

Convolutional Neural Nets

Exploiting stationarity, locality, and compositionality of natural data

Input layer / samples

$$\mathcal{X} = \{\mathbf{x}^{(p)} \in \mathbb{R}^n \mid \mathbf{x}^{(p)} \text{ is a data sample}\}_{p=1}^P \quad \text{input samples}$$

$$\mathcal{X} = \{ \mathbf{x}^{(p)} : \overset{\text{domain}}{\Omega} \rightarrow \overset{\text{channels}}{\mathbb{R}^c}, \boldsymbol{\omega} \mapsto \mathbf{x}^{(p)}(\boldsymbol{\omega}) \}_{p=1}^P$$

$$\Omega = \{1, 2, \dots, \overset{\text{total time}}{T/\Delta t}\} \subset \mathbb{N}, \quad c \in \{1, 2, \overset{\text{stereo}}{5+1}, \dots\}$$

sampling interval mono Dolby 5.1

$$\Omega = \{1, \dots, \overset{\text{height}}{h}\} \times \{1, \dots, \overset{\text{width}}{w}\} \subset \mathbb{N}^2, \quad c \in \{1, \overset{\text{grey scale}}{3}, \overset{\text{colour}}{20}, \dots\} \quad \text{hyperspectral}$$

$$\Omega = \overset{\text{four-momentum}}{\mathbb{R}^4} \times \underset{\text{space-time}}{\mathbb{R}^4}, \quad c = \underset{\text{Hamiltonian}}{1} \quad x(\omega_1, \omega_2) = \begin{pmatrix} r(\omega_1, \omega_2) \\ g(\omega_1, \omega_2) \\ b(\omega_1, \omega_2) \end{pmatrix}$$

