## TemaFinale23

A company intends to build a *ColdStorageService*, composed of a set of elements:

- 1. a service area (rectangular, flat) that includes:
  - o an INDOOR port, to enter food (fruits, vegetables, etc.)
  - o a ColdRoom container, devoted to store food, upto MAXW kg.

The *ColdRoom* is positioned within the service area, as shown in the following picture:



2. a DDR robot working as a *transport trolley*, that is intially situated in its HOME location. The transport trolley has the form of a square of side length **RD**.

The transport trolley is used to perform a deposit action that consists in the following phases: GESTITO IN SPRINT1

- 1. pick up a food-load from a *Fridge truck* located on the INDOOR
- 2. go from the INDOOR to the PORT of the ColdRoom
- 3. deposit the food-load in the *ColdRoom*
- 3. a ServiceAcessGUI that allows an human being to see the current current weigth of the material stored in the ColdRoom and to send to the ColdStorageService a request-to store new FW kg of food. If the request is accepted, the services return a ticket that expires after a prefixed amount of time (TICKETTIME secs) and provides a field to enter the ticket number when a *Fridge truck* is at the INDOOR of the service.
- 4. a ServiceStatusGUI that allows a Service-manager (an human being) to supervises the state of the service.

## Alarm requirements

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The system includes a a *Sonar* and a *Led* connected to a RaspnerryPi.

The Sonar is used as an 'alarm device': when it measures a distance less that a prefixed value **DLIMT**, the *transport trolley* must be stopped; it will be resumed when *Sonar* detects again a distance higher than **DLIMT**.

The *Led* is used as a *warning devices*, according to the following scheme:

1 of 2 6/18/23, 11:17

- the Led is off when the transport trolley is at HOME
- the *Led* **blinks** while the *transport trolley* is moving
- the *Led* is **on** when *transport trolley* is stopped.

## Service users story

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The story of the *ColdStorageService* can be summarized as follows:

- 1. <u>A Fridge truck driver uses the ServiceAcessGUI to send a request to store its load</u> of **FW** kg. If the request is accepted, the driver drives its truck to the service, before the ticket exipration time **TICKETTIME**.
- 2. When the truck is at the INDOOR of the service, the driver uses the ServiceAcessGUI to enter the ticket number and waits until the message **charge taken** (sent by the ColdStorageService) appears on the ServiceAcessGUI. At this point, the truck should leave the INDOOR.
- 3. When the service accepts a ticket, the *transport trolley* reaches the INDOOR, picks up the food, sends the **charge taken** message and then goes to the *ColdRoom* to store the food.
- 4. When the deposit action is terminated, the *transport trolley* accepts another ticket (if any) or returns to HOME.
- 5. While the *transport trolley* is moving, the <u>Alarm requirements</u> should be satisfied. However, the *transport trolley* should not be stopped if some prefixed amount of time (**MINT** msecs) is not passed from the previous stop.
- 6. A Service-manager migtht use the ServiceStatusGUI to see:
  - the **current state** of the **transport trolley** and it **position** in the room;
  - the **current weigth** of the material stored in the *ColdRoom*;
  - the **number of store-requests rejected** since the start of the service.

## About requirements

The development of the *ServiceStatusGUI* is optional. However, it is required if the working team is composed of 3 person.

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QUANTO IL CAMION LASCIA

LA MIDOOR?

2 of 2 6/18/23, 11:17