1. Description

1.1. Project

Project Name	Gyro(F4_V1
Board Name	Gyro(F4_V1.0)
Generated with:	STM32CubeMX 4.23.0
Date	10/29/2018

1.2. MCU

MCU Series	STM32F4
MCU Line	STM32F405/415
MCU name	STM32F405RGTx
MCU Package	LQFP64
MCU Pin number	64

2. Pinout Configuration
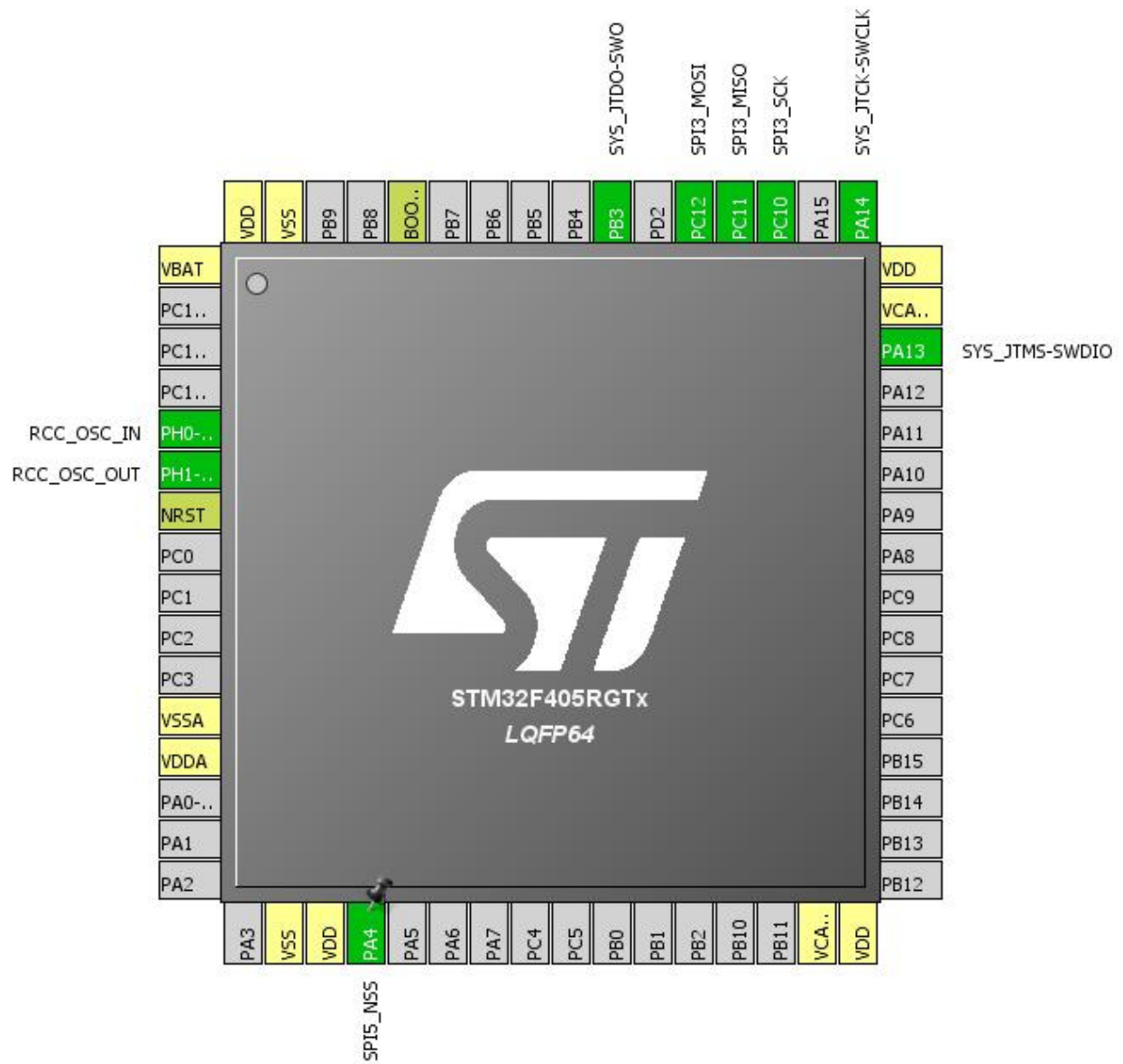
3. Pins Configuration

Pin Number LQFP64	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
1	VBAT	Power		
5	PH0-OSC_IN	I/O	RCC_OSC_IN	
6	PH1-OSC_OUT	I/O	RCC_OSC_OUT	
7	NRST	Reset		
12	VSSA	Power		
13	VDDA	Power		
18	VSS	Power		
19	VDD	Power		
20	PA4 *	I/O	GPIO_Output	SPI5_NSS
31	VCAP_1	Power		
32	VDD	Power		
46	PA13	I/O	SYS_JTMS-SWDIO	
47	VCAP_2	Power		
48	VDD	Power		
49	PA14	I/O	SYS_JTCK-SWCLK	
51	PC10	I/O	SPI3_SCK	
52	PC11	I/O	SPI3_MISO	
53	PC12	I/O	SPI3_MOSI	
55	PB3	I/O	SYS_JTDO-SWO	
60	BOOT0	Boot		
63	VSS	Power		
64	VDD	Power		

