Poincaré group.

Let (xo, X1, X2, X3) E R4, with scalar product

$$\chi_{q} = \chi^{8}q^{6} - \chi'q' - \chi^{2}q^{2} - \chi^{3}q^{3} = g_{\mu\nu} \chi^{\mu}q^{\nu}$$

this space is called the Minkowski space. The linear transforms in this space

$$\chi \longrightarrow \chi' = \Lambda \chi + q$$

 $\chi'^{\mu} = \Lambda^{\mu}_{\nu} \chi^{\nu} + q^{\mu}$, $\mu, \nu = 0,1,2,3$.
Translations.

which them satisfy.

$$g_{\mu\nu} I_{\sigma}^{\mu} = g_{\sigma}$$
 > Lorentz transformation.

$$= \partial^{\mu \lambda} \bigvee_{v}^{\delta} \bigvee_{r}^{\Delta} \times_{\delta} A_{\alpha}$$

$$= \partial^{\mu \lambda} \bigvee_{v}^{\delta} X_{\delta} \bigvee_{r}^{\Delta} A_{\alpha}$$

$$X_{i} \cdot A_{i} = \partial^{\mu \lambda} X_{i, w} A_{i, \lambda}$$

Called inhomogeneous lorentz transformations and they are denoted by (Λ, y) and the homogeneous part (Λ, o) leaves invariant the scalar product.

$$x_1 A_1 = d^{N \lambda} x_{N \lambda} x_{1 \lambda} = d^{N \lambda} V_{\lambda} x_{\delta} x_{\delta} = x A$$

this inhomogeneous transformations form a group, called Poincaré group P.

$$(\Lambda_{1}, Q_{1})(\Lambda_{2}, Q_{2}) = (\Lambda_{1}, \Lambda_{2}, Q_{1} + \Lambda_{1}Q_{2})$$

$$\times \longrightarrow \times^{1} = \Lambda_{2} \times + Q_{2}$$

$$\times^{1} \longrightarrow \times^{1} = \Lambda_{1}(\Lambda_{2} \times + Q_{2}) + Q_{1}$$

$$= \Lambda_{1}\Lambda_{2} \times + \Lambda_{1}Q_{2} + Q_{1}$$

$$= (\Lambda_{1}\Lambda_{2}, \Lambda_{1}Q_{2} + Q_{1})$$

In the natural topology of the matrices, L has fourth disconnected parts.

$$(g_{\mu\nu} \bigwedge_{9}^{\mu} \bigwedge_{V}^{\nu} = g_{9V}) \rightarrow (1 \circ 0 \circ 0)$$

$$X \cdot y = g_{\mu\nu} \chi^{\mu} y^{\nu} = \sum_{M,\nu=0}^{3} g_{M,\nu} \chi^{\mu} y^{\nu}$$

$$g_{\mu\nu} \bigwedge_{0}^{\mu} \bigwedge_{0}^{\nu} = 1$$

$$\Rightarrow (\Lambda_{0}^{\circ})^{2} = 1, \sum_{K=1}^{3} (\Lambda_{0}^{\kappa})^{2} > 1.$$

→ 1°71 06 1°6-1.

the fourth parts of Lare

•
$$L_{+}^{?} = \det \Lambda = +1$$
, Sign $\Lambda_{o}^{o} = +1$.
This part contains to the identity matrix I and it is a group. It is called eigen lorentz group.

•
$$L^2$$
: det $\lambda = -1$, sgn $\lambda_0^* = +1$
Contains to the element
$$I_{\leq X} = (X_1^* - X_1^* - X_2^* - X_3^*)$$

$$T_{\ell}X = (-X_{1}^{n}X_{1}^{n}X_{1}^{2}X_{1}^{3})$$

$$\cdot L_{1}^{n} : de+\Lambda = +1, \quad sgn \, \mathring{N}_{0} = -1$$

$$TsT_{\ell}$$

$$L_{1}^{n} \simeq SO(3,1) \simeq SL(2,\mathbb{C})/\mathbb{Z}_{2}$$

The group SL(2,C)

Consist in the complex matrices 2x2.

$$Q = \begin{pmatrix} Q_{11} & Q_{12} \\ Q_{21} & Q_{22} \end{pmatrix} , Q_{1k} \in \mathbb{C} , i, k=1,2.$$

