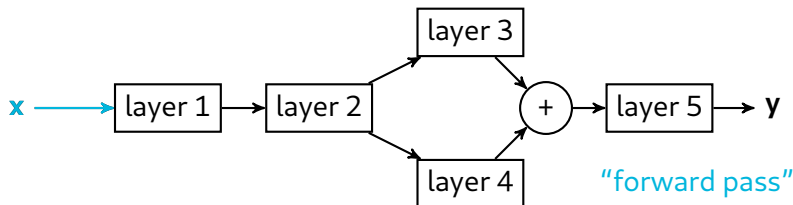
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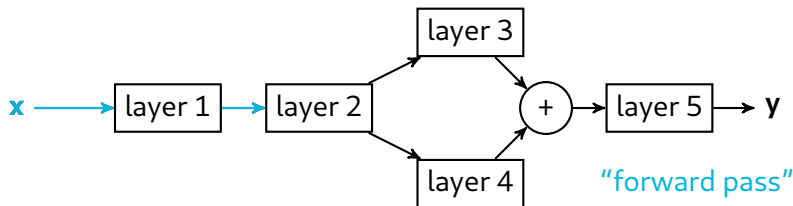




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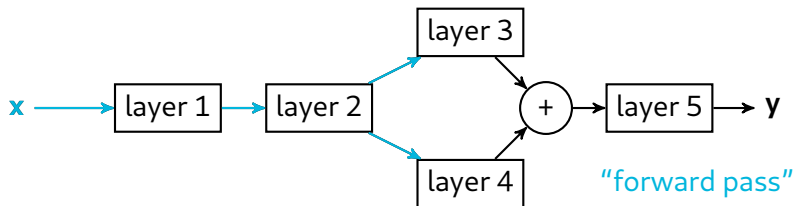
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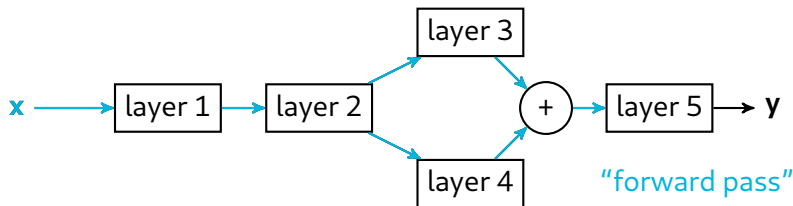
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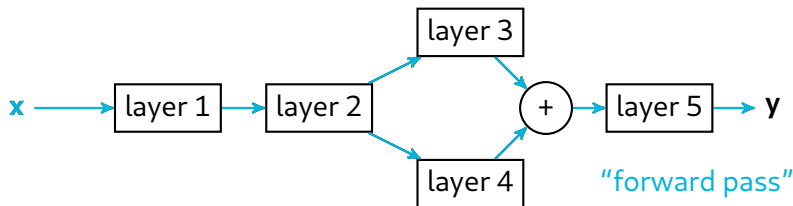
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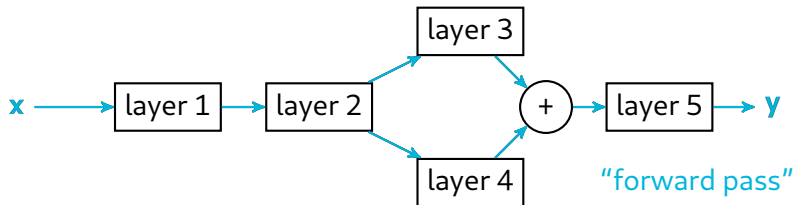
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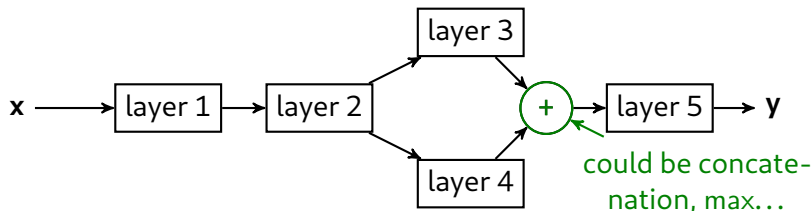
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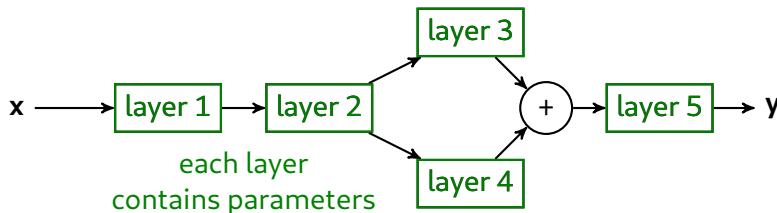
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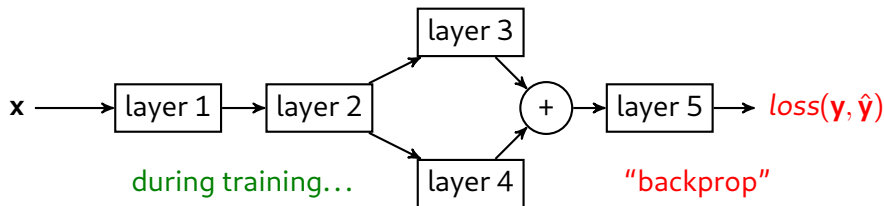
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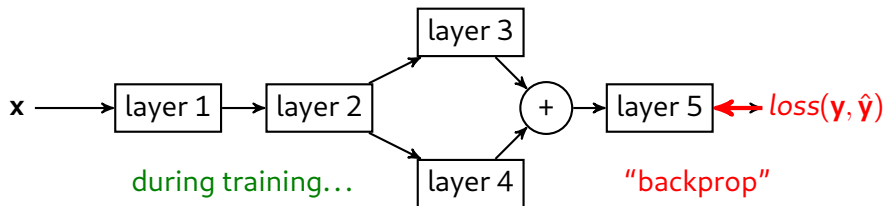




