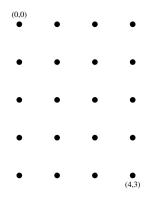
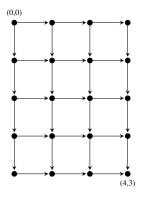
Computing for Applied Mathematics Fall 2022

Least Cost Path in a Rectangular Grid

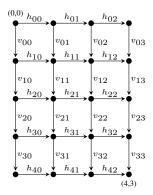
Consider a rectangular grid points/nodes at locations (i,j) in a matrix where i and j are integers with $0 \le i \le m$ and $0 \le j \le n$. Here, as usual for locations in a matrix, the index i refers to a row and index j refers to a column. For example, we can take m=4 and n=3 and our grid is shown in the following figure.



Assume that for each node we connect it to its neighbor on its right (if there is one) by a horizontal arrow, and to its neighbor below by a vertical arrow (if there is one).

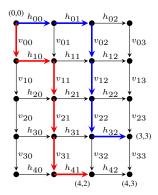


Assume each horizontal arrow from (i, j) to (i, j + 1) is assigned a cost denoted by h_{ij} , and each vertical arrow from (i, j) to (i + 1, j) is assigned a cost v_{ij} .



The problem is to find the least cost path from (0,0) to (m,n) along a sequence of arrows, where the cost of a path is the sum of the costs at all of its individual arrows. This is an example of a problem that can be solved using dynamic programming. The basic idea is to work backwards. In order to get from (0,0) to (m,n) we first have to first visit either the node (m,n-1) or (m-1,n).

For example, suppose we already know the best path from (0,0) to (4,2) shown in red, and the best path from (0,0) to (3,3) shown in blue, in the following figure.



Then we need only decide between the completions of two possible paths.

The best path from (0,0) to (4,3) would involve following the red path and then a final horizontal move or taking the blue path followed by a final vertical. Assuming the cost of the red path is $C_{4,2}$ the cost of it plus the final move is

$$C_{4,2} + h_{42}$$

and if the cost of the blue path is $C_{3,3}$ then the cost of that path plus the final move is

$$C_{3,3} + v_{33}$$
.

Comparing these two costs leads to our decision as to which path to take. If there is a tie, we can take either path. We then conclude that

$$C_{4,3} = \min\{C_{4,2} + h_{42}, C_{3,3} + v_{33}\}.$$

We refer a node (i', j') as a *predecessor* of a node (i, j) if there is an arrow pointing from (i', j') to (i, j). Observer that a node can have 0, 1 or 2 predecessors.

- (0,0) has 0 predecessors,
- (i,0) has 1 predecessor if i > 0,
- (0, j) has 1 predecessor if j > 0, and
- (i, j) has 2 predecessors if i > 0 and j > 0.

For any node (i,j) we denote the cost of an optimal path from (0,0) to (i,j) by $C_{i,j}$

We define a direction $d_{i,j}$ associated with any node with at least one predecessor. If there is a least cost path from (0,0) to (i,j) whose final step is from (i-1,j) to (i,j) we define $d_{ij} = V$. Otherwise, there must be a least cost path from (0,0) to (i,j) whose final step is from (i,j-1) to (i,j) and we define $d_{ij} = H$.

Key observation. Once we have determined $d_{i,j}$ for every node (i,j) we can find an optimal path from (0,0) to (m,n) working backwards from (m,n) to find out least cost path from (0,0) to (m,n). I.e. if $d_{m,n} = H$ then the optimal path visited (m,n-1) and if $d_{m,n} = V$ then our optimal path visited (m-1,n) before reaching (m,n) in the next step. Whichever node we determine to have visited, we repeat this process to determine the previously visited node, until we get to (0,0).

Getting started

To get started with the algorithm, note that there is only one path along the right hand border of our grid from (0,0) to (m,0) so we can initialize $C_{0,0}=0$ and $C_{i,0}=\sum_{p=0}^{m-1}v_{p0}$ for $i=1,\ldots,m,$ and similarly there is only one path across the top from (0,0) to (0,n) we can immediately calculate the values of $C_{0,j}=\sum_{p=0}^{n-1}h_{0p}$ for $j=1,\ldots,n.$

Now whenever we know the values of $C_{i',j'}$ for every predecessor of (i',j') of (i,j) so we can calculate $C_{i,j}$ and $d_{i,j}$, so we proceed to compute these quantities for the nodes in the following order

Observe that if we use this ordering of the nodes, whenever we reach node (i, j) we will have already found $C_{i',i'}$ and $d_{i',i'}$ for its two predecessors.