This group is conected [T:SL(2,C) -> SU(2)]. We may parametrize it by

 $a = a_0e + \sum_{k=1}^{3} a_k \sigma_k$, $a_{0,a_k} \in \mathbb{C}$, e is the identity matrix I_{2x2}

$$\mathfrak{T}_{1} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \mathfrak{T}_{2} = \begin{pmatrix} 0 & -\hat{c} \\ \hat{c} & 0 \end{pmatrix}, \quad \mathfrak{T}_{3} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Pauli's Matrices

any point of the Minkowski space may be represent as a matrix.

$$X \mapsto X = X^{\circ}C + \sum_{k=1}^{3} X^{k} I_{k}$$

$$\begin{vmatrix} x^{\circ} \\ x^{i} \\ x^{3} \end{vmatrix} = \times r \longrightarrow \begin{pmatrix} x^{\circ} + x^{3} & x^{1} - ix^{2} \\ x^{1} + ix^{2} & x^{\circ} - x^{3} \end{pmatrix} = q$$

$$||x||^{2} = g_{\mu\nu} x^{\mu} x^{\nu} \qquad \text{def} (a) = x^{\circ^{2}} - x^{3^{2}} - x^{1^{2}} - x^{2^{2}}$$

Using a ESL(2,0), we may define a linear map of SL(2,0) in itself.

$$x^{l} = a x a^{t}$$

Preserves the inner product.

$$(x')^2 = det(x') = det(axa^{\dagger}) = det(x) = (x)^2$$

Let's write this correspondence as.

$$x' = \alpha x \alpha^{\dagger} \longrightarrow x' = \Lambda(\alpha) x$$

$$\Lambda_{o}^{k} = |Q_{o}|^{2} + \sum_{k=1}^{3} |Q_{k}|^{2}$$

$$\Lambda_{o}^{k} = \alpha_{o} \overline{Q_{k}} + \overline{Q_{o}} Q_{k} + i \varepsilon^{klm} Q_{l} \overline{Q_{m}}$$

$$\Lambda_{k}^{l} = \delta_{k}^{l} \left(|Q_{o}|^{2} - \sum_{k=1}^{3} |Q_{k}|^{2} \right) Q_{k} \overline{Q_{l}} + \overline{Q_{k}} Q_{k} + i \varepsilon^{klm} (\overline{Q_{o}} Q_{m} - Q_{o} \overline{Q_{m}})$$

Moreover.

$$\bigwedge_{\nu}^{\nu}(a) = T_{\varepsilon}(\Lambda(a)) = T_{\varepsilon}(a)^{2} = 4|\alpha_{o}|^{2}$$

Since SL(2,C) is connected, the map on L gives that the image of SL(2,C) is L..

We can invert

$$Q_{o}C+\sum_{k=1}^{3}Q_{K}\overline{Q_{K}}=\overline{D^{-1}}\left\{ \bigwedge_{y}^{y}C+\sum_{k=1}^{3}\left(\bigwedge_{o}^{K}+\bigwedge_{k}^{o}+\mathcal{L}_{\varepsilon}^{oK\phi\tau}\bigwedge_{y}^{\tau}\right)\overline{Q_{K}}\right\}$$

$$D^{2} = 4 - T_{i}(\Lambda\Lambda) + (T_{i}(N^{2}) + i \mathcal{E}^{Myg\tau} \Lambda_{\mu}^{g} \Lambda_{\mu}^{\tau})$$

In other words

$$SL(2,C) \ni \pm e \longrightarrow I_{4x_4} \in L_+^{\uparrow}$$

 $L_+^{\uparrow} \simeq SL(2,C)/\mathbb{Z}_2$

Subgroups of SU(2,C)

Given the equivalence between LT and SL(2,C) is easier to Study SL(2,C) xTa

$$SU(2) \subseteq SL(2,\mathbb{C})$$
: which is formed by $u^{\dagger} = u^{-1}$

and its convenient to parametrize
$$SU(2)$$
 by $U = U \cdot e + i \sum_{k=1}^{3} U_k T_k$, $U_0, U_k \in \mathbb{R}$

SU(1,1), $v \in SL(2,\mathbb{C})$: Formed by $v^{\dagger} \overline{D_3} = Tv^{-1}$ Its parametrized by $v = V_0 e + V_1 \overline{U_1} + V_2 \overline{U_2} + \overline{U_3} \overline{U_3}$ With $V_0^2 - V_1^2 - V_2^2 + V_3^2 = 1$, $V_0 , V_K \in \mathbb{R}$

SL(2,R)=SL(2,C): Formed by

 $Q^{\dagger} U_2 = U_2 Q^{-1}$

and its parametrized by

a = a0 e ta, T, t ca2 T2 ta3 T3,

a, a, ER.