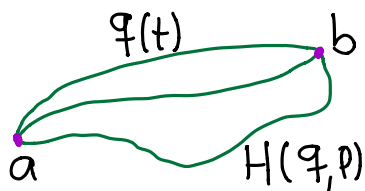


# Path integral



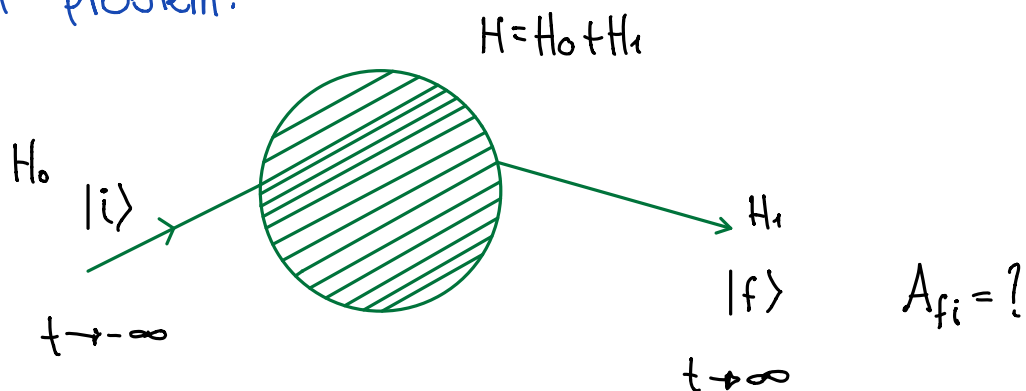
$$\langle b|a \rangle = \lim_{N \rightarrow \infty} \int \prod_{i=1}^N \frac{dp_i}{2\pi} dq_i e^{i(p_i \frac{\delta q_i}{\delta t} - H) \delta t}$$

$$= \int Dp(t) Dq(t) e^{i \int_a^b dt (p\dot{q} - H)}$$

then,  $\langle b|a \rangle \propto \int Dq(t) e^{iS[q]}$

$$S[q] = \int dt \mathcal{L}(q, \dot{q})$$

Dispersion problem:



S matrix:

$$S = T \exp \left( -i \int_{-\infty}^{\infty} dt H_I(t) \right)$$

$$S_{fi} = \langle f | S | i \rangle$$

Then,

$$\langle f | e^{-iH\tau} | i \rangle = \int dq_f dq_i \langle f | q_f \rangle \langle q_f | e^{-iH\tau} | q_i \rangle \langle q_i | i \rangle$$

$$= \int dq_f dq_i \psi_f^*(q_f) \langle q_f | e^{-iH\tau} | q_i \rangle \psi_i^*(q_i)$$

In particular:

$$Z = \langle 0 | e^{-iH\tau} | 0 \rangle$$

dispersion of amplitude of  $|0\rangle \rightarrow |0\rangle$ .

Path integral:

$$Z \equiv \int Dq(t) e^{iS[q]}$$

Quantization of the scalar field:

$$q \rightarrow \varphi: L \longrightarrow \int d^3x \mathcal{L} \rightarrow S[\varphi] = \int d^4x \mathcal{I}(\varphi)$$

$$\varphi \rightarrow \hat{\varphi}: \langle q_a, t_a | q_b, t_b \rangle \longrightarrow \langle \varphi_b(\bar{x}, t'') | \varphi_a(\bar{x}', t') \rangle$$

$$\lim_{\substack{t' \rightarrow -\infty \\ t'' \rightarrow \infty}} = \int D\pi D\varphi e^{i \int d^4x \mathcal{I}(\varphi)}$$

