

## Functions in groups

lets to denote the translations

$$f(t) \longmapsto T_{t_1} f(t - t_1)$$

and integrate them in an invariant way, under translations

$$f(t) \longmapsto I_f = \int f(t) dt \text{ is invariant}$$

A pair of integrable functions are in convolution

$$f_1 \cdot f_2(t) = \int f_1(t) f_2(t - t_1) dt,$$

We can define real functions or complex in any group G.

If the group is topological, let's consider the continuous functions and if it is of Lie, the differentiable. We may have the operations.

I) Translations by the left

$$T^l g, f(g) = f(g \cdot g)$$

II) Translations by the right

$$T^r g, f(g) = f(g \cdot g)$$

as

$$T^l g_1 T^l g_2 = T^l g_1 g_2, \quad T^r g_1 T^r g_2 = T^r g_1 g_2$$

## Invariant measures

In any Lie's group G, there are two invariant measures (Haar's Measure), that may be defined, by asking for invariance by right.

$$\int f(g) d\mu_r(g) = \int f(gg_1) d\mu_r(g)$$

or by left

$$\int f(g) d\mu_l(g) = \int f(g_1 g) d\mu_l(g)$$

are unique until a constant factor. If the group is compact, both match.

for  $SL(2, \mathbb{C})$ , use the parametrization

$$a = a_0 e + \sum_{k=1}^3 a_k \tau_k \quad Dz = dx dy$$

then

$$d\mu(a) = C_0 \delta(a_0^2 - \sum_{k=1}^3 a_k^2 - 1) \prod_{i=0}^3 da_i, \quad C_0 \text{ by convention.}$$

In a similar way for  $SU(2), SU(1,1), SL(2, \mathbb{R})$ .

•  $SU(2)$ :

$$d\mu(u) = C_0 \delta(u_0^2 + \sum_{j=1}^3 u_j^2 - 1) \prod_{i=0}^3 du_i$$

•  $SU(1,1)$ :

$$d\mu(v) = C_0 \delta(\det(v) - 1) \prod_{i=0}^3 dv_i$$

•  $SL(2, \mathbb{R})$ :

$$d\mu(a) = C_0 \delta(\det(a) - 1) \prod_{i=1}^3 da_i$$

for  $SU(2)$ , the parameters

$$u_0^2 + \sum_{k=1}^3 u_k^2 = 1$$

And therefore, thus

**Homework:**

$$\int_{SU(2)} d\mu(u) = \int_{SU(2)} C_0 \delta(u_0^2 + \sum_{j=1}^3 u_j^2 - 1) du_0 du_1 du_2 du_3 = \frac{1}{2} C_0 \Omega_4.$$

where  $\Omega_4$  is the area of the unitary sphere in  $\mathbb{R}^4$ .

$$\Omega_4 = 2\pi^2 \longrightarrow C_0 = \frac{1}{\pi^2}$$

Let's consider the Lie's group, formed by a semidirect product  $G = H \times T$ , with multiplication

$$g = (h, t), \quad h \in H, t \in T.$$

$$(h_1, t_1)(h_2, t_2) = (h_1 h_2 t_1, t_1 + A_{h_1}(t_2))$$

where  $A_h$  is a linear transformation on  $T$ .

The invariant measure of  $G$  is the product of the invariant measures if  $\det(A_h) = 1$ .

for the invariant case  $SL(2, \mathbb{C}) \times T_4$

$$d\mu = d\mu_{SL(2, \mathbb{C})} d\mu(T_4), \text{ since } |\det(A)| = |\det(\Lambda)| = 1$$

### Unitary representations

A unitary representation is a homeomorphism of the  $G$  group in the set of unitary operators  $U$ , in the Hilbert space  $H$ .

$$g \mapsto U_g, \quad U_g U_{g'} = U_{g' g}, \quad U_e = I$$

In general, we assume that it is continuous.

$$\|U_g \xi - U_{g_0} \xi\| \rightarrow 0 \quad \text{if } g \rightarrow g_0, \quad \forall \xi \in H.$$

A representation is irreducible if and only if its unique invariant subspaces of  $H$ , are  $H$  and the null space.

