

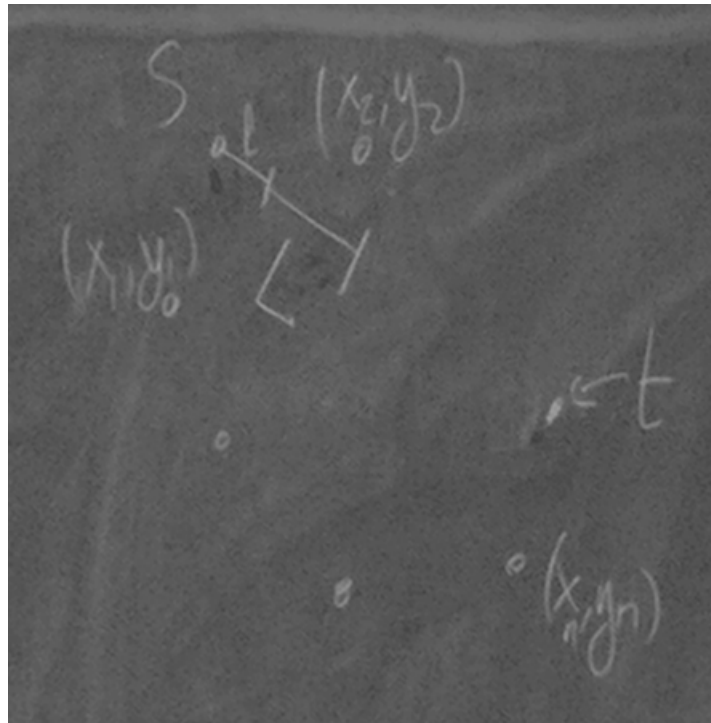
LECTURE 25

Friday March 10, 2017

based on notes by Denis Pankratov

Assignment 2

Question 3

Figure 1: *Visualization of problem**Approach:* Modified Dijkstra (P, n, s, t, l) P – array of points $P[i].x, P[i].y$ Distance $2D(P_1, P_2)$ = Euclidean 2D distance between points P_1 & P_2 Algorithm:

```

1  def ModifiedDijkstra(P, n, s, t, l):
2    let W be an array of size nxn

```

```

3   for i = 1 to n:
4       for j = 1 to n:
5           W[i,j] = max(Distance2d(P[i],P[j]) - 1, 0)
6   init array L of size n
7   /* L[i] will contain smallest value of L required to reach i from s
8       by edges of length <= L */
9   for i = 1 to n:
10      L[i] = float('inf')
11  L[S] = 0
12
13  Q = PriorityQueue([n]) /* ordered by min value of L[.] */
14
15  while Q is not empty:
16      V = Q.ExtractMin()
17      for u = 1 to n:
18          # See Figure 2 (below)
19          if max(L[v],W[v,u]) < L[u]:
20              L[u] = max(L[v],W[v,u]) /* causes DecreaseKey */
21
22  return L[t]