* The pin is affected with an I/O function

4. Clock Tree Configuration
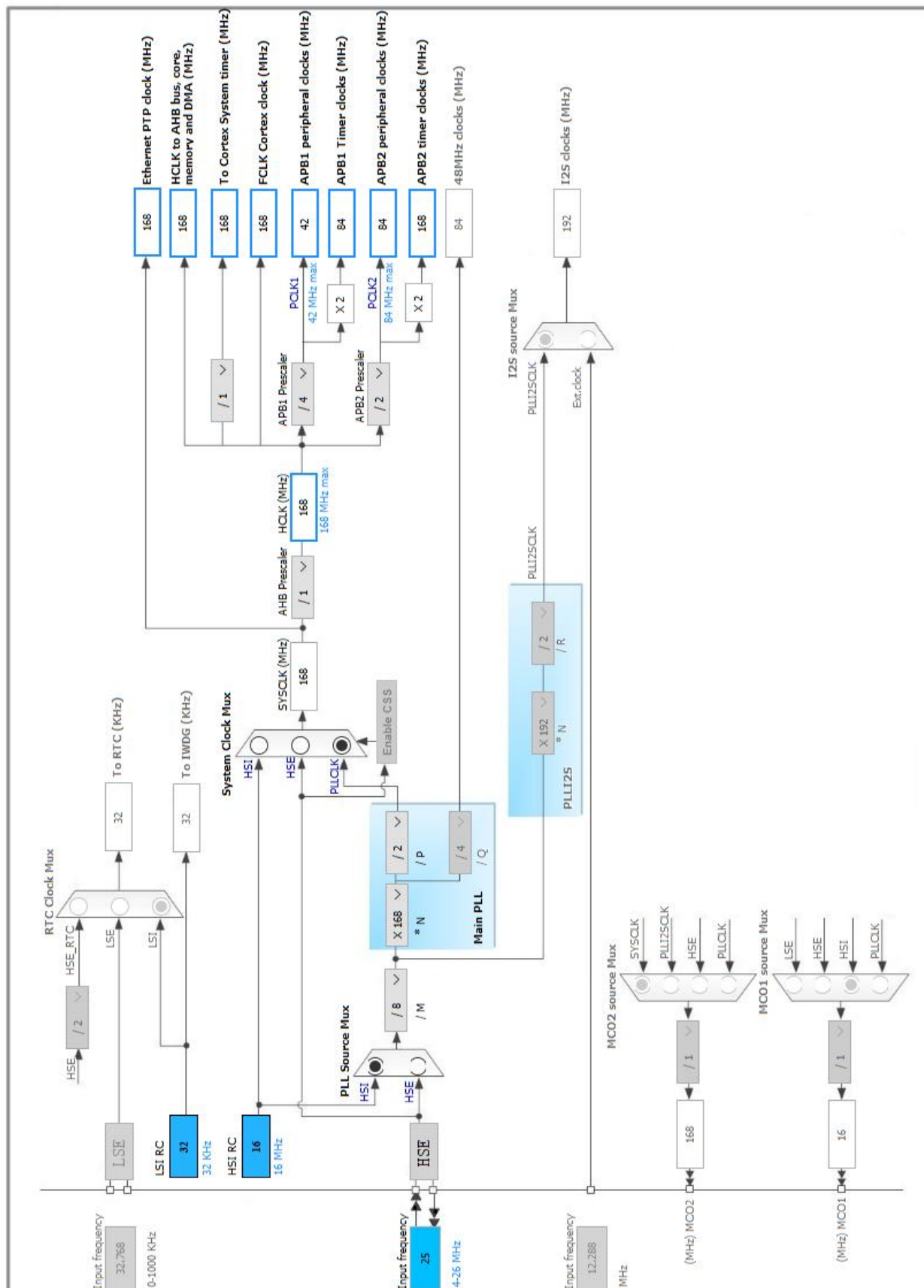
5. IPs and Middleware Configuration

5.1. RCC

High Speed Clock (HSE): Crystal/Ceramic Resonator

5.1.1. Parameter Settings:

System Parameters:

VDD voltage (V)	3.3
Instruction Cache	Enabled
Prefetch Buffer	Enabled
Data Cache	Enabled
Flash Latency(WS)	5 WS (6 CPU cycle)

RCC Parameters:

HSI Calibration Value	16
HSE Startup Timout Value (ms)	100
LSE Startup Timout Value (ms)	5000

Power Parameters:

Power Regulatror Voltage Scale	Power Regulator Voltage Scale 1

5.2. SPI3

Mode: Full-Duplex Master

5.2.1. Parameter Settings:

Basic Parameters:

Frame Format	Motorola
Data Size	8 Bits
First Bit	MSB First

Clock Parameters:

Prescaler (for Baud Rate)	2
Baud Rate	**21.0 MBits/s ***
Clock Polarity (CPOL)	Low
Clock Phase (CPHA)	1 Edge

Advanced Parameters:

