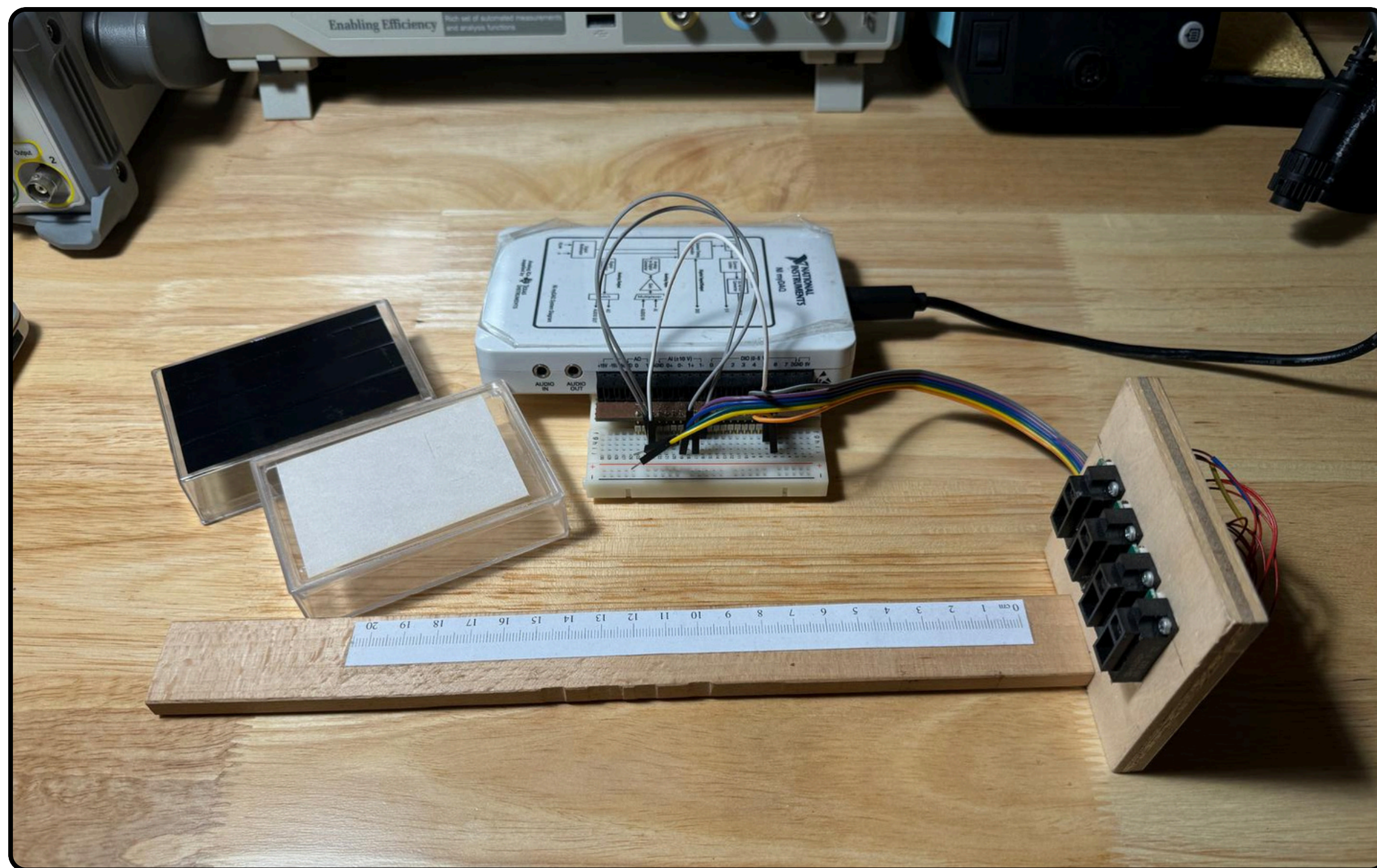
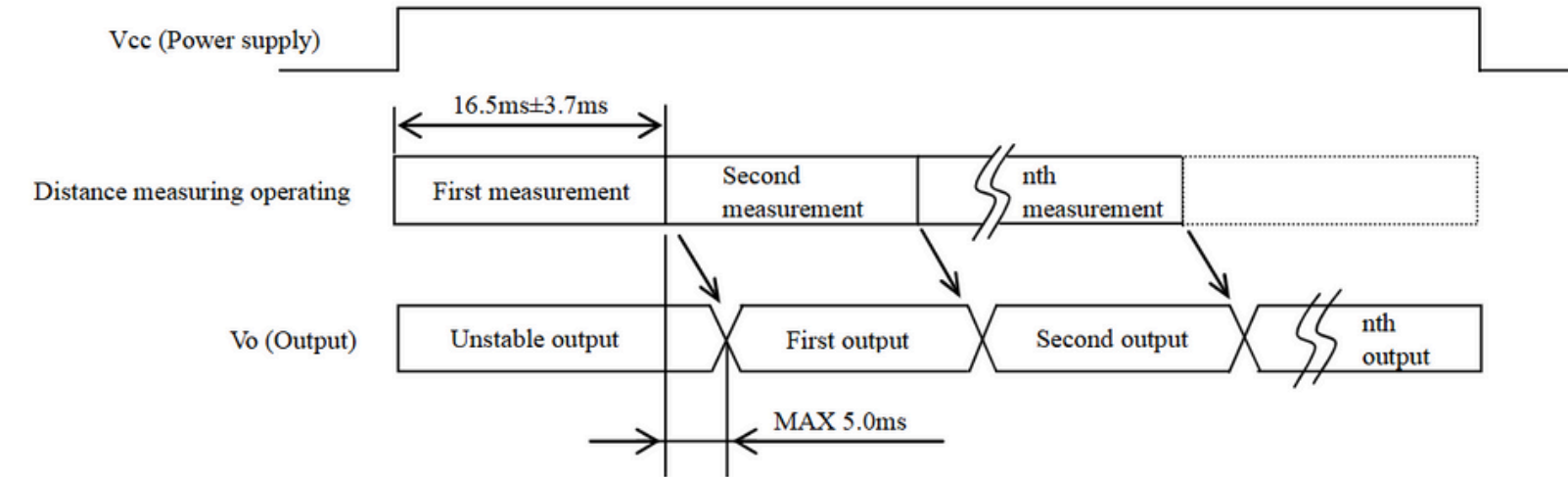
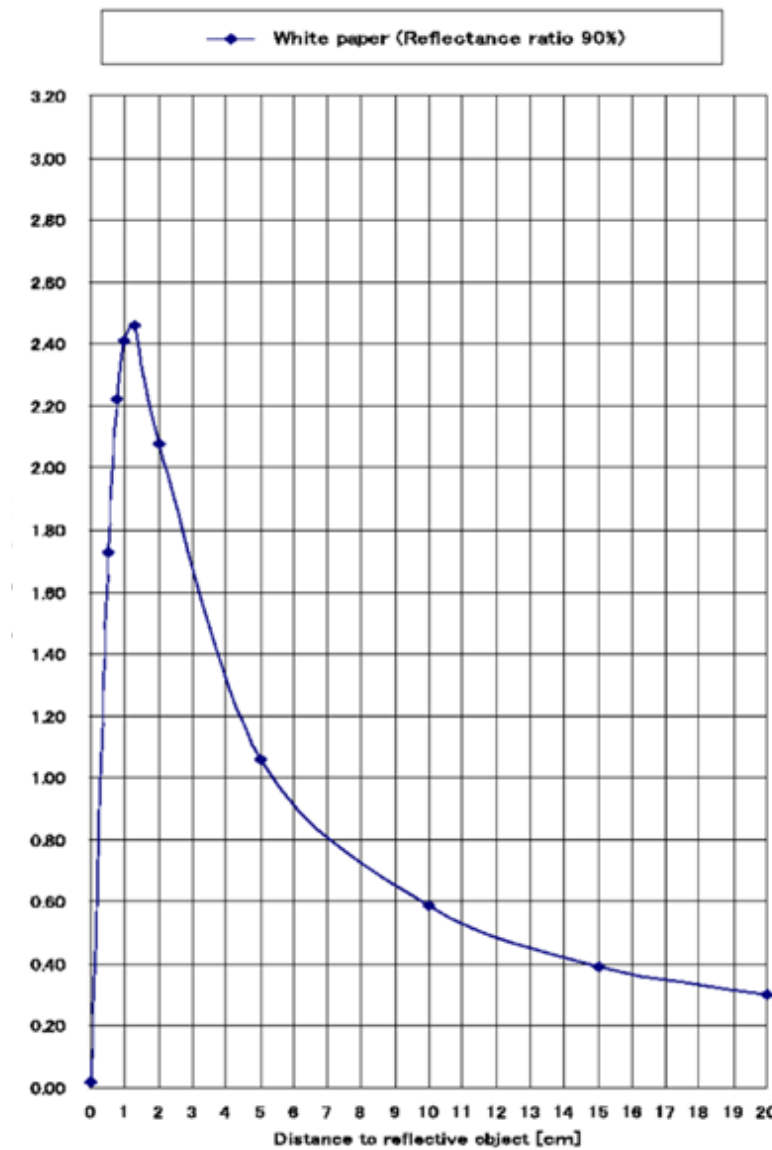


Caratterizzazione sensori di distanza



Specifiche di progetto

- Sensore di distanza analogico SHARP GP2Y0A51SK0F

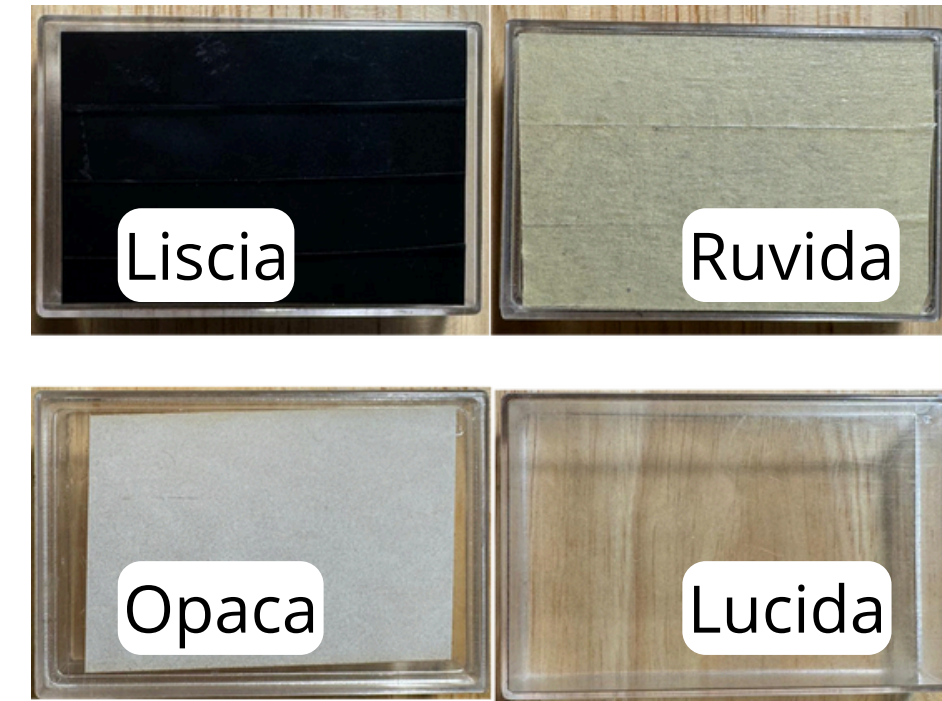


(Ta=25°C, Vcc=5V)