Pseudo-Code

We can now write some pseudo-code for finding a solution to our problem in the general case. The inputs to our problem are:

- *m*, *n*
- an $m \times (n+1)$ matrix $V = (v_{ij})_{i=0,\dots,m-1}^{j=0,\dots,n}$ with v_{ij} giving the cost of a vertical (down) move from (i,j) to (i+1,j)
- an $(m+1) \times n$ matrix $H = (h_{ij})_{i=0,\dots,m}^{j=0,\dots,n-1}$ with h_{ij} giving the cost of a horizontal (right) move from (i,j) to (i,j+1).

We'll use an $(m+1) \times (n+1)$ matrix $C = (c_{ij})_{i=0,\dots,m}^{j=0,\dots,n}$ to store the *cost* of a shortest path from (0,0) to (i,j) for $i=0,\dots,m$ and $j=0,\dots,n$.

We'll use an $(m+1) \times (n+1)$ matrix of strings $D = (d_{ij})_{i=0,\dots,m}^{j=0,\dots,n}$ to store, at each node (i,j) the value "H" if there is a best path from (0,0) to (i,j) whose last step is a move from predecessor (i,j-1) to (i,j) otherwise the value is "V" since there must be a best path from (0,0) to (i,j) whose last step is a move from the predecessor (i-1,j) to (i,j).

Now we proceed as follows to calculate the terms in the matrices C and D.

```
Initialize c_{0,0} = 0

Initialize c_{i,0} = \sum_{p=0}^{i-1} v_{p0} and d_{i,0} = \text{"V"} for i = 1, \dots, m.

Initialize c_{0j} = \sum_{p=0}^{j-1} h_{0p} and d_{0,j} = \text{"H"} for j = 1, \dots, n.

For i = 1, \dots, m:

For j = 1, \dots, n:

If C_{i-1,j} + v_{i-1,j} \leq C_{i,j-1} + h_{i,j-1}

Take C_{i,j} = C_{i-1,j} + v_{i-1,j} and d_{i,j} = \text{"V"}

Else
```

Take
$$C_{i,j} = C_{i,j-1} + h_{i,j-1}$$
 and $d_{i,j} = \text{"H"}$

Observe that once we run this algorithm, for every node (i, j) except for (0, 0) it is the case that

- either (i-1,j) is a predecessor of (i,j) and $d_{i,j} = \text{"V"}$, or
- (i, j 1) is a predecessor of (i, j) and $d_{i,j} =$ "H".

This gives us the cost $C_{i,j}$ of the optimal path from (0,0) to (i,j) with the cost of (0,0) to (m,n) as a special case. Next we carry out the following steps to find the actual optimal path - the list of nodes visited by the optimal path.

```
Initialize list of OptimalPathNodes list as [(m,n)] While length of Optimal PathNodes list is less than m+n+1 Let (i,j) be the last element in OptimalPathNodes. If (i-1,j) is a predecessor of (i,j) and d_{(i,j)} ="V" Append (i-1,j) to OptimalPathNodes Else Append (i,j-1) to OptimalPathNodes Reverse the OptimalPathNodes list Return OptimalPathNodes list
```

Solving by brute-force

For small values of m and n it is possible to enumerate every possible path from (0,0) to (m,n). Since every such path must contain m horizontal moves and n vertical moves the paths are in one-to-one correspondence with the permutations of the list consisting of m values of "H" and n values of "V". The number of such permutations is

$$\binom{m+n}{n}$$
.

There is a function in the *sympy* package that can be used to generate all permutations of a list that contains repeated elements. The following code

```
import numpy as np
m=3
n=2
L=["V" for i in range(m)]+["H" for i in range(n)]
allpaths=multiset permutations(L)
```

```
for a in allpaths:
    print(a)
```

yields the output

```
['H', 'H', 'V', 'V', 'V']
['H', 'V', 'H', 'V', 'V']
['H', 'V', 'V', 'H', 'V']
['H', 'V', 'V', 'V', 'H', 'V']
['V', 'H', 'H', 'V', 'V', 'V']
['V', 'H', 'V', 'H', 'V', 'H']
['V', 'V', 'H', 'V', 'H', 'V']
['V', 'V', 'H', 'Y', 'H', 'H']
```

To get the optimal path, we simply compute the cost of each path and take a path that gives the lowest cost.