Adriann Liceralde Dr. Brian McPherson EGI at the University of Utah EGI Arduino Collection Project Last Updated January 26, 2022

#### Information for the MH-Z16 CO<sub>2</sub> Sensor

### Introduction

- The MH-Z16 is a low-cost rod-shaped sensor that uses NDIR technology to measure CO<sub>2</sub>.
- Any microcontroller can be used to control this sensor. However, this guide and the associative codes will use an Arduino Uno to operate the device.
- It is compatible with three different communication methods: I<sup>2</sup>C, UART, and PWM
- The sensor connects to a blue I<sup>2</sup>C/UART Interface board that easily connects to an Arduino or Raspberry Pi.

# **Important Notes**

- The sensor is sensitive to sunlight. Therefore, DO NOT place it in direct contact with sunlight.
- Do not expose the sensor to water or rainy conditions.

## **Specifications**

	Via I <sup>2</sup> C/UART	Via PWM
Range	0 - 10,000  ppm	0 - 5,000  ppm
Frequency	± (100ppm+5%	± (50ppm+5%
	reading)	reading)
Resolution	1 ppm	N/A
Current	60 mA (avg)	60 mA (avg)
	150 mA (max)	150 mA (max)
Voltage	4.5 V - 5.5 V	4.5 V - 5.5 V
<b>Response Time</b>	60 sec (T90)	60 sec (T90)
Lifespan	> 5 years	> 5 years

### Links

• Product Info:

https://sandboxelectronics.com/?product=mh-z16-ndir-co2-sensor-with-i2cuart-5v3-3v-interface-for-arduinoraspeberry-pi

• Datasheet:

https://sandboxelectronics.com/wp-content/uploads/2018/08/Z16DS.pdf

- Arduino Library:
  - https://github.com/SandboxElectronics/NDIR
- Arduino Code for I2C:
  - https://github.com/RiceAllDay22/EGI Arduino Collection/tree/main/MH-Z16 w I2C
- Arduino Code for PWM: https://github.com/RiceAllDay22/EGI Arduino Collection/tree/main/MH-Z16 w PWM



Figure 1. Picture of the sensor and the interface board connected to an Arduino Uno

# Wiring

- Communication with the sensor is performed via the I<sup>2</sup>C, UART, or PWM methods.
- The Interface board allows for the I<sup>2</sup>C and UART methods.
- The MH-Z16 sensor is still operable without an Interface board via the PWM method.
- This guide will cover how to use the sensor through I<sup>2</sup>C and PWM.

### Wiring – Method # 1 (Recommended for ease and more accurate data)

- This method requires the Interface board so that I<sup>2</sup>C is used to communicate with the sensor.
- Connect the sensor rod to the interface board using the 7-wire Grove connector. Then connect the interface board to an Arduino Uno using four M/F jumper wires.
- Run the MH-Z16 w I2C code to operate.
- Below is a wiring diagram and a schematic diagram of the circuit.

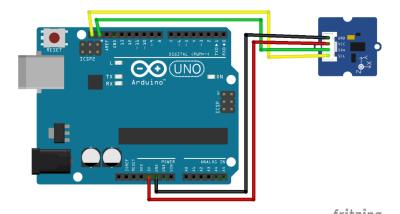
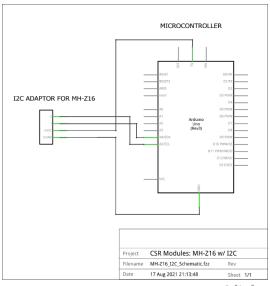


Figure 2. Wiring Diagram between an Arduino Uno and the interface board



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Figure 3. Schematic between an Arduino Uno and the interface board

# Wiring – Method #2 (Not recommended, but is usable)

- This method does not require the Interface board.
- Use this only if an Interface board is unavailable.
- Run the MH-Z16\_w\_PWM code to operate.

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### **Contact**

For any questions or assistance, email Adriann Liceralde at adriann8399@gmail.com.