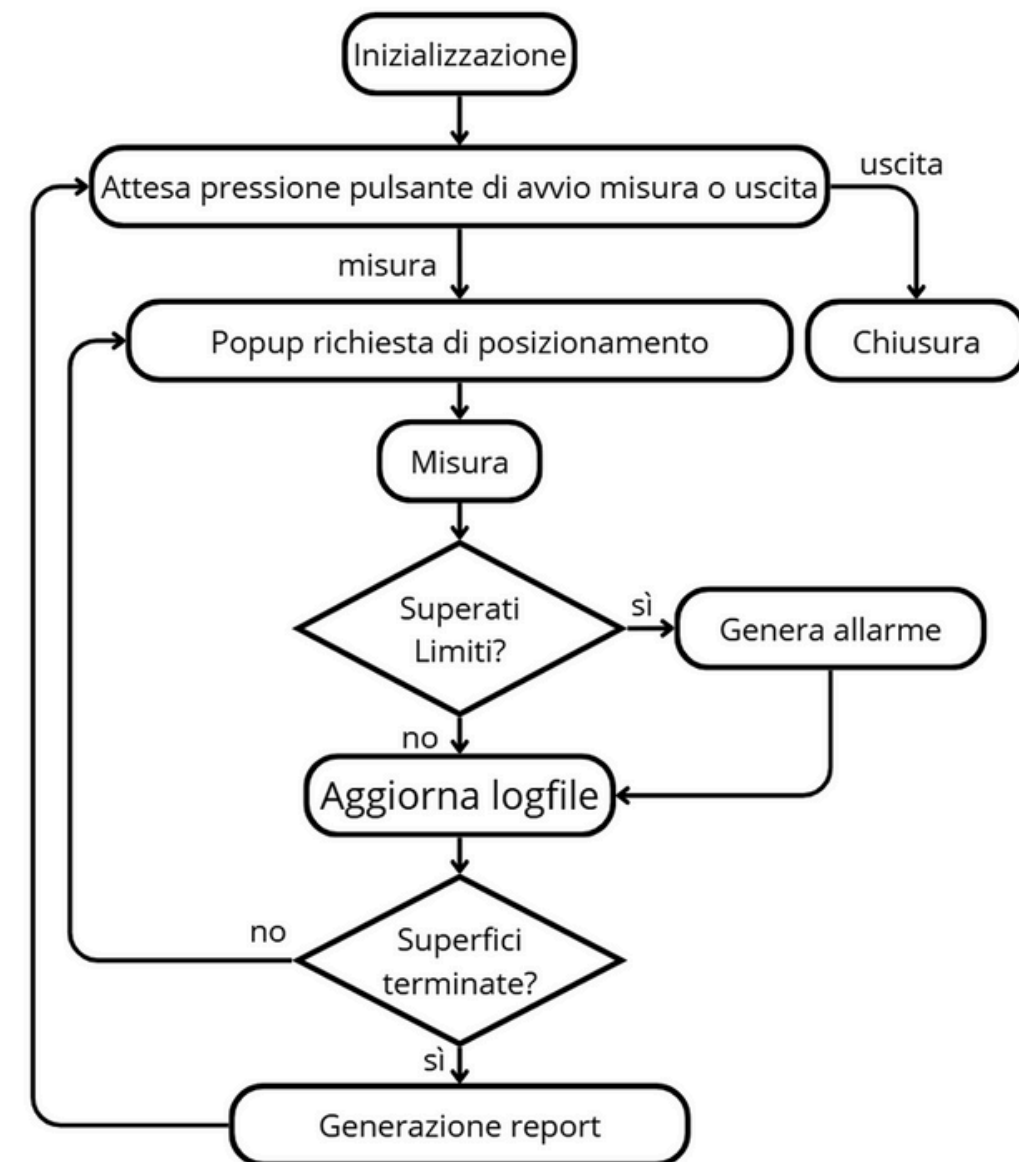
Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Measuring distance range	ΔL	(Note 1)	2	-	15	cm
Output terminal voltage	V_o	L=15cm (Note 1)	0.25	0.4	0.55	V
Output voltage difference	ΔV_o	Output change at L change (15cm → 2cm) (Note 1)	1.35	1.65	1.95	V
Average supply current	Icc	L=15cm (Note 1)	-	12	22	mA

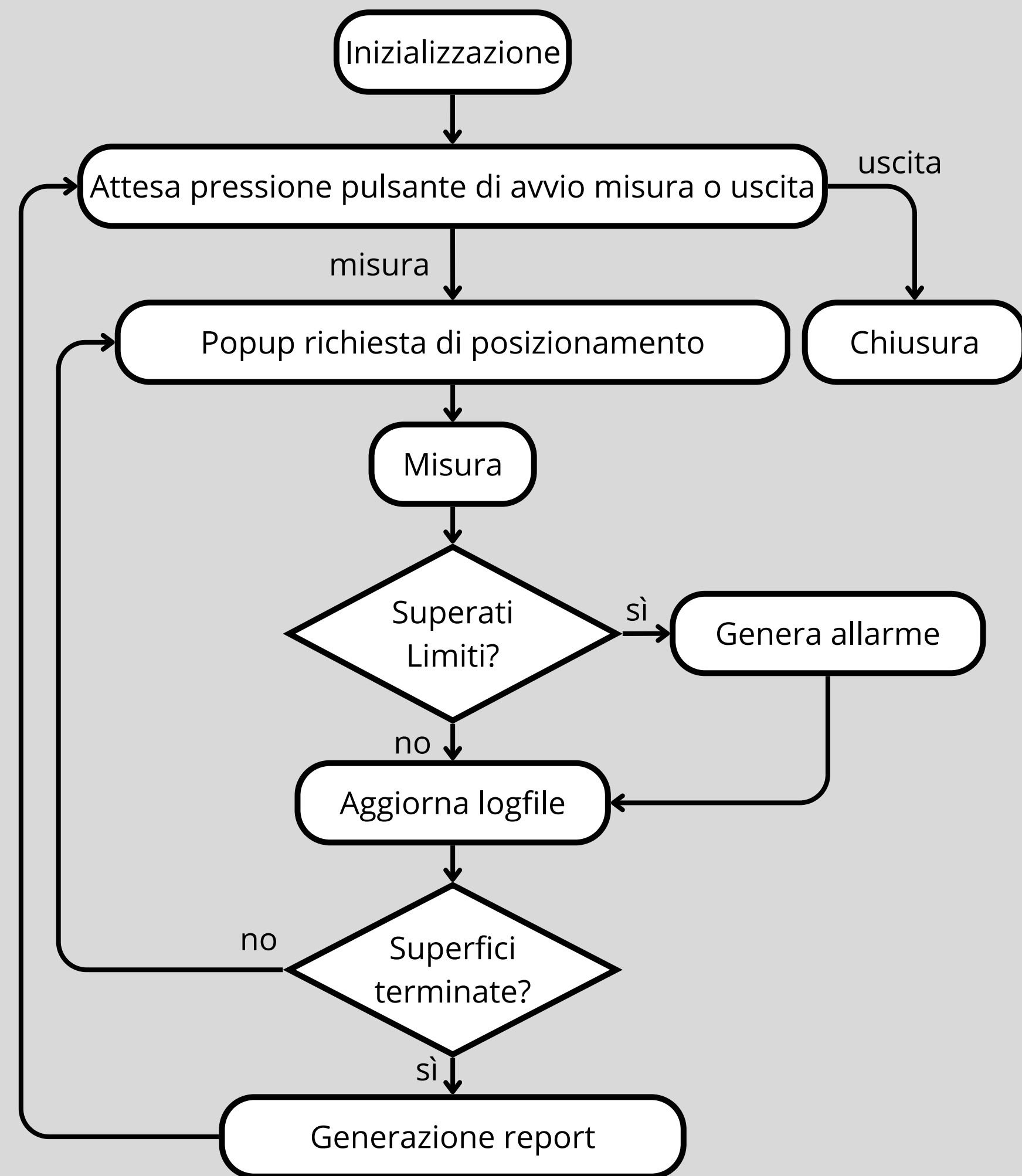
Specifiche di progetto

- Utilizzo di 4 superfici differenti



- Macchina a stati definita





FSM

- Inizializzazione: apertura logfile, predisposizione canali di misura
- Popup richiesta di posizionamento: dialog box con indicazioni su tipologia di superficie e distanza
- Misura: acquisizione valori dei due sensori
- Genera allarme: accensione led di allarme in caso di errori
- Aggiorna logfile: aggiunta riga della misurazione sul logfile ed eventuale allarme
- Generazione report: generazione tabella di media e varianza al termine del ciclo di misura
- Chiusura: chiusura del file

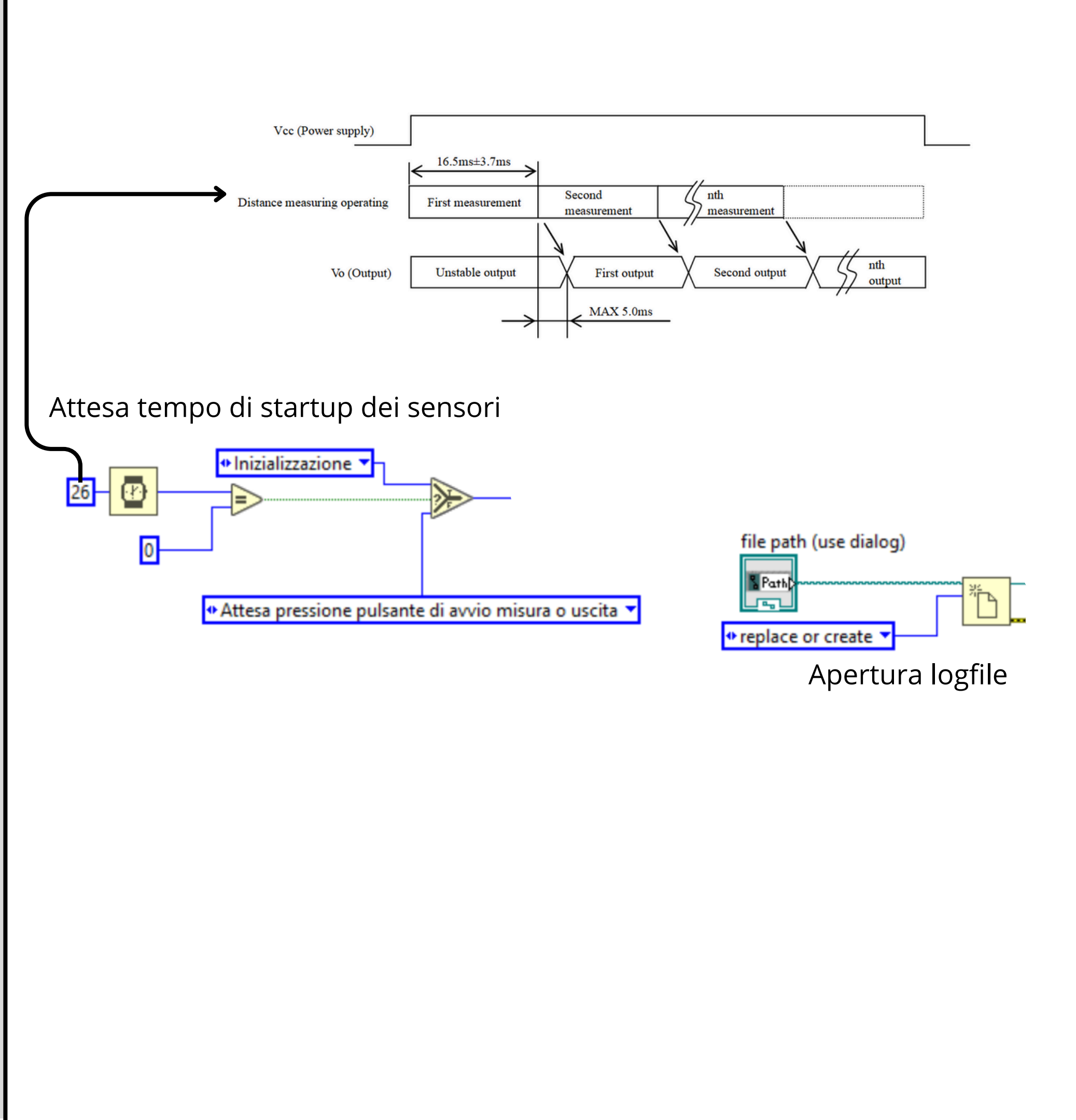
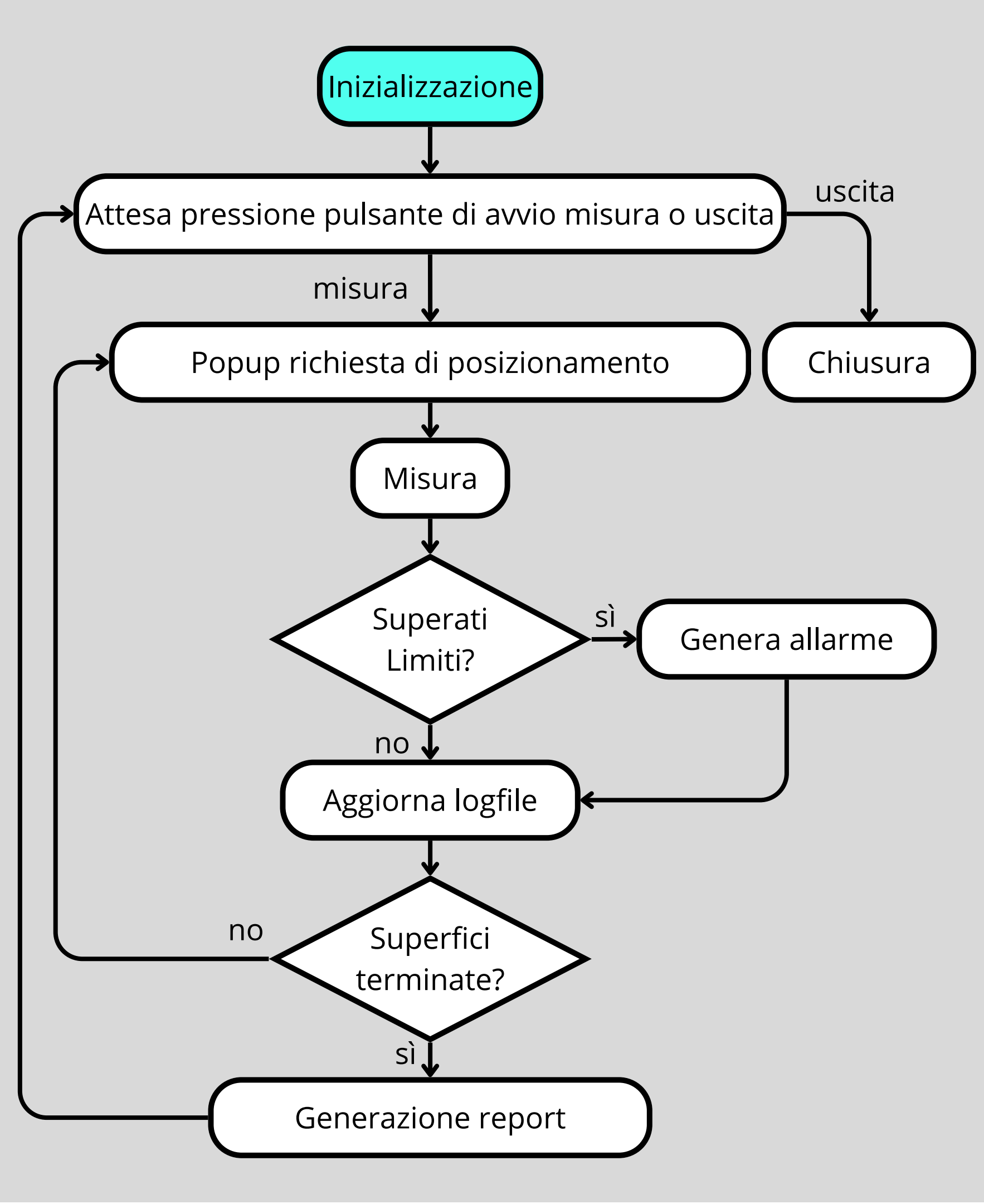
Scelte effettuate per l'implementazione