```

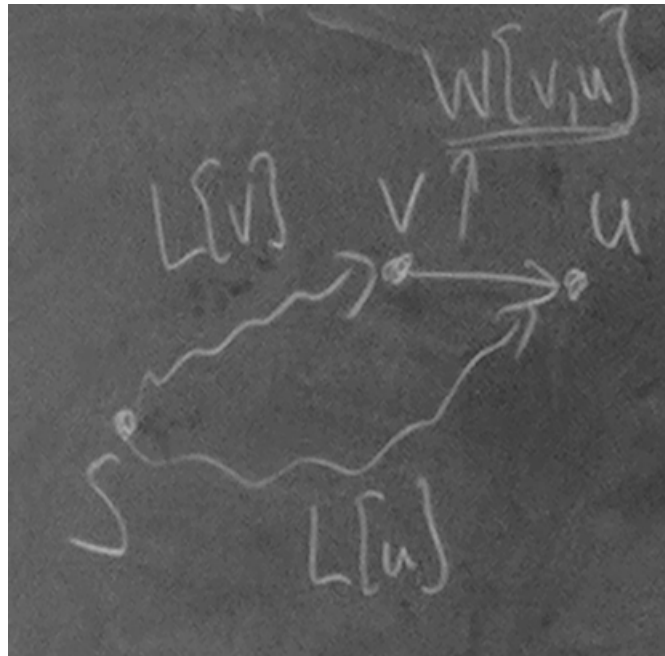


Figure 2: Visualization of DecreaseKey loop

Runtime: n – ExtractMin operations

n^2 – DecreaseKey operations

If we use binary heaps, we get $\Theta(n^2 \log n)$ runtime.

Array implementation of PQ

$A[i]$ – priority of node i , or NIL if $i \notin PQ$

DecreaseKey takes $\mathcal{O}(1)$

ExtractMin takes $\mathcal{O}(n)$

ModifiedDijkstra runs in $\mathcal{O}(n^2)$ with array input implementation of PQ .

Set of nodes U – processed nodes (nodes taken off the queue)

$T = [n] \setminus U$ – set of *not yet fully processed* nodes

For $u \in U$, $L[u]$ is computed correctly.

For $u \in T$, $L[u]$ stores smallest L so that u is reachable from s via edges of length $\leq L$ & using as intermediate nodes only nodes from U .

Question 5

$G = (V, E), c, s, t$ flow network

c – integral

f – max flow, integral

$p : E \rightarrow \mathbb{N}$ price

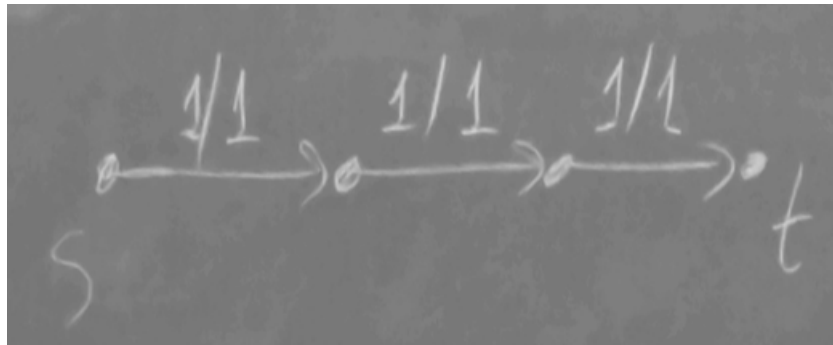


Figure 3: Visualization of problem

Algorithm: Considering that $(i, j) \in E^* \Leftrightarrow (i, j) \in E$ or $(j, i) \in E$

```

1  def ComputeEdges(G, s, t, c, p, f):
2      create a weigh function w: E* → R
3      for e in E_f:
4          if c_f(e) > 0:
5              w(e) = 0
6
7      for e in E:
8          if c_f(e) = 0:
9              w(e) = p(e)
10

```

```

11  # On CLRS,  $v.pi = prev[v]$ 
12  Run Dijkstra on  $(V, E^*)$  w/ weights  $w$  from  $s$ ,
13      which returns two arrays  $prev[-]$ ,  $dist[.]$ 
14
15  Ans = []
16  cur = t
17
18  while cur  $\neq s$ :
19      if  $c_f(prev[cur], cur) = 0$  and  $(prev[cur], cur) \in E$ :
20          Ans.insert( $(prev[cur], cur)$ )
21          cur = prev[cur]
22
23  return Ans