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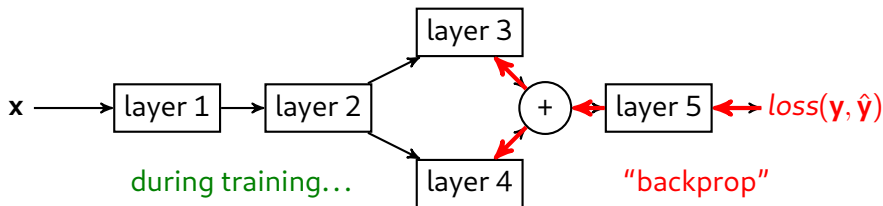
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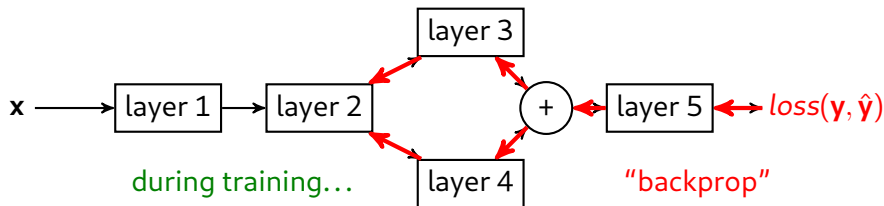
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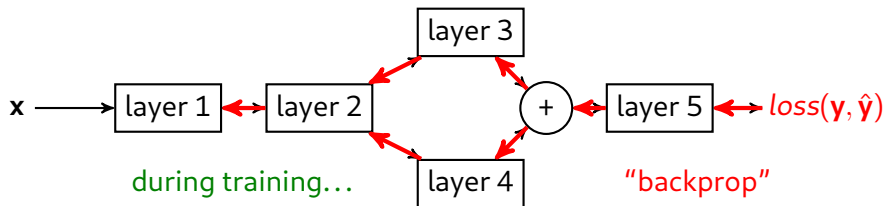
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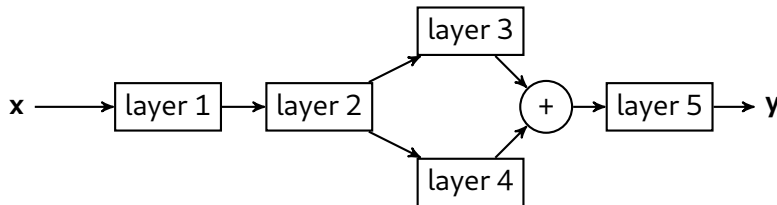
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Number of layers, choice of the architecture are **hyperparameters**