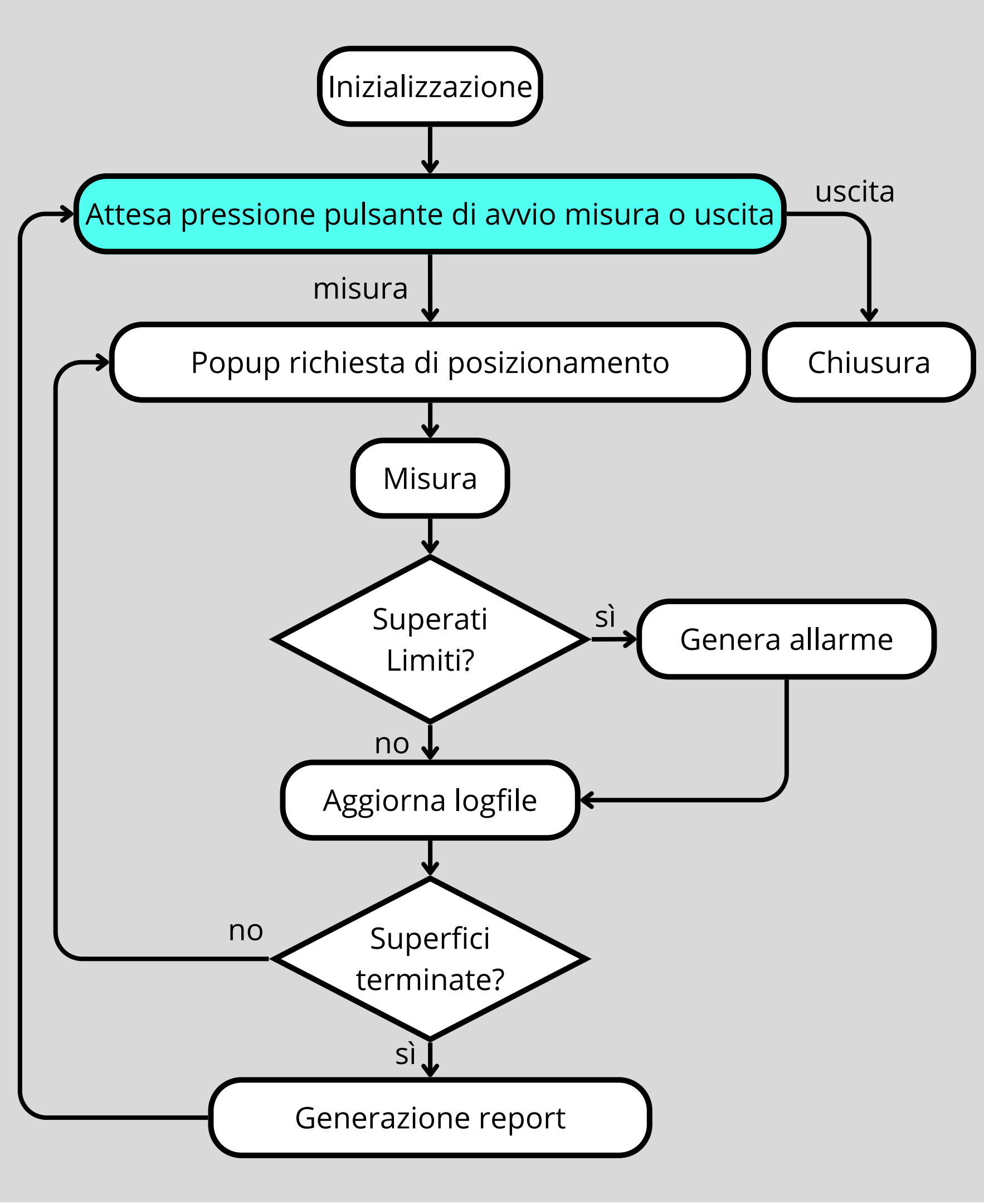
```
graph LR; A[Scelte effettuate per l'implementazione] --> B[Coerenza con le specifiche di progetto]; A --> C[Leggibilità]; A --> D[Semplicità e fruibilità];
```

Coerenza con le specifiche di progetto

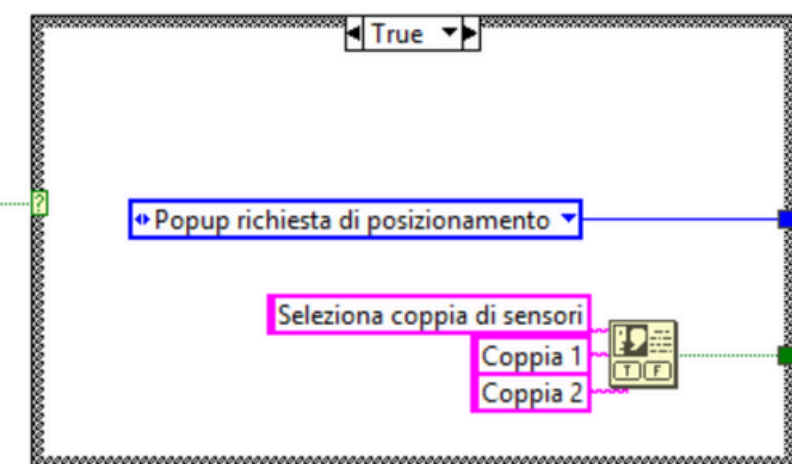
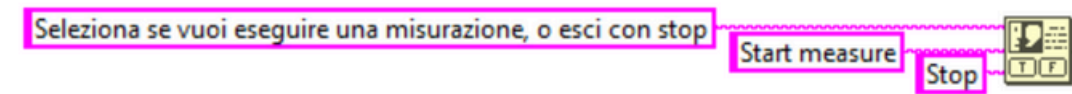
Leggibilità

Semplicità e fruibilità

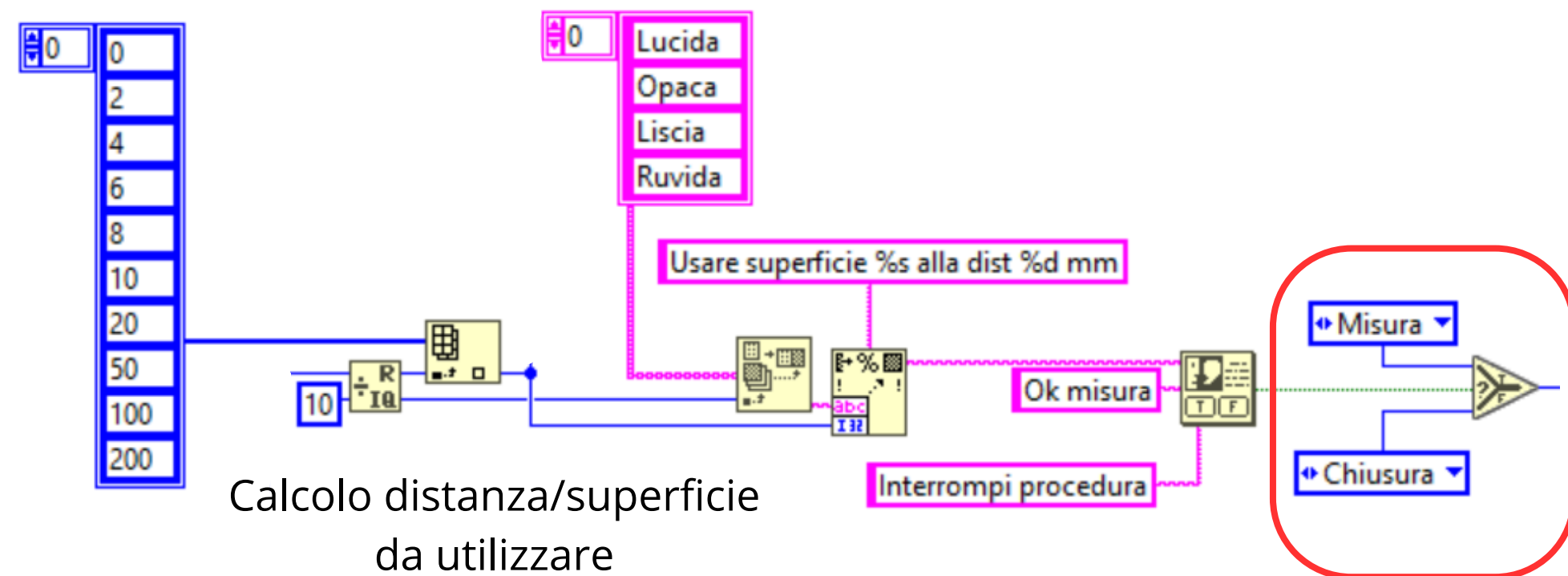
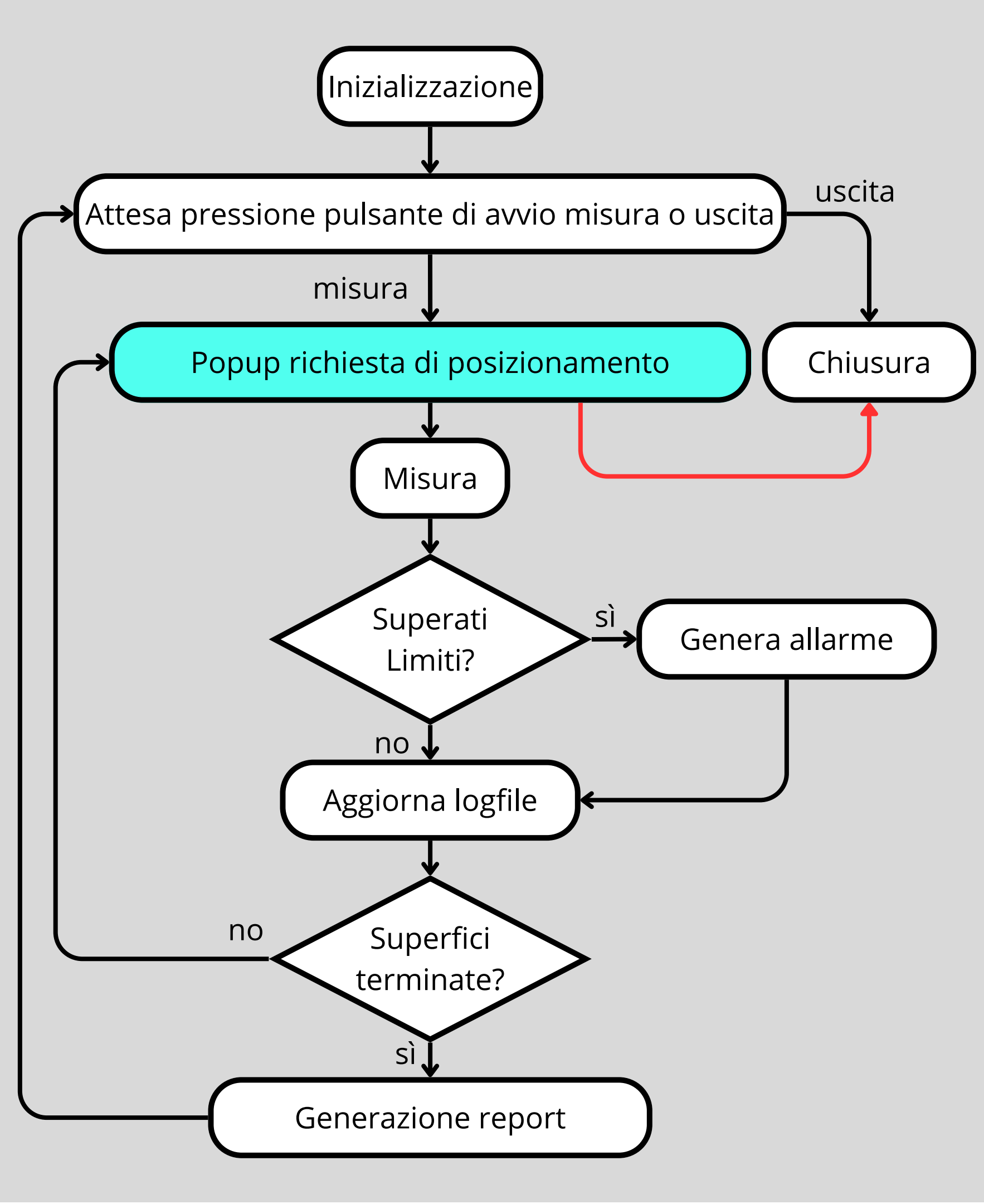