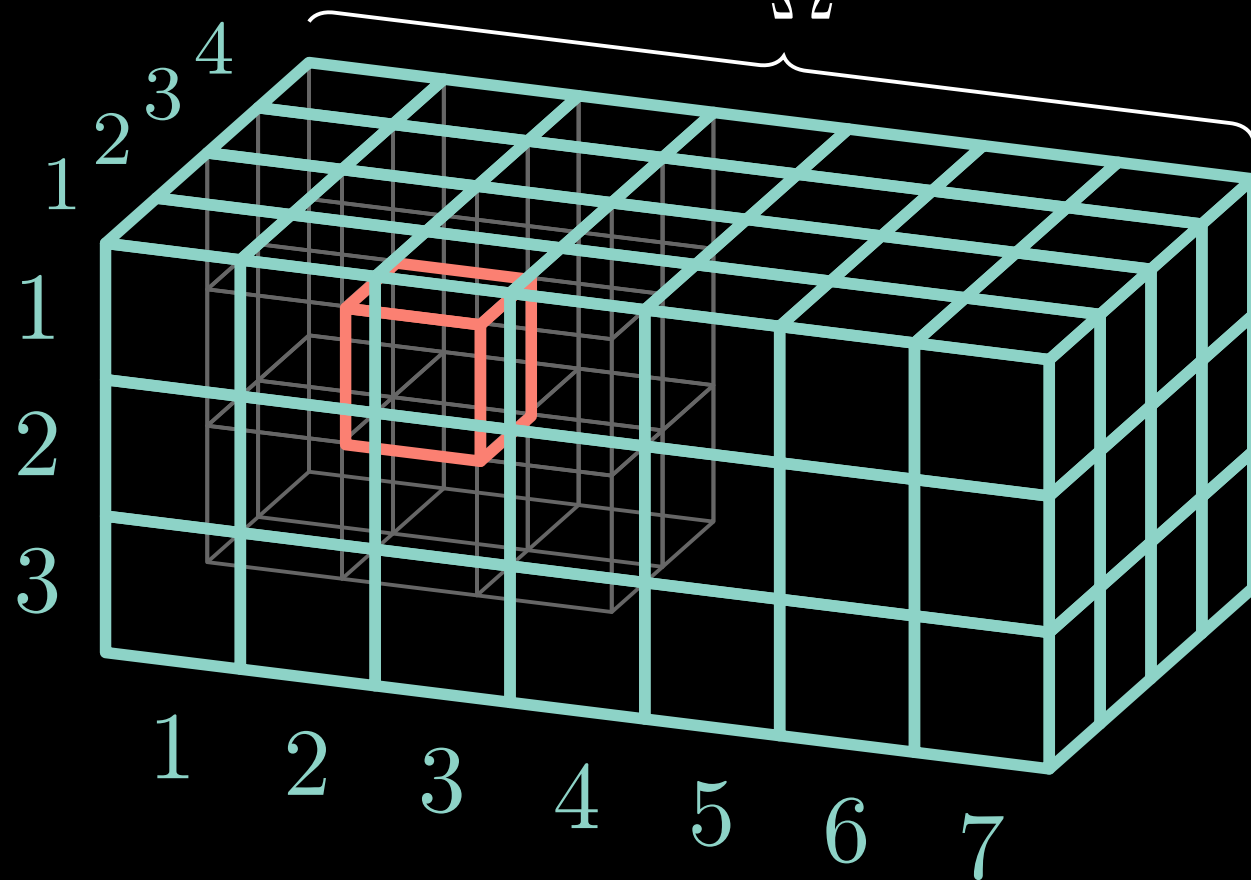
Regular domains

 Ω

1,1	2,1	3,1	4,1	5,1	6,1	7,1
1,2	2,2	3,2	4,2	5,2	6,2	7,2
1,3	2,3	3,3	4,3	5,3	6,3	7,3
1,4	2,4	3,4	4,4	5,4	6,4	7,4

 Ω

1	2	3	4	5	6	7
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 Ω 

Signals can be represented as vectors



