Free scalar field: Path integral

Generating function

$$W_{\circ}[J] \sim \int D\varphi e^{iS_{\circ}[\Psi,J]}$$

$$S_{0}[\Psi,J] = \int dx \left(\int_{-1}^{1} f(x) \Psi(x) \right); \quad \int_{-1}^{1} \int_{2}^{1} dx \Psi \partial^{n} \Psi - \frac{1}{2} m^{2} \Psi^{2}$$

denote: dax - dx

$$\leq_{\circ} [\Psi, J] = -\frac{1}{2} \int dx \, \Psi(\Box + m^2) \, \Psi + \int dx \, J\Psi$$

$$DA \longrightarrow DA$$

$$(\Box + W_s) A = 2 \longrightarrow A = A + A^{\circ}$$

$$S_{o}[\Psi, J] \rightarrow \int dx \left[-\frac{1}{2} (\Psi_{+} \Psi_{o}) (\Box + M^{2}) (\Psi_{+} \Psi_{o}) + J (\Psi_{+} \Psi_{o}) \right]$$

$$S_{0}[4, 3] = \int dx \left[\frac{1}{2} (4) - 4(\Box + m^{2}) 4 - \frac{1}{2} 4 (\Box + m^{2}) 4 + \frac{1}{2} (4 + 4) \right]$$

$$= \int dx \left[\frac{1}{2} (4) - 4 - \frac{1}{2} 4 + \frac{1}{2} 4 + \frac{1}{2} 4 \right]$$

therefore,

$$S_{0}[\Psi,J] = \int dx \left[\int_{-\infty}^{\infty} (\Psi) + \frac{1}{2} \Psi_{0}J \right]$$

$$\mathcal{W}_{o}[J] \propto \int \mathcal{D} e^{i \mathcal{S}_{o}(Q)} \cdot e^{i \frac{1}{2} \int dx \, Q_{o}J}$$

$$\therefore W_o[J] = e^{i\frac{1}{2}\int dx J(x) \ell(x)}.$$

Pot:
$$(\Box + w_s) A^{\circ}(x) = I(x)$$

$$V_{o}(x) = i \int dq \Delta_{F}(x-q) J(q)$$

$$W_{o}[J] = e^{-\frac{1}{2}\int dx dy J(x) \Delta_{f}(x-y)J(y)}$$

Generating function for the free scalar field.

Green functions

$$C_{(n)}(x_1,...,x_N) = (-i)^n \frac{\delta^n W_0(j)}{\delta^n W_0(x_1,...,x_N)} \Big|_{J=0}$$

$$G^{(1)}(x) = -i \frac{S ||S||}{S ||S||} = -i \frac{S}{S ||S||} \exp \left[-\frac{1}{2} \int dq dz ||S|| \Delta_{\pm} (q - z) ||S|| \right]_{J=0}$$

$$= -i \frac{S ||S||}{2} \frac{S ||S||}{S ||S||} \int dq dz ||S|| \Delta_{\pm} (q - z) ||S$$

$$= -i (-) \int dq \Delta_{F}(x-q) J(q) \Big|_{J=0} \longrightarrow G^{(n)}(x) = 0$$

$$\longrightarrow \langle O| \Psi(x) | O \rangle = 0$$

$$G^{(2)}(x_{\ell}, x_{2}) = (-i)^{2} \frac{\langle W_{o}[J] \rangle}{\langle J(x_{2}) \langle J(x_{1}) \rangle}|_{J=0}$$

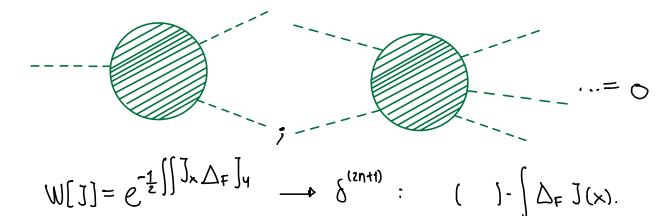
$$= (-i)^{2} \frac{\langle W_{o}[J] \rangle}{\langle J(x_{2}) \langle J(x_{1}) \rangle}|_{J=0}$$

$$= (-i)^{2} (-i) \left[\frac{\langle W_{o} \rangle}{\langle J(x_{2}) \rangle} \right] dq \Delta_{F}(x_{r}, q) J(q) + W \cdot \Delta_{F}(x_{r} - x_{2}) \int_{J=0}^{J=0}$$

$$= + \qquad -W_{o} \left[dq' \Delta_{F} J \cdot \int dq \Delta_{F} J \rightarrow 0 \right]$$

therefore,
$$G^{(2)}(X_1,X_2) = \Delta_F(X_1-X_2)$$
 $X_1 = X_2$

|||.
$$G^{(2n+1)} = 0$$



IV.
$$G^{(4)}(x_{1,...,1}x_{4}) = (-i)^{4} (-i)^{4} (-i)^{4} \frac{\delta^{2}}{\delta^{3}(x_{4})\delta^{3}(x_{3})} W_{o} \left[-\int dq \int \Delta_{F}(q-x_{1}) \int dq' \int \Delta_{F}(q'-x_{2}) + \Delta_{F}(x_{1}-x_{2}) \right]_{J=0}^{J}$$

$$= (-) \left[\frac{\delta^{2} W_{o}}{\delta J(x_{4}) \delta J(x_{3})} \Big|_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right]_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right]_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta J} \right)_{J=o} \left(- \left(\int J \Delta \right)^{2} + \Delta_{F}(x_{1}-x_{2}) - \frac{\delta W_{o}}{\delta$$

therefore,

$$G^{(4)}(X_{1,...,1}X_{4})=$$

 $\triangle_F(\chi_1-\chi_2) \triangle_F(\chi_3-\chi_4) + \triangle_F(\chi_4-\chi_3) \triangle_F(\chi_2-\chi_4) + \triangle_F(\chi_4-\chi_4) \triangle_F(\chi_2-\chi_3)$

