

Let M be a manifold of dim n , with basis x^μ , vector field $\{\partial_\mu\}$

$$g(\partial_\mu, \partial_\nu) = g_{\mu\nu}$$

$$\text{vol} \equiv \sqrt{|\det g_{\mu\nu}|} dx^1 \wedge \dots \wedge dx^n$$

Suppose other basis x'^μ , vector field $\{\partial'_\mu\}$

$$g(\partial'_\mu, \partial'_\nu) = g'_{\mu\nu}$$

$$\text{vol}' \equiv \sqrt{|\det g'_{\mu\nu}|} dx'^1 \wedge \dots \wedge dx'^n$$

$$dx'^\nu = T^\nu_\mu dx^\mu$$

$$T^\nu_\mu = \frac{dx'^\nu}{dx^\mu}$$

then,

$$\begin{aligned} dx^1 \wedge dx^2 \wedge \dots \wedge dx^n &= (T^1_\mu dx^\mu) \wedge (T^2_\mu dx^\mu) \wedge \dots \wedge (T^n_\mu dx^\mu) \\ &= (\det T) dx^1 \wedge dx^2 \wedge \dots \wedge dx^n. \end{aligned}$$

To show $\text{vol} = \text{vol}'$, first show

$$\sqrt{|\det g'_{\mu\nu}|} = (\det T)^{-1} \sqrt{|\det g_{\mu\nu}|}$$

$$\begin{aligned} g'_{\mu\nu} &= g(\partial'_\mu, \partial'_\nu) = g\left(\frac{\partial x^\alpha}{\partial x'^\mu} \partial_\alpha, \frac{\partial x^\beta}{\partial x'^\nu} \partial_\beta\right) \\ &= (T^{-1})^\alpha_\mu (T^{-1})^\beta_\nu g_{\alpha\beta} \end{aligned}$$

then,

$$\det g'_{\mu\nu} = (\det T)^{-2} \det g_{\mu\nu}$$

det T > 0 orientable.

Therefore,

$$\sqrt{|\det g'_{\mu\nu}|} = (\det T)^{-1} \sqrt{|\det g_{\mu\nu}|}$$

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$$\text{vol} = \sqrt{g} d^n x$$

$$\int f \sqrt{g} d^n x$$

• If M is a Lorentzian manifold

$$\text{vol} = \sqrt{-g} d^n x.$$

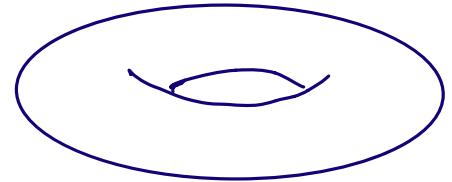
$$S[q(t)] = \int_{t_0}^{t_1} L\left(q(t), \frac{dq}{dt}(t)\right) dt \quad q: \mathbb{R} \rightarrow \mathbb{R}$$

$$0 = \delta S \rightarrow \frac{\delta L}{\delta q} - \frac{d}{dt} \left(\frac{\delta L}{\delta (\frac{dq}{dt})} \right) = 0$$

$$S = \int d^n x \mathcal{L}(\phi, \partial_\mu \phi) \sqrt{| \det g_{\mu\nu} |} ; \quad \phi: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$\delta S = 0 \rightarrow \frac{\delta \mathcal{L}}{\delta \phi} - \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi)} \right) = 0$$

$$\mathcal{L} = \frac{1}{2} \partial_\mu \phi \partial^\mu \phi$$



$$\begin{aligned} \nabla \cdot \vec{B} &= 0 \\ \nabla \times \vec{E} + \frac{\partial \vec{B}}{\partial t} &= 0 \end{aligned} \quad \left\{ \begin{array}{l} dF = 0 \rightarrow ds B = 0 \quad B - 2\text{-form.} \\ \partial_t B + ds E = 0 \quad E - 1\text{-form.} \end{array} \right.$$

$$\nabla \cdot \vec{E} = \rho$$

$$\nabla \times \vec{B} - \frac{\partial \vec{E}}{\partial t} = \vec{j}$$

Let M be a semi-Riemannian manifold of dim n . The inner product of two p -forms w, μ is a function $\langle w, \mu \rangle$ in M . Define the star Hodge operator (Hodge dual)

$$*: \Omega^p(M) \rightarrow \Omega^{n-p}(M)$$

is a linear map from p -form to $(n-p)$ -form. Such that $w \wedge * \mu = \langle w, \mu \rangle \text{vol.}$

\star are n -form

let e^1, \dots, e^n be an orthonormal basis of 1-forms

$$\langle e^\mu, e^\nu \rangle = 0 \text{ if } \mu \neq \nu.$$

$$\langle e^\mu, e^\nu \rangle = \epsilon(\mu); \text{ with } \epsilon(\mu) = \pm 1 \text{ if } \mu = \nu.$$

Let be different $1 \leq i_1, \dots, i_p \leq n$

$$*(e^{i_1} \wedge \dots \wedge e^{i_p}) = \pm e^{i_{p+1}} \wedge \dots \wedge e^{i_n}$$

with $\{i_{p+1}, \dots, i_n\}$ the integers from 1 to n, not included in $\{i_1, \dots, i_p\}$.

Where the sign \pm is given by

$$\text{Sign}(i_1, \dots, i_n) \in (+) \dots (-)$$

here, $\text{Sign}(i_1, \dots, i_n)$ is the permutation of $(1, \dots, n)$.