$$\mathbf{x} = [x_1 \ x_2 \ x_3 \ \dots \ x_t \ \dots]^\top$$

x_t are waveform heights



$$\mathbf{x} = [x_{11} \ x_{12} \ \dots \ x_{1n} \ x_{21} \ x_{22} \ \dots]^\top$$

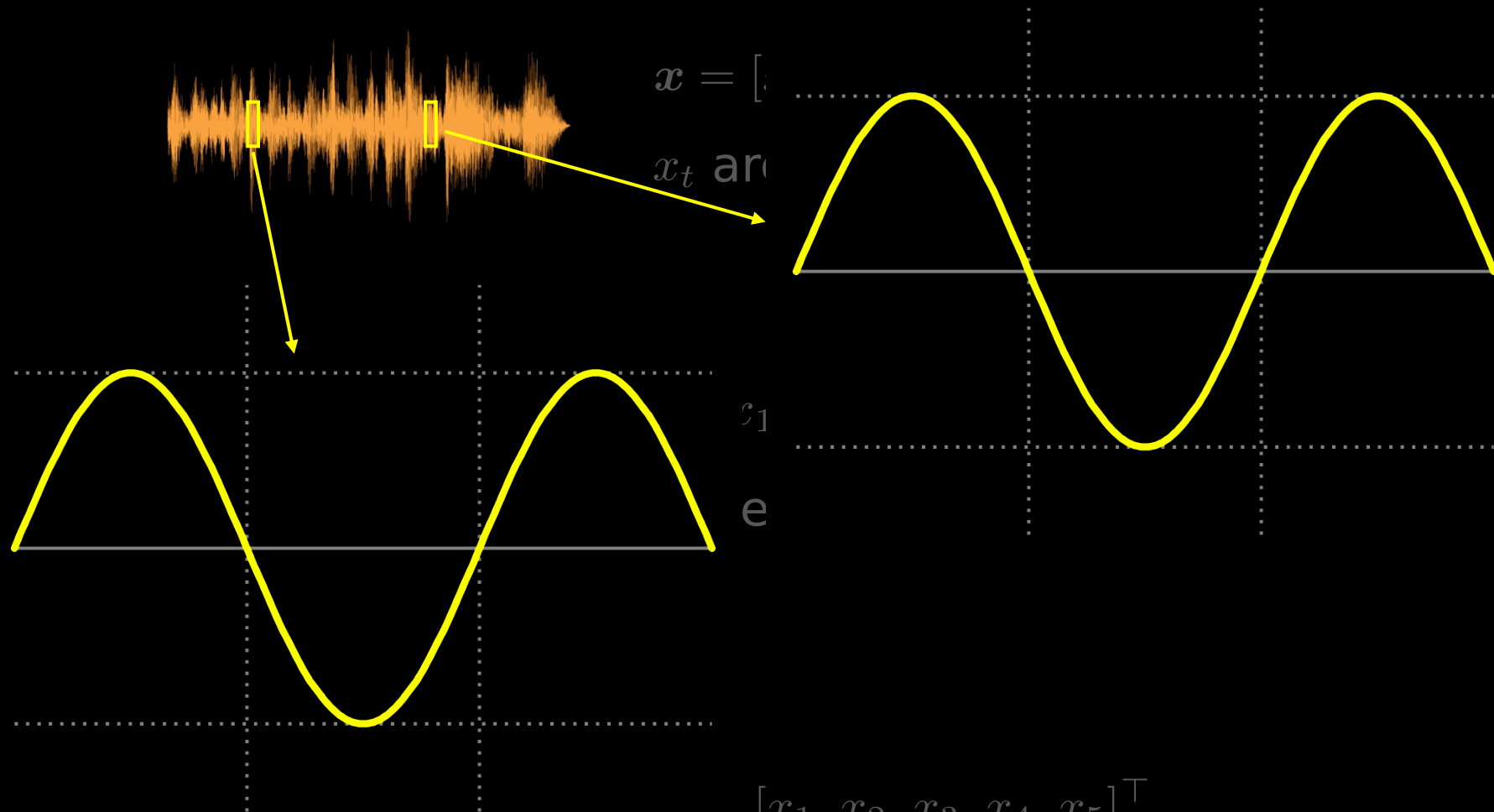
x_{ij} are pixel values

“John picked up the apple”

