$$g(\vec{e}_{A\dot{B}}, \vec{e}_{c\dot{b}}) = -\epsilon_{Ac} \epsilon_{\dot{B}\dot{D}} \qquad (*)$$

$$\vec{e}_{A\dot{B}} = \begin{pmatrix} \vec{E}_{4} & \vec{E}_{2} \\ \vec{E}_{1} & \vec{E}_{3} \end{pmatrix}$$

$$\vec{e}_{A\dot{B}} = \frac{1}{\sqrt{2}} \vec{D}_{A\dot{B}}^{\alpha} \vec{e}_{\alpha}$$

As consequence of (*).

The scalars are called conexion symbols or infield.

The symbols of Levi-Cirita are used to raise and lower spinorial indices A,B. Using the convension.

$$\Psi_A = \mathcal{E}_{AB} \Psi^B$$
, $\Psi^A = \Psi = \Psi_B \mathcal{E}^{BA}$

then

$$\Psi^{2} = \Psi_{1}, \quad \Psi' = -\Psi_{2}$$

$$\Psi^{A} = \Psi_{B} \mathcal{E}^{BA}$$

$$\Psi^{2} = \Psi_{B} \mathcal{E}^{B2} \qquad \mathcal{E}^{AB} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

$$\Psi^{2} = \Psi_{1} \mathcal{E}^{A} + \Psi_{2} \mathcal{E}^{AB}$$

$$\Psi^{3} = \Psi_{4} \mathcal{E}^{AB} + \Psi_{5} \mathcal{E}^{AB}$$

the antisymmetrie of EAB, implies

$$\Psi^{A} \bigoplus_{A} = \Psi^{A} \mathcal{E}_{AB} \bigoplus_{B} = -\Psi^{A} \mathcal{E}_{BA} \bigoplus_{B} = -\Psi_{B} \bigoplus_{B} = -\Psi_{A} \bigoplus_{A} \Phi^{A}.$$

$$\Longrightarrow \Psi^{A} \Psi_{A} = 0.$$

Also,

$$\mathcal{E}^{A}_{B} = \delta^{A}_{B}$$
 and $\mathcal{E}_{A}^{B} = -\delta^{B}_{A}$.

$$\delta_{c}^{A} = \mathcal{E}_{BC} \mathcal{E}^{BA}$$

$$\delta_{l}^{I} = \mathcal{E}_{Bl} \mathcal{E}^{Bl} = \mathcal{E}_{ll} \mathcal{E}^{ll} + \mathcal{E}_{2l} \mathcal{E}^{2l} = 1.$$

$$\delta_{2}^{I} = \mathcal{E}_{B2} \mathcal{E}^{Bl} = \mathcal{E}_{l2} \mathcal{E}^{ll} + \mathcal{E}_{22} \mathcal{E}^{2l} = 0.$$

Proof: Any antisymmetric 2x2 matrix is of the form

$$\begin{pmatrix} 0 & \alpha \\ -\alpha & 0 \end{pmatrix}$$

which may be wriften as $\alpha(E_{AB})$. Then Y_{AB} is antisymmetric and $Y_{AB} = \alpha E_{AB}$, for some a, Contracting by E^{AB} , then $Y^{A}_{A} = 2\alpha$.

$$\psi^{B}_{B} = \varepsilon^{AB} \psi_{AB} = Q \varepsilon_{AB} \varepsilon^{AB} = Q \varepsilon^{B}_{B}$$

$$\Longrightarrow \psi^{B}_{B} = Q \delta^{B}_{B} = 2Q.$$

In a similar way

$$\Psi^{AB} = \underline{1} \Psi^{R}_{R} \varepsilon^{AB}$$

If (M^Rs) a 2×2 matrix (real or complex) $\mathcal{E}_{AC}M^A{}_BM^C{}_D = (def(M^Rs)) \mathcal{E}_{BD}$