CRC Calculation	Disabled

NSS Signal Type	Software

5.3. SYS

Debug: Trace Asynchronous Sw
Timebase Source: SysTick

5.4. FREERTOS

mode: Enabled

5.4.1. Config parameters:

Versions:

FreeRTOS version	9.0.0
CMSIS-RTOS version	1.02

Kernel settings:

USE_PREEMPTION	Enabled
CPU_CLOCK_HZ	SystemCoreClock
TICK_RATE_HZ	1000
MAX_PRIORITIES	7
MINIMAL_STACK_SIZE	128
MAX_TASK_NAME_LEN	16
USE_16_BIT_TICKS	Disabled
IDLE_SHOULD_YIELD	Enabled
USE_MUTEXES	Enabled
USE_RECURSIVE_MUTEXES	Disabled
USE_COUNTING_SEMAPHORES	Disabled
QUEUE_REGISTRY_SIZE	8
USE_APPLICATION_TASK_TAG	Disabled
ENABLE_BACKWARD_COMPATIBILITY	Enabled
USE_PORT_OPTIMISED_TASK_SELECTION	Enabled
USE_TICKLESS_IDLE	Disabled
USE_TASK_NOTIFICATIONS	Enabled

Memory management settings:

Memory Allocation	Dynamic
TOTAL_HEAP_SIZE	15360
Memory Management scheme	heap_4

Hook function related definitions:

USE_IDLE_HOOK	Disabled
USE_TICK_HOOK	Disabled

USE_MALLOC_FAILED_HOOK	Disabled
USE_DAEMON_TASK_STARTUP_HOOK	Disabled
CHECK_FOR_STACK_OVERFLOW	Disabled

Run time and task stats gathering related definitions:

GENERATE_RUN_TIME_STATS	Disabled
USE_TRACE_FACILITY	Disabled
USE_STATS_FORMATTING_FUNCTIONS	Disabled

Co-routine related definitions:

USE_CO_ROUTINES	Disabled
MAX_CO_ROUTINE_PRIORITIES	2

Software timer definitions:

USE_TIMERS	Disabled

Interrupt nesting behaviour configuration:

LIBRARY_LOWEST_INTERRUPT_PRIORITY	15
LIBRARY_MAX_SYSCALL_INTERRUPT_PRIORITY	5

5.4.2. Include parameters:

Include definitions:

vTaskPrioritySet	Enabled
uxTaskPriorityGet	Enabled
vTaskDelete	Enabled
vTaskCleanUpResources	Disabled
vTaskSuspend	Enabled
vTaskDelayUntil	**Enabled** *
vTaskDelay	Enabled
xTaskGetSchedulerState	Enabled
xTaskResumeFromISR	Enabled
xQueueGetMutexHolder	Disabled
xSemaphoreGetMutexHolder	Disabled
pcTaskGetTaskName	Disabled
uxTaskGetStackHighWaterMark	**Enabled** *
xTaskGetCurrentTaskHandle	Disabled
eTaskGetState	Disabled
xEventGroupSetBitFromISR	Disabled
xTimerPendFunctionCall	Disabled
xTaskAbortDelay	Disabled
xTaskGetHandle	Disabled

* User modified value

6. System Configuration

6.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
RCC	PH0-OSC_IN	RCC_OSC_IN	n/a	n/a	n/a	
	PH1-OSC_OUT	RCC_OSC_OUT	n/a	n/a	n/a	
SPI3	PC10	SPI3_SCK	Alternate Function Push Pull	No pull-up and no pull-down	**Very High** *	
	PC11	SPI3_MISO	Alternate Function Push Pull	No pull-up and no pull-down	**Very High** *	
	PC12	SPI3_MOSI	Alternate Function Push Pull	No pull-up and no pull-down	**Very High** *	
SYS	PA13	SYS_JTMS-SWDIO	n/a	n/a	n/a	
	PA14	SYS_JTCK-SWCLK	n/a	n/a	n/a	
	PB3	SYS_JTDO-SWO	n/a	n/a	n/a	
GPIO	PA4	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	SPI5_NSS

6.2. DMA configuration

nothing configured in DMA service

6.3. NVIC configuration

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Pre-fetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	15	0
System tick timer	true	15	0
PVD interrupt through EXTI line 16	unused		
Flash global interrupt	unused		
RCC global interrupt	unused		
SPI3 global interrupt	unused		
FPU global interrupt	unused		

* User modified value

7. Power Consumption Calculator report

7.1. Microcontroller Selection

Series	STM32F4
Line	STM32F405/415
MCU	STM32F405RGTx
Datasheet	022152_Rev8

7.2. Parameter Selection

Temperature	25
Vdd	3.3

8. Software Project

8.1. Project Settings

Name	Value
Project Name	Gyro(F4_V1.0)
Project Folder	C:\Users\hp\Desktop\cubeMX\Gyro(F4_V1.0)
Toolchain / IDE	MDK-ARM V5
Firmware Package Name and Version	STM32Cube FW_F4 V1.17.0

8.2. Code Generation Settings

Name	Value
STM32Cube Firmware Library Package	Copy all used libraries into the project folder
Generate peripheral initialization as a pair of '.c/.h' files	Yes
Backup previously generated files when re-generating	No
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power consumption)	No