```

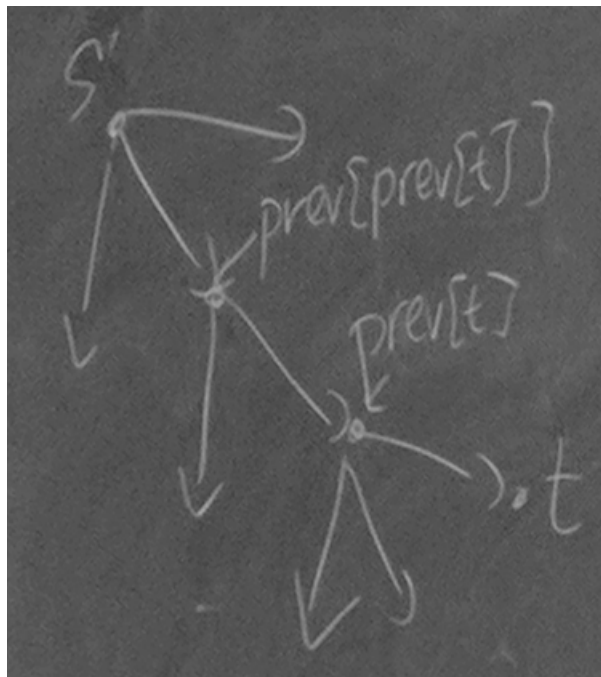


Figure 4: Visualization of algorithm: flow is a function; flow value is a real number

Question 1

(d)

False: Only update edges from a vertex u when u is taken off the queue & u is taken only once off the queue.

(g)

False:

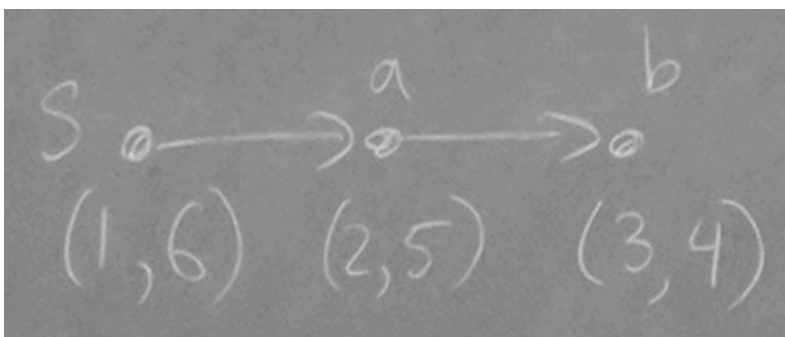


Figure 5: Graph is not strongly connected, so we can only move from *left to right*

Question 4

(e)

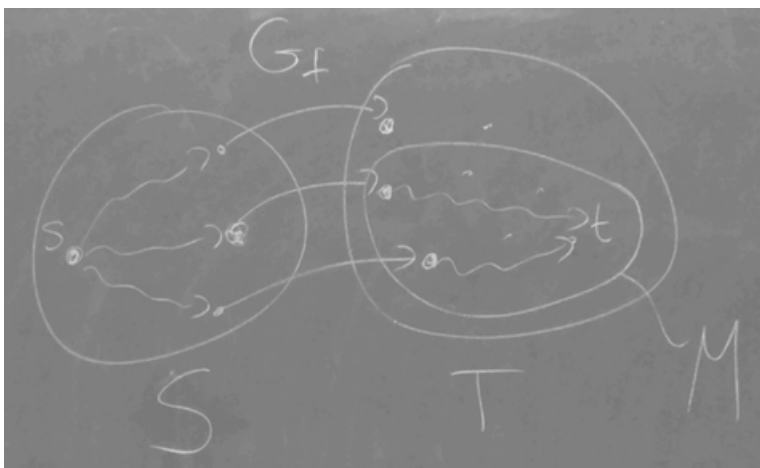


Figure 6: M = set of all nodes in G_f so that t is reachable from those nodes

1. Compute max flow f
2. Compute S = set of nodes reachable from s in G_f – *BFS*
3. Compute G_f^T (transpose of the graph, all edges reversed)
4. Run *BFS* from t in G_f^T & compute M
5. Collect all edges $e = (u, v) \in E$ so that $u \in S, v \in M$