$$\lambda \varphi^{4}$$

$$W[J] \propto \exp\left(-i\int dx L_{I}\left(-i\frac{\delta}{\delta J(x)}\right)\right)W_{0}[J]$$

1, (((x)):

$$\underline{i} - \longleftarrow (\underline{x}) \psi$$

Vacuum diagonal (J=0):

$$W[J] = \underbrace{e^{i\int dx L_{IM}(-i\frac{\delta}{\delta J(x)})} W_{o}[J]}_{i\int dx L_{IM}(-i\frac{\delta}{\delta J(x)}) W_{o}[J]|_{J=0}}$$

for 2,4-point Green function

$$G^{(z)}(X_{1}, X_{2}) = \frac{1}{X_{1}} + \frac{1}{2} \times \frac{1}{X_{1}}$$

$$G^{(q)}(\chi_{1,\ldots,1}\chi_{4}) = \sum_{\text{Posign}} \frac{\chi_{1}}{\chi_{3}} + \sum_{\text{Posign}} \frac{1}{2} + \chi_{3}$$

$$\sum_{X_1,\dots,X_2} : \Delta_F(X_1-X_2) \qquad : (-i\chi) \int d\chi \Delta_F(X_-X_i) \cdots$$

$$: \Delta_{\mathsf{F}}(\mathsf{X} - \mathsf{X})$$

$$([L]W)n) = [[L]X]$$

$$(X[J] = [n(W)] + [n(W)]$$

$$(Xi) \quad \text{for } X$$

for $L_{N}(1+x)=x$

$$(X_{zwz} = (-iX)) \left[-6 \int dx dx_1 dx_2 \Delta_F(x_1 - x) \Delta_F(x - x_2) J(x_1) J(x_2) \right]$$

$$+ \int d \times d \times_1 \cdots d \times_4 \Delta_F (X_4 - X) \cdots \Delta_F (X_4 - X) \cdot J(\times_1) J(\times_2) J(\times_3) J(\times_4) \bigg]$$

Then, the connected diagrams:

$$\frac{[C]X^n\delta_j}{(iX)C\delta\cdots(iX)C\delta} = {n\choose i}$$

$$g^{(2)}(X_{1}, X_{2}) = ---- + \frac{1}{2}$$

$$g^{(q)}(\chi_1,...,\chi_q) =$$

In the moment space.

$$g^{(n)}(P_1,...,P_n)(2\pi)^4\delta(P_1+\cdots+P_n) = \int dx_1\cdots dx_n g^{(n)}(x_1,...,x_n)e^{-i\Sigma P_1 x_1}$$

$$g^{(2)}(p,-p) = \widetilde{\Delta}_{F}(p) + \frac{1}{2}(-i \times) \int \frac{d^{4}K}{(2\pi)^{4}} \widetilde{\Delta}_{F}(p) \widetilde{\Delta}_{F}(K) \widetilde{\Delta}_{F}(p)$$

Feynman diagram:

$$---- = -- \rightarrow --- + 1$$

Feynman rules: $\lambda \phi^a$

1. (ine :
$$--\frac{1}{p^2-m^2+i\epsilon} = \widetilde{\triangle}_F(p)$$

II. Vertex:
$$(\sum P_i = 0)$$

IV. Loop:
$$\left(\begin{array}{c} 1 \\ 1 \end{array}\right) : \int \frac{d^4k}{(2\pi)^4}$$

OPI functions

$$\Psi_c(x) = \delta x[J]$$
; $i x = i x_o + i x_{mi}$

$$i X_{\text{INV}} = \frac{1}{2} \int dx dy J(x) \Delta_{\text{F}}(x-y) J(y).$$

$$i X_{\text{INV}} = \frac{(-ix)}{4!} \int dx \left[-6\Delta_{\text{F}}(0) \left(\int \Delta_{\text{F}} J \right)^{2} + \left(\int \Delta_{\text{F}} J \right)^{4} \right] + \mathcal{O}(\lambda^{2})$$

then

$$\begin{aligned} & \text{Y}_{c}(X) = i \int dq \, \Delta_{F}(X - q) \, J(q) + \frac{1}{2} \int dX_{1} \, dX_{2} \, \Delta_{F}(X - X_{1}) \Delta_{F}(X_{1} - X_{2}) \, J(X_{2}) \\ & - \frac{1}{6} \int dX_{1} \left[\int dX_{2} \, \Delta_{F}(X_{1} - X_{2}) \, J(X_{2}) \right]^{3} \, \Delta_{F}(X - X_{1}) + \cdots \end{aligned}$$

Computing, $(\Box_x + m^2) \ell_c(x)$ and $Using(\Box_x + m^2) \Delta_F(x - y) = -i\delta(x - y)$, we may write

$$J(x) = (\Box + m^2) (C(x) + \frac{1}{2} \times \Delta_{\epsilon}(0) (C(x) + \frac{1}{6} \times (C(x))^3 + \dots$$

self-interaction

Effective action:

$$\Gamma[\{Q_c\}] = -\frac{1}{2} \int dx \, \{C(\Box_x + m^2) \, \{Q_c - \frac{\lambda}{4}\} \, dx \, \Delta_F(x - x) \, \{Q_c(x)\}^2$$

$$-\frac{1}{4!} \lambda \int dx \, \{Q_c(x)\}^4 + \dots$$

$$\mathcal{F}[\varphi_c^2, \varphi_c^3] \rightarrow \Gamma^{(2)}; \Gamma^{(4)}$$
 non-noll.

$$i \widetilde{\Gamma}^{(2)}(P, -P) = i (P^2 - \mu^2) + \underbrace{1}_{2} (-i\lambda) \Delta_F(0)$$

$$= (------)^4 + \underbrace{1}_{2}$$

$$(-i\lambda) \int_{(2\pi)^4} \Delta_F(k)$$

$$i \widetilde{\Gamma}^{(4)}(P, -P) = (-i\lambda) i$$

$$\widetilde{\mathfrak{f}}^{(a)}(P_1,\ldots,P_a)=(-1\lambda):$$

Propagators of external legs "cutted".