$$\mathbf{x} = [x_1 \ x_2 \ x_3 \ x_4 \ x_5]^\top$$

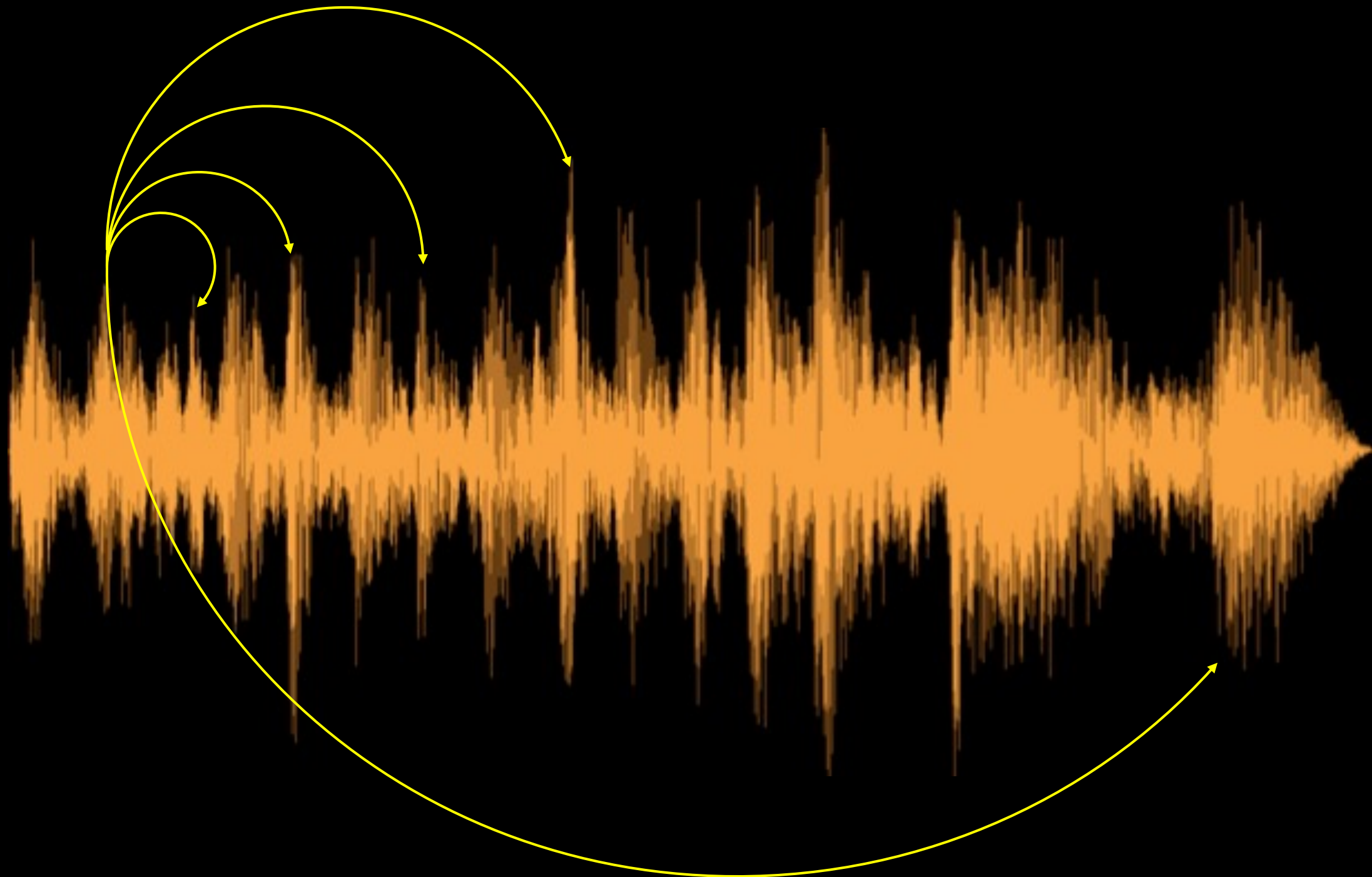
x_t are one-hot vectors

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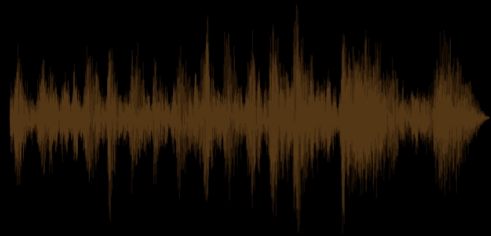
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