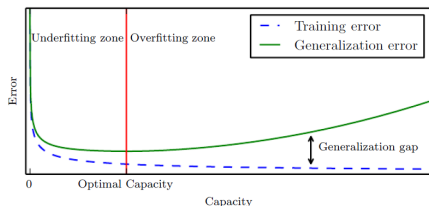
# Generalization vs Overfitting

## Learning Objectives

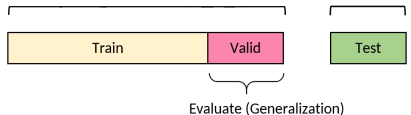
- Reduce the training error AND reduce the gap between training and **generalization error** (error on new inputs)
- Avoid **overfitting**, increase generalization for better performances on test set

## Validation Set

- Examples from the training distribution NOT observed during training (e.g. 20%, 80% split) to check model generalization



**X n\_epochs**  
Iterate on epochs  
To tune hyperparameters



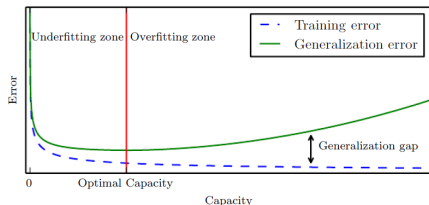
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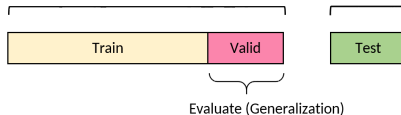
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# Some additional details

## Layers

- $\mathbf{x} \mapsto h(\mathbf{W}\mathbf{x} + \mathbf{b})$ .
  - $h$  is a nonlinear parameterwise function (often without parameters),
  - $\mathbf{W}$  is a tensor:
    - Can be agnostic of the structure: **fully-connected layers**,
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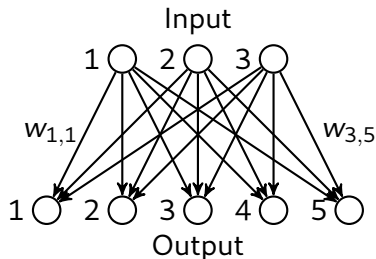
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## Fully connected layer



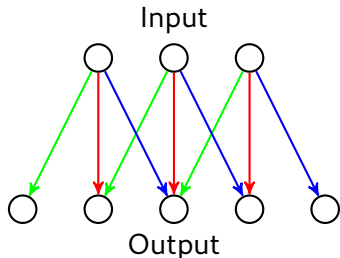
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## Convolutional layer



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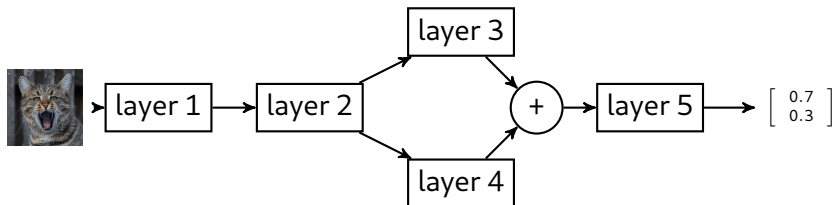
## Batches

- Inputs are often treated **concurrently** using small **batches**.