then $Y_{DB} = E_{AC}M^{A}_{D}M^{c}_{B} = -E_{CA}M^{c}_{B}M^{A}_{D} = -\Psi_{BD}.$

$$\Psi_{R}^{R} = \Psi_{1}^{1} + \Psi_{2}^{2} = -\Psi_{21} + \Psi_{12} = 2\Psi_{12}$$

$$= 2 \mathcal{E}_{AC} M_{1}^{A} M_{2}^{C} = 2(M_{1}^{1} M_{2}^{2} - M_{1}^{2} M_{1}^{1})$$

$$= 2 \mathcal{E}_{AC} (M_{5}^{R})$$

Choise of connection symbols

Comparing the
$$\vec{E}_a = (\vec{E}_A \vec{B}) = \begin{pmatrix} \vec{E}_A & \vec{E}_2 \\ \vec{E}_1 & -\vec{E}_3 \end{pmatrix}$$

and
$$\vec{e}_{A\dot{B}} = \frac{1}{\sqrt{2}} \vec{\nabla}^{\alpha}_{A\dot{B}} \vec{e}_{\alpha}$$

$$(D'_{A\dot{B}}) = \begin{pmatrix} O & I \\ I & O \end{pmatrix} , \quad (D'_{A\dot{B}}) = \begin{pmatrix} O & -\dot{C} \\ \dot{C} & O \end{pmatrix}$$

$$(O^3A\dot{g}) = \begin{pmatrix} 1 & O \\ O & -1 \end{pmatrix} , \quad (O^4A\dot{g}) = \begin{pmatrix} \dot{t} & O \\ O & \bar{t} \end{pmatrix}$$

$$(\mathring{\mathcal{D}}_{A\dot{B}}) = \begin{pmatrix} \mathring{\mathcal{D}}_{A\dot{B}} \end{pmatrix} =$$

$$(\sigma^3 A \dot{g}) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \qquad , \qquad (\sigma^4 A \dot{g}) = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$(\mathcal{D}'_{A\dot{B}}) = \begin{pmatrix} \mathcal{O} & 1 \\ 1 & \mathcal{O} \end{pmatrix} , \quad (\mathcal{D}'_{A\dot{B}}) = \begin{pmatrix} -1 & \mathcal{O} \\ \mathcal{O} & -1 \end{pmatrix}$$

$$(\sigma^3 A \dot{g}) = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} , \quad (\sigma^4 A \dot{g}) = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$(\overline{U_{AB}^{a}}) = \begin{cases} U_{AB}^{a} & \text{Euclidean} \\ U_{AB}^{a} & \text{Lovent tian.} \end{cases}$$

Contracting with orcio

As the T symbols are invertibles.

If tab...s the component of a tensor with respect to the orthonormal base 3 = 1, = 2, = 3, = 1, the tensorial equivalent.

1s convenient

$$t_{A\dot{A}B\dot{B}...D\dot{D}} = \frac{1}{\sqrt{2}} \vec{D}_{A\dot{A}} \frac{1}{\sqrt{2}} \vec{D}_{B\dot{B}}...\frac{1}{\sqrt{2}} \vec{D}_{D\dot{D}} t_{ab}...d.$$

also

Honework:

$$t_{ab\cdots d} = \left(\frac{1}{\sqrt{2}} \int_{ab}^{b} \left(\frac{1}{\sqrt{2}} \int_{ab}^{b} b \right) \cdot \cdot \cdot \cdot \left(\frac{1}{\sqrt{2}} \int_{ab}^{b} b \right) t_{ab} b \cdot \cdot \cdot b b$$

$$\sqrt{a} \vec{e}_{a} = -\frac{1}{\sqrt{2}} \vec{0}_{A\dot{A}} \sqrt{a\dot{A}} \vec{e}_{a}$$

$$= -\sqrt{a\dot{A}} \vec{e}_{A\dot{A}}$$

where $\vec{e}_{ai} \simeq \vec{e}_{a} \otimes \vec{e}_{a}$ Spin space.