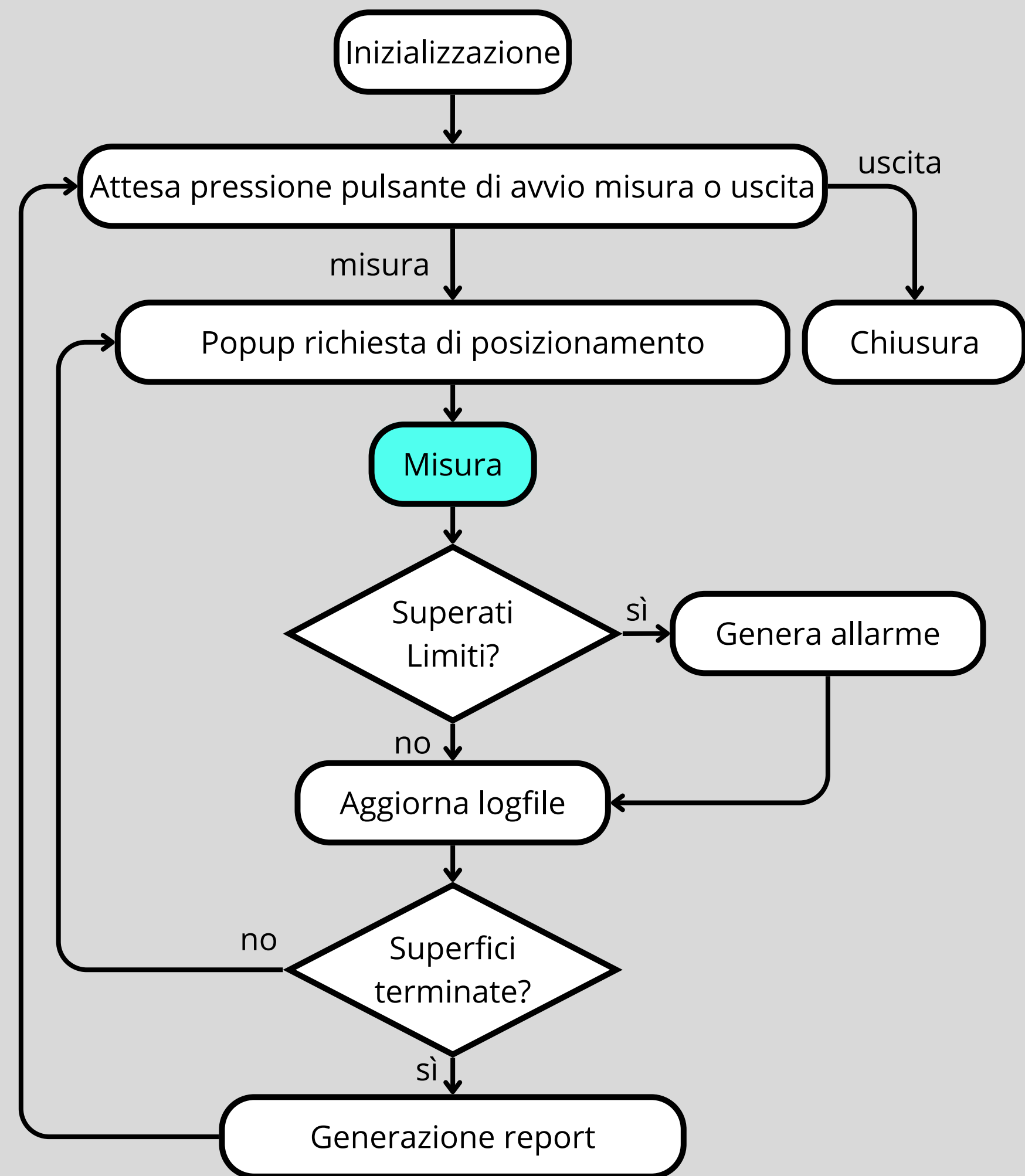


Selezione misura/uscita

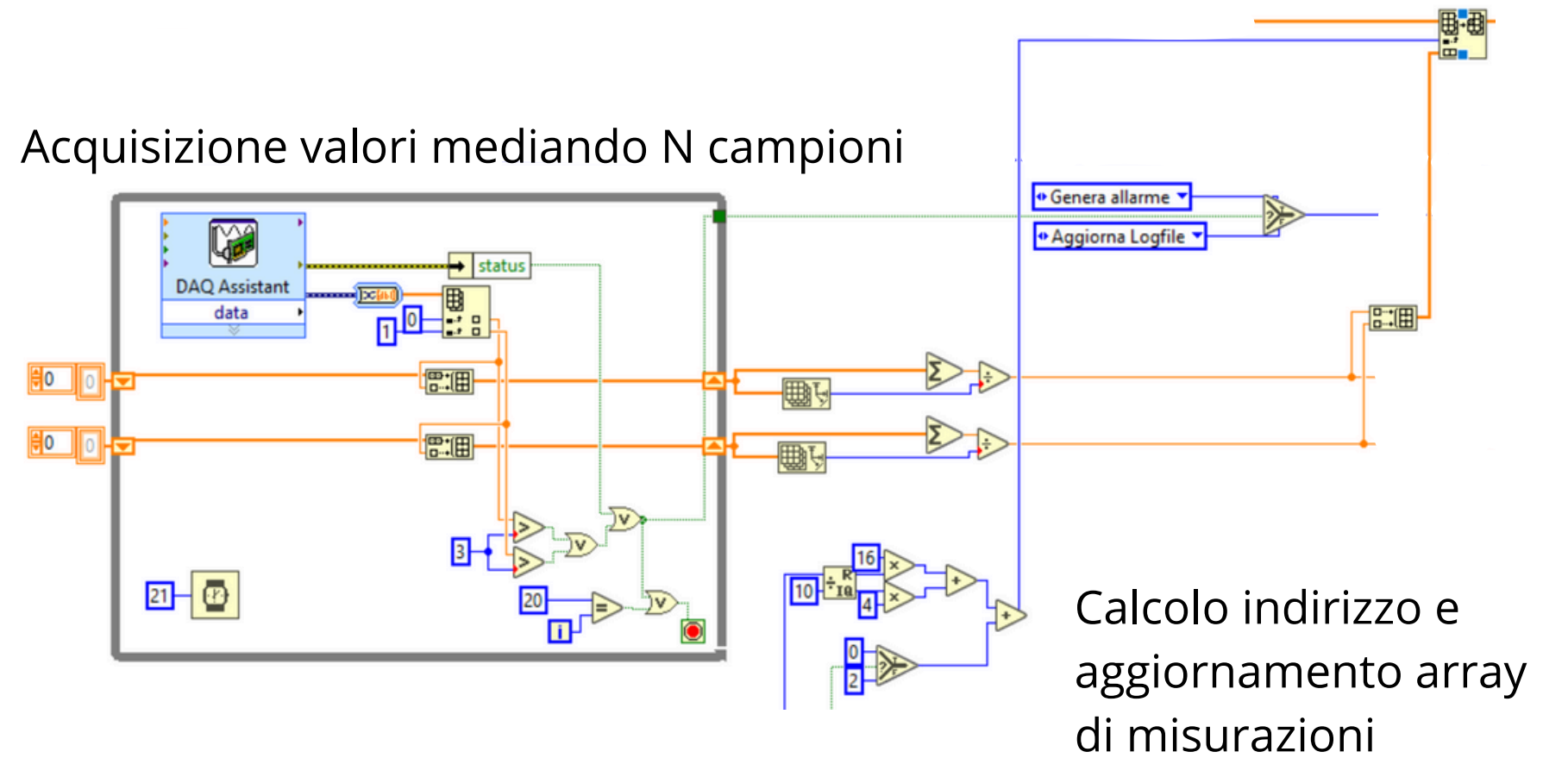


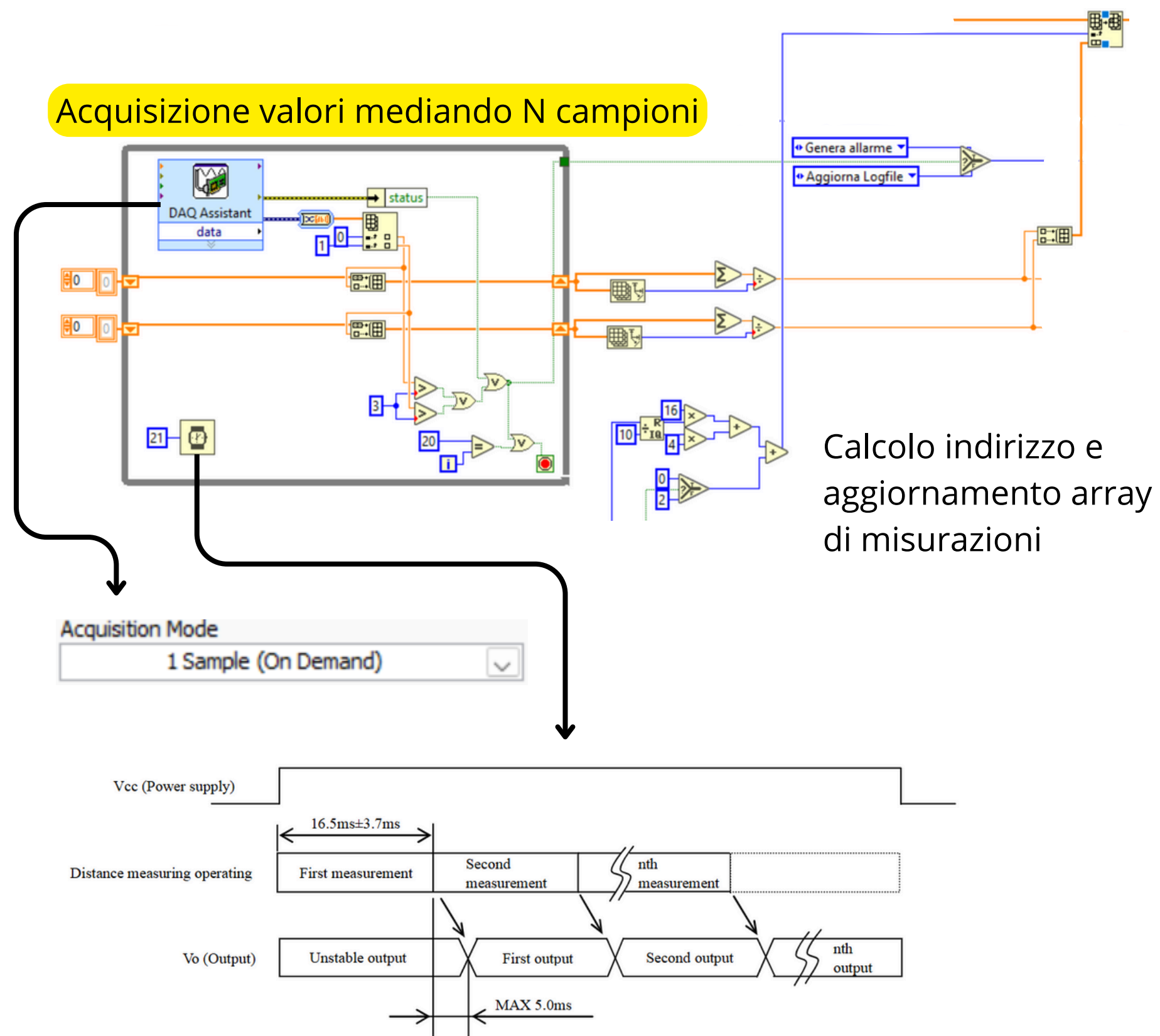
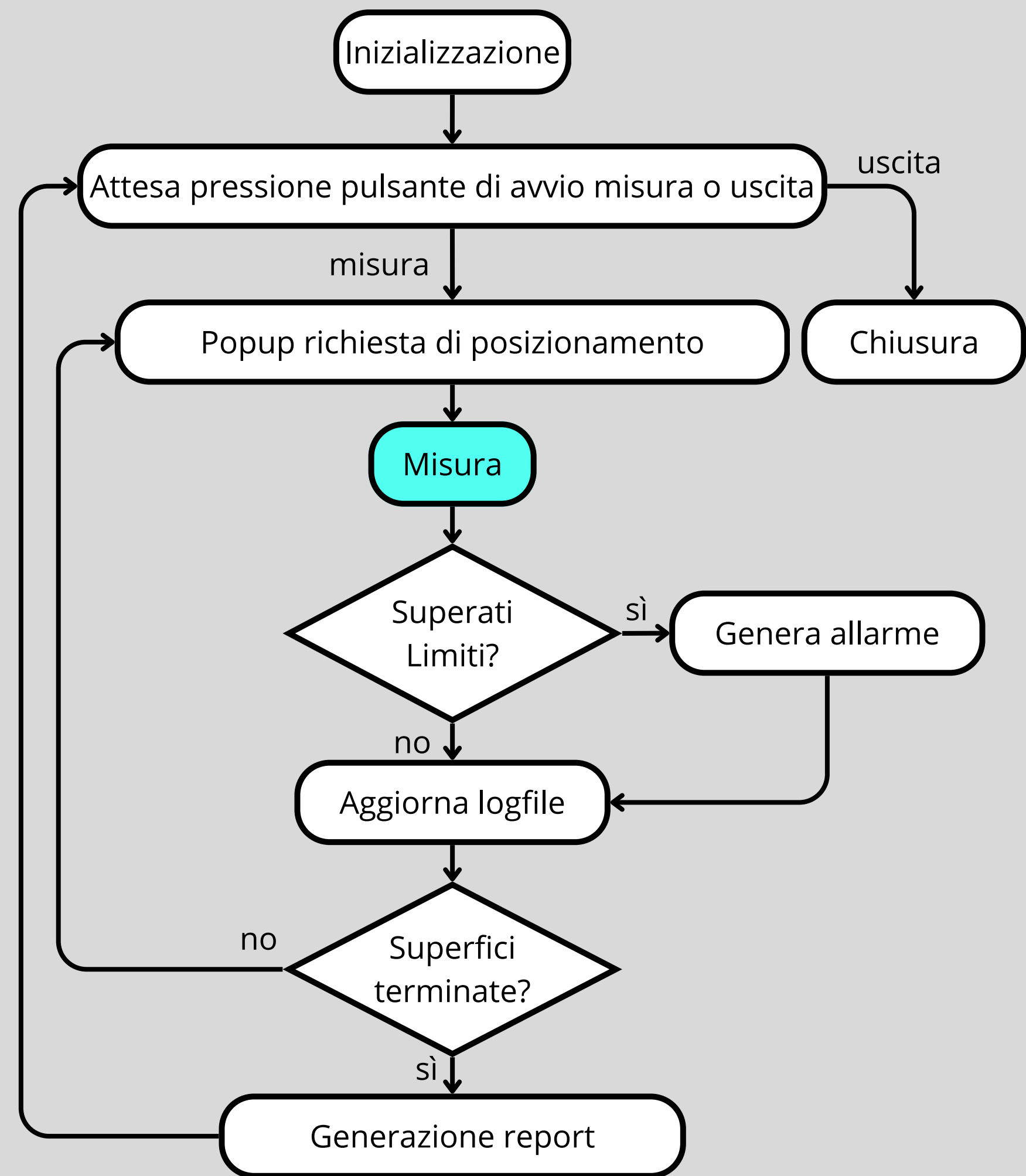
Selezione coppia di sensori