In general, $G^{(2n)}(X_1,...,X_{2n}) = \sum_{\text{Permutations}} G^{(3)}(X_{p_{i,1}}X_{p_2}) - \cdots G^{(3n)}(X_{p_{(2n-1)}},X_{p_{(2n)}})$

Disconected, due to absence of interactions.

Definition: Generating function of conected Green functions. $W[J] = e^{ix(J)}$

Definition: Conected Green function.

$$\begin{aligned} & (i)^{n} \mathcal{G}^{(n)}(x_{1},...,x_{n}) = i \cdot \frac{\delta^{n} x[J]}{\delta^{J}(x_{n}) \cdot \cdot \cdot \delta^{J}(x_{1})} \Big|_{J=0} \\ & \times [J] = \sum_{n=1}^{\infty} \frac{(i)^{n-1}}{N!} \int \left(\prod_{i=1}^{n} dx_{i} \right) \mathcal{G}^{(n)}(x_{1},...,x_{n}) J(x_{n}) \cdot \cdot \cdot J(x_{n}) \\ & \times [0] = 0 \end{aligned}$$

Free scalar field:

$$X_{\bullet}[J] = \frac{7}{2} \int dx dy J(x) \Delta_{\#}(x-y) J(y)$$

therefore

$$g^{(2)}(x_1, x_2) = \Delta_F(x_1, x_2)$$
 is non-now.

Detinition: Medicible Green functions for a particle (OPI).

- Corected diagrams that not may be disconected by "cutting" just one intern line.

observe,
$$X_{\circ}[J] = \frac{i}{2} \left[dx dy J(x) \Delta_{\varepsilon}(x-y) J(y) \right]$$

 $\frac{\delta x_{o}[j]}{\delta J(x)} = i \int dq \Delta(x-q) J(q) = \ell_{c}(x)$ classic solution then,

Definition: effective action:

$$\Box(\varphi_c) = \chi[J] - \int d\chi J(\chi) \Psi_c(\chi)$$

$$\Box(\varphi_c) = \sum_{n=1}^{\infty} \int_{\eta_c} \int_{\eta_c} \int_{\eta_c} \int_{\eta_c} (\chi_{\eta_c, \dots}, \chi_n) \Psi(\chi_n) \dots \Psi(\chi_n)$$

$$\Box(\varphi_c) = \sum_{n=1}^{\infty} \int_{\eta_c} \int_{\eta_c} \int_{\eta_c} \int_{\eta_c} (\chi_{\eta_c, \dots}, \chi_n) \Psi(\chi_n) \dots \Psi(\chi_n)$$
OPI fonction

Free theory:
$$\Gamma_{\circ}[\P_{c}] = -\frac{1}{2} \int dx \, \P_{c}(x) J(x) = -\frac{1}{2} \int dx \, \P_{c}(\Box + m^{2}) \, \P_{c}$$

then, $\Gamma_{\circ}[\P_{c}] = S_{\circ}[\P_{c}]$

Unique non-null function:

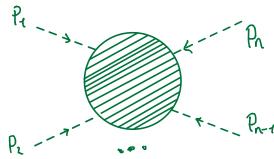
$$\Gamma^{(2)}(x,y) = \left(\Box_x + m^2 \right) \delta(x-y)$$

Green function in the momentum space

Traslational invariance — Green function: $Y(x_i - x_j)$

momentum conservation.

$$\int dx_1 - dx_n + \int_{0}^{\infty} (x_1, ..., x_n) e^{i \sum_{i} P_i x_i} = \sum_{i}^{\infty} (p_1, ..., p_n) (2\pi)^4 \delta(\sum_{i} P_i)$$



clearly,

$$\widetilde{\mathcal{G}}^{(2)}(\rho_1 - \rho) = \widetilde{\Delta}_{f}(\rho) = \frac{1}{\rho^2 - M^2 + 1}$$

while

$$\widetilde{\bigcap}^{(2)}(p) = -(p^2 - M^2) \rightarrow \widetilde{\bigcap}^{(2)}(p) = \left[\frac{1}{p^2 - M^2}\right]^{-1} = \widetilde{\triangle}_F^{-1}(p)$$

Notice,

$$\widehat{C} \widehat{\Gamma}^{(2)}(p) = \widehat{\Delta}_{\mathfrak{F}}^{-1}(p) \Delta_{\mathfrak{F}}(p) \Delta_{\mathfrak{F}}^{-1}(p)$$