# The case of deep learning in classification

## Inputs/outputs

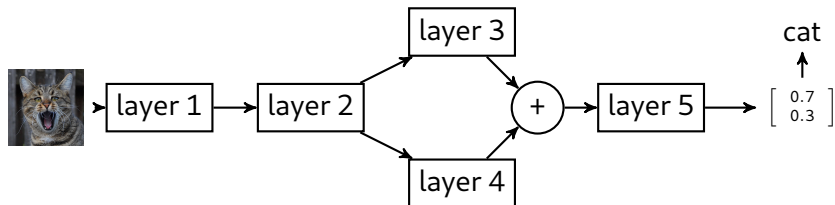
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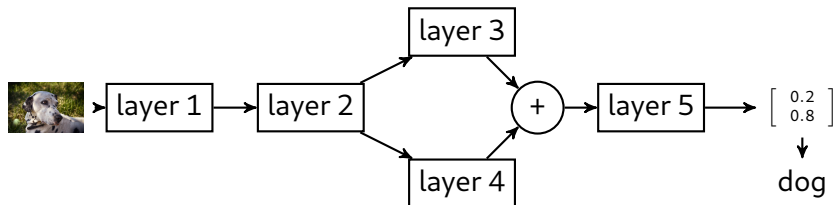




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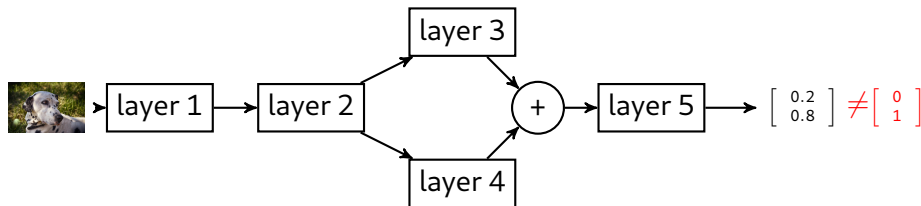
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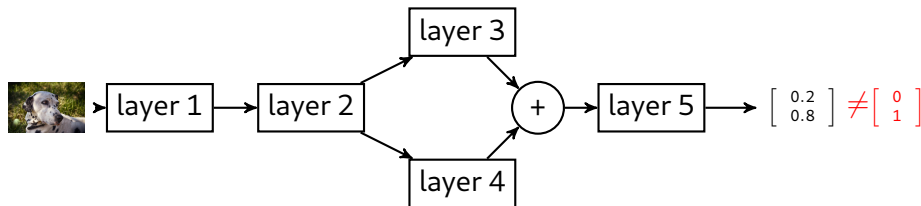
## Loss and targets

- Labels are encoded as one-hot-bit vectors and called **targets**,
- Outputs are **softmaxed**:  $y_i \leftarrow \exp(y_i) / \sum_j \exp(y_j)$ ,
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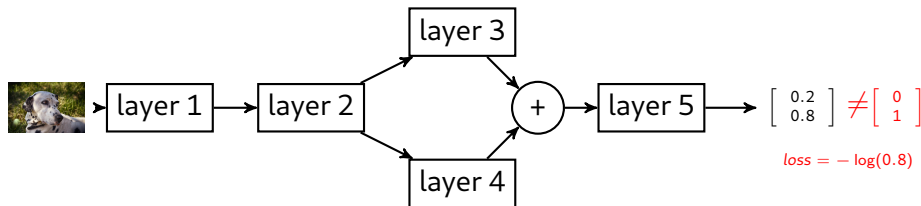
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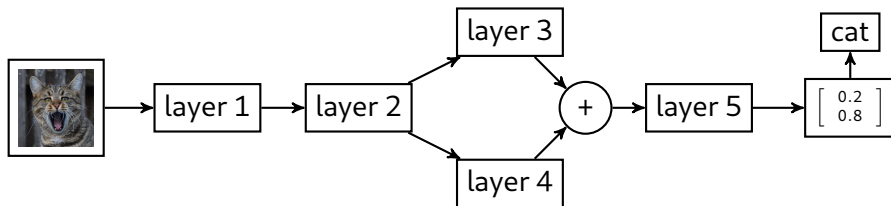
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Idea: use **feature vectors** from a **backbone** (pretrained) network to train a **downstream** classifier.