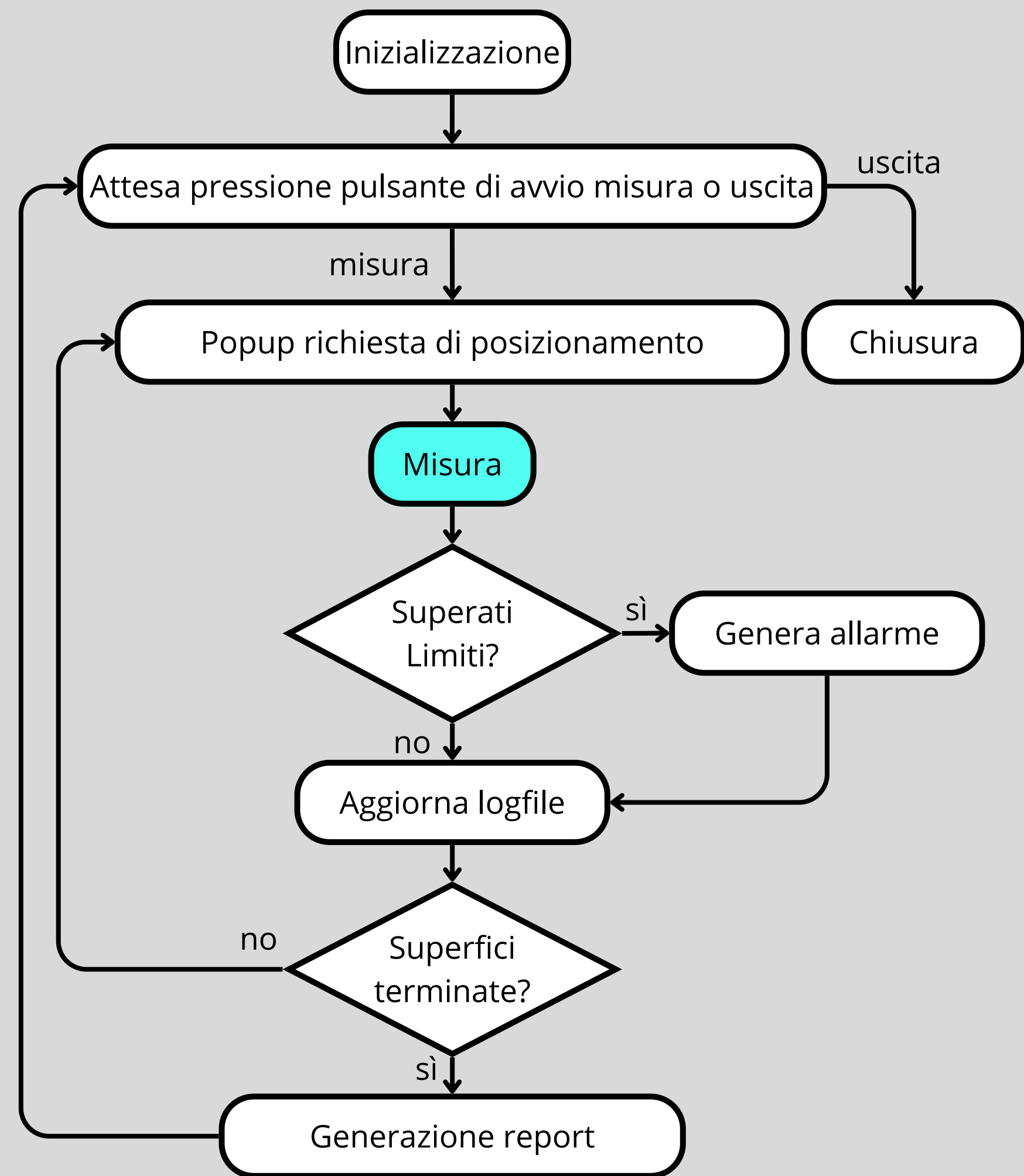




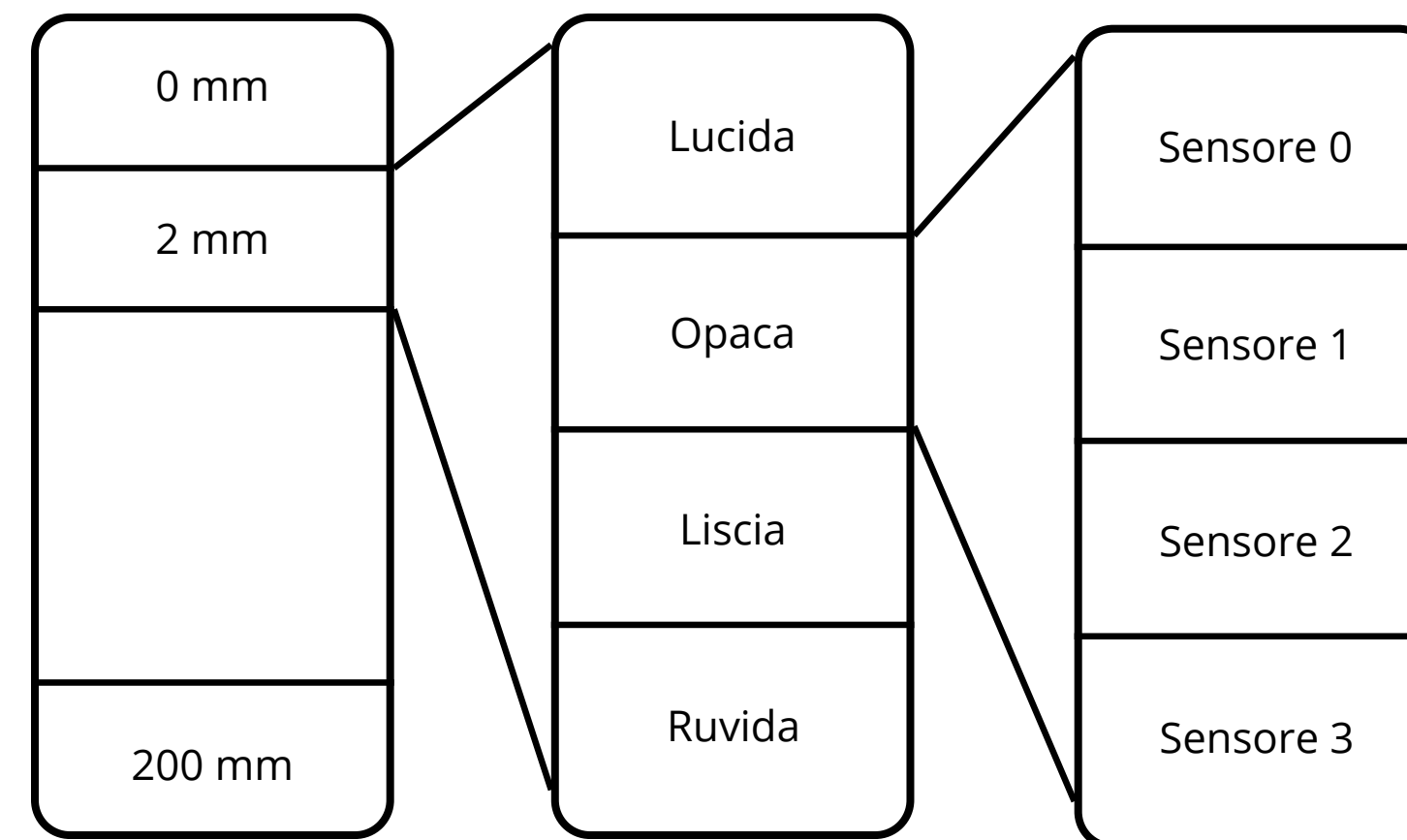
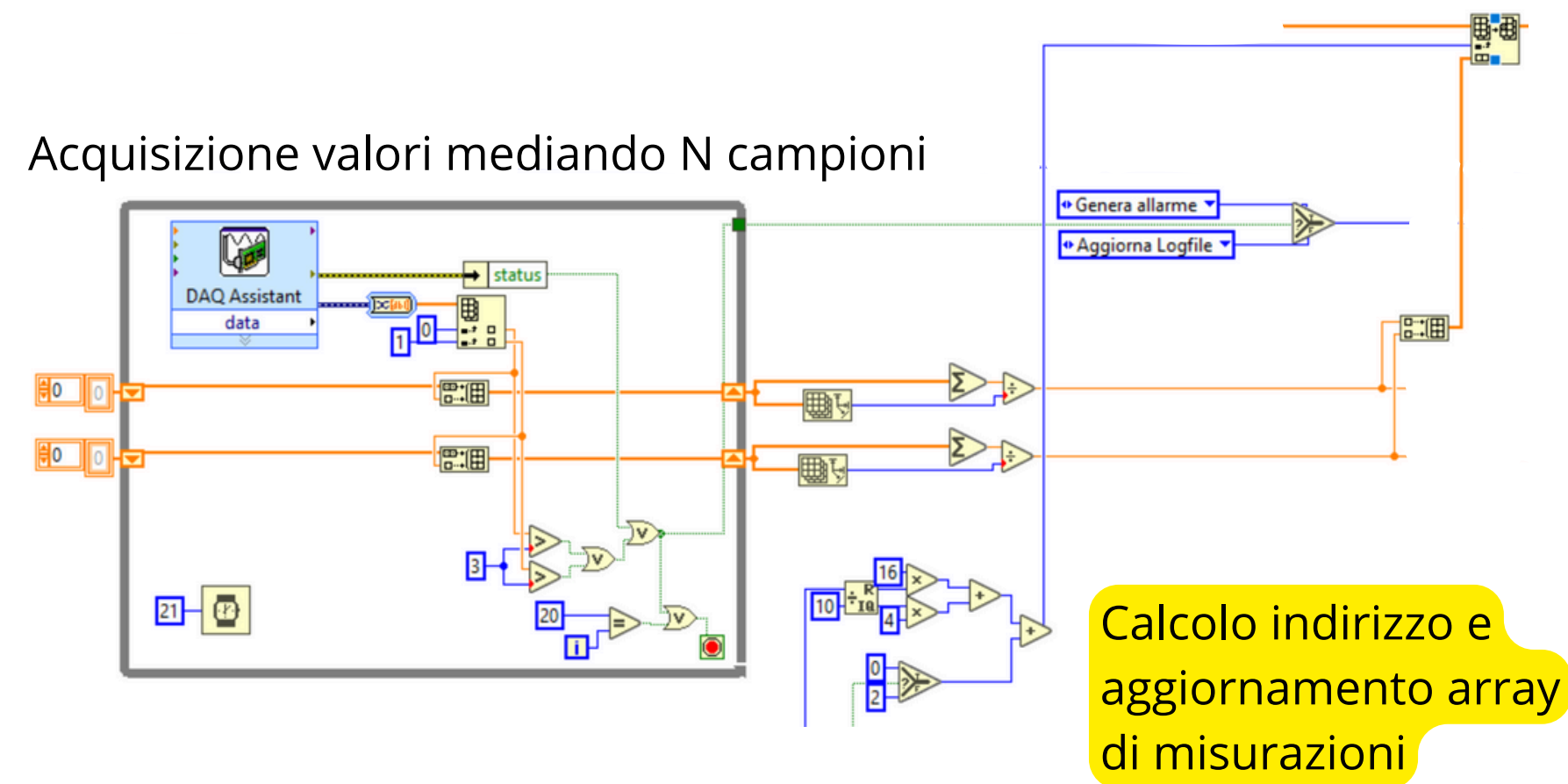
Acquisizione valori mediando N campioni