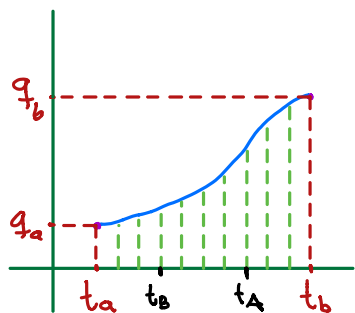
therefore,  $Z \propto \int D\varphi e^{iS[\varphi]}$

$$\langle 0 | T(\hat{\varphi}(x_1) \dots \hat{\varphi}(x_n)) | 0 \rangle = ?$$

Consider

$$\langle q_b | t_b | Q(t_A) Q(t_B) | q_a, t_a \rangle$$

$$t_A > t_B$$



$$= \int \prod_i dq_i \langle q_b, t_b | q_{N-1}, t_{N-1} \rangle \dots \langle q_{A+1}, t_{A+1} | Q(t_A) | q_A, t_A \rangle$$

$$\times \langle q_{B+1}, t_{B+1} | Q(t_B) | q_B, t_B \rangle \dots \langle q_1, t_1 | q_a, t_a \rangle$$

$$= \int \prod_i dq_i \underbrace{q_A q_B}_{\text{permutables}} \langle q_b, t_b | q_{N-1}, t_{N-1} \rangle \dots \langle q_1, t_1 | q_a, t_a \rangle$$

$$= \langle q_b, t_b | Q(t_B) Q(t_A) | q_a, t_a \rangle \quad t_B > t_A$$

therefore,

$$\langle q_b, t_b | T[Q(t_A) | Q(t_B)] | q_a, t_a \rangle = \int Dp Dq q(t_A) q(t_B) e^{iS(q,p)}$$

In general,

$$\langle b | T(Q(t_n) \dots Q(t_1)) | a \rangle = \int Dp Dq q(t_1) \dots q(t_n) e^{iS(q,p)}$$

$$\langle 0 | \hat{\varphi}(x_1) \dots \hat{\varphi}(x_n) | 0 \rangle = \int D\pi D\varphi \varphi(x_1) \dots \varphi(x_n) e^{iS[\varphi]}$$

with fixed boundary conditions:  $\varphi(t \rightarrow \pm\infty)$

then,  $\int D\pi$  can generally be "incorporated" into a normalization factor.

Definition:

$$W[J] = \int D\pi D\varphi e^{i \int d^4x (L + J(x)\varphi(x))}$$

$$\equiv {}_{out} \langle 0 | 0 \rangle_m^J$$

by definition, we require:

I.  $W[J=0] = 1$  (Normalisation), is enough with consider in general

$$W[J] \equiv \frac{1}{Z} \int D\varphi e^{iS[\varphi, J]} ; Z \equiv \int D\varphi e^{iS[\varphi]} = \left[ \int D\pi \right]^{-1}$$

$$\text{II. } \frac{\delta W}{\delta J(x)} \Big|_{J=0} = \int D\pi D\varphi \frac{\delta}{\delta J(x)} e^{iS[\varphi, J]} \Big|_{J=0}$$

$$= \int D\pi D\varphi (i) \left( \frac{\delta S[\varphi, J]}{\delta J(x)} \right) e^{iS[\varphi, J]} \Big|_{J=0}$$

but,  $\frac{\delta S}{\delta J(x)} = \varphi(x) \rightarrow \frac{\delta W}{\delta J(x)} \Big|_{J=0} = i \int D\pi D\varphi \varphi(x) e^{iS[\varphi]}$

iterate:

$$\frac{\delta^n W[J]}{\delta J(x_n) \cdots \delta J(x_1)} \Big|_{J=0} = (i)^n \langle 0 | T(\varphi(x_1) \cdots \varphi(x_n)) | 0 \rangle$$

then,  $G^{(n)}(x_1, \dots, x_n) = (-i)^n \frac{\delta^n W[J]}{\delta J(x_n) \cdots \delta J(x_1)} \Big|_{J=0}$

$W[J]$ : Generating function:

$$W[J] = \sum_{n=0}^{\infty} \frac{1}{n!} \int d^4x_1 \cdots d^4x_n \frac{\delta^n W[J]}{\delta J(x_n) \cdots \delta J(x_1)} \Big|_{J=0} J(x_1) \cdots J(x_n)$$

$$\langle 0 | 0 \rangle^J = W[J] = \sum_{n=0}^{\infty} \frac{1}{n!} \int d^4x_1 \cdots d^4x_n (i)^n G^{(n)}(x_1, \dots, x_n) J(x_1) \cdots J(x_n)$$