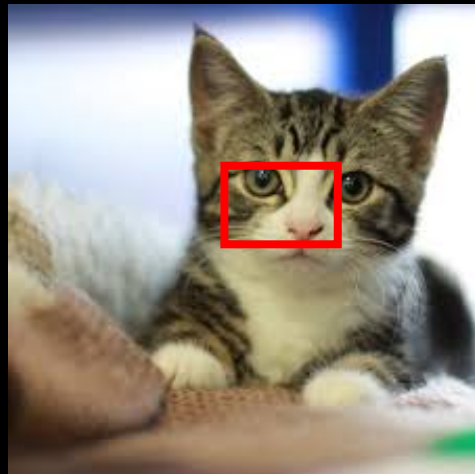
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x_t are waveform heights



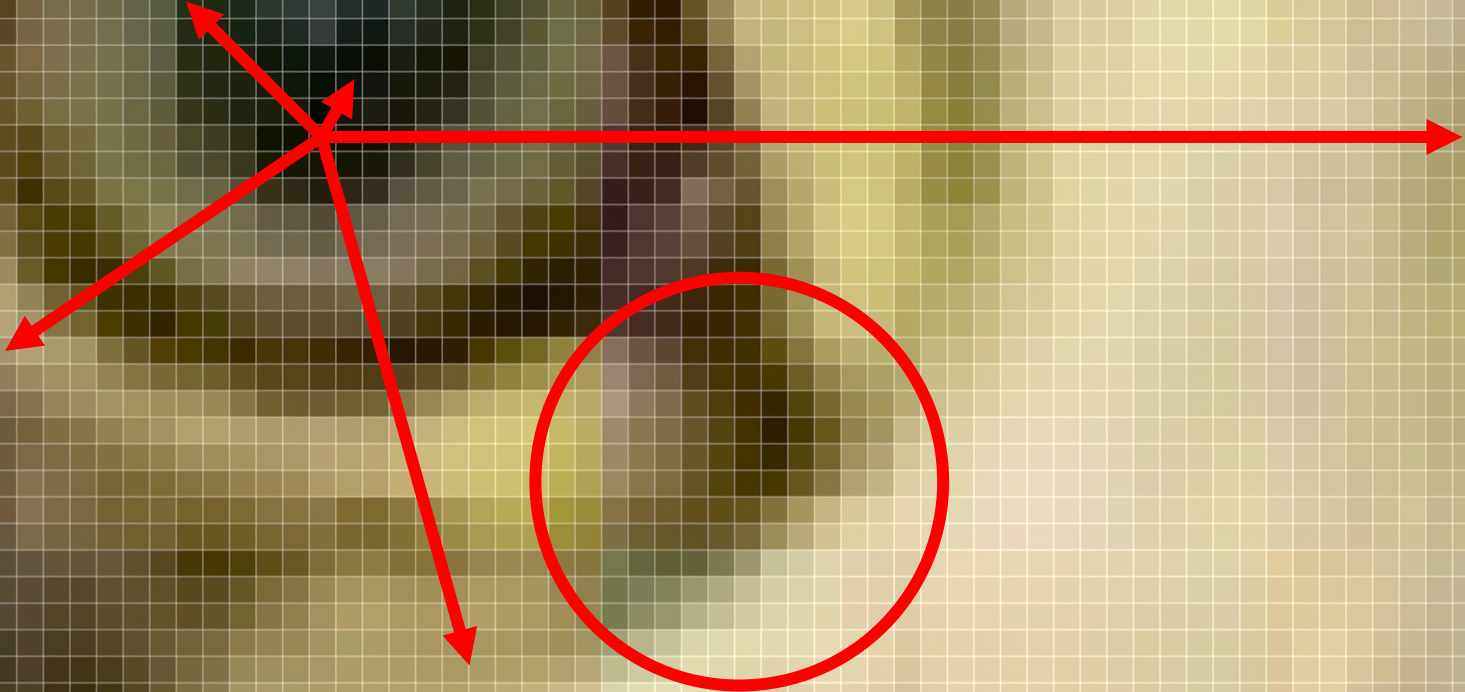
$$\mathbf{x} = [x_{11} \ x_{12} \ \dots \ x_{1n} \ x_{21} \ x_{22} \ \dots]^\top$$