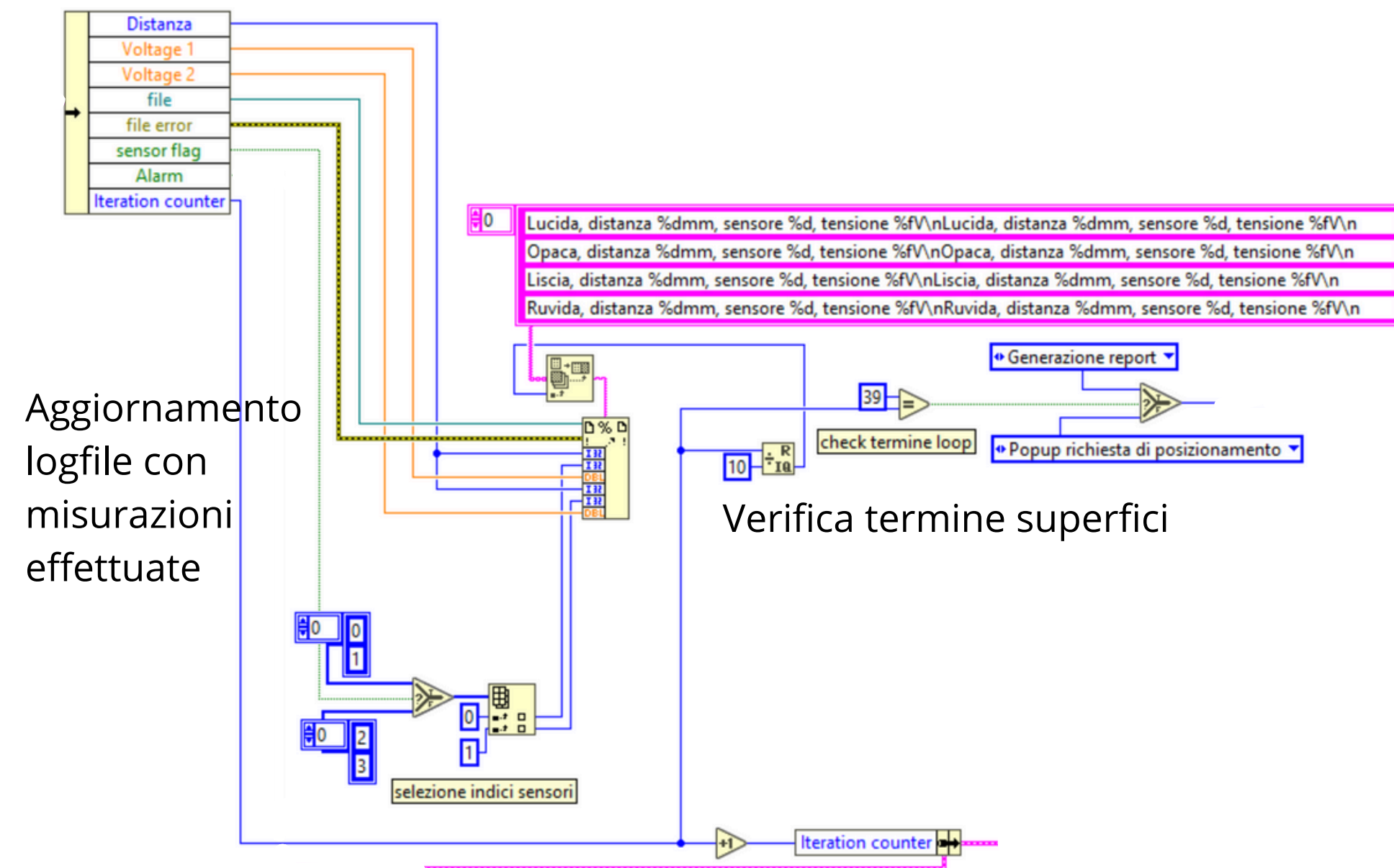
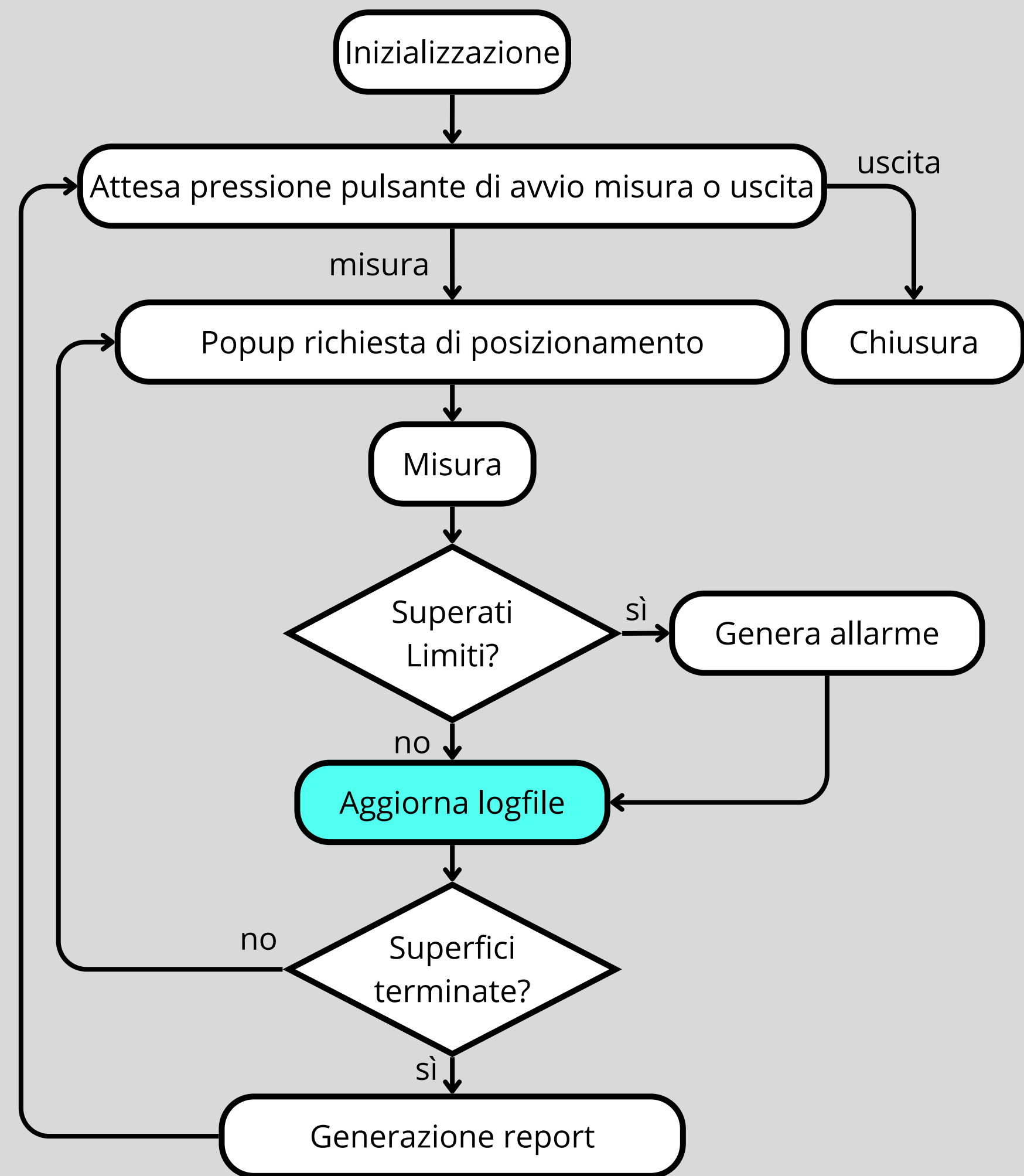