Example: In \mathbb{R}^3 , we have 1-forms $\{dx, dy, dz\}$

$$*dx = dy \wedge dz$$

$$\text{Sign}(1, 2, 3) \in (+)$$

$$= (+1)(+1).$$

$$*dy = dz \wedge dx$$

$$\text{Sign}(2, 3, 1).$$

$$*dz = dx \wedge dy.$$

$$*(dx \wedge dy) = dz$$

$$\text{Sign}(1, 2, 3) \in (+) \in (-)$$

$$*(dy \wedge dz) = dx$$

$$*(dz \wedge dx) = dy$$

$$*1 = dx \wedge dy \wedge dz$$

$$\text{Sign}(1, 2, 3).$$

$$*(dx \wedge dy \wedge dz) = 1.$$

Homework: let ω be a 1-form in \mathbb{R}^3 ($\omega = \omega_\mu dx^\mu$).

$$*\omega \quad (\text{rotational})$$

$$d*\omega \quad (\text{divergence})$$

Second pair of equations.

$$F = B + E \wedge dt = \frac{1}{2} F_{\mu\nu} dx^\mu \wedge dx^\nu$$

$$F_{\mu\nu} = \begin{pmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & B_z & -B_y \\ E_y & -B_z & 0 & B_x \\ E_z & B_y & -B_x & 0 \end{pmatrix}$$

Now, the metric is Minkowski.

$$\eta(v, w) = -v^0 w^0 + v^1 w^1 + v^2 w^2 + v^3 w^3.$$

$$*F = \frac{1}{2} (*F)_{\mu\nu} dx^\mu \wedge dx^\nu$$

$$\begin{aligned} * \left(\frac{1}{2} F_{\mu\nu} dx^\mu \wedge dx^\nu \right) &= \frac{1}{2} F_{01} * (dx^0 \wedge dx^1) \\ &= \frac{1}{2} F_{01} (-1) (dx^2 \wedge dx^3) \\ &= \frac{1}{2} E_x dx^2 \wedge dx^3 \end{aligned}$$

$$\text{Sign}(0, 1, 2, 3) \epsilon(x_0) \epsilon(x_1)$$

$$= (+1)(-1)(+1)$$

$$(*F)_{\mu\nu} = \begin{pmatrix} 0 & B_x & B_y & B_z \\ -B_x & 0 & E_z & -E_y \\ -B_y & -E_z & 0 & E_x \\ -B_z & E_y & -E_x & 0 \end{pmatrix}$$

$\boxed{dF = 0} \quad F = dA$
 $\boxed{d*F = 0} \quad dF = d^2 A = 0$
 \downarrow
 $d*dA = 0.$

In other words, the dual of F means replace

$$E_i \mapsto -B_i, \quad B_i \mapsto E_i$$

$$\nabla \cdot \vec{B} = 0, \quad \nabla \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0 \quad \rightarrow dF = 0$$

$$\nabla \cdot \vec{E} = 0, \quad \nabla \times \vec{B} - \frac{\partial \vec{E}}{\partial t} = 0 \longrightarrow \vec{J} * F = 0$$

$$j = j_1 dx + j_2 dy + j_3 dz \quad (j_1, j_2, j_3)$$

$$J = j - \rho dt.$$

$$* J * F = J$$

Lie (algebras & groups)

Definition: A group G , is a set equipped with a binary operation

$$\bullet : G \times G \longrightarrow G,$$

called product, or operation

$$^{-1} : G \longrightarrow G$$

called inverse and an element $1 \in G$, called identity, such that $\forall g, h, k \in G$

$$\text{I. } (g \cdot h) k = g \cdot (h \cdot k)$$

$$\text{II. } g \cdot 1 = 1 \cdot g = g$$

$$\text{III. } g \cdot g^{-1} = g^{-1} \cdot g = 1$$

Notation $g \cdot h = gh$

Most of the groups with applications, are matrix groups, ex.

$GL(n, \mathbb{R})$ - General linear group, invertible $n \times n$ matrices,
 $GL(n, \mathbb{C})$.

A subgroup is a subset of a group such that is closed under the multiplication and the inverse

$$GL(n, \mathbb{R}) \subseteq GL(n, \mathbb{C})$$

The special linear group, is the set of $n \times n$ matrices, with $\det = 1$, $SL(n, \mathbb{R})$. (Preserves volume).

If p, q are non-negative integers such that $p+q=n$. Let g be a metric in \mathbb{R}^n with signature (p, q) .

$$g(v, w) = v^1 w^1 + v^2 w^2 + \dots + v^p w^p + v^{p+1} w^{p+1} + \dots + v^{p+q} w^{p+q}.$$

$$g(Tv, Tw) = g(v, w)$$

The orthogonal group $O(p, q)$, in the set of matrices $n \times n$, such that,

$$g(Tv, Tw) = g(v, w), \quad \forall v, w \in \mathbb{R}^n$$

$$SO(p, q) \subseteq O(p, q)$$

$$\left\{ \begin{array}{l} T \in O(p, q), \\ \det T = 1 \end{array} \right.$$

If $p=n$, g is the euclidean metric, write $O(n)$ and $SO(n)$.

The group $SO(3, 1)$, are the orthogonal matrices in the Minkowski metric and it is labeled the Lorentz group.

In a space \mathbb{C}^n

$$\langle v, w \rangle = \sum_{i=1}^n \bar{v}_i w_i$$

the group $U(n)$ unitary and saves the inner product, then

$$SU(n) \subseteq U(n).$$