### Homogeneous function space.

The representations of  $SL(2, \mathbb{C})$ , may be constructed using the homogeneous function space. Which is a generalization of the polynomial space of grade  $2s$  and  $2s'$  in the variables  $(\xi^1, \xi^2)$  and  $(n_1, n_2)$ , and then we are going to denote them by  $(z_1, z_2)$  and  $(\bar{z}_1, \bar{z}_2)$ .

We say that  $F(z_1, z_2)$  is homogeneous of grade  $\lambda$  and  $\mu$  in  $z_1, z_2$  if for all  $\alpha \in \mathbb{C}$ ,  $\alpha \neq 0$ .

$$F(\alpha z_1, \alpha z_2) = \alpha^{\lambda} \alpha^{\mu} F(z_1, z_2)$$

We can change the condition of homogenous

$$F(e^{i\omega} z_1, e^{i\omega} z_2) = e^{i(\lambda-\mu)\omega} F(z_1, z_2)$$

It is reduced to the identity if  $\omega = 2\pi n$ ,  $n \in \mathbb{Z}$ . This requires that

$$\mu - \lambda = m \in \mathbb{Z}$$

Instead of the grades  $\mu$  and  $\lambda$ . Characterizing the homogeneous functions by the tags  $X\{n_1, n_2\} = (m, \varphi)$

$$n_1 = \lambda + 1 = -\frac{1}{2} m + \frac{i}{2} \varphi$$

$$n_2 = \mu + 1 = \frac{1}{2} m + \frac{i}{2} \varphi$$

The space of homogeneous functions  $\mathcal{D}_x$ , it's define as:

- 1)  $\mathcal{D}_x$  is a vectorial space of the homogeneous functions of grade  $x$ .
- 2) Any element infinitely differentiable in  $z_1, \bar{z}_1, z_2, \bar{z}_2$

The importance of  $\mathcal{D}_x$ , is that we may define an operator  $T_a^x$ , for  $a \in SL(2, \mathbb{C})$  such that

$$T_{a_1}^x T_{a_2}^x = T_{a_1 a_2}^x$$

### Group operations:

We define an operator  $T_a^x$ , for  $a \in SL(2, \mathbb{C})$  in  $\mathcal{D}_x$

$$T_a^x F(z_1, z_2) = F(z'_1, z'_2) = F(z_1 a_{11} + z_2 a_{21}, z_1 a_{12} + z_2 a_{22})$$

as the origin  $z_1 = z_2 = 0$ , map itself  $z'_1 = z'_2 = 0$ .

$$T_a^x F \in \mathcal{D}_x, \text{ if } F \in \mathcal{D}$$

It's is very useful to use other form  $\mathcal{D}_x$

$$F(z) = F(z, 1)$$

Because of the homogeneity of  $F(z_1, z_2)$ , know  $F(z)$  is sufficient to construct  $F(z_1, z_2)$

$$F(z_1, z_2) = z_2^{n_1-1} z_1^{n_2-1} f\left(\frac{z_1}{z_2}\right)$$

In this space  $T_a^x$  looks like

$$T_a^x f(z) = \alpha(z, a) f(z_a)$$

$$z_a = \frac{a_{11}z + a_{21}}{a_{12}z + a_{22}}, \quad \alpha(z, a) = (a_{12}z + a_{22})^{n_1-1} (a_{11}z + a_{21})^{n_2-1}$$

The transformation  $T_a^x F(z_1, z_2)$  may be written by multiplication

$$\begin{pmatrix} \dots & \dots \\ z_1 & z_2 \end{pmatrix} \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} = \begin{pmatrix} \dots & \dots \\ z'_1 & z'_2 \end{pmatrix}$$

The matrix consisting of  $z_1$  and  $z_2$

$$\begin{pmatrix} \cdots & \cdots \\ z_1 & z_2 \end{pmatrix} = \begin{pmatrix} z_1^{-1} & \cdots \\ 0 & z_2 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ \frac{z_1}{z_2} & 1 \end{pmatrix}$$

as any matrix of  $SL(2, \mathbb{C})$ , may decomposed as a product

$$a = k \begin{pmatrix} 1 & 0 \\ z & 1 \end{pmatrix}, \text{ if } a_{22} \neq 0 \quad k = \begin{pmatrix} z_1^{-1} & 0 \\ 0 & z_2 \end{pmatrix}$$

$SL(2, \mathbb{C})/K$  maps to  $z \in \mathbb{C}$ .