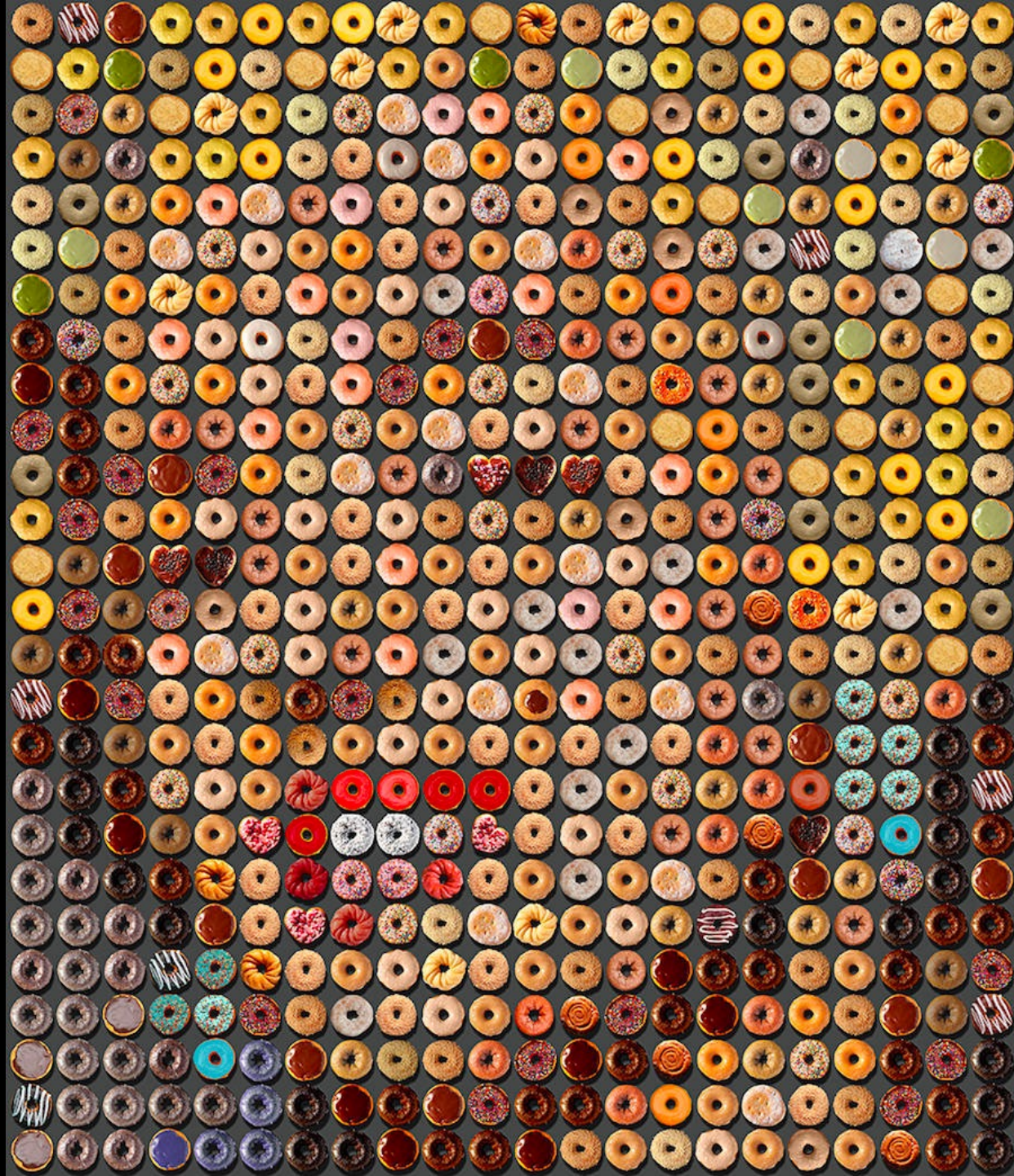
x_{ij} are pixel values

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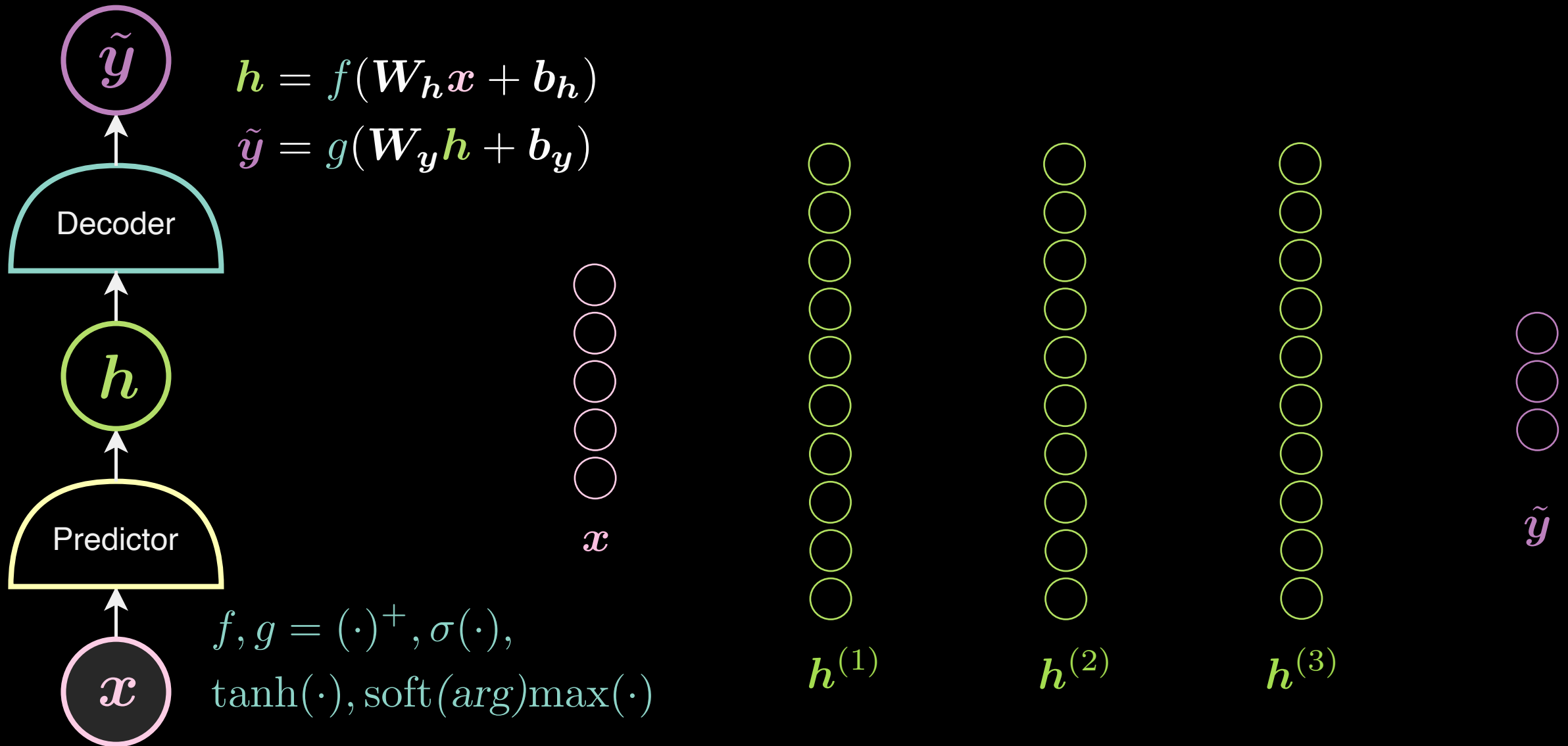
$$\mathbf{x} = [x_1 \ x_2 \ x_3 \ x_4 \ x_5]^\top$$