## Two usecases

- **Fine-tuning:** both the backbone and downstream networks are trained,
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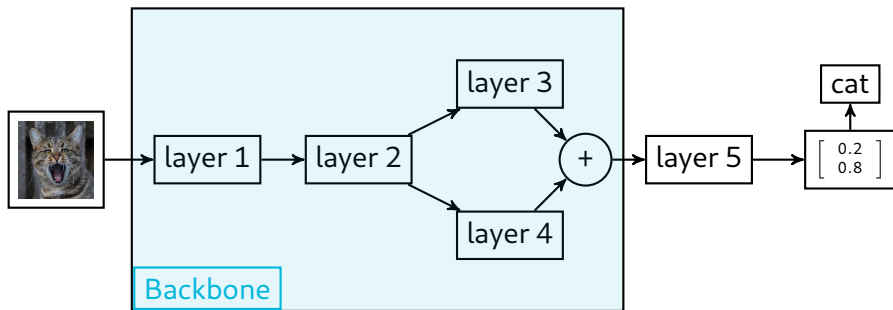


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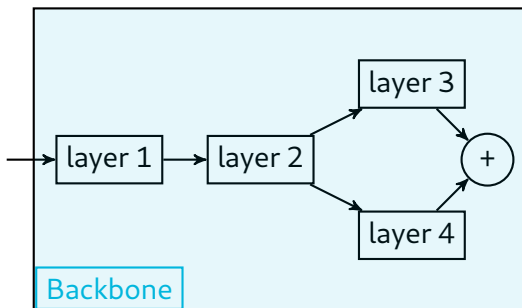


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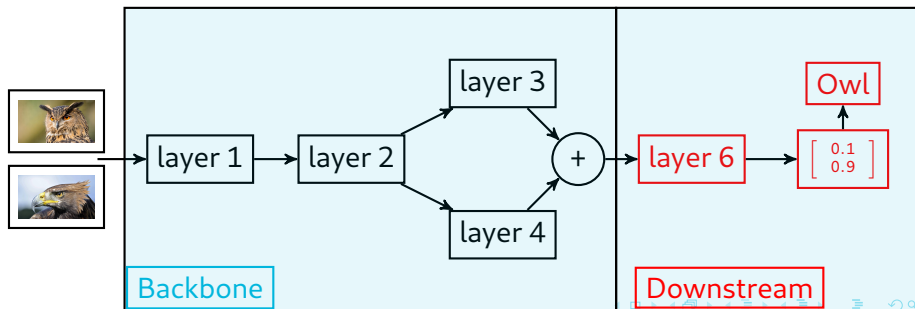


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- Number of layers
- Architecture choice (e.g. ResNet, DenseNet, VGG, ...)

## Training

- Learning rate and scheduling
- Regularization (e.g. weight decay)
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# Lab Session 1 and assignment

## Introduction to Deep Learning

- Introduction to Deep Learning in Pytorch
- Train a full DL model from scratch
- Train a downstream model using transfer learning

## Project 1 (oral presentation)

Explore one of the following architectures : ResNet, DenseNet, PreActResNet, VGG.

You have to prepare a 10 minutes (+5 min Q&A) presentation for session 2, in which you explain :

- Description of the architecture
- Hyperparameter search and results
- Study the compromise between architecture size, performance and training time.