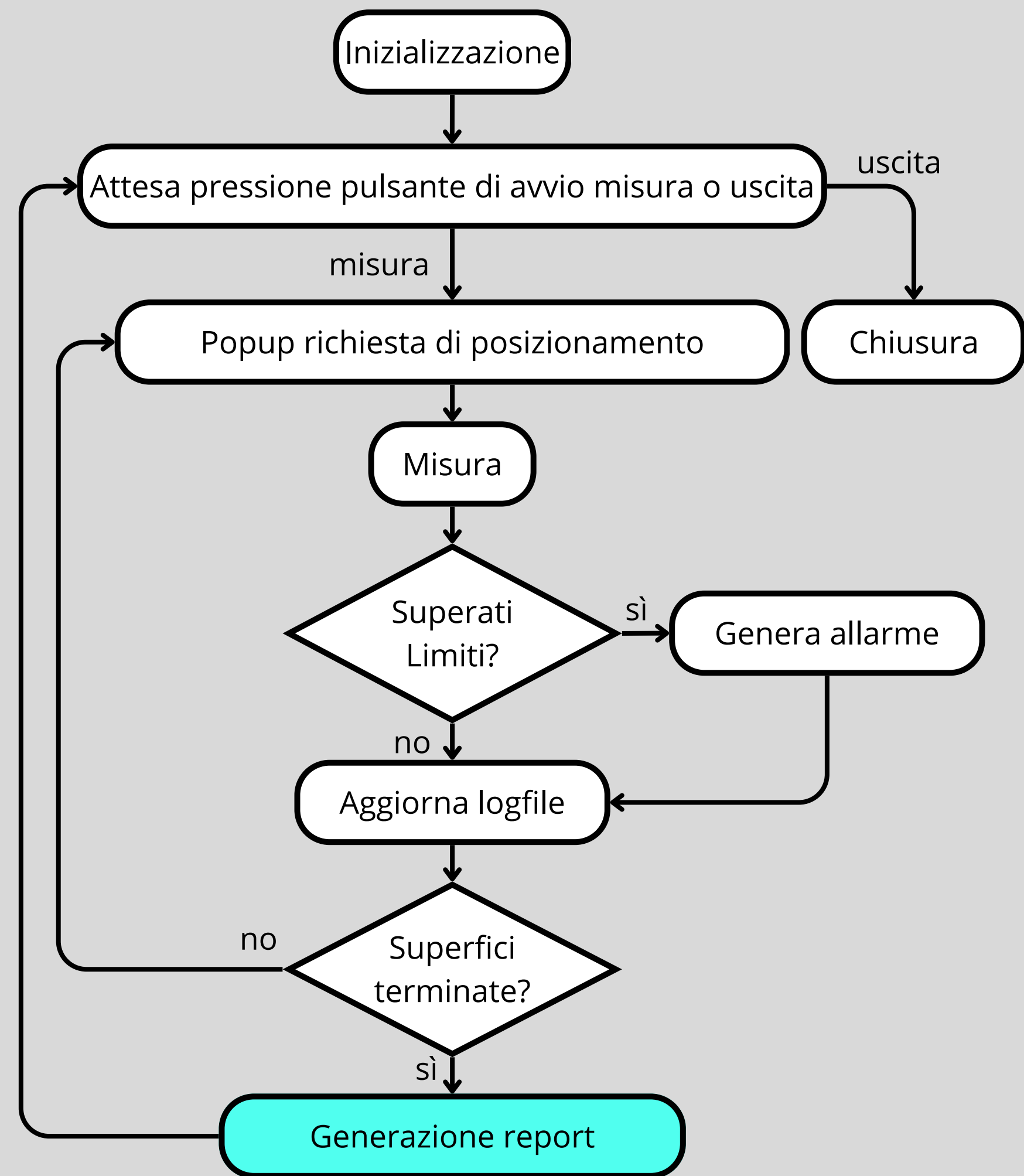




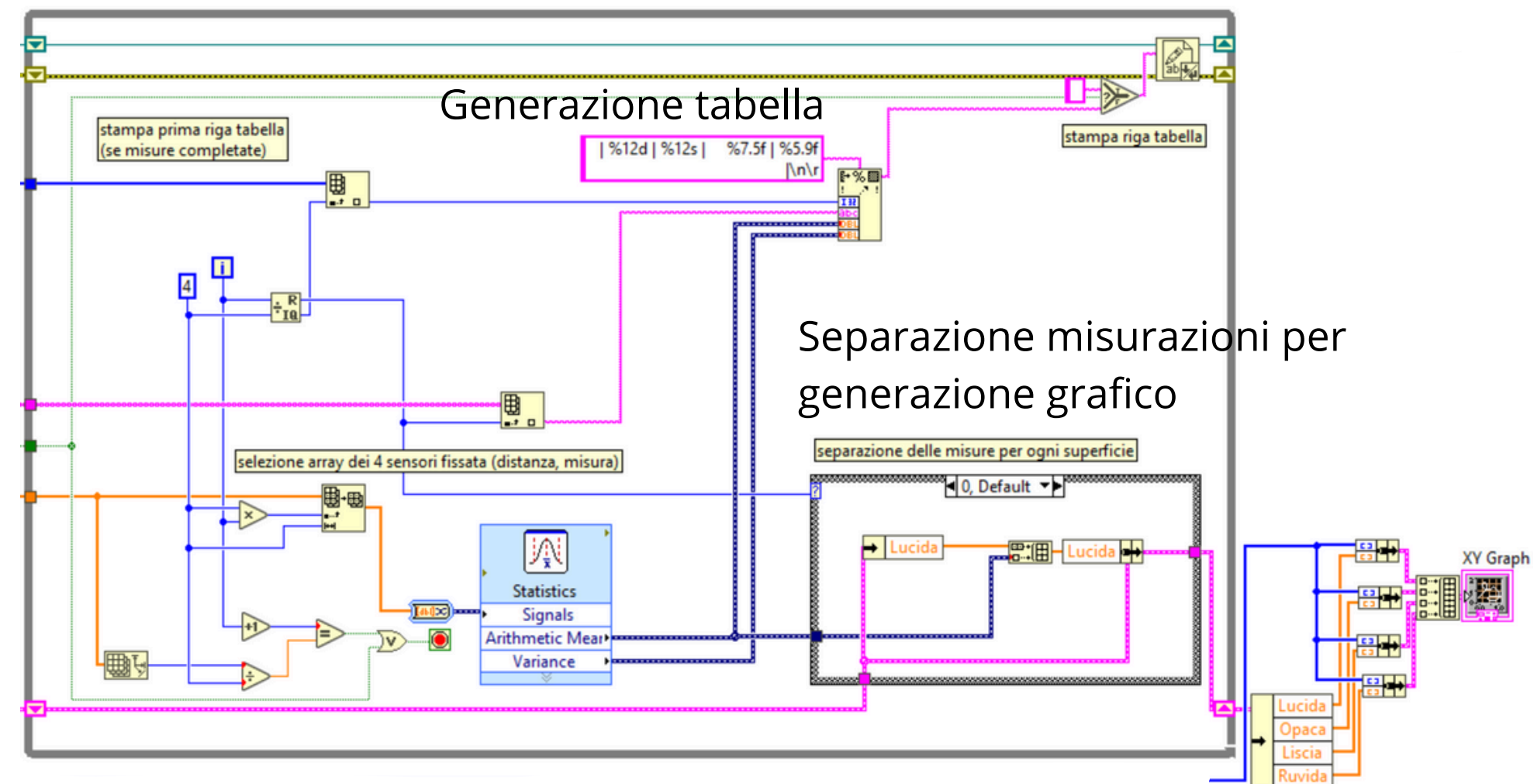
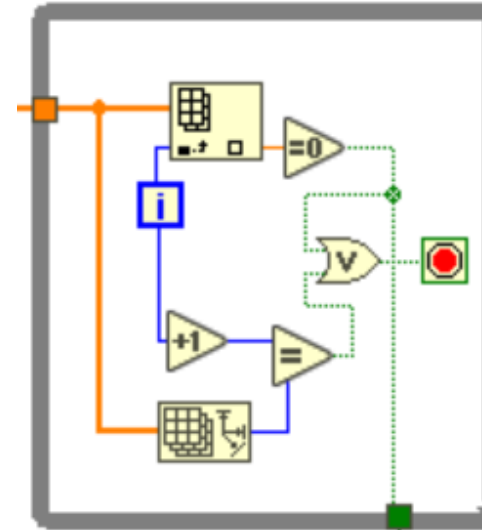
Acquisizione valori mediando N campioni



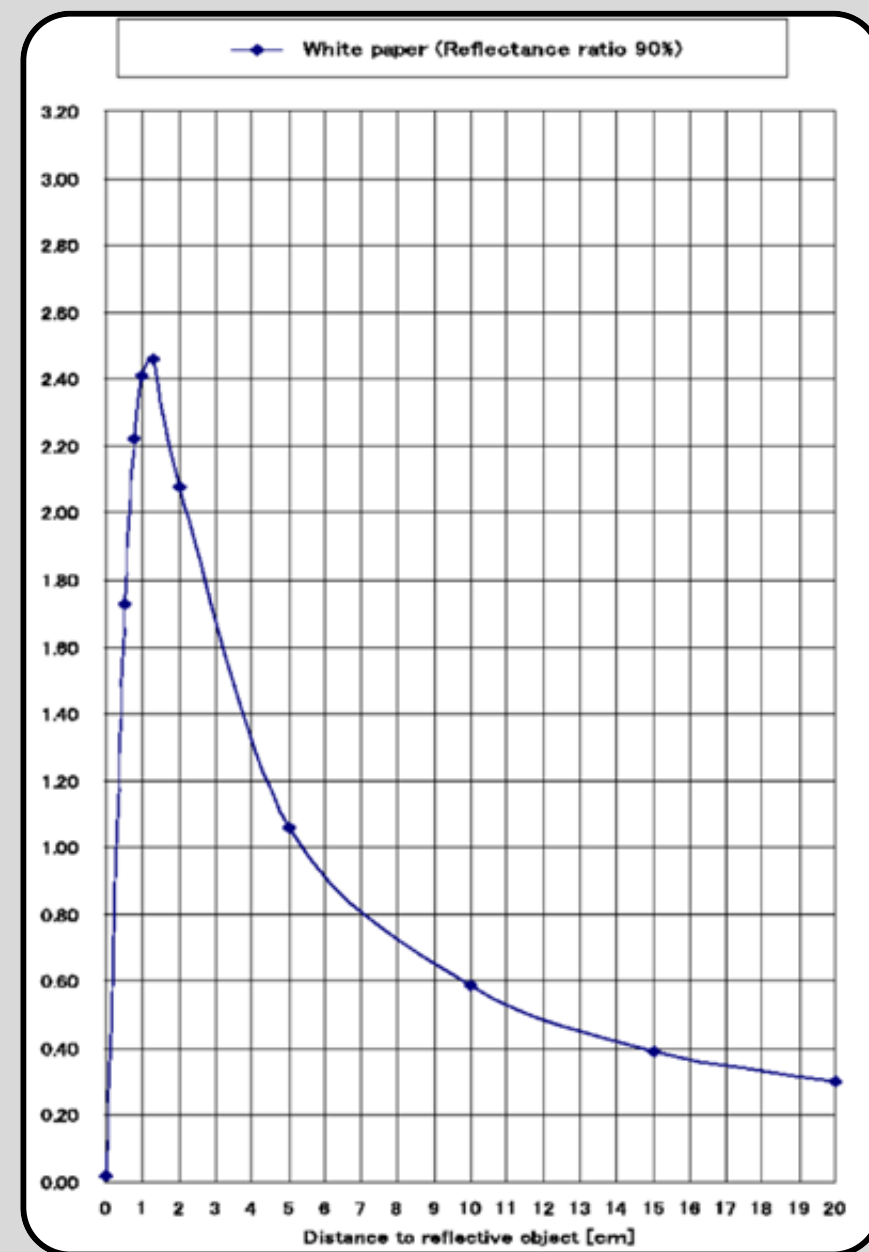




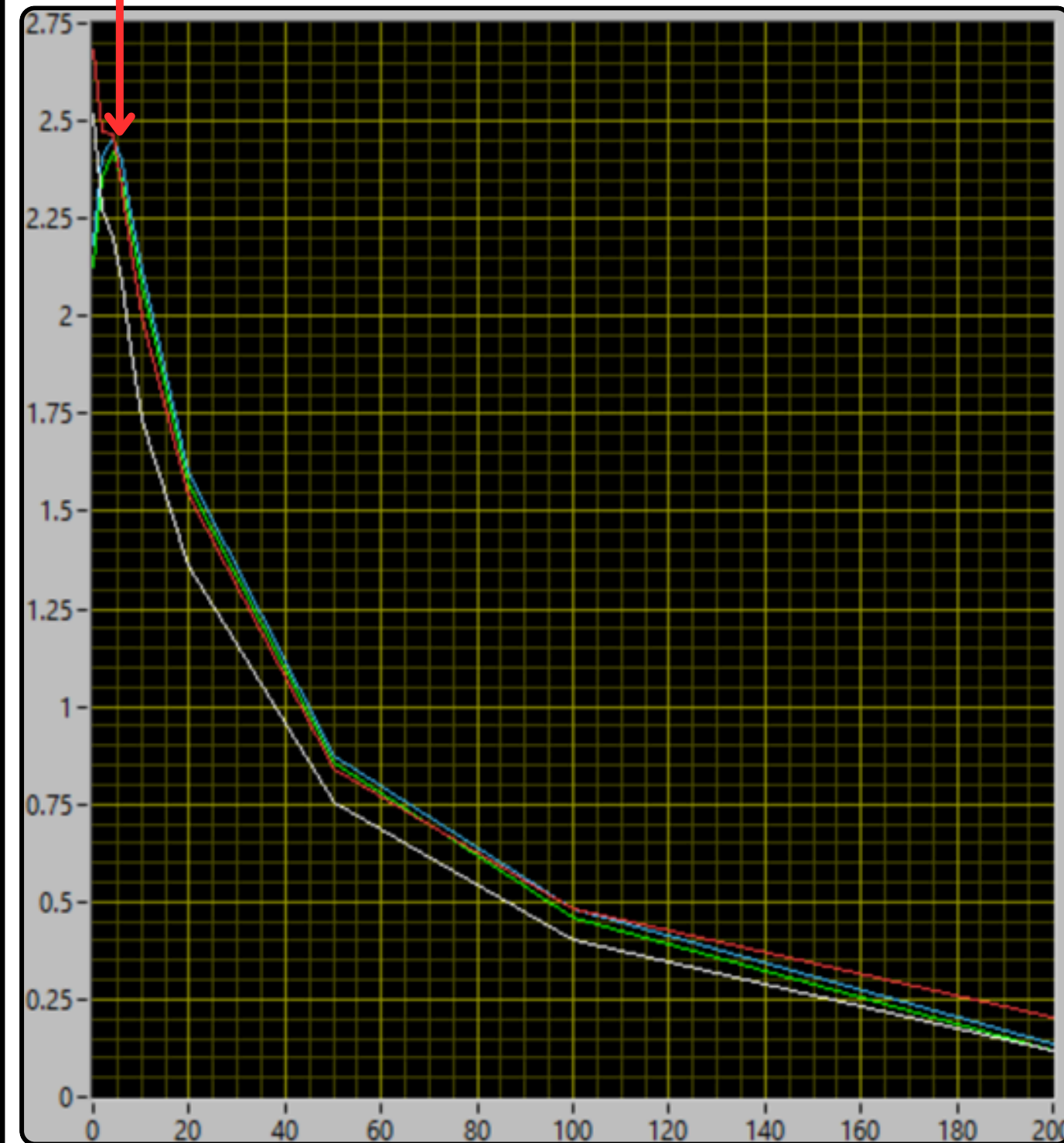
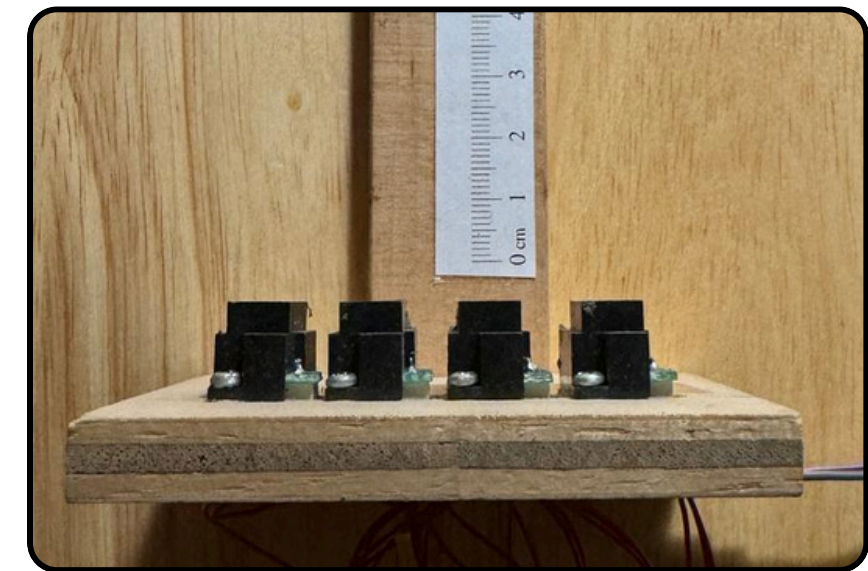
Valutazione di completamento misurazioni con tutti i sensori