x_t are one-hot vectors





Fully connected (FC) layer

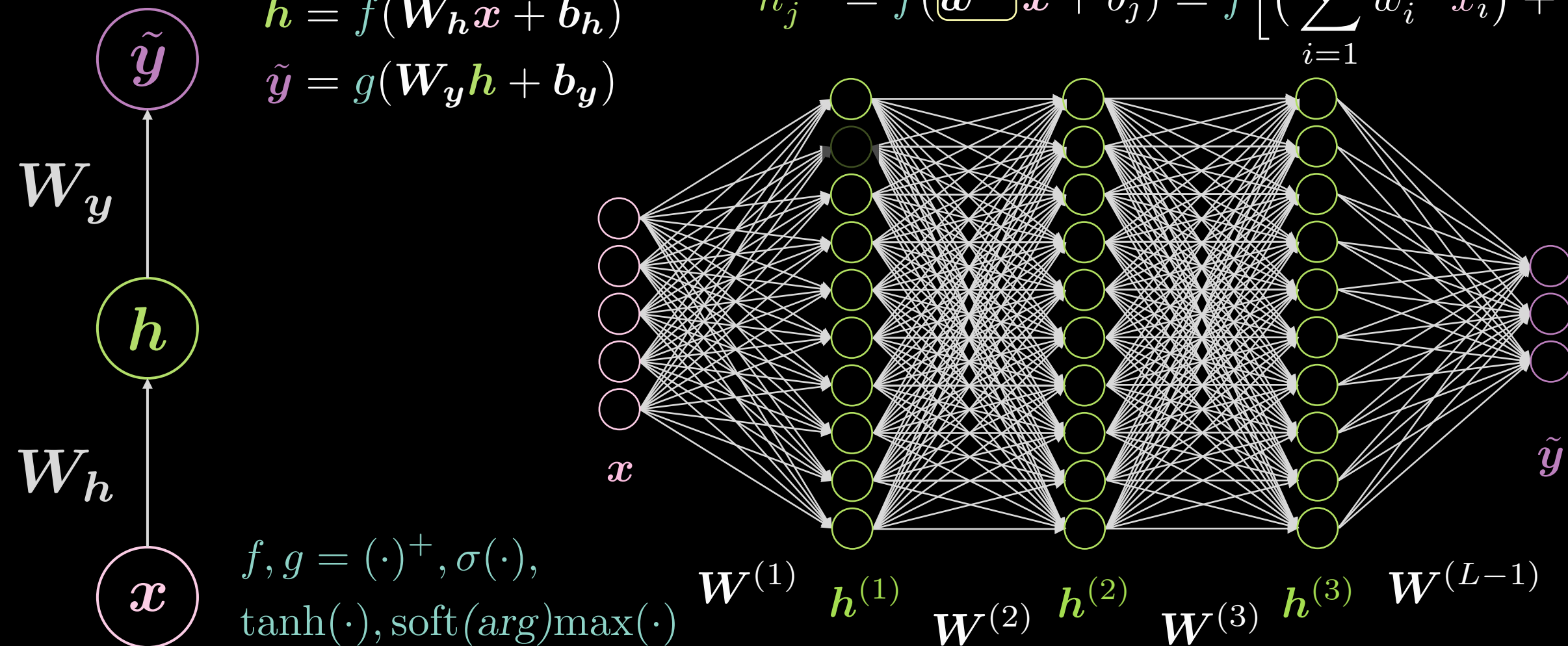


Fully connected (FC) layer

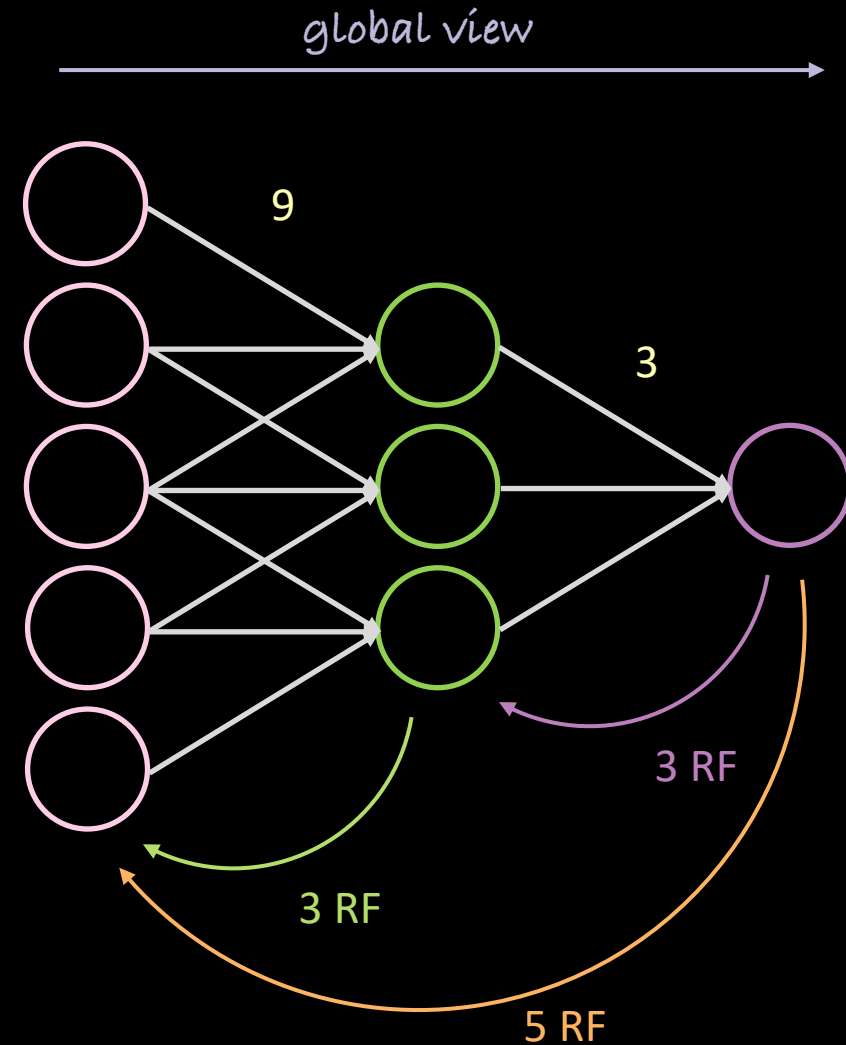
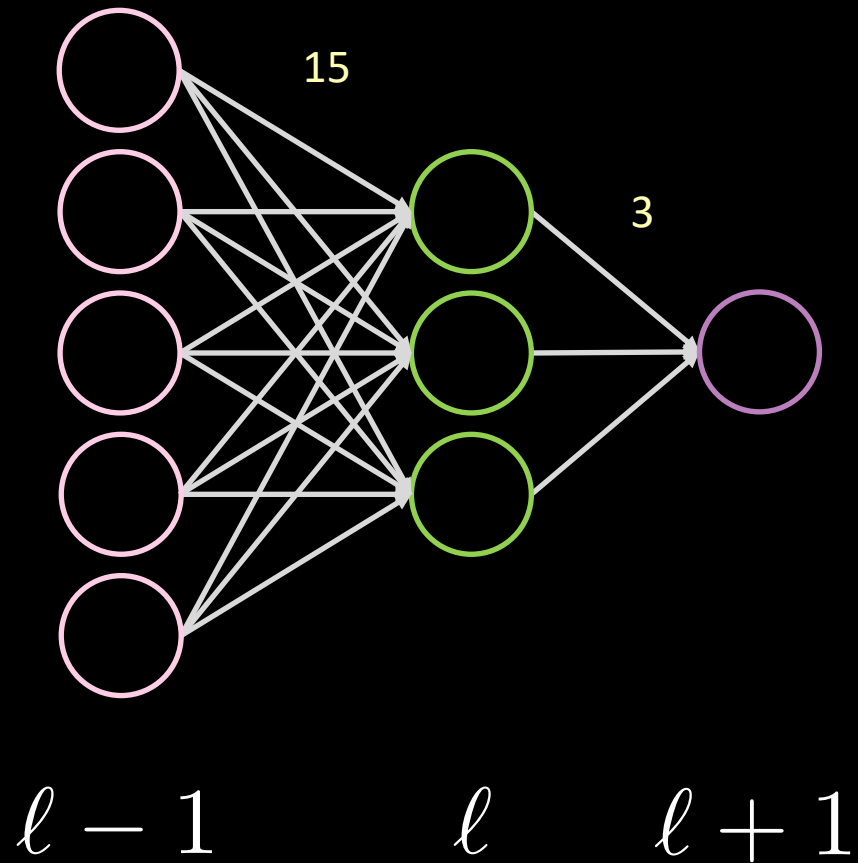
$$\mathbf{h} = f(\mathbf{W}_h \mathbf{x} + \mathbf{b}_h)$$

$$\tilde{\mathbf{y}} = g(\mathbf{W}_y \mathbf{h} + \mathbf{b}_y)$$

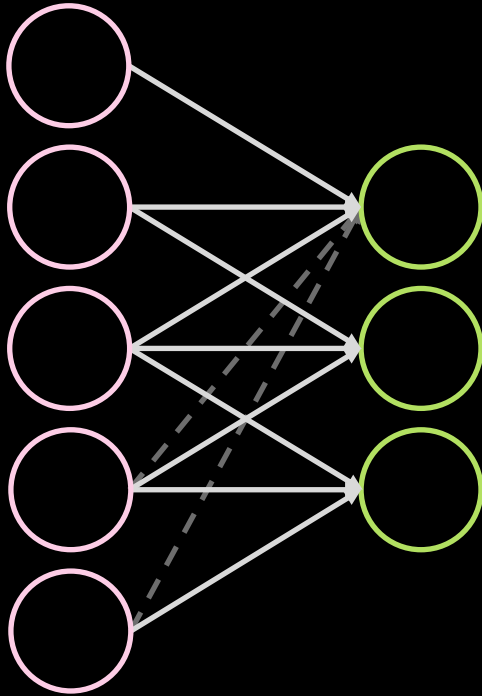
$$h_j^{(1)} = f(\boxed{w^{(j)}} \mathbf{x} + b_j) = f\left[\left(\sum_{i=1}^n w_i^{(j)} x_i\right) + b_j\right]$$



Locality \Rightarrow sparsity



Stationarity \Rightarrow parameters sharing



Parameters sharing

- faster convergence
- better generalisation
- not constrained to input size
- kernel independence
 \Rightarrow high parallelisation

Connection sparsity

- reduced amount of computation