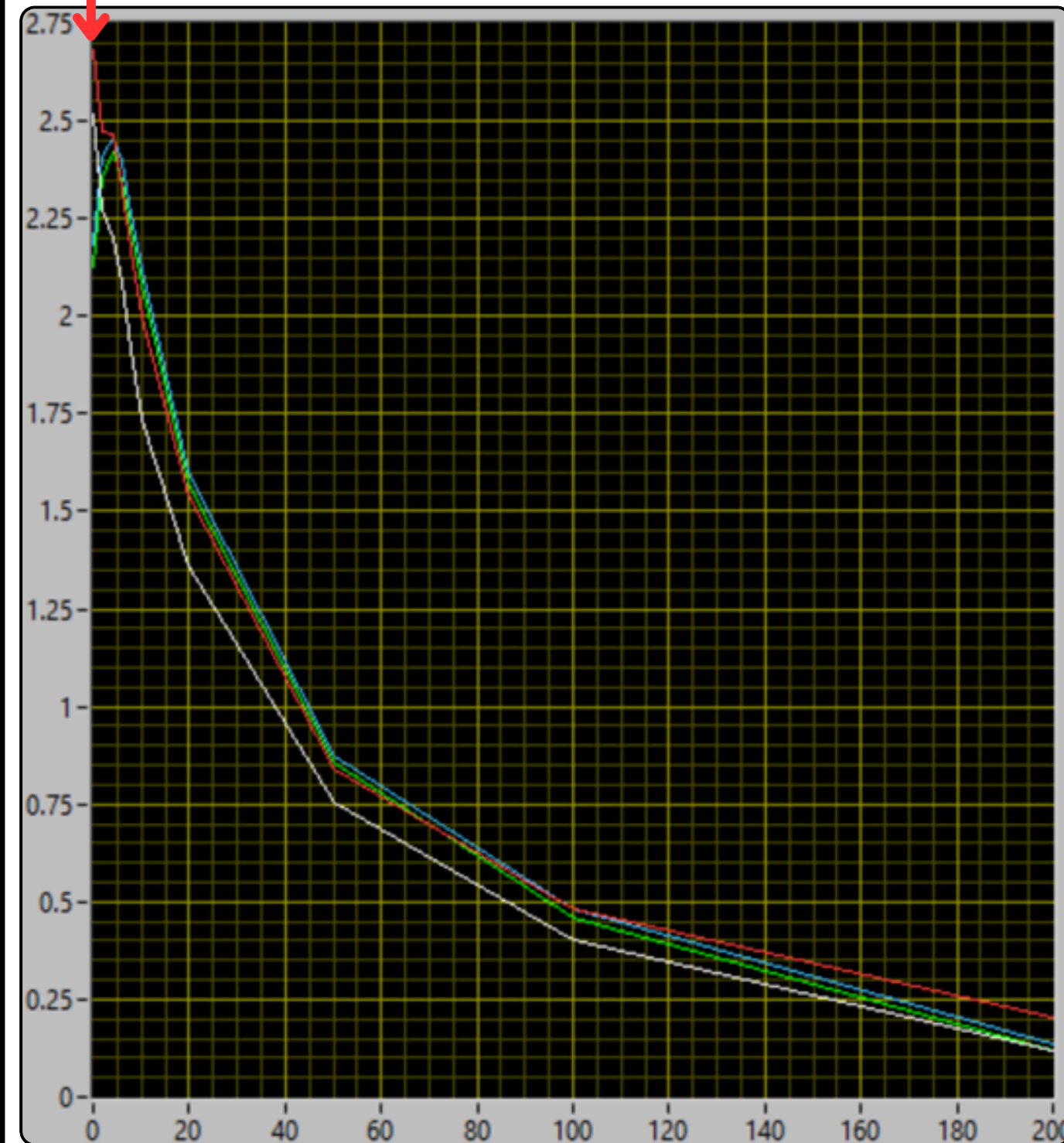
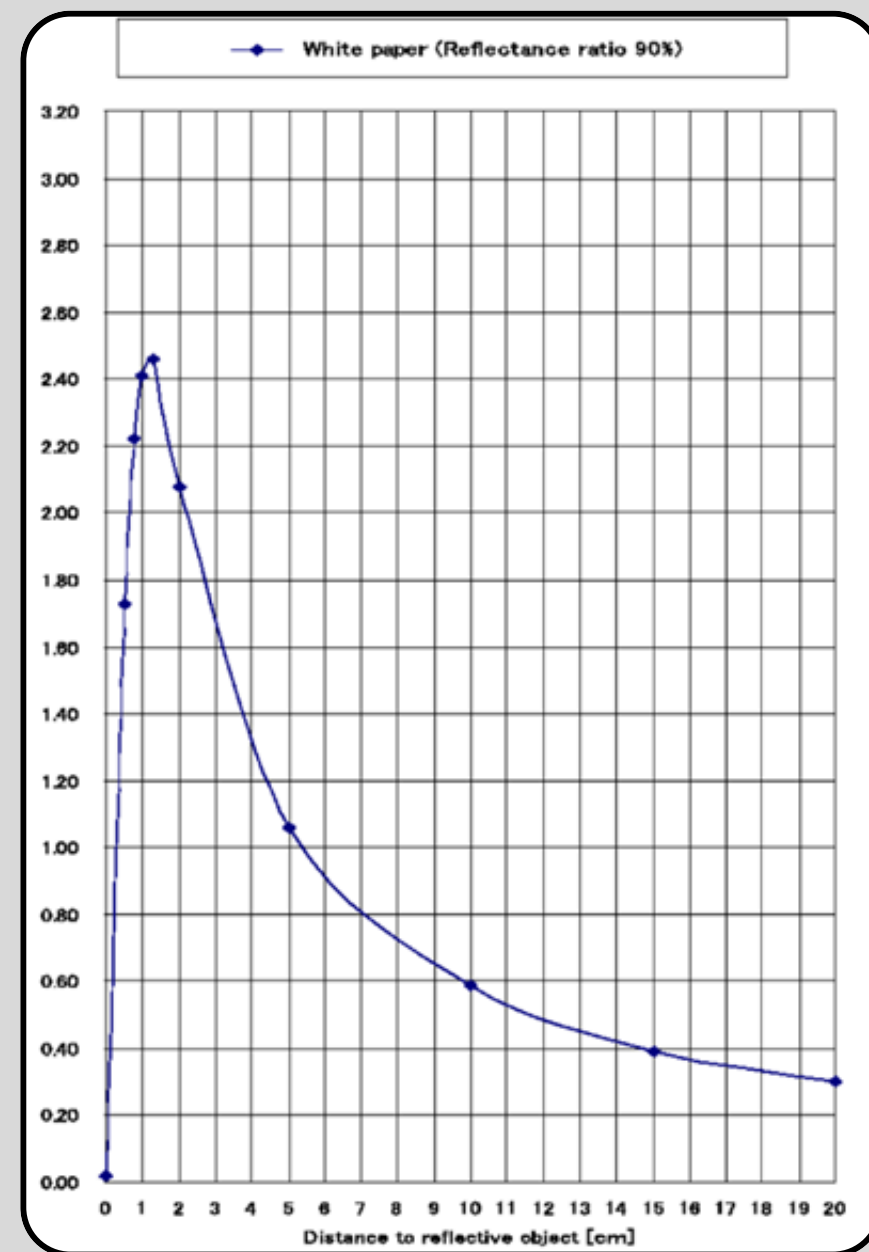
Risultati sperimentali



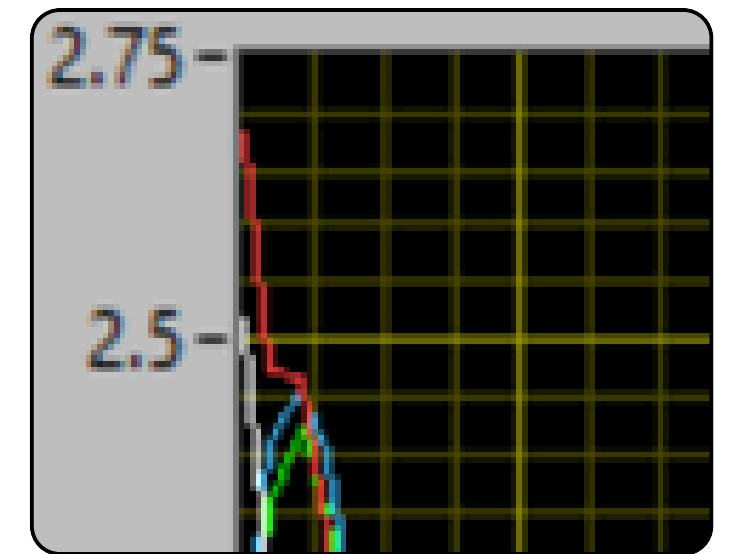
- Superficie **Opaca, Ruvida**:
picco misurazioni intorno ai 4 mm



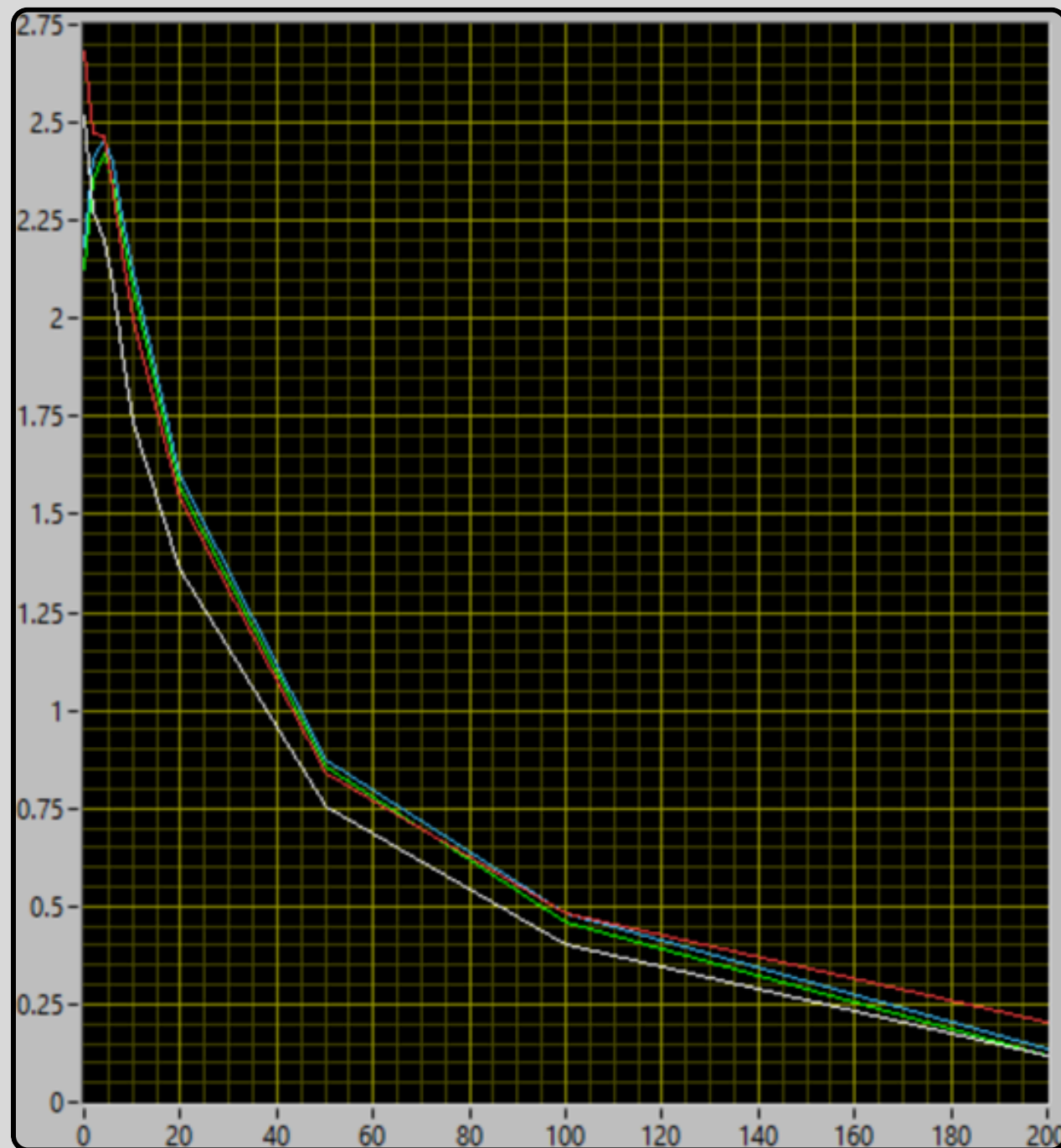
Risultati sperimentali



- Superficie **Lucida, Liscia**: andamento anomalo



Risultati sperimentali



	Varianza sui 4 sensori (E-2)			
Distanza (mm)	Lucida	Liscia	Opaca	Ruvida
0	0,4038408	0,0901377	0,5629859	0,3250390
2	0,0766196	0,2577998	0,5591988	0,0981543
4	0,1475025	0,3870833	0,1832123	0,1494924
6	0,4949315	0,2687210	0,4099933	0,2475959
8	0,7856214	0,3830274	0,2776534	0,2879699
10	0,4652597	0,6840736	0,5226121	0,1622398
20	0,3543921	1,0080748	0,3161767	0,1651000
50	0,4161374	0,3493794	0,2295391	0,1486012
100	0,1306746	0,1076963	0,1003408	0,0898861
200	0,0595967	0,0561440	0,0440848	0,0280693

Conclusioni

- Risultati coerenti per superfici poco riflettenti / rifrangenti (opaca, ruvida)
- Offset legato all'errore di misura
- Fenomeni di riflessione / rifrazione e interferenze con la luminosità ambientale più rilevanti per superfici riflettenti / rifrangenti (liscia, lucida)
- Differenze ragionevolmente basse tra i sensori

Possibili miglioramenti

- Circuito di preprocessing per matchare dinamica del segnale a DR dell'ADC
- Migliore sistema di misura (illuminazione controllata, struttura di misura più precisa)